PREDICTIVE MAINTENA	NCE OF INDUSTRIAL MOTOR	S
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DONE BY : NISHITHA V		

1) INTRODUCTION:

1.1 OVERVIEW:

The objective of this kind of motor maintenance is to ensure that the right kind of maintenance is carried out at the right time. In order to define these two parameters, it is necessary to monitor the motor operation regularly and thereby detect problems before they actually occur.

1.2 PURPOSE:

To prevent critical breakdowns rather than repairing them. In plant operations, unscheduled stoppage of production or long repair shutdowns are intolerable. The resultant downtime eats deeply into production times. Periodic inspections of motors are necessary to ensure best operating results.

2) LITERATURE SURVEY:

2.1 EXISTING PROBLEM:

When an electric motor needs repairs, it is usually for one of the following reasons.

- Winding failures: Stressful mechanical, environmental, and electrical operating conditions can all cause electric motor failure
- Contamination: Grease, oil, and dirt are common contaminants that can make their way into electric motors. Moisture, which is a damaging contaminant, can also negatively affect ac motors and dc motors.
- Electrical and mechanical issues: Electrical and mechanical problems are
 other significant electric motor repair causes. Ranging from electrical
 overload to broken and worn parts, electrical and mechanical issues can
 severely impact a motor's ability to work correctly. These issues usually
 affect the electric motor winding.

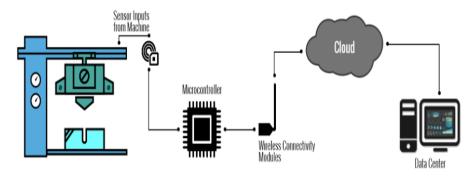
2.2 PROPOSED SOLUTION:

- Winding failures: To avoid conditions that cause stress to the electrical appliances.
- Contamination: To make sure that the motor doesn't get in contact with external dust, grease, oil and dirt and kept in a dry place and make sure its not moist.

• Electrical and mechanical issues: To make sure that the motors are serviced properly in equal intervals of time and make sure they don't get electrical damage.

3) THEORITICAL ANALYSIS:

3.1 Block diagram:



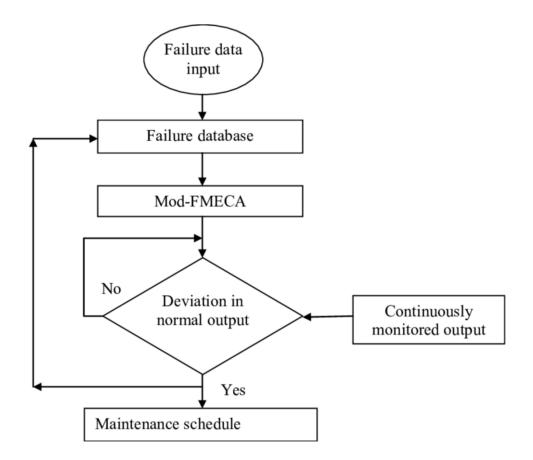
3.2 Software designing:

Software components used are: 1.IBM cloud 2.IBM IOT platform 3.IBM Watson 4.node-red 5.Python IDLE 6.MIT app inventor

4) EXPERIMENTAL INVESTIGATIONS:

MCCB traditional maintenance process is done by removing dust and internal soil by cleaning the external body only. Therefore, carbon atoms are formed at the contact points. In this work, a new maintenance technique is proposed to enhance the maintenance process, adding the titanium oxide (TiO_2) into the insulating oil to prevent contamination .

5) FLOWCHART:



6) RESULT:

This was built using IBM watson assistant, IOT sensor simulator to check the maintenance of motors in industries.

7) ADVANTAGES & DISADVANTAGES

ADVANTAGE:

- Electric supply to the motor is proper.
- Bearings and shafts are fixed properly with no contamination .

DISADVANTAGE:

- More money upfront
- Over maintenance
- More workers

8) APPLICATIONS:

- Allows exchanging data from one end to other .
- Improves the usage quality of motor .
- Saves money.

- Better adherence to the maintenance of the motors.
- Reduction in investing money to get new motors .

9) CONCLUSION

The predictive maintenance app is available on your phones. Any time, any place it can be accessible. It is very feasible and eco-friendly. This helps to detect any problem in the motors and can be rectified when necessary.

10) FUTURE SCOPE

- With more High-end hardware and software, the Predictive maintenance can be customized and can be upgraded and improved for more efficiency and success rate in future.
- 11) BIBILOGRAPHY
- Github
- youtube
- smart internz

12) APPENDIX

A. SOUURCE CODE:

1. DHT11 SENSOR TO MEASURE HUMIDITY AND TEMPERATURE:

```
#include <dht.h>
#define dht_apin A0
dht DHT;
void setup(){
Serial.begin(9600); delay(500);
Serial.println("DHT11 Humidity & temperature Sensor\n\n"); delay(1000);
}
void loop(){
DHT.read11(dht_apin);
Serial.print("Current humidity = ");
Serial.print(DHT.humidity);
Serial.print("% ");
```

```
Serial.print("temperature = ");
Serial.print(DHT.temperature);
Serial.println("C ");
delay(5000);
2.<u>VIBRATION SENSOR</u>:
int vib_pin=7;
int led_pin=13;
void setup() {
 pinMode(vib_pin,INPUT);
 pinMode(led_pin,OUTPUT);
void loop() {
 int val;
 val=digitalRead(vib_pin);
 if(val==1)
  digitalWrite(led_pin,HIGH);
  delay(1000);
digitalWrite(led_pin,LOW);
  delay(1000);
 }
else
digitalWrite(led_pin,LOW);
3.CURRENT SENSOR:
void setup() {
Serial.begin(9600);
}
void loop() {
unsigned int x=0;
```

```
float AcsValue=0.0,Samples=0.0,AvgAcs=0.0,AcsValueF=0.0;
for (int x = 0; x < 150; x++)
AcsValue = analogRead(A0);
Samples = Samples + AcsValue;
delay (3);
}
AvgAcs=Samples/150.0;
AcsValueF = (2.5 - (AvgAcs * (5.0 / 1024.0)))/0.185;
Serial.print(AcsValueF);
delay(50);
}
4.SWITCH AND LED INDICATION:
void setup() {
pinMode(13, OUTPUT);
}
void loop() {
digitalWrite(13, HIGH);
delay(1000);
digitalWrite(13, LOW);
delay(1000);
B. UI output Screenshot.
```

