Seminar paper

# Conditional trees

or

# Recursive partitioning by conditional inference

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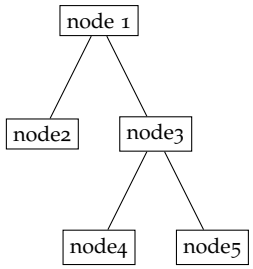
# *Recursive Partitioning*

Recursive partitioning is a powerful yet simple tool in predictive and explanatory statistics. [1]. Models built by partitioning have the shape of decision trees, which makes the approach easy to understand for everyone, without having to understand the algorithm behind. The algorithm partitions the data to reconstruct the relationship between the response variable $Y$ and the covariates matrix $X$.

[1] For a detailed introduction to trees please read Friedman et al. [2001, page 305]

$Y = f(X)$

Partitioning can be done with many different approaches and therefore there is a great variety of algorithms to grow trees. They could be categorized into those which can do regression, those which can do classification and those which can do both. Another characteristic is the number of splits per partition step. There are binary splits, which divide a partition into two new partitions and multiway splits which yield more than two partitions. There is even more variety in the philosophy of how to determine which variable to take for the next step and where to split it. Also the stopping criterion, when the tree is not grown any more, differs for the algorithms. But they all have the tree like structure in common. The presented algorithm is called "Recursive binary partitioning by conditional inference" [2]. It is an algorithm for recursive partitioning algorithm, with binary splits and all of it's split decisions are based on statistical hypothesis tests. Their creators are Torsten Hothorn, Kurt Hornik and Achim Zeileis. This work is mainly based on Hothorn et al. [2006].




[2] Will be called "Conditional tree algorithm" throughout this paper for simplicity

# *Motivation*

Problems of trees

Recursive partitioning suffers from different problems, some of which are already solved by some approaches.

CART (Classification And Regression Trees) by Breiman et al. [1984] is a popular and widely used partitioning algorithm. Let us take a closer look at the problems taking CART as an example and how the conditional trees approach solves them.

Overfitting

[3] Splits which separates only a few observations

If a tree is allowed to grow full length, pathological splits [3] can happen and if the covariate space is large enough we would end up with a tree, which contains only one observation in each terminal node. This tree would very likely be overfitting on the training data and deliver very bad results on new data. Approaches to avoid this problem are techniques called early stopping and pruning. Early stopping forces trees to stop growing when a criterion is not fullfilled. This criterion could be a minimum number of observations in a node. Pruning lets the tree grow at first and prunes the leafs back afterwards. The CART algorithm uses both early stopping and pruning to avoid overfitting.

Heuristic approach, lack of statistical model

Connected to overfitting is the lack of a statistical concept behind the splits. Mingers [1987] mention, that the algorithm "[...] has no concept of statistical significance, and so cannot distinguish between a significant and an insignificant improvement in the information measure." In CART and many other algorithms, the next split is just an heuristic, as the algorithm only searches for the next best split. The conditional trees algorithm measures the association and uses the covariate with the strongest association with the response variable.

Variable selection bias

Exhaustive search procedures as used by the CART algorithm tend

to choose variables with more possible split points (variable selection bias). This is a problem of multiple comparison. Covariates with many possible splits are searched more often for the best split. This problem was identified by different researchers, among them are the inventors of the CART algorithm Breiman et al. [1984, p. 42]

Restriction on possible measurement scales of $Y$ and $X$

In the family of partitioning algorithm, the CART algorithm is one of the more powerful ones, as it can do regression as well as classification. Many other algorithm are restricted to one of the both tasks. Though, CART still lacks support for other scales of $X$ and $Y$. Examples are: ordinal regression and censored data, just to name two. Conditional trees offer a very general test statistic which can handle more cases than simple regression or classification.

The next chapter explains how the conditional trees algorithm is designed, to overcome the mentioned problems and to offer an alternative approach.

# *Recursive partitioning by conditional inference*

"Classic" recursive partitioning algorithms often have a kind of loss function, which is to be minimized with the next split. The optimization is done by an exhaustive search over all possible split points. After splitting the data, the steps are repeated for the new partitions until a stop criterion dictates to stop.

Summary of the conditional trees algorithm

Recursive partitioning with the conditional trees algorithm works different. In contrast to CART or other algorithms, variable selection and the search for the best split are strictly seperated. Dependency between response and covariate is tested with hypothesis tests. To get rid of the problem of different scales for different covariates, the measurement for the association is the p-value. After choosing a covariate for the split, it is searched for the best split point. The stopping criterion is formulated in terms of statistical test theory as well: stop when the null-hypothesis of independence cannot be rejected any more.

All of the hypothesis testing is done by permutation tests. [4] When using permutation tests you are free to choose the test statistic. Some are better than others. It will depend on the scales of the response and the covariate and on how you want to formulate the problem. The test statistics used by the algorithm is derived from a framework developed by Strasser and Weber [1999]. They offer a very general formulation of a test statistic for permutation tests, which can handle arbitrary scales for response and covariate.

[4] For a quick introduction to permutation tests, please visit the appendix, page 31. A good idea of permutation tests is required to understand the recursive partitioning algorithm.

The following chapter explains the algorithm in detail.

