

Derivative of SVD for complex-valued matrices

$A \in \mathbb{C}^{m \times n}$ of rank $k \leq \min(m, n) \Rightarrow A = USV^T$ with $U \in \mathbb{C}^{m \times k}$,

$S \in \mathbb{R}^{k \times k}$ diagonal, $V \in \mathbb{C}^{n \times k}$, and $U^T U = V^T V = \mathbb{I}_k$ (i) (non-unitary)

$$\Rightarrow dA = dU S V^T + U dS V^T + U S dV^T \quad (\text{ii})$$

Differentiating constraint (i) yields $dU^T U + U^T dU = 0$; $dV^T V + V^T dV = 0$

$\Rightarrow d\Omega_U := U^T dU$ and $d\Omega_V := V^T dV$ are $k \times k$ anti-Hermitian matrices!

We can always find matrices $U_1 \in \mathbb{C}^{m \times (m-k)}$ and $V_1 \in \mathbb{C}^{n \times (n-k)}$ such that

$[U \ U_1]$ and $[V \ V_1]$ are unitary (unitary completion, e.g. via Gram-Schmidt!).

We may then expand dU as $dU = U d\Omega_U + U_1 d\Omega_{U_1}$ with $d\Omega_{U_1} \in \mathbb{C}^{(m-k) \times k}$ uncontrolled,
and expand dV as $dV = V d\Omega_V + V_1 d\Omega_{V_1}$ with $d\Omega_{V_1} \in \mathbb{C}^{(n-k) \times k}$ uncontrolled.

We proceed by left-multiplying (ii) by U^T and right-multiplying by V :

$$\begin{aligned} dP &:= U^T dA V = U^T dU S + dS + S dV^T V \\ &= d\Omega_U S + dS + S d\Omega_V^T \\ &\quad \uparrow \\ dU &= U d\Omega_U + U_1 d\Omega_{U_1} \\ dV^T &= d\Omega_V^T V^T + d\Omega_{V_1}^T V_1^T \end{aligned}$$

Since $d\Omega_U$ and $d\Omega_V$ are anti-Hermitian, their diagonal elements are purely imaginary.

However, dS is a diagonal matrix with purely real entries. Thus it's clear that

$$dS = \mathbb{I}_k \circ \operatorname{Re}[dP] \quad \uparrow \text{because singular values are always real!}$$

Hadamard product

$$\text{and } d\Omega_U S - S d\Omega_V = \mathbb{I}_k \circ i \operatorname{Im}[dP] + \mathbb{I}_k \circ dP \quad (\text{iii})$$

Taking the complex conjugate transpose yields $-S d\Omega_U + d\Omega_V S = -\mathbb{I}_k \circ i \operatorname{Im}[dP] + \mathbb{I}_k \circ dP^T$ (iv)

To proceed, we right-multiply (iii) by \mathcal{S} and left-multiply (iv) by \mathcal{S} and add them together, yielding

$$\begin{aligned} d\Omega_U \mathcal{S}^2 - \mathcal{S} d\Omega_U \mathcal{S} - \mathcal{S}^2 d\Omega_U + \mathcal{S} d\Omega_U \mathcal{S} &= \left[\bar{\Pi}_U \circ i \operatorname{Im}[dP] \right] \mathcal{S} - \mathcal{S} \left(\bar{\Pi}_U \circ i \operatorname{Im}[dP] \right) + \left[\bar{\Pi}_U \circ dP \right] \mathcal{S} + \mathcal{S} \left[\bar{\Pi}_U \circ dP^\dagger \right] \\ \Rightarrow d\Omega_U \mathcal{S}^2 - \mathcal{S}^2 d\Omega_U &= \bar{\Pi}_U \circ S dP + \bar{\Pi}_U \circ dP^\dagger \mathcal{S} \end{aligned}$$

$$\begin{aligned} D(A \circ B) &= DA \circ B = A \circ DB \\ (A \circ B) D &= AD \circ B = A \circ BD \end{aligned}$$

\uparrow
 $A \circ B = A \circ C$
 $= B \circ (B \circ C)$

$$\Rightarrow \bar{\Pi}_U \circ [dPS + SdP^\dagger] = d\Omega_U \mathcal{S}^2 - \mathcal{S}^2 d\Omega_U$$

$$\bar{\Pi}_U \circ Z \stackrel{!}{=} X D - D X \quad \text{with } Z^\dagger = Z, X^\dagger = -X, D \in \mathbb{R}^{n \times n} \text{ diagonal, solve for } X.$$

$$X = F \circ Z \quad \text{with } F_{ij} = \begin{cases} \frac{1}{d_i - d_j} & i \neq j \\ 0 & i=j \end{cases} \quad \Rightarrow \quad X^\dagger = F^\dagger \circ Z^\dagger = -F \circ Z \quad \text{is skew-symmetric.} \quad \checkmark$$

$$XD - DX = (F \circ Z)D - D(F \circ Z) = (FD) \circ Z - (DF) \circ Z = (X)$$

$$\begin{aligned} \text{let } i \neq j, \text{ then} \quad (FD)_{ij} &= \sum_k F_{ik} d_{kj} = \sum_k \frac{1}{d_i - d_k} d_{kj} d_j = \frac{d_j}{d_i - d_j} \\ (DF)_{ij} &= \sum_k d_{ij} F_{kj} = \sum_k d_i d_{kj} \frac{1}{d_j - d_i} = \frac{d_i}{d_j - d_i} \end{aligned}$$

$$\text{also, } (FD)_{ii} = (DF)_{ii} = 0$$

$$\Rightarrow (FD)_{ij} = \begin{cases} \frac{d_j}{d_i - d_j} & i \neq j \\ 0 & i=j \end{cases}, \quad (DF)_{ij} = \begin{cases} \frac{d_i}{d_j - d_i} & i \neq j \\ 0 & i=j \end{cases}$$

$$(X) = (FD - DF) \circ Z = \bar{\Pi}_U \circ Z \quad \checkmark$$

Therefore, the equation is solved by $d\Omega_U = F \circ [dPS + SdP^\dagger]$ (v)

