Scientific Seminar

SmartRaCon Introduction





















Scientific Seminar



SRC1SS 2.5.

25. June 2019, in presence in Villeneuve d'Ascq, France 1 Day event: 9 contributions, posters, round table

SRC2SS

24. November 2020, online from Donostia-San Sebastian, Spain 1 Day event: 13 contributions, round table

SRC3SS

2. September 2021, online from Braunschweig, Germany 1 Day event: 10 contributions, round table

SRC4SS

20. October 2022, hybrid from Donostia-San Sebastian, Spain 1 Day event: 10 contributions, round table

SRC5SS

25. May 2023, hybrid from Berlin, Germany 1 Day event: 16 contributions, round table















Scientific Seminar



























SmartRaCon







SRC2SS

SRC3SS

SRC4SS

SRC5SS

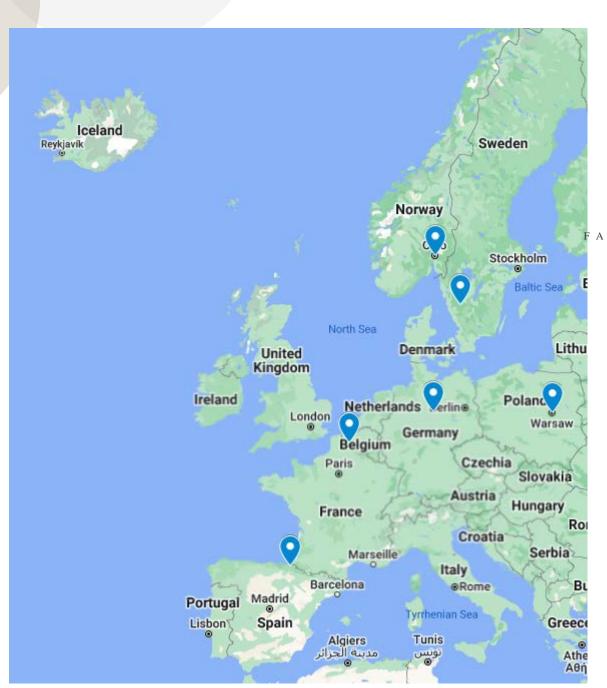
SRC5SS

23-24. October 2024, hybrid from Donostia-San Sebastian, Spain





Scientific Seminar







 $\label{eq:falling} F~A~1~,~~F~A~2~,~~F~A~3~,~~F~A~4~,~~F~A~5~,~~F~A~6~,~~T~T$







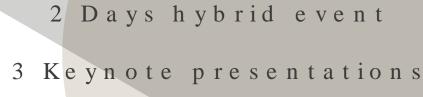












7 PhD presentations

13 Project Presentations

10 Posters

28 Presenters

16 Presenting entities

10 Projects



 $F A 1 \,, \quad F A 2 \,, F A 4 \,\,, \quad F A 5 \,\,, \quad F A 6$



FA2, FA3, FA4, FA7, ER



F A 1, F A 3, F A 5



FA6







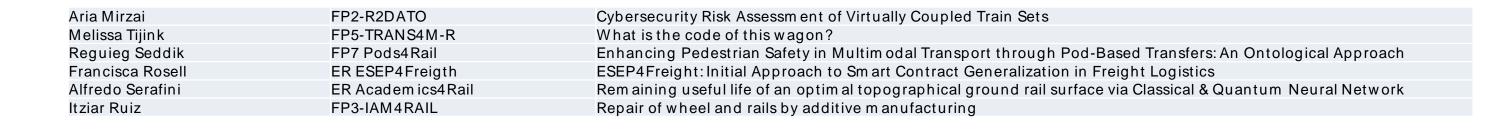


Scientific Seminar

PhD Session 1 Paul Unterhuber	Communications
PhD Session 2 Marion Berbienau	Monitoring and Automation
Project Session 1 Marvin Damschen	Rail management and planning
Project Session 2 Gorka de Miguel	Digitalisation
Project Session 3 Marie Lindland	Autom ation