# *Algorithm*

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## *The test statistic*

All decisions in steps 1.) and 2.) of the algorithm are embeded in hypothesis tests. These are done with permutation tests (conditional inference). Also step 3.) makes use of the following test statistic, although nothing is tested. The test statistic from Hothorn et al. [2006, page 4]: [5]

$$\mathbf{T}_j(L_n, w) = vec\left(\sum_{i=1}^{n} w_i g_j(X_{ij}) h(Y_i, (Y_1, ..., Y_n))^T\right) \in \mathbb{R}^{p_j q}$$

is derived from Strasser and Weber [1999] and can be used to test if a response $Y$ and a covariate $X$ are independent. This test statistic is standardized before it is used. The test statistic $T$ is not only standardized but is also mapped to a scalar value. In order to map the (possible) vector $T$ to a scalar value, one obvious choice is to take the maximum of the standardized test statistic. This yields the following standardized linear test statistic: [6]

$$c(\mathbf{t}, \mu, \Sigma) = \max_{k=1,...,pq} \left| \frac{(\mathbf{t} - \mu)_k}{\sqrt{(\Sigma)_{kk}}} \right|$$

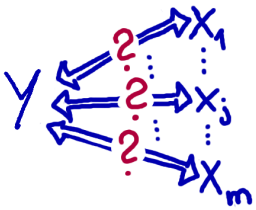
Thus $c$ is the test statistic which is calculated for each permutation. Extreme values for c for the observed data compared to the permutations will lead to the rejection of the null hypothesis of independence.

[5] This test statistic might look difficult in the first place, because it is a very general formulation. When looking at particular examples the formula becomes very friendly and seems more natural. This can be seen in the two included examples for regression 17 and classification 23 At this point you can accept the test statistic as it is or you can read more in the appendix (page 33) about it.

[6] see page 33 for the calculation of $\mu$ and $\Sigma$ of $T$

### *Stop criteria (1) and variable selection (2)*

The first step in each partition is to test if the partition should be split at all. This is formulated as a statistical hypothesis test with the global[7] null hypothesis of independence. It is composed of many (local) null hypotheses of independence between the response $Y$ and each covariate $X_j$, which can be reformulated in terms of the marginal distribution of $Y$. If $Y$ and $X_j$ are independent, the distribution of $Y$ given $X_j$ is the same as the marginal distribution of $Y$. Or more formally:




[7] Note that global means global for the partition but not for the whole tree

$H_0$ : The response $Y$ is independent from all covariates $X_j, \quad j \in 1, \ldots, m$

$$H_0 = \cap_{j=1}^{m} H_0^j \text{ and } H_0^j : D(\mathbf{Y}|X_j) = D(\mathbf{Y})$$

One way to test for such a compound hypothesis is to test each of the $m$ [8] hypothesis seperately and to reject the global null hypothesis if one of the covariates and $Y$ are significantly dependent. To overcome the problem of multiple testing a p-value correction has to take place. The whole procedure:

[8] Let $m$ be the number of covariates

1. Choose an influence function $h$ depending on scale of $Y$
2. For each covariate $X_j$ do the following:
   1) Choose an apropriate function $g_j$, which depends on the scale of the covariate $X_j$ [9]
   2) Calculate the test statistic $c_{j0}$ for the observed data.
   3) Permute the observations in the node
   4) Calculate $c$ for all permutations
   5) Calculate the p-values[10] (number of test statistics $c$, where $|c| > |c_0|$
3. Correct p-value for multiple testing[11]
4. p-value $< \alpha$?[12] $\Rightarrow$ reject global $H_0$ and search variable for splitting else don't split.

[9] The functions $h$ and $g_j$ stays the same for each partition, so in theory it is enough to choose them once before the first split

[10] Each $X_j$ gets an own p-value

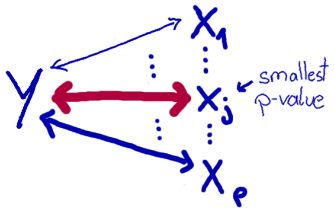
[11] Result is the p-value for the global test

[12] *alpha* is the prespecified confidence level

Assuming the null hypothesis of independence was rejected, then the next step is to find the best variable for the split. While CART

takes the variable which increases a criterion most (which leads to the variable selection bias), the conditional trees algorithm uses the p-value for variable selection. By using the p-values, the question of association strength is switched to statements of probability, where the original scales don't matter.

Thus the covariate with the smallest p-value is taken for the next split. Smallest p-value means the smallest probability of independence between the chosen covariate and the response. From the procedure it should get clear, why variable selection and stop criteria are combined in one step. For testing the global null hypothesis every single p-value from each test is needed. These are also needed for the variable selection.




## *Splitting criteria (3)*

Steps 1) and 2) of the algorithm are completed. The covariate $X_{j*}$ with the strongest association is chosen for the next split. Every covariate (which is not binary) has more than one possible split points. To determine where to split, a criterion which measures the goodness of the split has to be applied. The CART algorithm uses Gini for classification and sum of squares for regression. Both of the criteria could be used by the conditional tree algorithm as well, but the used approach is different. Because of the different types of possible regression- /classification - models (categorial, ordinal, numeric, censored, ...) a more general approach is suitable. The solution is again the test statistic derived from Strasser and Weber [1999]. A special case of the linear test statistic can be used, the formula is:

$$T_j^A(L_n, w) = vec\left(\sum_{i=1}^{n} w_i I(X_{j*i} \in A) \cdot h(Y_i, (Y_1, \ldots, Y_n))^T\right)$$

with $A$ being a possible partition of the current observations and

$$I(X_{j*i} \in A) = \begin{cases} 1, & X_{j*i} \in A \\ 0 & X_{j*i} \notin A \end{cases}$$

