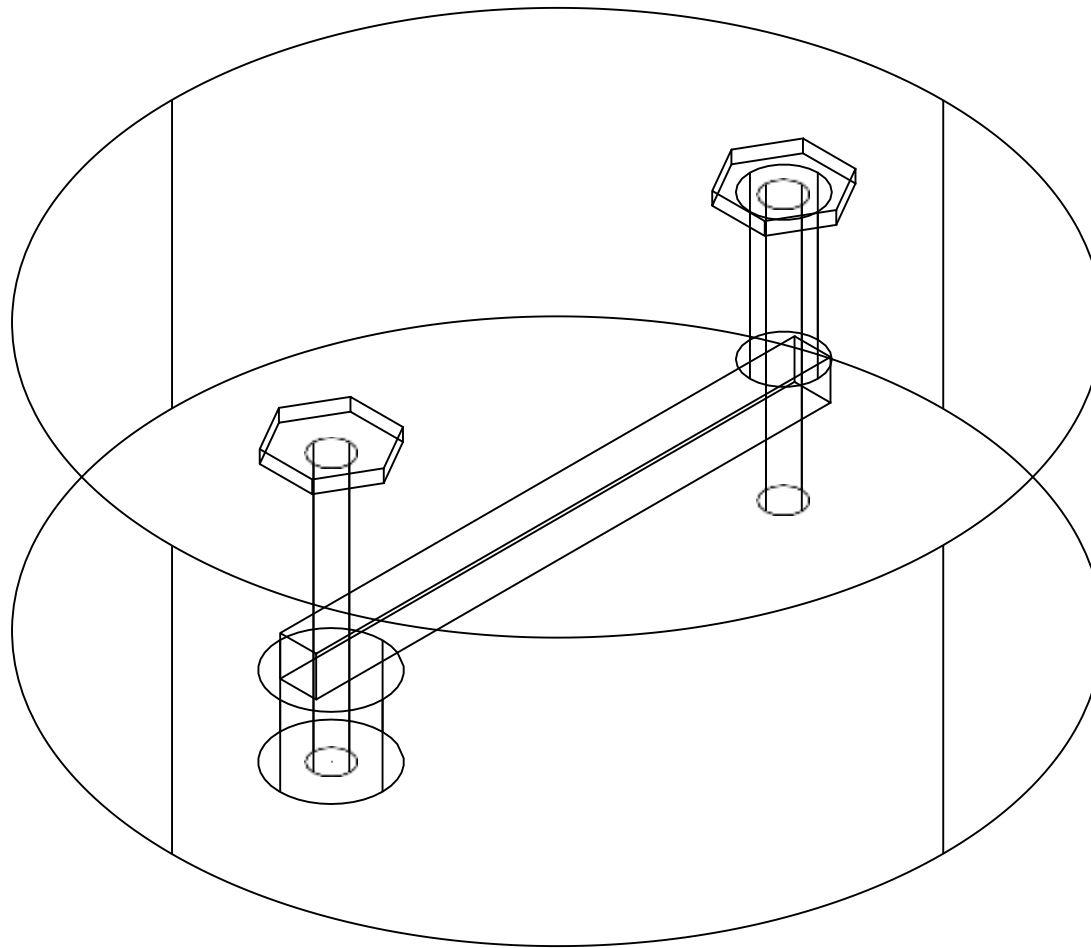
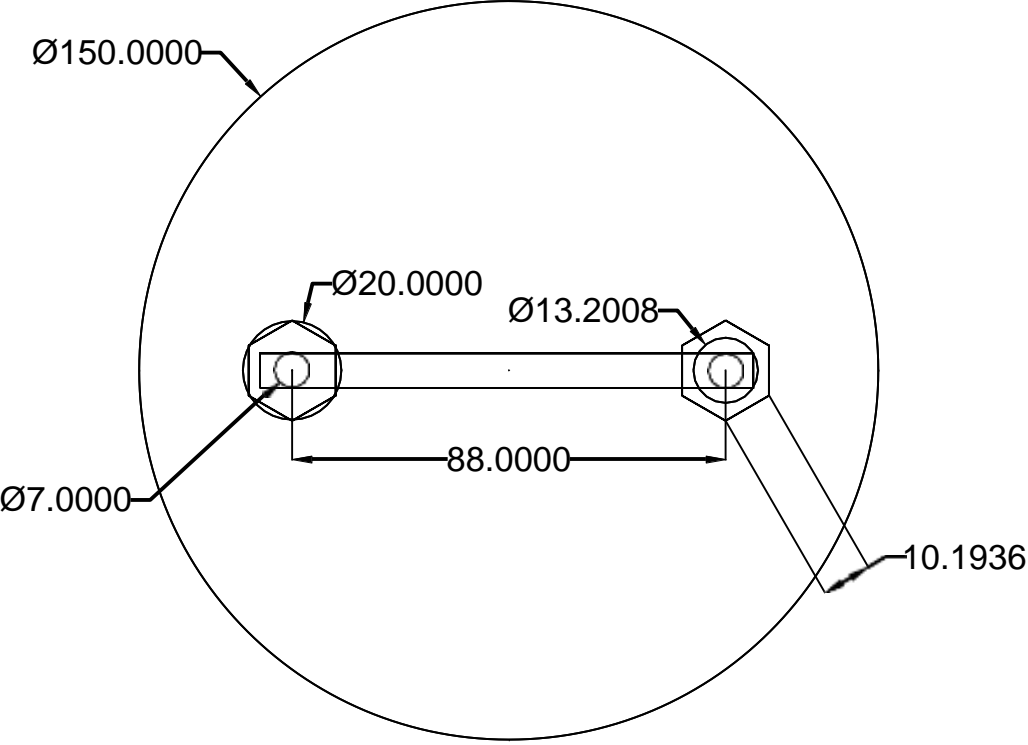