Round table Jaizki Mendizabal Marco Ferreria (Siemens)
Marvin Damschen (RISE)
Jan Bergstrand (Trafikverket)
Lea Paties (ERJU)
Carles Miralpeix (FGC)







Proceedings

Proceedings of the 6th SmartRaCon Scientific Seminar SRC6SS

Proceedings of the 6th SmartRaCon Scientific Seminar (SRC6SS)

Marion Berbineau, Markus Brachner, Marvin Damschen, Agnieszka Łukasiewicz, Jaizki Mendizabal, Michael Meyer zu Hörste

Deutsches Zentrum für Luft- und Raumfah

Institut of Transportation Systems





SmartRaCon	SRC6SS proceedings	₽ _{DI}
11. Planning Problems in a Co	ombined Yard and Intermodal Rail Freight Terminal	89
11.1. Introduction		89
11.2. Challenges when planning o	perations	90
11.2.1. Time horizons		90
11.2.2. Competition between actor	ors	90
11.2.3. A web of related planning	problems	91
11.3. Case-study: Optimizing load	ing tracks assignment	91
11.3.1. Planning in isolation		91
11.3.2. Combining with yard plans	ning	91
11.4. Decision Intelligence suppor	t	92
11.5. Conclusions		92
Bibliography		93
List of Abbreviations		93
Zoom Authors		93
12. Digital Twin Developmen	t for Test Site: Foundation for Innovative Cost-Effectiv	e Train
12. Digital Twin Developmen Positioning Alignment	t for Test Site: Foundation for Innovative Cost-Effectiv	e Train 95
12. Digital Twin Developmen Positioning Alignment 12.1. Introduction	t for Test Site: Foundation for Innovative Cost-Effectiv	e Train 95 95
12. Digital Twin Developmen Positioning Alignment 12.1. Introduction	t for Test Site: Foundation for Innovative Cost-Effectiv	e Train 95 95
12. Digital Twin Developmen Positioning Alignment 12.1. Introduction	t for Test Site: Foundation for Innovative Cost-Effectiv	e Train 95 95 96
12. Digital Twin Developmen Positioning Alignment 12.1. Introduction 12.2. Method 12.3. Results 12.4. Future work and expected o	t for Test Site: Foundation for Innovative Cost-Effectiv	e Train 95 95 96 97
12. Digital Twin Developmen Positioning Alignment 12.1. Introduction 12.2. Method 12.3. Results 12.4. Future work and expected o	t for Test Site: Foundation for Innovative Cost-Effectiv	e Train 95 95 96 97
12. Digital Twin Developmen Positioning Alignment 12.1. Introduction 12.2. Method 12.3. Results 12.4. Future work and expected o Bibliography	t for Test Site: Foundation for Innovative Cost-Effectiv	e Train 95 95 96 97 99
12. Digital Twin Development Positioning Alignment 12.1. Introduction 12.2. Method 12.3. Results 12.4. Future work and expected o Bibliography Zoom Authors	t for Test Site: Foundation for Innovative Cost-Effectiv	e Train 95 95 96 97 99 99
12. Digital Twin Developmen Positioning Alignment 12.1. Introduction 12.2. Method 12.3. Results 12.4. Future work and expected o Bibliography Zoom Authors 13. EURAIL – FA6 FutuRe Proj	t for Test Site: Foundation for Innovative Cost-Effectiv utcomes ject: Innovative solutions for G2 regional lines	e Train9596979999100
12. Digital Twin Developmen Positioning Alignment 12.1. Introduction 12.2. Method 12.3. Results 12.4. Future work and expected o Bibliography Zoom Authors 13. EURAIL – FA6 FutuRe Proj 13.1. Abstract	t for Test Site: Foundation for Innovative Cost-Effectiv	e Train9596979999100101101