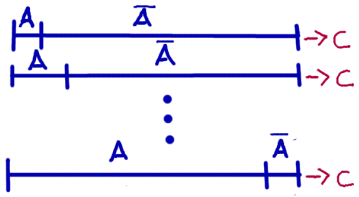
The difference to the test statistic for the association test is the transformation of $X_{j*}$. We only look at the different partitions of $X_{j*}$. Therefore the scale of $X_{j*}$ is not of any interest anymore, but the partition which emerges by a certain split point. An appropriate function to capture only the difference in the partition, the transformation of $X_{j*}$ is the indicator function. This results in the statistic

$$c_{max}(\mathbf{t}, \mu, \Sigma) = max_k \left| \frac{(\mathbf{t}^A - \mu)_k}{\sqrt{(\Sigma)_{kk}}} \right|$$

Note that the test statistic does not depend on the transformation $g_{j*}$ of $X_{j*}$. The scale of the chosen covariate $X_{j*}$ is regarded in another way: The possible partitions $A$ and $A^C$ depend on the scale of $X_{j*}$. For example if $X_{j*}$ is categorial the different partitions $A$ are combinations of the different categories. A continuous covariate will be searched for a split on the real line. Ordinal covariates will be searched for splits where the two resulting partitions are a result of a inbetween the ordered categories.

We search the partition $A$ which maximizes $c$:

$$A^* = argmax_A c(t^A_{j*}, \mu^A_{j*}, \Sigma^A_{j*})$$

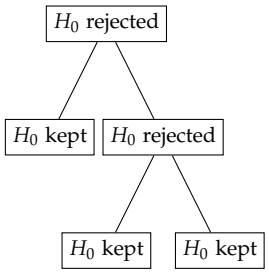



Maximizing $c$ means, that we search for the partition with the strongest deviation of $h(Y)$ from what we would expect under independence between $Y$ and $X_{j*}$. Additional stopping criteria like stopping, when the resulting partitions would become to small, can be implemented by restricting the searched split points.

## *Repeat(4)*

The three steps: stop criteria, variable selection and best split search are repeated until in every partition, which is at the end of the tree (so called terminal node) the null hypothesis of independency cannot be rejected anymore.

If there is no significant dependency of the response and any covariate, than there would be no split at all, every observation is in the same partition.



The user has to specify the significance level $\alpha$, which is the significance level for each global null hypothesis. The value $\alpha$ can also be seen as a tuning parameter for the trees. Low values yield smaller and larger values larger trees. Because a larger $\alpha$ leads to receject-ing the null hypothesis more frequently and thus splitting more frequently.

# *Continuous Regression: Example bodyfat*

The first example is a continuous regression model, where both the response and the covariates are measured on a numeric scale. The model is illustrated with the *bodyfat* data set, which is available in the mboost package developed by Hothorn et al. [2012].

$Y$, $X_j$ numeric, $\quad j = 1, \ldots, m$

## *Data set*

The data set contains observations of 71 healthy women. The data contains body fat values, which are measured by DXA (Dual-energy X-ray absorptiometry), a method to determine the amount of body fat. Other variables in the data set are anthropometric measurements like the breadth of the knee, the waist circumference, the hip circumference etc.. The objective is to predict the body fat with the anthropometric measurements, because the DXA method is more expensive and not always available.

$n = 71$

Predict bodyfat with body measurements as input

## *Test statistic*

Bodyfat measured by DXA as well as body measurements are numeric variables. Thus one possible choice for the influence function $h$ and the transformation function $g_j, \quad j = 1, \ldots, m$ is the identity function, which means the variables will not be transformed at all.

Thus:

$$h = \mathbf{Y}_i \quad \text{and} \quad g_j = \mathbf{X}_j \quad j = 1, \ldots, m$$

This yields following not-standardized test statistic:[13]

$$\mathbf{T}_j(\mathcal{L}_n, \mathbf{w}) = \sum_{i=1}^{n} w_i \mathbf{X}_{ji} \mathbf{Y}_i = \sum_{i \in node} \mathbf{X}_{ji} \mathbf{Y}_i$$

[13] The formulation $\sum_{i \in node}$ means sum over all observations in the node (= partition). This is the same as the sum over all observations with additional weights, because only observations in the current node have weigth $w = 1$, the other have weights $w = 0$

The next step is to standardize the test statistic:[14] [15]

$$c_{max}(\mathbf{t}, \mu, \Sigma) = \max_{k=1,\ldots,pq} \left| \frac{(t-\mu)_k}{\sqrt{(\Sigma)_{kk}}} \right| = \left| \frac{t-\mu}{\sqrt{\Sigma}} \right|$$

$$\begin{aligned}
\mu_j &= \left( \sum_{i=1}^{n} w_i X_{ji} \right) \mathbb{E}_{node}(h) = n_{node} \cdot \bar{X}_{j,node} \bar{Y}_{node} \\
\Sigma &= \frac{n_{node}}{n_{node}-1} \mathbb{V}_{node}(h) \cdot \sum_{i=1}^{n} w_i X_{ji}^2 - \frac{1}{n_{node}-1} \mathbb{V}_{node}(h) n_{node}^2 \bar{X}_{j,node}^2 \\
&= \frac{1}{n_{node}} \sum_{i \in node} (Y_i - \bar{Y}_{node})^2 \sum_{i=1}^{n} X_{ji}^2 \\
&\quad - \frac{1}{n_{node}-1} \cdot \frac{1}{n_{node}} \sum_{i \in node} (Y_i - \bar{Y}_{node})^2 n_{node}^2 \bar{X}_{j,node}^2 \\
&= \frac{1}{n_{node}-1} \sum_{i \in node} (Y_i - \bar{Y}_{node})^2 \left( \sum_{i \in node} X_{ji}^2 - n_{node} \bar{X}_{j,node}^2 \right) \\
&= \frac{1}{n_{node}-1} \left( \sum_{i \in node} (Y_i - \bar{Y}_{node})^2 \right) \left( \sum_{i \in node} (X_{ji} - \bar{X})^2 \right)
\end{aligned}$$

Therefore:

$$c \propto \left| \frac{\sum_{i \in node} X_{ji} Y_i - n_{node} \bar{X}_{j,node} \bar{Y}_{node}}{\sqrt{\left( \sum_{i \in node} (Y_i - \bar{Y}_{node})^2 \right) \left( \sum_{i \in node} (X_{ji} - \bar{X}_{j,node})^2 \right)}} \right|$$

The linear test statistic is proportional to the pearson correlation coefficient. This means, that the permutation test is testing if the correlation between $Y$ and any $X_j$ is different than zero. Thus by choosing the identity function for $h$ and $g_j$ the null hypothesis of independence between $Y$ and $X_j$ is formulated as "The correlation between $Y$ and $X_j$ is zero".