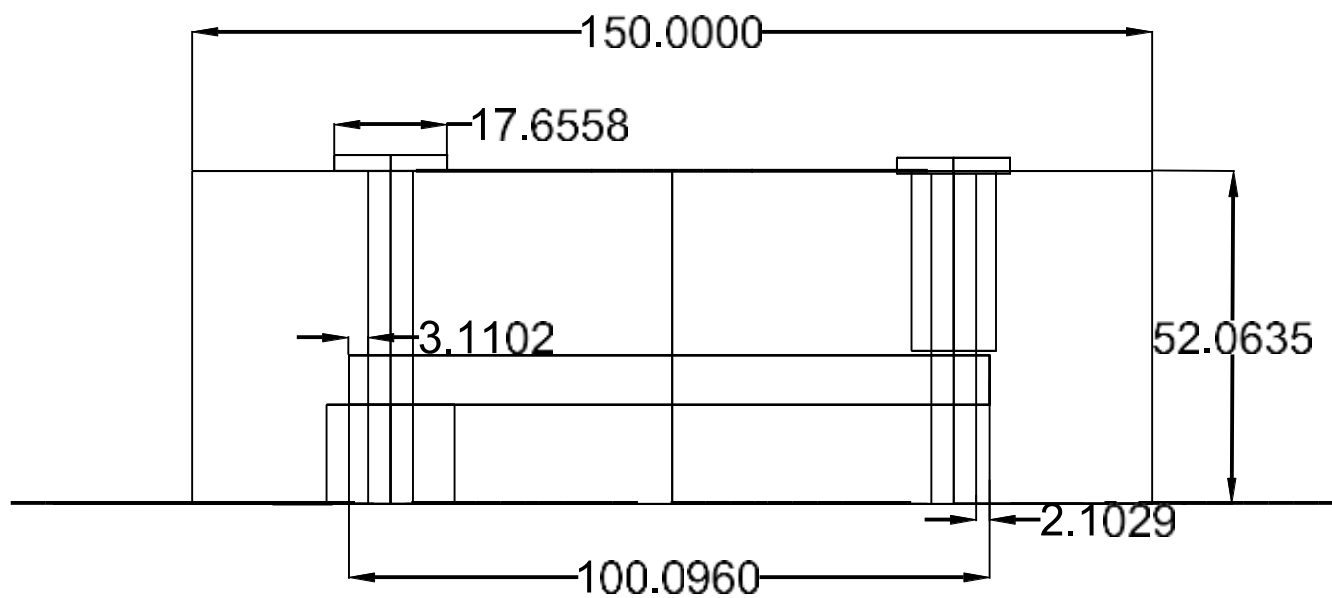
**PART NAME : LOAD CELL    ISOMETRIC VIEW    ANGLE OF PROJECTION : 120 DEGREES**