12. Digital Twin Development Positioning Alignment 12.1. Introduction 12.2. Method 12.3. Results 12.4. Future work and expected o Bibliography Zoom Authors 13. EURAIL – FA6 FutuRe Proj 13.1. Abstract 13.2. Introduction	t for Test Site: Foundation for Innovative Cost-Effectiv utcomes ject: Innovative solutions for G2 regional lines	e Train95969799100101101101
12. Digital Twin Development Positioning Alignment 12.1. Introduction 12.2. Method 12.3. Results 12.4. Future work and expected o Bibliography Zoom Authors 13. EURAIL – FA6 FutuRe Proj 13.1. Abstract 13.2. Introduction 13.2.1. Key cost drivers affecting r	t for Test Site: Foundation for Innovative Cost-Effectiv utcomes ject: Innovative solutions for G2 regional lines	e Train9595969799100101101101101
12. Digital Twin Developmen Positioning Alignment 12.1. Introduction 12.2. Method 12.3. Results 12.4. Future work and expected o Bibliography Zoom Authors 13. EURAIL – FA6 FutuRe Proj 13.1. Abstract 13. 2. Introduction 13.2.1. Key cost drivers affecting in 13.3. G2 Lines Architecture	t for Test Site: Foundation for Innovative Cost-Effectiv outcomes ject: Innovative solutions for G2 regional lines regional low-density lines competitiveness.	e Train95969799100101101101101101102
12. Digital Twin Development Development String Alignment 12.1. Introduction 12.4. Future work and expected o Bibliography Zoom Authors 13. EURAIL – FA6 FutuRe Proj 13.1. Abstract 13.2. Introduction 13.2.1. Key cost drivers affecting r 13.3. G2 liers Architecture 13.3. Rationale 13.3.	t for Test Site: Foundation for Innovative Cost-Effective Innovative Cost-Effective Interest Site: Foundation for Innovative Cost-Effective Interest Site: Foundation for Innovative Cost-Effective Innovative	e Train 95 96 97 99 100 101 101 101 101 102 102 102
12. Digital Twin Development Positioning Alignment 12.1. Introduction 12.4. Future work and expected o Bibliography Zoom Authors 13.1. Abstract 13.1. Abstract 13.2. Introduction 13.2.1. Key cost drivers affecting 13.3.6 Lines Architecture 13.3.1. Standardisation and Interes 13.3.2. Standardisation and Interes	t for Test Site: Foundation for Innovative Cost-Effectiv utcomes ject: Innovative solutions for G2 regional lines regional low-density lines competitiveness.	e Train 95 95 96 97 99 100 101 101 101 101 102 102 103
12. Digital Twin Developmen Positioning Alignment 12.1. Introduction 12.2. Method 12.3. Results 12.4. Future work and expected o Bibliography Zoom Authors 13. EURAIL – FA6 FutuRe Proj 13.1. Abstract . 13.2. Introduction 13.2.1. Key cost drivers affecting r 13.3. G2 Lines Architecture 13.3.1. Rationale. 13.3.2. Standardisation and Interc 13.3.3. Building blocks.	t for Test Site: Foundation for Innovative Cost-Effective Innovative Cost-Effective Interest Site: Foundation for Innovative Cost-Effective Interest Site: Foundation for Innovative Cost-Effective Innovative	e Train9595969999100101101101101101102102103103
12. Digital Twin Developmen Positioning Alignment 12.1. Introduction 12.2. Method 12.3. Results 12.4. Future work and expected o Bibliography Zoom Authors 13. EURAIL – FA6 FutuRe Proj 13.1. Abstract 13.2.1. Nety cost drivers affecting r 13.3. G2 Lines Architecture 13.3.1. Rationale 13.3.2. Standardisation and Intere 13.3.3. Builing blocks. 13.4. Conclusions.	t for Test Site: Foundation for Innovative Cost-Effectiv utcomes ject: Innovative solutions for G2 regional lines regional low-density lines competitiveness.	e Train95959699100101101101101102102103103105