The next step is to calculate the test statistic (the pearson correlation coefficient multiplied with a constant) for the observation in the current partition (where $w \neq 0$). The response of the observations will be permutated and the test statistic calculated again. This will be done often enough to approximate the distribution of the test statistic for the sample. If the correlation coefficient of the original data is very extreme compared to the permutated test statistics, the p-value

[14] Definitions of $\mu$ and $\Sigma$ can be found on page 33

[15] $n_{node} := \sum_{i=1}^{n} w_i$ =Number of observation in node
$\bar{Y}_{node}$: Mean of $Y$ in node
$\bar{X}_{j,node}$: Mean of $X_j$ in node

will be very low.

The procedure of calculating the test statistic for the original data and the permutations is done for every covariate $X_j, \quad j \in 1, \ldots, m$ seperatly.

*Test statistic for splitting criteria*

For regression and the identitiy function for the influence function $h$, the statistic used to find the best split is the following: [16]

[16] $n_A$: Number of observations in partition $A$
$\bar{Y}_A$: Mean of $Y$ in $A$

$$\mathbf{T}^A_{j*}(\mathcal{L}_n, \mathbf{w}) = \sum_{i=1}^{n} w_i I(X_{j*i} \in A) \cdot Y_i = \sum_{i: x_{j*i} \in A} Y_i = n_A \bar{Y}_A$$

$$\mu^A_{j*} = \sum_{i=1}^{n} w_i I(X_{j*i} \in A) \cdot \frac{1}{n_{node}} \sum_{i=1}^{n} w_i Y_i = n_A \bar{Y}_{node}$$

$$\begin{aligned}
\Sigma^A_{j*} &= \frac{n_{node}}{n_{node} - 1} \frac{1}{n_{node}} \sum_{i=1}^{n} w_i (Y_i - \bar{Y}_{node})^2 \cdot \sum_{i=1}^{n} w_i I(X_{j*i} \in A)^2 \\
&\quad - \frac{1}{n_{node} - 1} \frac{1}{n_{node}} \sum_{i=1}^{n} w_i (Y_i - \bar{Y}_{node})^2 \cdot \left( \sum_{i=1}^{n} w_i I(X_{j*i} \in A) \right)^2 \\
&= \frac{1}{n_{node} - 1} \sum_{i \in node} (Y_i - \bar{Y}_{node})^2 n_A \left( 1 - \frac{n_A}{n_{node}} \right) \\
&= Var(Y_{node}) \cdot Var(Z)
\end{aligned}$$

with

$$Z \sim B(n_{node}, \pi = \frac{n_A}{n_{node}})$$

Can be interpretated as the probability that z observations would be assigned to $A$ if the process of aissigning would be random with probability $\frac{n_A}{n_{node}}$. Thus the standardized test statistic is:

$$c_{max}(\mathbf{t}^A_{j*}, \mu^A_{j*}, \Sigma^A_{j*}) = max_k \left| \frac{(\mathbf{t}^A - \mu)_k}{\sqrt{(\Sigma)_{kk}}} \right| = n_A \left| \frac{\bar{Y}_A - \bar{Y}_{node}}{\sqrt{Var(Y_{node}) \cdot Var(Z)}} \right|$$

The partition which maximizes the above expression will be chosen. Maximizing $c_{max}$ means finding the partition, where the difference between the mean of $Y$ in the partition and the mean of $Y$ in the whole partition is large and the number of observations in $A$ is large

at the same time.

*R-Code*

The data set for the example is available in the mboost (Hothorn et al. [2012]). In addition to the response DEXfat it contains the nine body measurements. The data set can be loaded using the `data()` function:

```
data(bodyfat, package = "mboost")
```

The conditional tree algorithm is implemented in the party package (Hothorn et al. [2006]), which is available on `http://cran.r-project.org/`. The usage is similiar to the `lm()`-function, with the formula interface. The formula `DEXfat` $\sim$`.` means that the tree should model the response DEXfat (bodyfat measurement) depending on all available covariates.

```
library("party")
## fit a conditional tree
cond_tree <- ctree(DEXfat ~ ., data = bodyfat)
```

The result is a tree (Figure 1) with six terminal nodes (five splits). The variable chosen for the first split is `hipcirc`, the circumference of the hip in cm. If it is bigger than 108cm the next measurement to look at is the breadth of the knee (`kneebreadth`). If the breadth is smaller than 10.6 cm the estimated is 39.7, which is equal to the mean in this terminal node.

```
plot(cond_tree)
```

The CART algorithm gives us a different tree (Figure 2). The variable for the first splits are different, CART uses the circumference of the waist while conditional trees algorithm uses the same measurement of the hip. There is even a covariate (kneebreadth) which is used by the conditional trees algorithm, but was not used by CART algorithm. The resulting trees are structurally different.