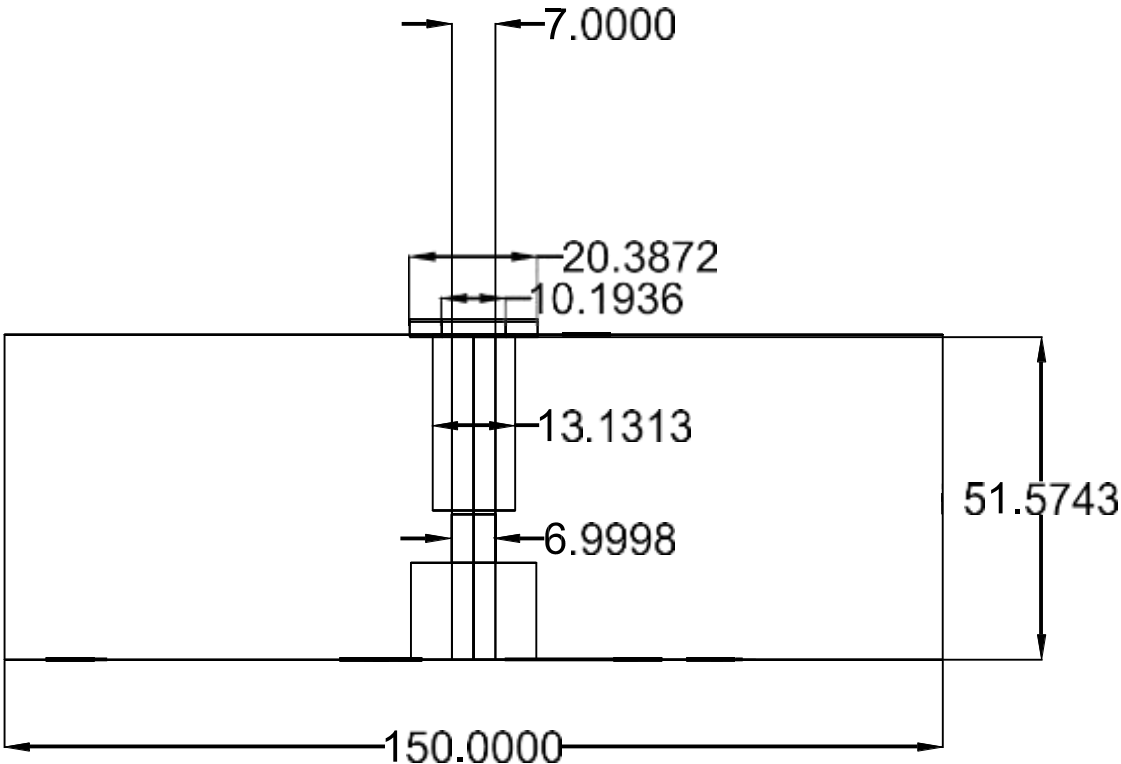
**LOAD CELL TOP VIEW**



## LOAD CELL FRONT VIEW



**LOAD CELL SIDE VIEW**



TEAM ID : TW=LAM=326

**PART DESCRIPTION :**

The above mechanical drawing are of the Load cell setup which we have used to measure the weight of the liquid dispensed