6th SmartRaCon

Inhalt	
6 th SmartRaCon Scientific Seminar Committees	
Keynote	
SmartRaCon Introduction	
1.1. Smart Rail Control Systems – SmartRaCon background at Shift2Rail	
1.2. Europe's Rail	
1.3. Partnership in the frame of international collaboration	
1.4. Europe's rail participation	
1.5. Research Infrastructures and Simulators	
1.6. SmartRaCon Scientific Seminar	
Bibliography	
Bibliography	
Zoom Authors	odal environment
Zoom Authors 2. Europe's Rail Flagship Project 1 - Mobility management multimodigital enablers 2.1 Introduction.	odal environment
Zoom Authors	odal environment
Zoom Authors 2. Europe's Rail Flagship Project 1 - Mobility management multimodigital enablers 2.1 Introduction. 2.2 Planning and Capacity Management System	odal environment
Zoom Authors 2. Europe's Rail Flagship Project 1 - Mobility management multimodigital enablers 2.1. Introduction 2.2. Planning and Capacity Management System 2.3. Operations - modernizing traffic management systems	odal environment
Zoom Authors 2. Europe's Rail Flagship Project 1 - Mobility management multimodigital enablers 2.1. Introduction 2.2. Planning and Capacity Management System 2.3. Operations - modernizing traffic management systems 2.4. Multimodal Integration	odal environment
Zoom Authors 2. Europe's Rail Flagship Project 1 - Mobility management multimodigital enablers 2.1. Introduction 2.2. Planning and Capacity Management System. 2.3. Operations - modernizing traffic management systems. 2.4. Multimodal Integration. 2.5. Digital Enablers for the European Rail System.	odal environment
Zoom Authors 2. Europe's Rail Flagship Project 1 - Mobility management multimodigital enablers 2.1. Introduction. 2.2. Planning and Capacity Management System 2.3. Operations - modernizing traffic management systems 2.4. Multimodal Integration 2.5. Digital Enablers for the European Rail System 2.6. Conclusion	odal environment
Zoom Authors 2. Europe's Rail Flagship Project 1 - Mobility management multimodigital enablers 2.1. Introduction 2.2. Planning and Capacity Management System 2.3. Operations - modernizing traffic management systems 2.4. Multimodal Integration 2.5. Digital Enablers for the European Rail System 2.6. Conclusion Bibliography Zoom Authors	odal environment
Zoom Authors 2. Europe's Rail Flagship Project 1 - Mobility management multimodigital enablers 2.1. Introduction 2.2. Planning and Capacity Management System 2.3. Operations - modernizing traffic management systems 2.4. Multimodal Integration 2.5. Digital Enablers for the European Rail System 2.6. Conclusion Bibliography Zoom Authors	odal environment
Zoom Authors 2. Europe's Rail Flagship Project 1 - Mobility management multimodigital enablers 2.1. Introduction 2.2. Planning and Capacity Management System 2.3. Operations - modernizing traffic management systems 2.4. Multimodal Integration 2.5. Digital Enablers for the European Rail System 2.6. Conclusion Bibliography Zoom Authors	odal environment
Zoom Authors 2. Europe's Rail Flagship Project 1 - Mobility management multime digital enablers 2.1. Introduction 2.2. Planning and Capacity Management System. 2.3. Operations - modernizing traffic management systems 2.4. Multimodal integration 2.5. Digital Enablers for the European Rail System. 2.6. Conclusion Bibliography Zoom Authors 3. Maglev Derived Systems for Rail	odal environment