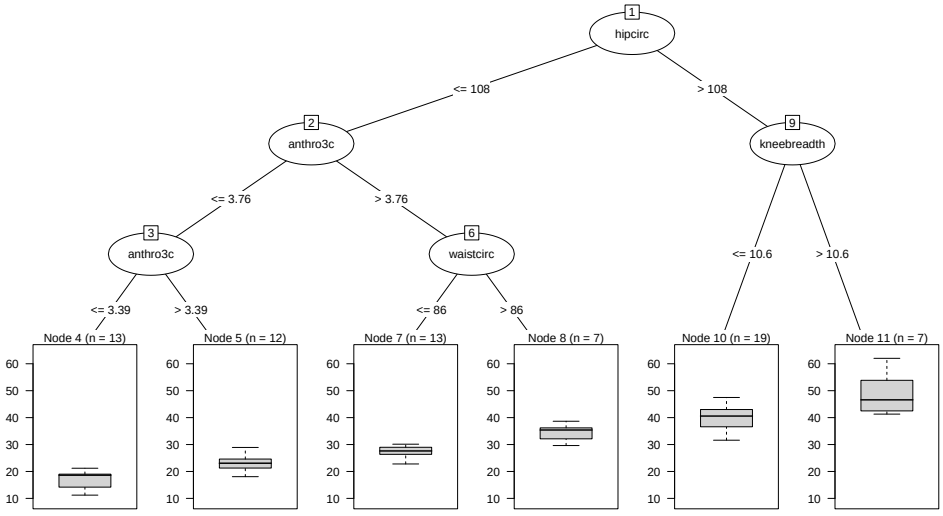



Figure 1: Conditional tree for bodyfat data

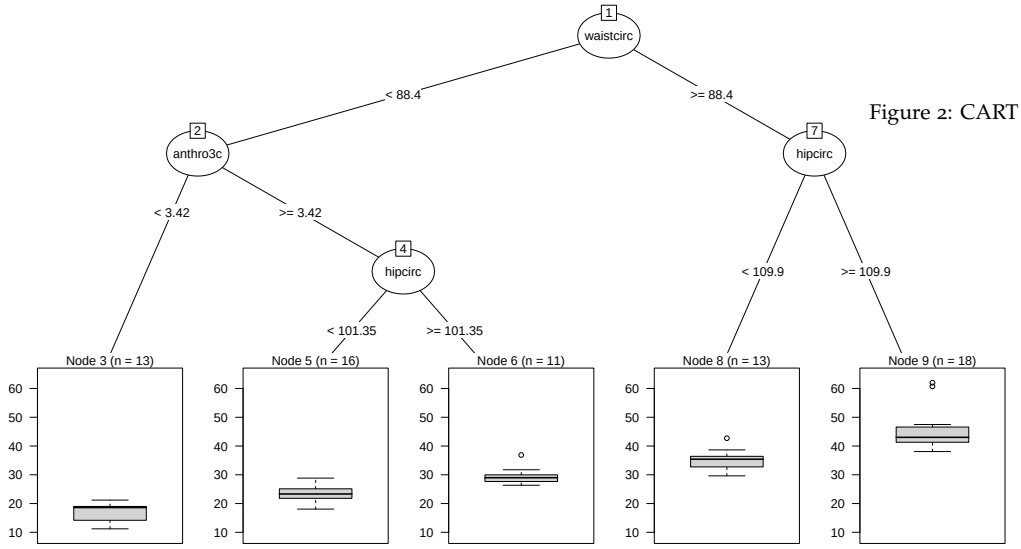



Figure 2: CART tree for bodyfat data

```
library("rpart")
library("partykit")
cart <- rpart(DEXfat ~ ., data = bodyfat)
plot(as.party(cart))
```

# *Classification: Example glaucoma*

This is an example of a classification tree with the conditional trees algorithm. The response is binary and all the covariates are measured on a numeric scale. The data for this illustration is available in the `ipred` package (Peters and Hothorn [2012]).

$Y$ binary, $X_j$ numeric $\quad j = 1, \ldots, m$

*Data set*

The glaucoma data set contains eye laser scanning of both healthy persons and persons with glaucoma. Glaucoma is an eye disease which in worst case can lead to blindness. If the person is healthy the response variable `Class` is zero else if the person suffers from glaucmoa, one. The subject is to predict if a person has the glaucoma disease or not, based on different laser scanning measurements. . Measured are different volumes and surfaces of the eye

n = 196

Predict glaucoma based on eye measurements

*Test statistic*

The test statistic is different to the one from the regression example. The transformation $g$ for the covariates stays the same, while the influence function $h(Y)$ changes, as the scale of $Y$ is different in the classification example. Instead of using the identity for $h$, the influence function is a vector with the same dimensionality as the number of categories, two-dimensional in the glaucoma example. The vector $h(Y_i)$ equals one at the position $k$ when observation $i$ is in cateogry $k$, and zeros at the other positions. The Glaucoma data set knows two classes, glaucoma and normal. Thus if person $i$ has glaucoma, the

vector $h(Y_i)$ is $(0,1)^T$.

$$h = e_J(\mathbf{Y}_i) = \begin{pmatrix} Y_{G,i} \\ Y_{N,i} \end{pmatrix} = \begin{cases} (1,0)^T & \text{Glaucoma} \\ (0,1)^T & \text{normal} \end{cases} \quad \text{and} \quad g(\mathbf{X}_{ji}) = \mathbf{X}_{ji}$$

This yields the following linear test statistic:[17]