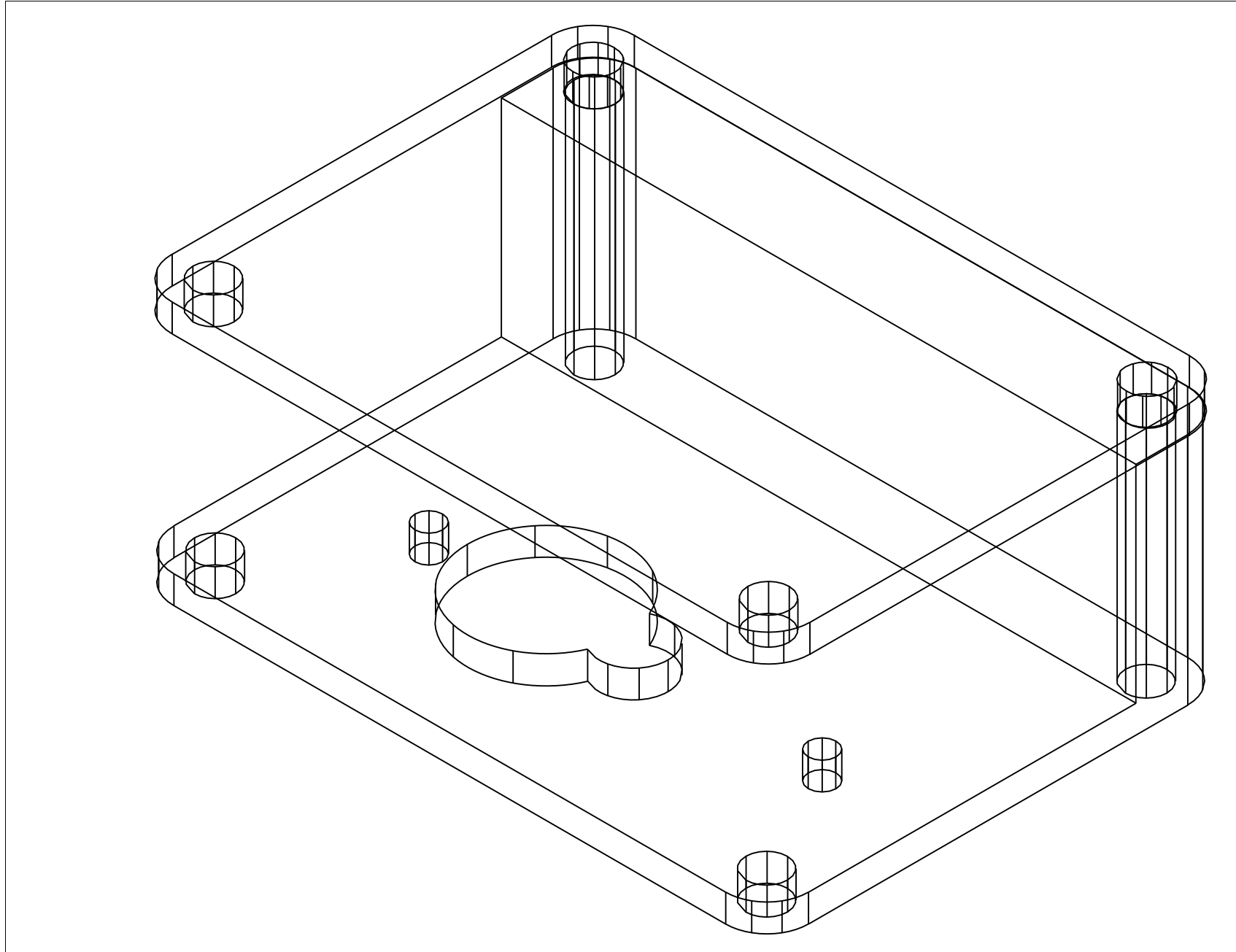
**QUANTITY : 1 Unit**

**MATERIAL : ACRYLIC SHEET**

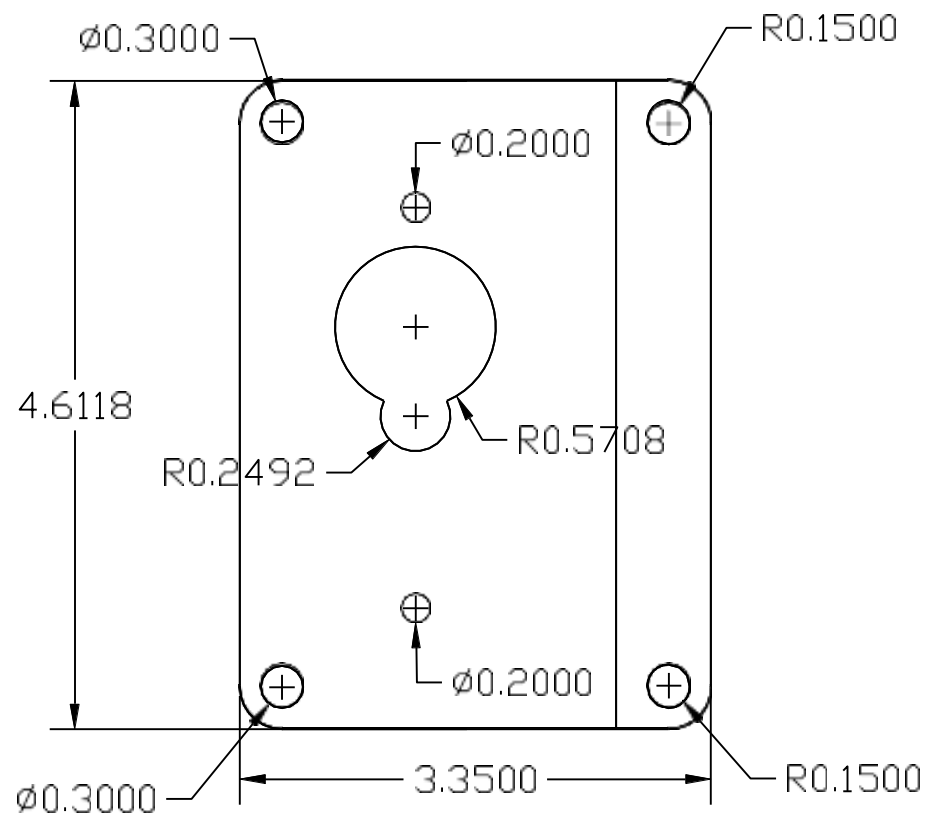
**SCALE : 1:1 ALL DIMENSIONS ARE IN mm**