We can obtain a similar equation for $d\Omega_V$ by left-multiplying (iii) by \mathcal{S} and right-multiplying (iv) by \mathcal{S} before adding:

$$\begin{aligned} S d\Omega_U \mathcal{S} - \mathcal{S}^2 d\Omega_V &= S \circ i \operatorname{Im}[dP] + \bar{\Pi}_U \circ S dP \\ - S d\Omega_U \mathcal{S} + d\Omega_V \mathcal{S}^2 &= -S \circ i \operatorname{Im}[dP] + \bar{\Pi}_V \circ dP^\dagger \mathcal{S} \end{aligned} \Rightarrow d\Omega_V \mathcal{S}^2 - \mathcal{S}^2 d\Omega_V = \bar{\Pi}_V \circ [SdP + dP^\dagger \mathcal{S}]$$

solved by $d\Omega_V = F \circ [SdP + dP^\dagger \mathcal{S}]$ (vi)

Equations (v) and (vi) do not fix the diagonals of $d\Delta u$ and $d\Delta v$, which are purely imaginary. We can fix this by looking at the diagonal part of eq. (iii):

$$\mathbb{1}_L \circ [d\Delta u S - S d\Delta v] = \mathbb{1}_L \circ i \operatorname{Im}[dP]$$

$$\Rightarrow \mathbb{1}_L \circ [d\Delta u - d\Delta v] = \mathbb{1}_L \circ i \operatorname{Im}[dP] S^{-1}$$

We can satisfy this equation by setting

I'm choosing this solution because of symmetry. I don't know
✓ if it actually matters how we "distribute" the dD
terms between $d\Delta u$ and $d\Delta v$

$$\begin{aligned} d\Delta u &= F \circ [dPS + SdP^T] + \mathbb{1}_L \circ dD \\ d\Delta v &= F \circ [SdP + dP^T S] - \mathbb{1}_L \circ dD \quad \text{with } dD = \frac{i \operatorname{Im}[dP] S^{-1}}{2} \end{aligned}$$

(Vii)

We are left with finding dK_u and dK_v . Multiplying (ii) by U_1^T yields

$$U_1^T dA = U_1^T dU S V^T = U_1^T (U d\Delta u + U_1 dK_u) S V^T = dK_u S V^T \quad | \cdot V \cdot S^{-1}$$

$$dK_u = U_1^T dA V S^{-1} \quad (\text{Vii})$$

Similarly, we can left-multiply (ii)^T by V_1^T to obtain

$$V_1^T dA^T = V_1^T dV S U^T = V_1^T (V d\Delta v + V_1 dK_v) S U^T = dK_v S U^T \quad | \cdot U \cdot S^{-1}$$

$$dK_v = V_1^T dA^T U S^{-1} \quad (\text{Viii})$$

Using all previous derivations, we can finally write

$$dU = U \left(F \circ [dPS + SdP^T] + \mathbb{1} \circ dD \right) + U_1 U_1^T dA V S^{-1}$$

$$dS = \mathbb{1}_L \circ \operatorname{Re}[dP]$$

$$dV = V \left(F \circ [SdP + dP^T S] - \mathbb{1} \circ dD \right) + V_1 V_1^T dA^T U S^{-1}$$

Using the fact that $M_U = [U U^\dagger]$ and $M_V = [V V^\dagger]$ are unitary:

$$\Rightarrow M_U M_U^\dagger = [U U^\dagger] \begin{pmatrix} U^\dagger \\ U_2^\dagger \end{pmatrix} = UU^\dagger + U_2 U_2^\dagger = \mathbb{1}_n ; \quad M_V M_V^\dagger = [V V^\dagger] \begin{pmatrix} V^\dagger \\ V_2^\dagger \end{pmatrix} = VV^\dagger + V_2 V_2^\dagger = \mathbb{1}_m$$

and we can rewrite

$$\boxed{\begin{aligned} dU &= U \left(F \circ [dPS + SdP^\dagger] + \mathbb{1}_n \cdot dD \right) + (\mathbb{1}_m - UU^\dagger) dA VS^{-1} \\ dS &= \mathbb{1}_n \circ \text{Re}[dP] \\ dV &= V \left(F \circ [SdP + dP^\dagger S] - \mathbb{1}_n \cdot dD \right) + (\mathbb{1}_m - VV^\dagger) dA^\dagger VS^{-1} \end{aligned}}$$

There is one small subtlety left to discuss. The SVD is not unique, but has a gauge degree of freedom: $\Lambda = USV^\dagger = U'SV'^\dagger = (UA)S(V\Lambda)^{-1} = U\Lambda SV^\dagger V = US(\Lambda\Lambda^\dagger)V$

with $\Lambda_{jj} = e^{i\theta_j}$ and $\Lambda_{ij} = 0$ for $i \neq j$. \Rightarrow k degrees of freedom!

\Rightarrow dU is illdefined, we can only really define derivatives of functions that are gauge invariant!