Snart Ra Cori SRC6SS proceedings	₽
Zoom Authors	106
4. Demand-driven Optimization of Public Transit	107
14.1. Introduction	107
14.2. Technical Background	107
14.2.1. Data Analysis for Occupancy Estimation	107
14.2.2. Addressing Data Imbalance in Occupancy Prognosis with SMOTE	109
14.2.3. Modelling Approach	109
14.2.4. Short-Term Forecasts	109
14.3. Applications	109
14.3.1. Occupancy Prognosis	109
14.3.2. Incident and Event Detection	110
14.3.3. Planning and Operation of Demand-Responsive Transport (DRT)	111
14.3.4. Building Timetables Based on Real Demand	112
14.4. Conclusion	113
Bibliography	113
List of abbreviations	113
Zoom Authors	113
5. Use cases and conceptual system specification for Self-Propelled Wagon	115
15.1. Introduction and aim	115
15.2. State of the art	115
15.3. Use case definition	116
15.4. Needs analysis	117
15.4.1. Workshop	117
15.4.2. Survey.	118
15.5. Conceptual analysis of the impact of the self-propelled wagon on digitalization of freight operation	119
15.6. Conceptual system architecture	120
15.7. Conclusions	121
Bibliography	122
Zoom authors	122
Cybersecurity Risk Assessment of Virtually Coupled Train Sets	124
16.1 Introduction	124
16.2. Background	124

SRC6SS proce	edings	V _D
3.2. Approach and method		27
3.2.1. Technology Readiness Assessment for the technology	gies involved in MDS	27
3.2.2. Definition of Use Cases and methodology of the MC		
3.2.3. Application of the MCA		29
3.2.4. Selection of three MDS configurations		
3.3. Conclusion and Perspective		32
Zoom Authors		32
PhD		_33
New Generation Train Communication Netwo	rk	_34
4.1. Introduction.		34
4.2. Related works		34
4.3. Requirements and User Needs		35
4.4. Train services		36
4.5. Scenarios and Use Cases		36
4.6. TCMS and OMTS Requirements		37
4.7. Candidate Wireless Technologies		38
4.7.1. LTE-V2X		38
4.7.2. Ultra-Wide Band		38
4.7.3. Wi-Fi		38
4.7.4. ITS-G5		39
4.7.5. NR-V2X		39
4.8. Conclusion		39
Bibliography		39
Zoom Authors		40
5. NG-TCN: Towards Network Slicing in on-board		orks 42
5.1. Introduction		_
5.2. Background		43
5.2.1. The Wireless Train Backbone Problem		43
5.2.2. The Network Slicing (NS) Principle		43
5.3. Related Works		44
5.4. Leveraging NS in WLTBN		44

itel: SRC6SS Proceedings Version: 1.0	Datum: 13.10.2024 Erstellt von: SmartRaCon	Geprüft von: SmartRaCon Preizabe von: SmartRaCon	Seite: 6 Datel Info: SRC6SS_Proceedings v1.0
SmartRaCon	SRC65	SS proceedings	4
16.2.1. Virtually Cou	upled Train Sets		124
16.2.2. Cybersecurit	ty Risk Assessment		124
16.3. System Descri	ption		125
16.4. Cybersecurity	Risk Analysis		127
16.4.1. Unmitigated	I Risk Analysis		127
16.5. Conclusion &	Future Directions		130
Bibliography			131
Zoom Authors			132
17. Preliminary co	encepts and specification	ns for a self-propelled w	ragon 134
,			134
	•		135
17.4. Traction syste	m requirements		136
	•		138
17.4.2. Scenario b).			138
			139
Conclusion			139
Bibliography			140
List of Abbreviation	5		140
Zoom Authors			141
	e Non-Destructive Me	thod using Ka Band I	Microwaves for Railway
nspection			143
nspection 18.1. Introduction			
18.1. Introduction 18.2. Method			143
18.1. Introduction 18.2. Method 18.3. Measurement 18.4. Results	and Data Processing		143 144 145 146
18.1. Introduction 18.2. Method 18.3. Measurement 18.4. Results	and Data Processing		143 144 145
nspection	t and Data Processing		143 144 145 146
18.1. Introduction 18.2. Method 18.3. Measurement 18.4. Results 18.5. Conclusions Bibliography	t and Data Processing		143 144 145 146 147
18.1. Introduction 18.2. Method 18.3. Measurement 18.4. Results 18.5. Conclusions Bibliography	and Data Processing		143 144 145 146 146 147
18.1. Introduction 18.2. Method 18.3. Measurement 18.4. Results 18.5. Conclusions Bibliography List of Abbreviation Zoom Authors	and Data Processing		143 144 145 146 147 148