**DATE OF DRAWING : 28/10/2024**

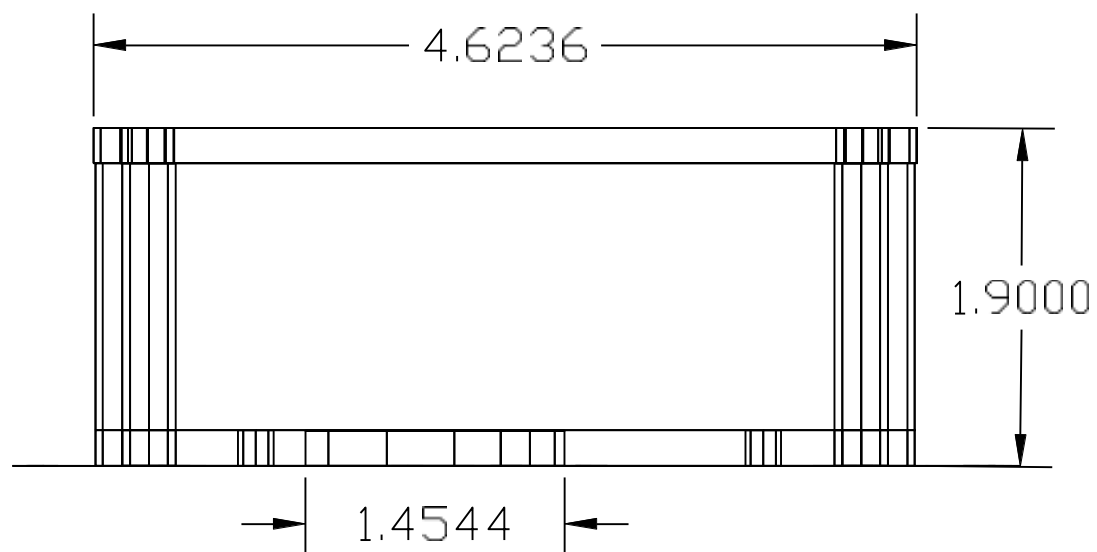
**PART NAME : PINCH VALVE    ISOMETRIC VIEW    ANGLE OF PROJECTION : 120 DEGREES**



## PINCH VALVE TOP VIEW

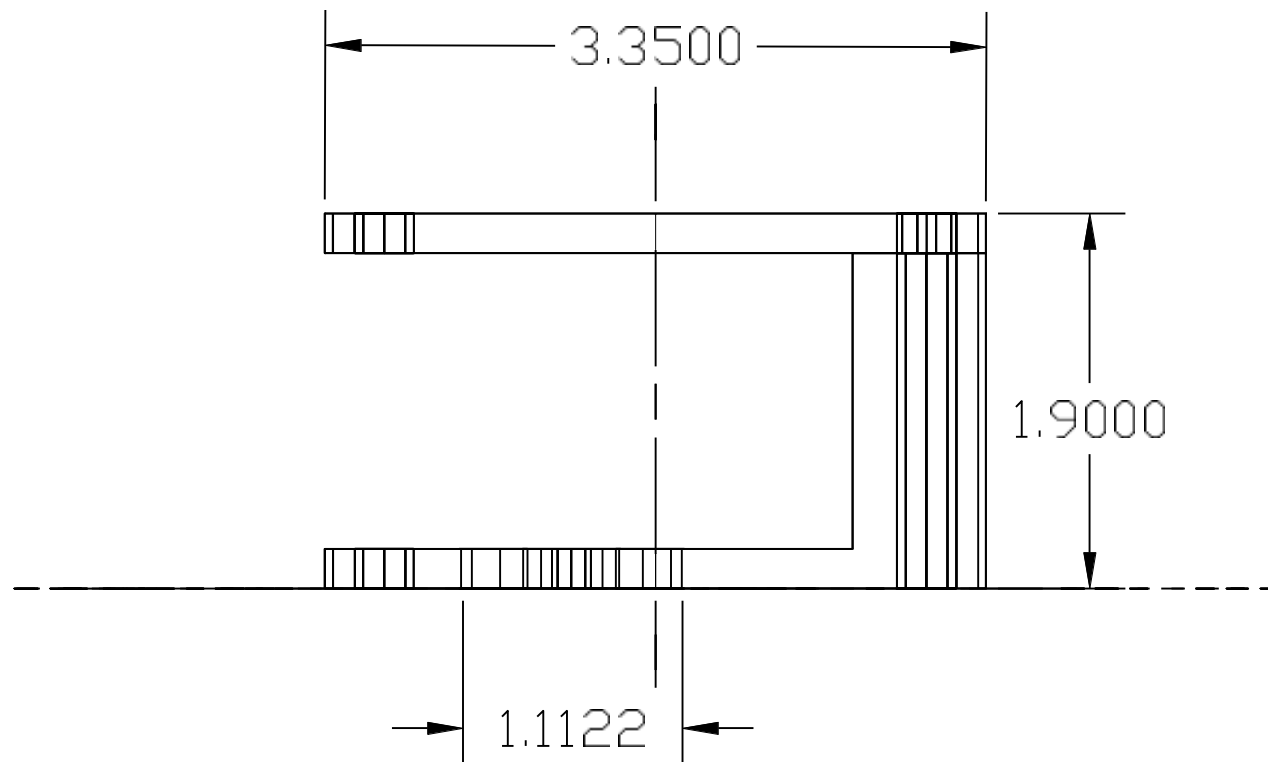


# PINCH VALVE FRONT VIEW





# PINCH VALVE SIDE VIEW



TEAM ID : TW=LAM=326

**PART DESCRIPTION :**

The above mechanical drawings are of the Pinch Valve setup which we use selectively choose which liquid to dispense into the beaker. This setup accommodates a servo which can constrict the flow of the liquid as needed.

