view frames Result Recorded at time: 1529678537.122 world Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1529678537.122 sec old) Buffer length: 0.000 sec rh\_forearm Broadcaster: /robot\_state\_publisher Average rate: 10.204 Hz Most recent transform: 1529678537.106 ( 0.015 sec old) Buffer length: 4.900 sec rh\_wrist Broadcaster: /robot\_state\_publisher Average rate: 10.204 Hz Most recent transform: 1529678537.106 (0.015 sec old) Buffer length: 4.900 sec Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10.204 Hz Most recent transform: 0.000 ( 1529678537.122 sec old) Most recent transform: 1529678537.106 ( 0.015 sec old) Most recent transform: 1529678537.106 (0.015 sec old) Most recent transform: 1529678537.106 (0.015 sec old) Most recent transform: 0.000 ( 1529678537.122 sec old) Most recent transform: 1529678537.106 ( 0.015 sec old) Most recent transform: 1529678537.106 ( 0.015 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 4.900 sec rh\_mfknuckle rh\_imu rh\_ffknuckle rh\_lfmetacarpal rh\_rfknuckle rh\_thbase rh\_manipulator Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10.204 Hz Most recent transform: 1529678537.106 ( 0.015 sec old) Most recent transform: 1529678537.106 ( 0.015 sec old) Most recent transform: 1529678537.106 (0.015 sec old) Most recent transform: 1529678537.106 (0.015 sec old) Most recent transform: 1529678537.106 ( 0.015 sec old) Buffer length: 4.900 sec rh\_lfknuckle rh\_ffproximal rh\_mfproximal rh\_rfproximal rh\_thproximal Broadcaster: /robot\_state\_publisher Broadcaster: /robot state publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10.204 Hz Most recent transform: 1529678537.106 ( 0.015 sec old) Most recent transform: 1529678537.106 (0.015 sec old) Buffer length: 4.900 sec rh\_rfmiddle rh\_ffmiddle rh\_lfproximal rh\_thhub rh\_mfmiddle Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10.204 Hz Most recent transform: 1529678537.106 ( 0.015 sec old) Most recent transform: 1529678537.106 ( 0.015 sec old) Most recent transform: 1529678537.106 (0.015 sec old) Most recent transform: 1529678537.106 (0.015 sec old) Most recent transform: 1529678537.106 ( 0.015 sec old) Buffer length: 4.900 sec rh\_thmiddle rh\_ffdistal rh\_lfmiddle rh\_rfdistal rh\_mfdistal Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10.204 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10.204 Hz Most recent transform: 0.000 ( 1529678537.122 sec old) Most recent transform: 1529678537.106 (0.015 sec old) Most recent transform: 0.000 ( 1529678537.122 sec old) Most recent transform: 0.000 ( 1529678537.122 sec old) Most recent transform: 1529678537.106 ( 0.015 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 4.900 sec Buffer length: 4.900 sec rh\_thdistal rh\_lfdistal rh\_fftip rh\_mftip rh\_rftip Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1529678537.122 sec old) Most recent transform: 0.000 ( 1529678537.122 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec rh\_lftip rh\_thtip