SRC6SS proceedings	٦
5.5. Challenges and Research Directions	4
5.5.1. Spectral Efficiency	4
5.5.2. Intelligent Resource Management	4
5.5.3. Service Reliability	4
5.6. Conclusion	4
Bibliography	4
Zoom Authors	4
6. Rail Fasteners Looseness Detection by Analysing Real and Synthetic Acceleration Data: A Dual Approach	
6.1. Introduction.	5
6.2. Methodology	5
6.2.1. Rail response under an impact excitation	5
6.2.2. Real acceleration data. Selection and analysis of rail segments with loosen fasteners	5
6.2.3. Virtual model creation and synthetic data generation	5
6.2.4. Methodological summary	5
6.3. Conclusions	5
Bibliography	5
List of Abbreviations	5
Zoom Authors	5
7. Health of railway infrastructure based on AI	5
7.1. Introduction	5
7.2. Review of the state of the art	6
7.3. Methodology	6
7.4. Preliminary results.	6
7.5. Future work	6
7.6. Conclusions	6
Bibliography	6
Zoom Authors	6
 Map-matching for train localisation: from the digital map to the map techniques 	-matchin 6
8.1. Introduction	6
	6

	7.6. Conclusions									
	Bibliography									
	Zoom Authors									
	Map-matching techniques 8.1. Introduction 8.2. Train localisation									map-mat
	Titel: SRC6SS Proceedings Version: 1.0	Detum: 13. Erstellt von	10.2024 : SmertReCon	G	eprüft vor reigabe vo	n: SmartRaCon n: SmartRaCo		Se De	ite: 7 tel Info: Si	RC6SS_Proceedings v
SmartRaCon		SRC6SS p	roceedings						4	DLR
19.2 Method									151	
	dv									
	-,									
	ntation and application									
	ins									
19.3. Results									154	
19.3.1. Model p	erformance								154	
19.3.2. Feature	analysis								154	
19.4. Conclusion	١								155	
Bibliography									155	
List of Abbreviat	tions								156	
Zoom authors									157	
20. A framewo	rk for GNSS-based	solutions p	erformance a	nalysis	s in a	n ERTM	S cont	ext	158	
	Progresses in GNSS-base									
	O project and our cont									
20.2.1. Contribu	tions to the developme		tbed for the eva							
20.2.2. Simulation	on chain								159	
	ven context detection									
	Learning process for er									
20.2.5. Error mo	dels								163	
20.3. Perspectiv	es								164	
Bibliography									164	
List of Abbreviat	tions								164	
Zoom Authors									165	
	fety in Regional N	etworks wit	th Decentrali	zation	− The	Auton	omou			
Setting Approa								_	167	
	n									
	als									
	lanagement System and		-							
	of Autonomous System									
	is Route Setting Architect									
21.4. Evaluation									171	

	SRC6SS proceedings	
8.2.1. Digital map		
8.2.2. Map-matching fo	or train localisation	
8.3. Current work and f	future work	
8.4. Conclusions		
Bibliography		
Zoom Authors		
9. CEIT's Multi-conne	ectivity Platform Development	
9.1. Introduction		
9.2. FRMCS and related	I research projects	
9.2.1. FRMCS		
9.2.2. 5GRAIL		
9.2.3. 5GMED		
9.2.4. X2RAIL-5		
9.2.5. Europe's Rail FP2	-R2DATO	
9.3. CEIT's Multi-conne	ctivity Platform (MP)	
9.4. Conclusions and Fu	ıture Work	
Bibliography		
Zoom Authors		
	the Preliminary Stages for ATO Lab Prototype	e in Sight of a Fu
Inspection Vehicle _		
10.1. Introduction		
10.2. Novel reference a	rchitecture for GoA 3/4 systems	
10.3. Test environment		
10.3.1. Components		
10.3.2. Relevant Interfa	nces	
10.4 Future works		
ZO. II. I GEGIC HOLLD		
10.5. Conclusions		
10.5. Conclusions Bibliography		
10.5. Conclusions Bibliography List of Abbreviations		