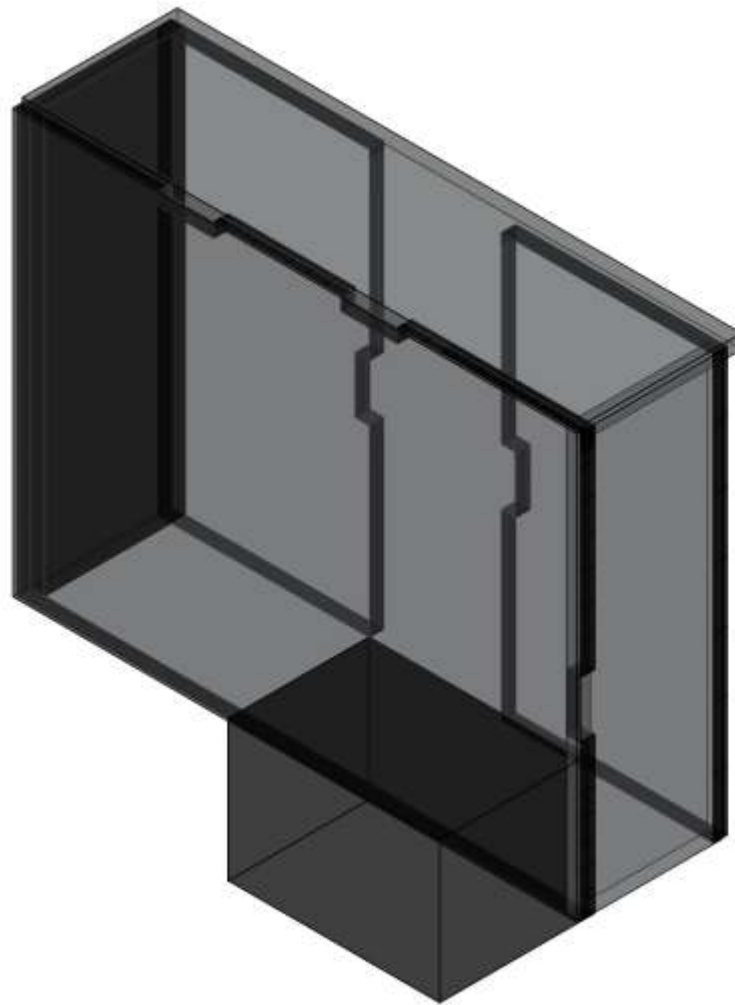
**QUANTITY : 1 Unit**

**MATERIAL : ACRYLIC SHEET**

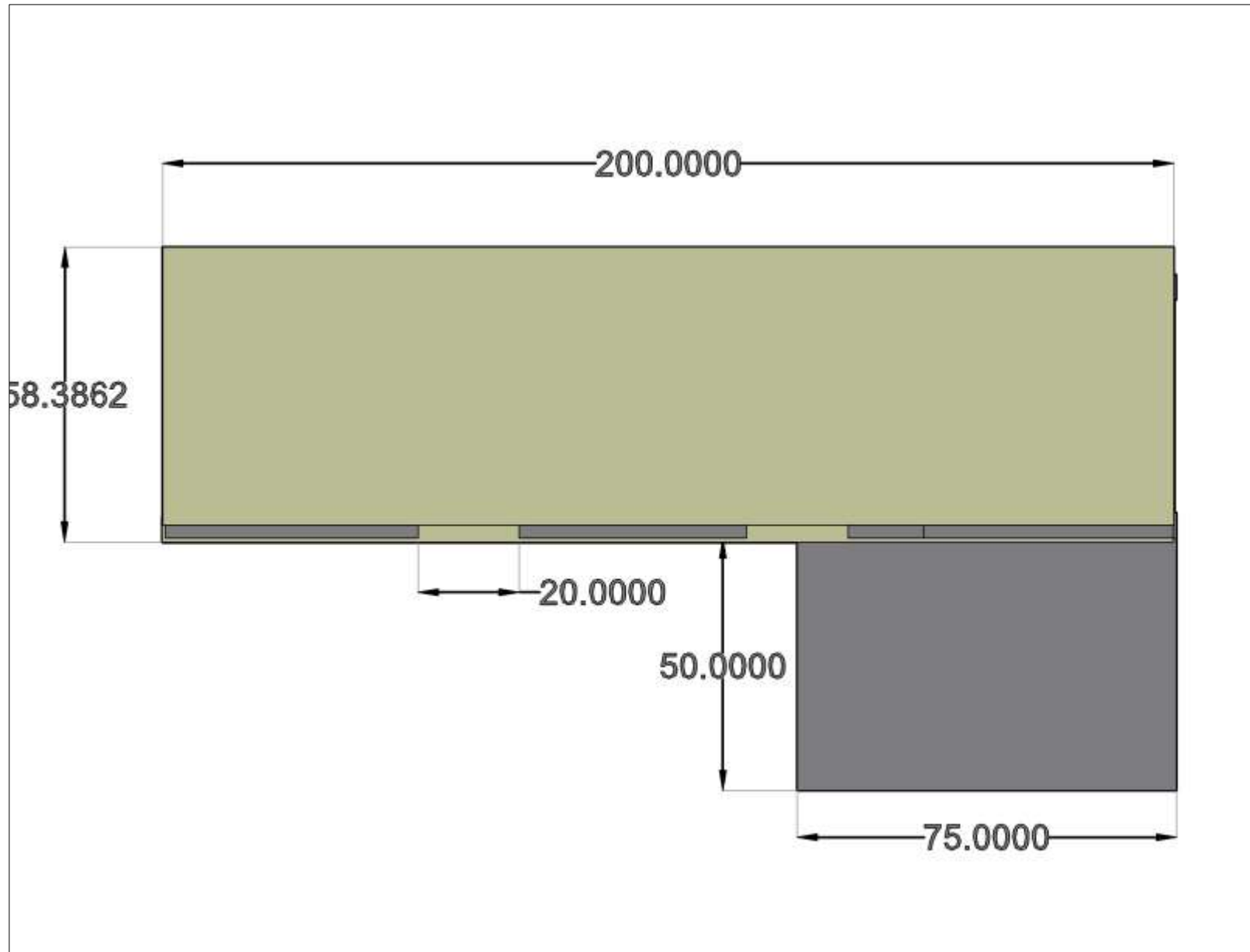
**SCALE : 1:1 ALL DIMENSIONS ARE IN mm**

