

# Contents

## §1. Lagrangian Mechanics

†a	Free Particle . . . . .	1
†b	Conservative Force . . . . .	1
†c	Constraint Force . . . . .	1

## I INTRODUCTION TO STATISTICS

### §1. Data Type

†a	Object . . . . .	3
†b	Binding and Input . . . . .	3
†c	Numeric . . . . .	3
†d	More on Bool . . . . .	4
†e	More on Float . . . . .	4

# §1 Lagrangian Mechanics

Let us start from defining the **action**:

$$S[\mathbf{q}(t)] = \int_0^T L(\mathbf{q}, \dot{\mathbf{q}}, t) dt,$$

the **Eular-Lagrange equation** is derived from  $\delta S = 0$ , with an additional restriction  $\delta \mathbf{q}(0) = \delta \mathbf{q}(T) = 0$ :

$$\begin{aligned} \delta \int_0^T L dt &= \int_0^T (\nabla_{\mathbf{q}} L \cdot \delta \mathbf{q} + \nabla_{\dot{\mathbf{q}}} L \cdot \delta \dot{\mathbf{q}}) dt \\ &= \int_0^T \left( \nabla_{\mathbf{q}} L - \frac{d}{dt} \nabla_{\dot{\mathbf{q}}} L \right) \cdot \delta \mathbf{q} dt = 0. \end{aligned}$$

Since the choice of  $\delta \mathbf{q}$  is arbitrary, we obtain the Eular-Lagrange equation (we place the highest order derivative at the beginning):

$$\frac{d}{dt} \nabla_{\dot{\mathbf{q}}} L - \nabla_{\mathbf{q}} L = \mathbf{0}. \quad (1)$$

But what is the **Lagrangian** function  $L$ ?

## †a Free Particle

First, there are some symmetry about the Lagrangian:

1) Space translation:  $L(\mathbf{q}, \dot{\mathbf{q}}, t) = L(\dot{\mathbf{q}})$ .

2) Rotation:  $L(\dot{\mathbf{q}}) = L(|\dot{\mathbf{q}}|^2)$ .

In this sense:

$$2 \frac{d}{dt} L'(|\dot{\mathbf{q}}|^2) \dot{\mathbf{q}}.$$

Compare to the Newtonian Mechanics:

$$m \ddot{\mathbf{q}} = 0,$$

we make  $L'(|\dot{\mathbf{q}}|^2)$  as a constant  $m/2$ :

$$L_{\text{free}} = T = \frac{1}{2} m |\dot{\mathbf{q}}|^2. \quad (2)$$

## †b Conservative Force

In the case of conservative force:

$$m \ddot{\mathbf{r}} = \mathbf{F} = -\nabla V(\mathbf{q}).$$

Then we have

$$\frac{d}{dt} \nabla_{\dot{\mathbf{q}}} T - \nabla_{\mathbf{q}} T + \nabla V(\mathbf{q}) = \frac{d}{dt} \nabla_{\dot{\mathbf{q}}} (T - V) - \nabla_{\mathbf{q}} (T - V) = 0.$$

So we define

$$L_{\text{conserve}} = T - V = \frac{1}{2} m |\dot{\mathbf{q}}|^2 - V. \quad (3)$$

## †c Constraint Force

Under the following conditions, we can use the **generalized coordinate**:

- 1) There is some holonomic constraint  $f(\mathbf{q}, t)$ .
- 2) The constraint force satisfies  $\mathbf{F} \cdot \delta \mathbf{q} = 0$ .

In Newtonian Mechanics:

$$m \ddot{\mathbf{q}} = \mathbf{F}_{\text{conserve}} + \mathbf{F}_{\text{constraint}}.$$

But in the variation of the action:

$$\begin{aligned} \delta S &= \int_0^T (m \ddot{\mathbf{q}} - \mathbf{F}_{\text{conserve}} - \mathbf{F}_{\text{constraint}}) \cdot \delta \mathbf{q} dt \\ &= \int_0^T (m \ddot{\mathbf{q}} - \mathbf{F}_{\text{conserve}}) \cdot \delta \mathbf{q} dt = 0 \end{aligned}$$



# Chapter 1

## Introduction to Statistics

### §1 Data Type

#### †a Object

Python is an **object-oriented** programming language. Everything is an **object** in Python:

$$\text{object} = \begin{cases} \text{identity}, \\ \text{type / class}, \\ \text{value / state}, \\ \text{methods / behaviors / operations.} \end{cases}$$

```
# print the identity, type, and the value for 4
print(id(4),type(4),4)
# type of any type is a type, the type itself is a type
print(type(type(4)))
print(type(type(type(4))))
```

```
140711773227544 <class 'int'> 4
<class 'type'>
<class 'type'>
```

- **Identity:** it guarantees that different objects have distinct identities at any given time.
- **Type:** objects of the same type support the same operations, and share the same properties.

#### †b Binding and Input

In Python, the **assignment** of  $a = b$  is like making the name  $a$  pointing to the object  $b$ .

```
# an example for binding
a,b=4,print
print(type(a),a,type(b),b,
      id(a),id(4),id(b),id(print))
b(a+5,"hello")
```

```
<class 'int'> 4 <class 'builtin_function_or_method'>
<built-in function print> 140723891816984
140723891816984 2069908885472 2069908885472
9 hello
```

The basic input in Python is through the function `input()`. The input takes ONE string as prompt, and it reads input as a string.

```
# an example for input function
n=input(f"{a} and hello\n")
print(type(n),n)
```

```
4 and hello
5
<class 'str'> 5
```

#### †c Numeric

The following are numeric types:

`bool ⊂ int ⊂? float ⊂? complex`

```
# an example for the above data types
print(type(True),True,type(1),1,
      type(1.0),1.0,type(1+0j),1+0j)
```

```
<class 'bool'> True <class 'int'> 1 <class 'float'> 1.0
<class 'complex'> (1+0j)
```

```
# subset example
if True==1==1.0==1+0j:
    print("Yes")
else:
    print("No")
```

```
Yes
```

We can use `bool()`, `int()`, `float()`, and `complex()` to convert a string to



```
# standard library fractions
import fractions
print(type(fractions.Fraction(1,10)), "\n",
      fractions.Fraction(1,10), fractions.Fraction("0.1"),
      fractions.Fraction(1,10)==decimal.Decimal("0.1"))
```

```
<class 'fractions.Fraction'>
1/10 1/10 True
```



# **Bibliography**