



McGill

ECSE 420

Lab 2: Finite Elements

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Outline

- Overview of finite element method
- Lab 2 info



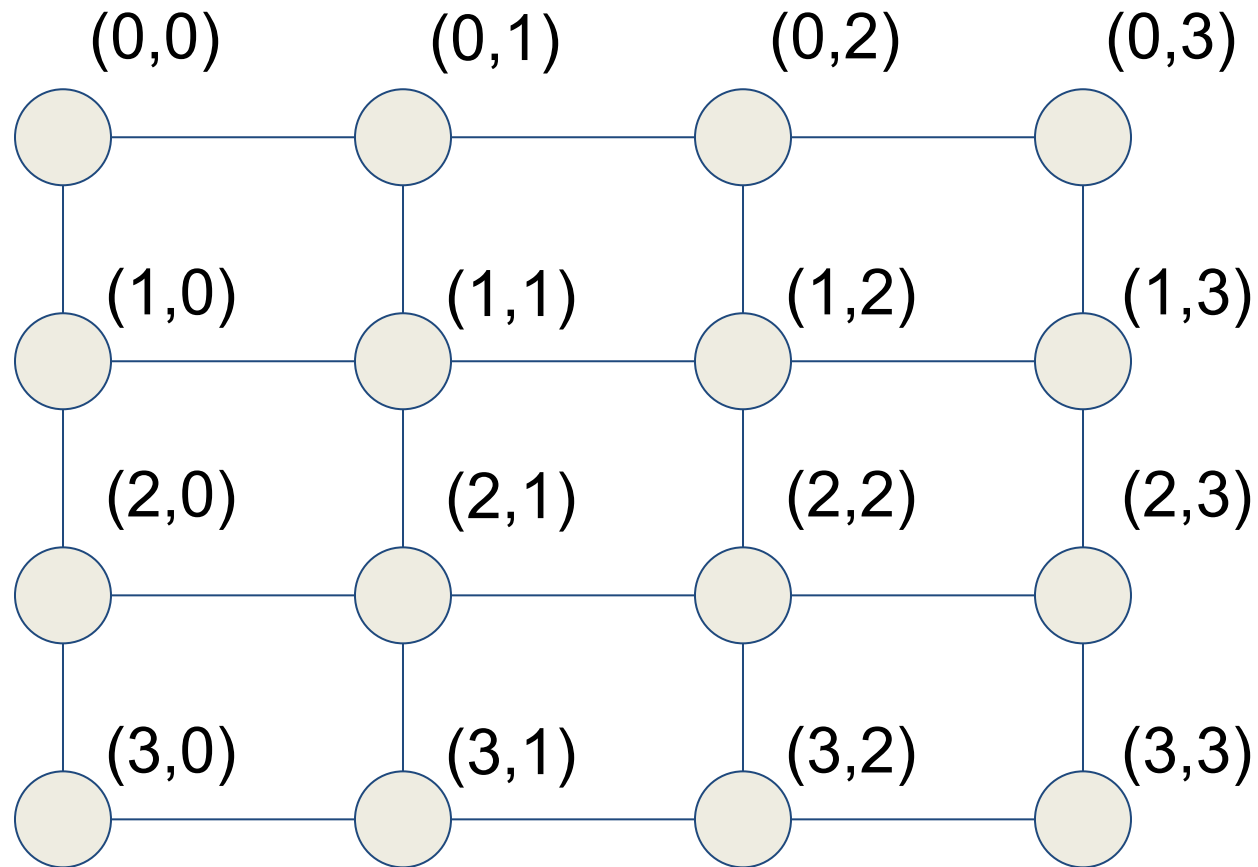
Finite Elements

- We can simulate a large or complex object by
 - breaking it into smaller, simpler objects (“finite elements”)
 - simulating the finite elements independently
 - sending data between elements as needed to model interaction
- Example: ocean simulator from Assignment 2
- This lab: simulate drum using grid of finite elements