[17] $n_N$: Number of healthy persons in the node
$n_G$: Number of persons with glaucoma in node

$$\mathbf{T}_j(\mathcal{L}_n, \mathbf{w}) = vec\left(\sum_{i=1}^{n} w_i \mathbf{X}_{ji} e_J(\mathbf{Y}_i)^T\right) = \begin{pmatrix} n_G \cdot \bar{X}_{j,G} \\ n_N \cdot \bar{X}_{j,N} \end{pmatrix}$$

The test statistic is the vector of the means of $X_j$ in the categories glaucoma and normal, weighted by the number of observations in this category. Again we need mean and variance to standardize $T_j$:

$$\begin{aligned}
\mu_j &= \sum_{i \in node} X_{ji} \frac{1}{n_{node}} \begin{pmatrix} n_G \\ n_N \end{pmatrix} = \begin{pmatrix} n_G \cdot \bar{X}_{j,node} \\ n_N \cdot \bar{X}_{j,node} \end{pmatrix} \\
\Sigma_j &= \frac{n_{node}}{n_{node}-1} V_{node}(h) \cdot \sum_{i \in node} X_{ji}^2 - \frac{1}{n_{node}-1} \left(\sum_{i \in node} X_{ji}\right) \left(\sum_{i \in node} X_{ji}\right) \\
&= \frac{1}{n_{node}-1} V_{node}(h) n_{node} \sum_{i \in node} \left(X_{ji} - \bar{X}_{j,node}\right)^2 \\
V_{node}(h) &= \frac{1}{n_{node}} \sum_{i \in node} \left(e_J(Y_i) - \begin{pmatrix} \frac{n_G}{n_{node}} \\ \frac{n_N}{n_{node}} \end{pmatrix}\right) \left(e_J(Y_i) - \begin{pmatrix} \frac{n_G}{n_{node}} \\ \frac{n_N}{n_{node}} \end{pmatrix}\right)^T \\
&= \frac{1}{n_{node}} \sum_{i \in node} \begin{pmatrix} Y_{G,i} - \frac{n_G}{n_{node}} \\ Y_{N,i} - \frac{n_N}{n_{node}} \end{pmatrix} \begin{pmatrix} Y_{G,i} - \frac{n_G}{n_{node}} \\ Y_{N,i} - \frac{n_N}{n_{node}} \end{pmatrix}^T \\
&= \frac{1}{n_{node}} \sum_{i \in node} \begin{pmatrix} Y_{G,i} - \bar{Y}_G \\ Y_{N,i} - \bar{Y}_N \end{pmatrix} \begin{pmatrix} Y_{G,i} - \bar{Y}_G \\ Y_{N,i} - \bar{Y}_N \end{pmatrix}^T \\
&= \frac{1}{n_{node}} \begin{pmatrix} \sum_{i \in node} (Y_{G,i} - \bar{Y}_G)^2 & \sum_{i \in node} (Y_{G,i} - \bar{Y}_G)(Y_{N,i} - \bar{Y}_N) \\ \sum_{i \in node} (Y_{G,i} - \bar{Y}_G)(Y_{N,i} - \bar{Y}_N) & \sum_{i \in node} (Y_{N,i} - \bar{Y}_N)^2 \end{pmatrix}
\end{aligned}$$

For the standardized test statistic only the diagonal elements of the

covariance matrix are needed:

$$(\Sigma_j)_{kk} = \frac{1}{n_{node}-1} \sum_{i \in node} (Y_{Class} - \bar{Y}_{Class})^2 \sum_{i \in node} (X_{ji} - \bar{X}_{ji})^2 \quad \text{Class} \in \{G, N\}$$
$$= \underbrace{n_{node} \bar{Y}_{Class}(1 - \bar{Y}_{class})}_{\widehat{Var}(Y_{Class,node})} \underbrace{\frac{1}{n_{node}-1} \sum_{i \in node} \left(X_{ji} - \bar{X}_{j,node}\right)^2}_{\widehat{Var}(X_{j,node})}$$

And finally the standardized test statistic:

$$c = \frac{n_{Class}\bar{X}_{j,Class} - n_{Class}\bar{X}_{j,node}}{\sqrt{(\Sigma)_{kk}}} = n_{Class} \frac{(\bar{X}_{j,Class} - \bar{X}_{j,node})}{\sqrt{\widehat{Var}(Y_{Class,node})\widehat{Var}(X_{j,node}))}}$$

This standardized test statistic has a very vivid interpretation. The numerator is the difference between the observed mean of the covariate $X_j$ for all the observations in the node which are in the class we are looking at and the mean of $X_j$ in the whole node. We expect $\bar{X}_{j,Class}$ to be very similar to $\bar{X}_{j,node}$ under the null hypothesis of independence of $X_j$ and $Y$. Thus in case of independence between response and covariate the numerator should be very small. The denominator contains the root of the product of variance $Y$ and variance $X_j$. It adjusts the difference. The whole term is weighted by $n_{Class}$.

*Test statistic for splitting criteria*

Finding the best split point differs to the regression example as well. The test statistic $T^A_{j*}$ looks like this:

$$T^A_{j*}(\mathcal{L}, w) = vec\left(\sum_{i \in node} I(X_{j*i} \in A) e_j(Y_i)^T\right) = \frac{1}{n_{node}} \sum_{i \in node} I(X_{j*i} \in A) \begin{pmatrix} Y_{G,i} \\ Y_{N,i} \end{pmatrix} =$$
$$= \frac{1}{n_{node}} \begin{pmatrix} \sum\limits_{i \in A} Y_{G,i} \\ \sum\limits_{i \in A} Y_{N,i} \end{pmatrix} = \frac{1}{n_{node}} \begin{pmatrix} \frac{1}{n_A} n_{G,A} \\ \frac{1}{n_A} n_{N,A} \end{pmatrix}$$