22.1. Introduction.		175
	ce architecture for GoA 3/4 automation level	
	mponents	
-	nms for driving functions	
	le Optimization Techniques	
	racking Control Techniques	
22.4. Opportunities	and challenges	179
22.4.1. Machine lea	arning for driving functions	179
22.4.2. Integration	real-time data	180
22.4.3. Perception	systems	180
22.5. Conclusions		180
Bibliography		181
List of Abbreviation	5	183
Zoom Authors		184
	/ Multimodal Integration B2B Financial Servi Other Mobility Modes	
ntegration with (/ Multimodal Integration B2B Financial Servi Other Mobility Modes	186
ntegration with (23.1. Introduction.	Other Mobility Modes	186
ntegration with (23.1. Introduction. 23.2. Revenue repa	Other Mobility Modes	186 186
23.1. Introduction. 23.2. Revenue repa 23.3. A typical jour	Other Mobility Modes	186 186 189
ntegration with (23.1. Introduction. 23.2. Revenue repa 23.3. A typical jour 23.4. Conclusion	Other Mobility Modes	186186189191
ntegration with (23.1. Introduction. 23.2. Revenue repa 23.3. A typical joun 23.4. Conclusion Zoom Authors	Other Mobility Modes rrition, a key 828 service for intermodal transport	
ntegration with (23.1. Introduction. 23.2. Revenue repa 23.3. A typical jour 23.4. Conclusion Zoom Authors	hther Mobility Modesrition, a key 828 service for intermodal transport	
ntegration with (23.1. Introduction. 23.2. Revenue repa 23.3. A typical jour 23.4. Conclusion Zoom Authors	Other Mobility Modes	
ntegration with 0 23.1. Introduction. 23.2. Revenue repa 23.3. A typical jour 23.4. Conclusion Zoom Authors Posters	hther Mobility Modesrition, a key 828 service for intermodal transport	



Program m e

6th SmartRaCon

				DAY 1	
	Session	Topic	Presenter/ 1st Author	Related Project	Contribution title
9:00					
9:10				Registrat	ion
9:20					
	PhD sessions opening		Jaizki Mendizabal		
9:40 9:50 10:00	0		Marion Berbineau	FP3-IAM4RAIL	New Generation Train Communication Network
10:10 10:20 10:30	PhD Session 1 Paul Unterhuber	Communications	David Kule Mukuhi	FP3-IAM4RAIL	NG-TCN: Towards Network Slicing in on-board Wireless Train communication networks
10:40 10:50 11:00			Andy Rodriguez	FP2-R2DATO	Overview of Train-Trackside Communication Systems and CEIT's Multi-connectivity Platform Development
11:10 11:20			•	Coffee Br	eak
11:30 11:40 11:50			Adrian Sansiñena	FP1-MOTIONAL / FP3-IAM4RAIL	Health of railway infrastructure based on Al
12:00 12:10 12:20	PhD Session 2		Imanol Bravo	FP3-IAM4RAIL	Rail Fasteners Looseness Detection by Analysing Real and Synthetic Axle-Box Acceleration Data: A Dual Approach
12:30 12:40 12:50	Marion Berbienau	Monitoring and Automation	FP2-R2DATO	Driving the Future of Automatic Train Operation: A Focus on Intelligent Driving Algorithms	
13:00 13:10 13:20			lker Millan	FP2-R2DATO	Map-matching for train localisation: from the digital map to the map-matching techniques