**DATE OF DRAWING : 28/10/2024**

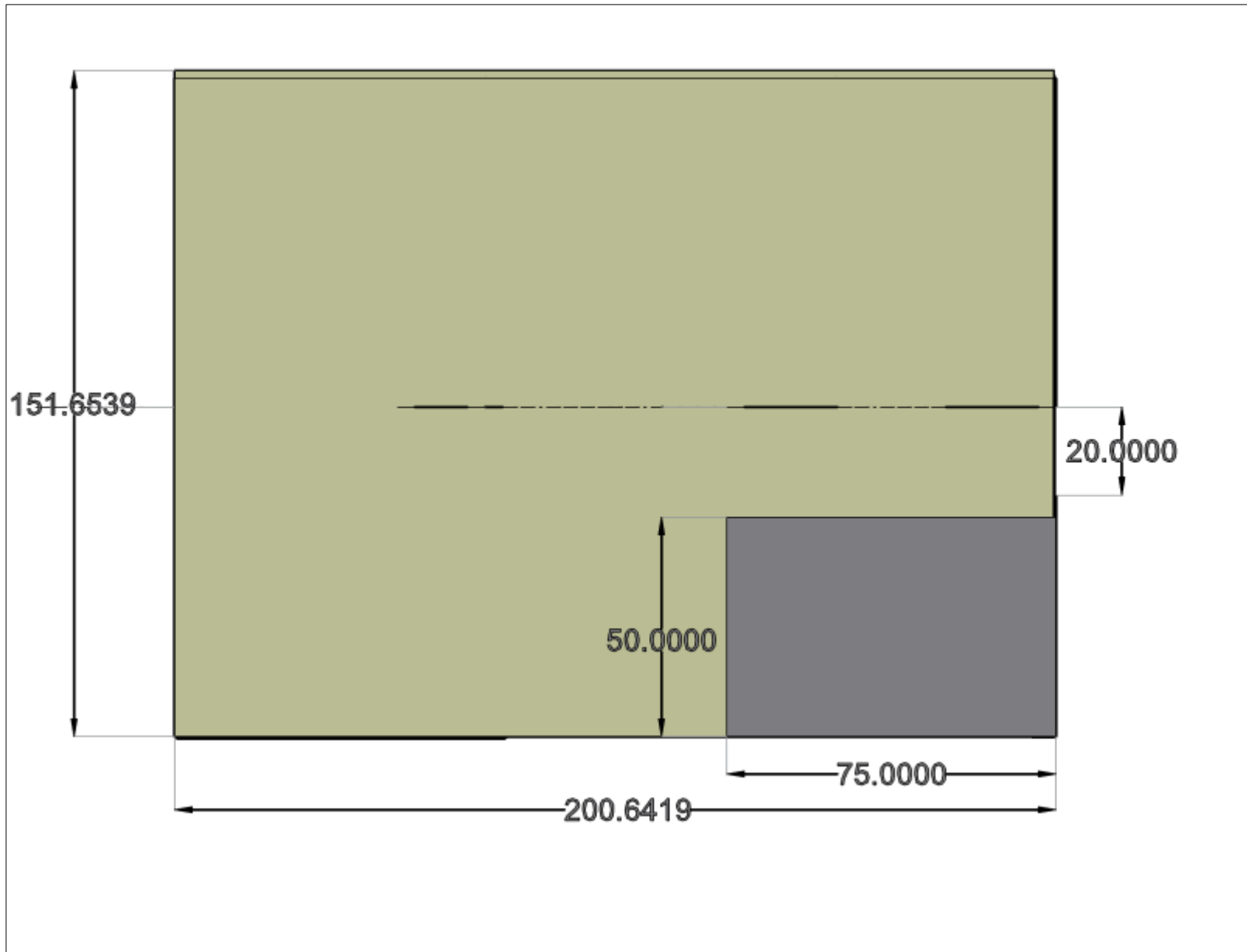
**PART NAME : SETUP STRUCTURE    ISOMETRIC VIEW**  
**ANGLE OF PROJECTION : 120 DEGREES**