The mean and variance of this test statistic are:

$$\begin{aligned}
\mu_{j*} =& \mathbb{E}(T|S) = vec\left(\sum_{i \in node} I_A(X_{j*i})\mathbb{E}(e_J(Y)|S)\right) = \\
=& \left(\sum_{i \in node} I_A(X_{j*i})\right)\left(\frac{1}{n_{node}} \sum_{i \in node} \begin{pmatrix} Y_{G,i} \\ Y_{N,i} \end{pmatrix}\right) = \\
=& \frac{n_A}{n_{node}} \begin{pmatrix} n_G \\ n_N \end{pmatrix} \\
\Sigma_{j*} =& \frac{1}{n_{node} - 1} \mathbb{V}(h)(n_{node} n_A - n_A^2)
\end{aligned}$$

$$\Rightarrow (\Sigma_{j*})_{kk} = \frac{1}{n_{node} - 1} \frac{1}{n_{node}} \underbrace{(Y_{Class} - \bar{Y}_{Class})^2}_{= n_{node} \bar{Y}_{Class}(1 - \bar{Y}_{Class}) = \hat{\mathbb{V}}(Y_{Class})} (n_{node} n_A - n_A^2) = \hat{V}(Y_{Class}) \frac{n_A}{n_{node} - 1} \left(1 - \frac{n_A}{n_{node}}\right)$$

This yields following standardized test statistic $c$:

$$c_{max,Class} = \frac{\frac{1}{n_{node}} n_{class,A} - \frac{n_A}{n_{node}} n_{class}}{(\Sigma_j)_{class}} = \frac{\frac{1}{n_{node}}(n_{class,A} - \frac{n_A \cdot n_{class}}{n_{node}})}{\hat{\mathbb{V}}(Y_{class}) \frac{n_A}{n_{node} - 1}(1 - \frac{n_A}{n_{node}})} \quad \text{Class} \in \{G, N\}$$

The enumerator contains the difference between the actual number of observations with glaucoma (or normal) in partition A and the number of observations in A with glaucoma (or normal) under complete randomness.

*R-Code*

```
library("rpart")
library("party")
data("GlaucomaM", package = "ipred")
cond_tree <- ctree(Class ~ ., data = GlaucomaM)
classic_tree <- rpart(Class ~ ., data = GlaucomaM)
```

```
plot(cond_tree)
```

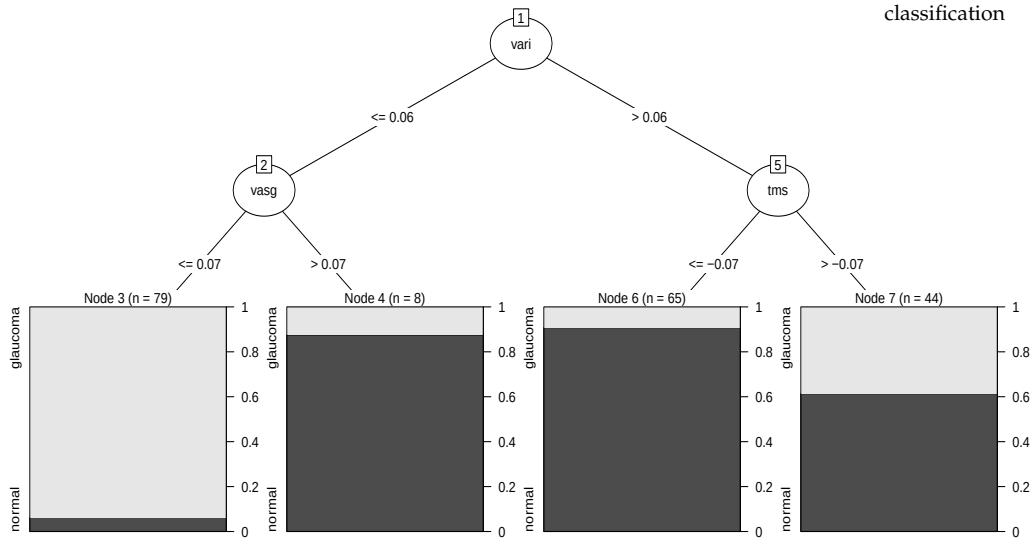



Figure 3: Conditional tree for Glaucoma classification

```
plot(as.party(classic_tree), cex = 1.5)
```

Like in the regression example, the tree grown with CART and conditional inference are structurally different. The measurement *vari* which is used for the first split in the conditional tree (Figure 3) is not even used for any split in the CART tree (Figure 4. Interestingly Hothorn et al. [2006] show, that the predictive accuracy of both approaches are very similar.