Program m e

6th SmartRaCon

15:00 15:10	Opening		Dr. Juan Melendez CEIT General Manager, Giorgio Travaini Europe's Rail Executive Diretor, Authority				
	Keynote SmartRaCon		Jaizki Mendizabal				
.00	Keynote MOTIONAL		Marco Ferreira				
15:50 16:00		Nihad Bahri	FP1-MOTIONAL	EU-RAIL FP1 / Multimodal Integration - B2B Financial Services as a Key Asset for Rail Integration with Other Mobility Modes			
16:10 16:20	Project Session 1	Rail management and planning		FP5-TRANS4M-R	Planning Problems in a Combined Yard and Intermodal Rail Freight Terminal		
16:30 16:40	Marvin Damschen			FA6-FutuRe	EURAIL – FA6 FutuRe Project Innovative solutions for G2 regional lines		
16:50 17:00			Christian Schwingenschlögl	FA6-FutuRe	Demand-driven Optimization of Public Transit		
17:10				Welcome coffee/drink a	t Poster zone		
17:20			Aria Mirzai	FP2-R2DATO	Cybersecurity Risk Assessment of Virtually Coupled Train Sets		
17:30			Melissa Tijink	FP5-TRANS4M-R	What is the code of this wagon?		
17:40			Reguieg Seddik	FP7 Pods4Rail	Enhancing Pedestrian Safety in Multimodal Transport through Pod-Based Transfers: An Ontological Approach		
17:50			Francisca Rosell		ESEP4Freight: Initial Approach to Smart Contract Generalization in Freight Logistics		
18:00			Alfredo Serafini		Remaining useful life of an optimal topographical ground rail surface via Classical & Quantum Neural Network		
18:10			Itziar Ruiz	FP3-IAM4RAIL	Repair of wheel and rails by additive manufacturing		
18:20							





Program m e

6th SmartRaCon

	Session	DAY 2 Session Presenter/ 1st Author Related Project			Contribution title		
9:00		Day 2 opening					
9:10 9:20	MADE4RAIL KeyNote	KeyNote Michael Meyer zu Hörste					
9:30 9:40	D D Project Session 2 D Gorka de Miguel D D	Digitalisation	Juliette Marais, Quentin Mayolle	FP2-R2DATO	A framework for GNSS-based solutions performance analysis in an ERTMS context		
9:50 10:00			Albert Lau	FA6-FutuRe	Digital Twin Development for Test Site: Foundation for Innovative Cost-Effective Train Positioning Alignment		
10:10 10:20			Aria Mirzai	FP2-R2DATO	Cybersecurity Risk Assessment of Virtually Coupled Train Sets		
10:30 10:40			Sergio Arana	FP2-R2DATO	Development of the Preliminary Stages for ATO lab prototype in sight of a future inspection vehicle		
10:50 11:00			Arne Lamm	FP2-R2DATO	Increase Safety in Regional Networks with Decentralization – The Autonomous Route Setting Approach		
11:10 11:20 11:30		Coffe Break at poster zone					
11:40 11:50 12:00 12:10 12:20 12:30 12:40 12:50 13:00	Round table Jaizki Mendizabal		Marco Ferreria (Siemens) Marvin Damschen (RISE) Jan Bergstrand (Trafikverket) Lea Paties (ERJU) Carles Miralpeix (FGC)				
13:10 13:20 13:30 13:40 13:50 14:00 14:10 14:20 14:30 14:40		Lunch					
14:50 15:00	0 0 0 0 0 0 0 0 0 0 0	Automation	Jonan Morales	FP5-TRANS4M-R	Preliminary concepts and specifications for a self-propelled wagon		
15:10 15:20			David Krüger	FP5-TRANS4M-R	Use cases and conceptual system specification for Self-Propelled Wagon		
15:30 15:40			Niloofar Minbashi	FP5-TRANS4M-R	An Integrated ETD Prediction System for Yards and Terminals		
15:50 16:00			Vladimir Israel Garcia Santos	FP3-IAM4RAIL	An Innovative Non-Destructive Method using Ka Band N	Microwaves for Railway Inspection	
16:10 16:20		Award ceremony					
16:30		Closure SRC6SS					





Scientific Seminar

SmartRaCon Introduction















Dr. Jaizki Mendizabal Dr. Michael Meyer zu Hörste Dr. Marvin Dam schen Germ any

Sweden

Dr. Marion Berbineau France

Dr. Markus Brachner Norway

Dr. Agnieszka Łukasiewicz Poland