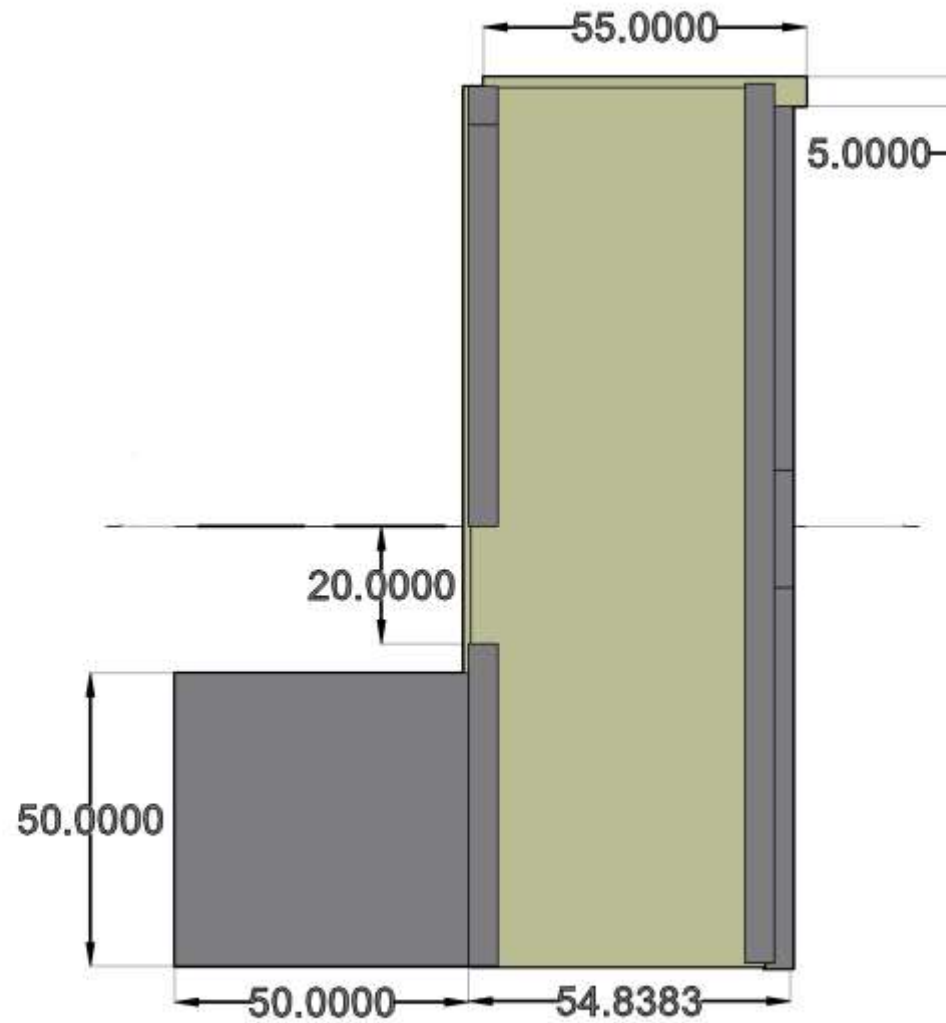
## OVERALL SETUP TOP VIEW



## OVERALL SETUP FRONT VIEW



## OVERALL SETUP SIDE VIEW



**TEAM ID : TW=LAM=326**

**PART DESCRIPTION :**

The above mechanical drawings are of the overall setup structure that we had assembled. The 2 servo motors go on top of the structure, with the T joint in front and a small cuboidal support in front for placing the peristaltic pump. Images of the setup has been attached for reference.

**QUANTITY : 1 Unit**

**MATERIAL : ACRYLIC SHEET**

**SCALE : 1:1 ALL DIMENSIONS ARE IN mm**

**DATE OF DRAWING : 29/10/2024**

