```
o sketch_aug03a | Arduino 1.8.13 (Windows Store 1.8.42.0)
File Edit Sketch Tools Help
  sketch_aug03a§
#include <dht.h>
#define dht apin A0
dht DHT;
void setup() {
  Serial.begin(9600);
  delay(500);
  Serial.println("DHTll Humidity & temperature Sensor\n\n");
  delay(1000);
}
void loop(){
    DHT.readll(dht_apin);
    Serial.print("Current humidity = ");
    Serial.print(DHT.humidity);
    Serial.print("% ");
    Serial.print("temperature = ");
    Serial.print(DHT.temperature);
    Serial.println("C ");
    delay(5000);
}
```

```
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long interval = 100; // Interval at which LED blinks
void setup()
  //The Following are our output
  pinMode (ledPin, OUTPUT);
  pinMode(buzzerPin,OUTPUT);
  //Button is our Input
  pinMode (buttonPin, INPUT);
  // Wait before starting the alarm
  delay(5000);
void loop()
  // To chech whether the motion is detected or not
  if (digitalRead(motionPin)) {
    buzzer mode = true;
   }
  // If alarm mode is on, blink our LED
  if (buzzer mode) {
    unsigned long currentMillis = millis();
    if(currentMillis - previousMillis > interval) {
       previousMillis = currentMillis;
       if (ledState == LOW)
         ledState = HIGH;
```

```
const char eventTopic[] = "iot-2/evt/status/fmt/json";
const char cmdTopic[] = "iot-2/cmd/led/fmt/json";
WiFiClient wifiClient:
void callback(char* topic, byte* payload, unsigned int payloadLength) {
  Serial.print("Message arrived [");
  Serial.print(topic);
  Serial.print("] ");
  for (int i = 0; i < payloadLength; i++) {
    Serial.print((char)payload[i]);
  Serial.println();
  // Switch on the LED if an 1 was received as first character
```

char server[] = ORG ".messaging.internetofthings.ibmcloud.com";

char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE ID;

#define TOKEN "12345678"

char token[] = TOKEN;

char authMethod[] = "use-token-auth";



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```
int Publish(char* payload, int payload size) {
  int rc = -1:
 MOTTClient client = {0};
 MQTTClient connectOptions conn opts = MQTTClient connectOptions initializer;
 MQTTClient message pubmsg = MQTTClient message initializer;
 MQTTClient deliveryToken token = {0};
 MQTTClient_create(&client, opts.address, opts.clientid,
                    MOTTCLIENT PERSISTENCE NONE, NULL);
  conn opts.keepAliveInterval = 60;
  conn opts.cleansession = 1;
  conn opts.username = k_username;
  conn opts.password = CreateJwt(opts.keypath, opts.projectid, opts.algorithm);
 MQTTClient SSLOptions sslopts = MQTTClient SSLOptions initializer;
  sslopts.trustStore = opts.rootpath;
  sslopts.privateKey = opts.keypath;
  conn opts.ssl = &sslopts;
  unsigned long retry interval ms = kInitialConnectIntervalMillis;
  unsigned long total retry time ms = 0;
  while ((rc = MQTTClient connect(client, &conn opts)) != MQTTCLIENT SUCCESS) {
    if (rc == 3) { // connection refused: server unavailable
      usleep(retry interval ms * 1000);
      total retry time ms += retry interval ms;
      if (total retry time ms >= kMaxConnectRetryTimeElapsedMillis) {
       printf("Failed to connect, maximum retry time exceeded.");
       exit(EXIT FAILURE);
```