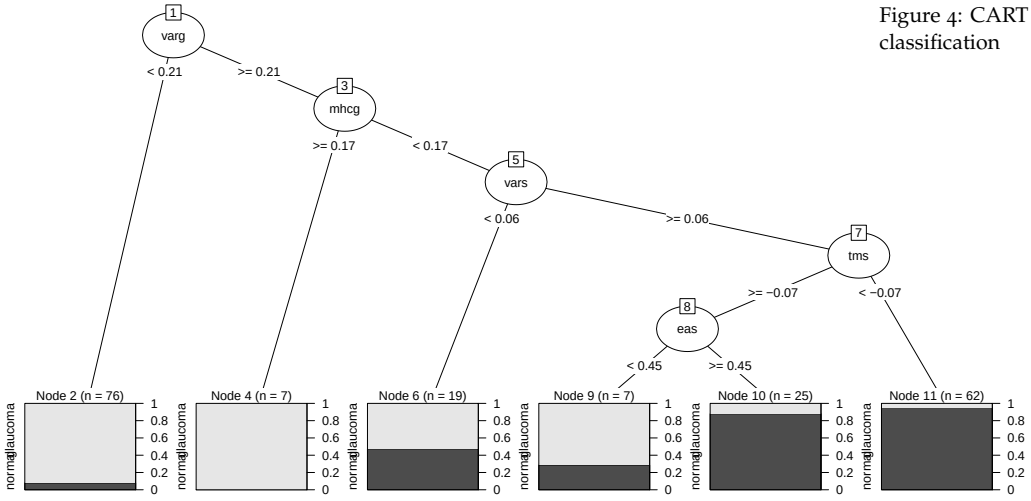



Figure 4: CART tree for Glaucoma classification

# *Summary*

Conditional inference trees are a statistical approach to recursive partitioning. The underlying theory is embedded in a well defined framework of conditional inference (permutation tests). Unlike most other partitioning algorithms, variable selection and best split search are seperated. The split criterion the variable selection for the next split are formulated in terms of statistical hypothesis tests. The framework covers a wide range of different scales for $Y$ and $X$, more than mentioned in this paper.

As CART trees finds application in the RandomForest - algorithm, conditional trees can also be used for a special implementation of a RandomForest - algorithm. This is implemented as well in the party package with the cforest function.

# *appendix: Permutation tests*

Permutation tests[18] are a special class of non-parametric tests. Sen [accessed February 12, 2013] In contrast to parametric tests, there is no distribution assumption for the data. The philosophy of permutation tests is that under the null hypothesis of independence, the pairs of $(Y_i, X_i)$ are exchangeable (which as well is required to perform a classic permutation test). That means we can obtain the distribution of a test statistic (under the assumption of independence) by calculating the test statistic for all possible permutation of $Y$ and $X$. The significance value $p$ is obtained by locating the observed statistic in the distribution.

One problem of permutation tests is, that the number of possible permutations grows very fast with a larger number $n$ of observations. The number of permutations is $n!$ and the time for calculating all possible test statistics is for most problems unreasonably. The trick here is to draw a number of random permutation to approximate the distribution of the test statistic. This is called Monte Carlo method.

[18] Synonyms are: exact tests, randomization tests, re-randomization tests

# *appendix: Test statistic*

Hothorn et al. [2006] use the following test statistic which is derived from Strasser and Weber [1999]

$$\mathbf{T}_j(L_n, w) = vec\left(\sum_{i=1}^{n} w_i g_j(X_{ij}) h(Y_i, (Y_1, ..., Y_n))^T\right) \in \mathbb{R}^{p_j q}$$

It may look difficult in the first place, but it can be broken down to the following:

- $vec()$ The core of the test statistic can be a matrix. In this case $vec()$ - Operator vectorizes the matrix

- $\sum$ The test statistic is a sum over all observations

- $w$ I lied: Not all observations, because observations which are not in the current partition will get the weight $w = 0$ and otherwise $w = 1$. This ensures us, that only the data in the current node is in focus.

- $g_j$ A transformation of the j-th covariate $X_j$. Transformation depends on scale of the covariate

- $h$ Influence function. Transformation of the response $Y$.

The test statistic has an expectation and variance, which are also

derived by the framework from Strasser and Weber [1999]:

$$\mu_j = \mathbb{E}(\mathbf{T}_j(\mathcal{L}_n, \mathbf{w})|S(\mathcal{L}_n, \mathbf{w})) = vec\left(\left(\sum_{i=1}^{n} w_i g_j(X_{ji})\right)\mathbb{E}(h|S(\mathcal{L}_n, \mathbf{w}))^T\right)$$

$$\begin{aligned}\Sigma_j &= \mathbb{V}(\mathbf{T}_j(\mathcal{L}_n, \mathbf{w})|S(\mathcal{L}_n, \mathbf{w})) \\ &= \frac{\mathbf{w}.}{\mathbf{w}. - 1}\mathbb{V}(h|S(\mathcal{L}_n, \mathbf{w})) \otimes \left(\sum_i w_i g_j(X_{ji}) \otimes w_i g_j(X_{ji})^T\right) \\ &- \frac{1}{\mathbf{w}. - 1}\mathbb{V}(h|S(\mathcal{L}_n, \mathbf{w})) \otimes \left(\sum_i w_i g_j(X_{ji})\right) \otimes \left(\sum_i w_i g_j(X_{ji})\right)^T\end{aligned}$$

$$\mathbf{w}. = \sum_{i=1}^{n} w_i$$

$$\mathbb{E}(h|S(\mathcal{L}_n, \mathbf{w})) = \mathbf{w}.^{-1}\sum_i w_i h(\mathbf{Y}_i, (\mathbf{Y}_1, \ldots, \mathbf{Y}_n)) \in \mathbb{R}^q$$

$$\begin{aligned}\mathbb{V}(h|S(\mathcal{L}_n, \mathbf{w})) = \mathbf{w}.^{-1}\sum_i w_i &(h(\mathbf{Y}_i, (\mathbf{Y}_1, \ldots, \mathbf{Y}_n)) - \mathbb{E}(h|S(\mathcal{L}_n, \mathbf{w}))) \\ &(h(\mathbf{Y}_i, (\mathbf{Y}_1, \ldots, \mathbf{Y}_n)) - \mathbb{E}(h|S(\mathcal{L}_n, \mathbf{w})))^T\end{aligned}$$

Thus we can standardize the linear tests statistic: $c(\mathbf{t}, \mu, \Sigma) = \max_{k=1,\ldots,pq}\left|\frac{(\mathbf{t}-\mu)_k}{\sqrt{(\Sigma)_{kk}}}\right|$

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