Three actors playing together in most movies

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graph, triangles count

1 Introduction

The IMDB dataset provides data about actors, movies and relations between them. Based on this dataset a number of interesting properties can be extracted from the data. The point, however, is doing this in efficient manner.

2 Problem Description

The **goal** is to find the three actors, whose movie count they have played together in is maximized among he whole dataset.

Input is a list of actors, movies and actor-movie pair, for each actor that has played in a movie.

Output is a list of actors with the desired property, on an empty list if no three actors have played together in the same movie.

3 Algorithm

The algorithm we are presenting works on two main steps:

- Build the data structure the efficiency of the algorithm is determined by the data structure it runs on. On the other hand, the data structure is specifically designed to solve this problem.
- Traverse data structure and output result the algorithm works by discarding part of the information on every iteration, thereby reducing the size of the problem.

3.1 Notations

Let G = (V,E) be an weighted, undirected simple graph and let n = |V| and m = |E|.

A vertex v denotes an actor. Any edge e between vertices v_1 and v_2 denotes a set of movies these two actors have played together. Weight of the edge, W(e) denotes the size of that set.

Denote by A(v) the set of adjacent edges to vertex v.

SET(e) is the set of (two) vertices adjacent to an edge e.

Unique $(v_1, v_2, ... v_n)$ - returns a set of unique elements.

Remove(v) - removes edges adjacent to v from the graph G.

MovieCount denotes the biggest number found so far of common movies between any given three actors.

3.2 Data structure

As mentioned in the previous section, the algorithm works starts by first building the data structure. The data structure is a graph, where vertices represent actors and edges between them represent the movie(s) these actors played together in.

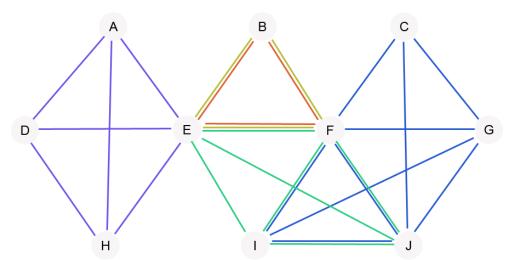


Figure 1: Graph Example

Figure 1 represents the data structure. To clearly illustrate the problem, the picture above represents a multi-graph, i.e. there can be multiple edges between two vertices. This is not the case of the actual data structure, however, as multiple edges are collapsed into a single one, where the weight is the sum of the weights of the original edges. The weight of an edge is the initially 1 - a single movie common to two actors (vertices). The edge contains sorted list of the movies common for two actors adjacent to the specific edge.

After the structure is constructed, the actual data processing takes place.

3.3 Pseudocode

Main algorithm we implemented is FindThreePlayers. After constructing the graph, we iterate over all vertices (actors). We find for each vertex all subsets of size of two of the set of adjacent edges to that vertex. We take an advantage of the fact that if an actor 1 played together in the same movie "A" with an actor 2 and the actor 1 played together with an actor 3 in the movie "A", that means that the actor 2 and the actor 3 had to play together in the movie "A". So we decided not to look for triangles in traditional way, but we look for pairs of edges having movies in common being adjacent to a specific vertex.

We examine each pair of edges and we find the number of common movies that actors played in together (this is a common set of the subsets - the movies from two edges). We do that only if minimal weight of edges is higher than found (by now) maximum number of movies that actors played together.

If the solution is better that the already found, we save it. We continue searching and at the end, we remove any references to the adjacent edges to the analysed vertex. This will make future iterations faster, since less edges need to be examined. We go to the next iteration.

Pseudocode for the algorithm is presented below:

```
Algorithm 1: FindThreePlayers()
1 moviesCount \leftarrow 0;
2 {a1,a2,a3};
3 FOR v \in V DO
4
    FOR i \leftarrow 0 to size of A(v) DO
5
         FOR j \leftarrow i + 1 to size of A(v) DO
6
              e1\leftarrow A(v)[i];
7
              e2 \leftarrow A(v)[j];
8
              IF MoviesCount < MIN(W(e1), W(e2)) THEN
9
                   count ← CommonMovieSubsetCount(e1, e2);
                   IF moviesCount < count THEN
10
11
                         movieCount \leftarrow count;
12
                         \{a1,a2,a3\} \leftarrow Unique(SET(e1), SET(e2));
13
                   END IF
14
               END IF
15
          END FOR
16
      END FOR
17 Remove A(v);
18 END FOR
```

We designed CommonMovieSubsetCount that returns number of items that are common in 2 subset given as arguments. We take advantage of the fact that the lists are sorted and we iterate over all the items in both list in linear time.

The pseudocode is present below:

```
Algorithm 2: CommonMovieSubsetCount(movies1, movies2)
1 count \leftarrow 0;
2 p1 \leftarrow 0;
3 p2 \leftarrow 0;
4 WHILE p1 < W(movies1) AND p2 < W(movies2)
    IF movies1[p1] = movies2[p2] THEN
6
      INCREMENT(count);
7
      INCREMENT(p1);
8
      INCREMENT(p2);
    ELSE IF movies1[p1] < movies2[p2]</pre>
9
10
      INCREMENT(p1);
    ELSE IF movies1[p1] > movies2[p2]
11
     INCREMENT(p2);
12
13 END IF
14 RETURN count;
```

3.4 Analysis

By not choosing to implement a traditional triangles counting, we avoided to examine three times the same triple of the actors and the number of their common movies thay played in. To be able to avoid this, we constructed a special data structure and by consolidating edges, we saved used space to save the data. In the worst cas scenario, when each actor played together with another one (it is not realistic situation though) we will have n vertices and $n^*(n-1)/2$ edges.

Complexity of the algorithm highly depends on degree of vertices. The higher it is, the longer computation time is needed. It is related to the process of looking for subsets of size two for each vertex. On the other hand after examination of found pairs, we can remove these edges from the list, so the complexity of the graph is getting smaller in faster pace. If we did not remove edges adjacent to the analysed vertex, the complexity of the algorithm would be: $\sum_{i=1}^{n} {k \choose 2}$ where k is size of of A(v), $v \in V$. We gain a lot by successfully making graph having less and less edges to be examined.

4 Experiments

Some experiments were conducted to verify the correctness of the algorithm and its running time. The results were compared with the "naive" approach - a brute force algorithm that checks any possible combinations. TO BE CONTINUED...