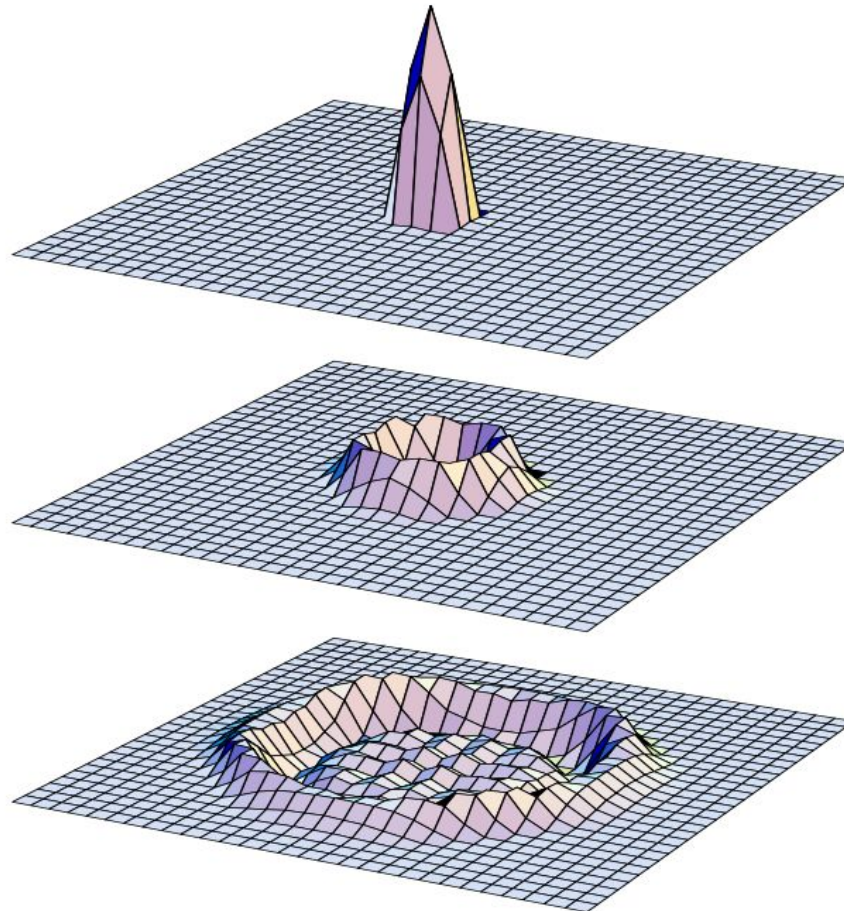
Finite Elements

- We will model a drum as elements of tensile material connected in a square grid



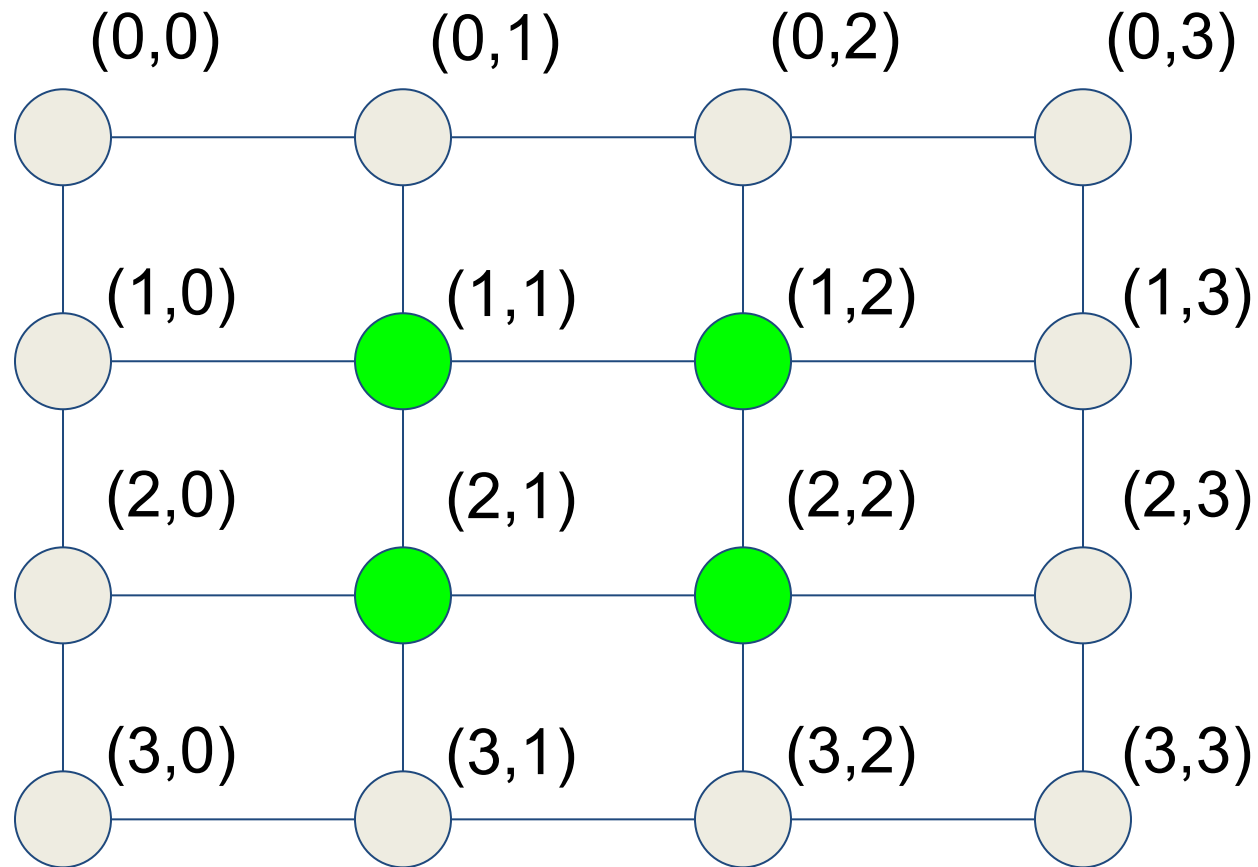
Finite Elements

- Response of grid to impulse at center:



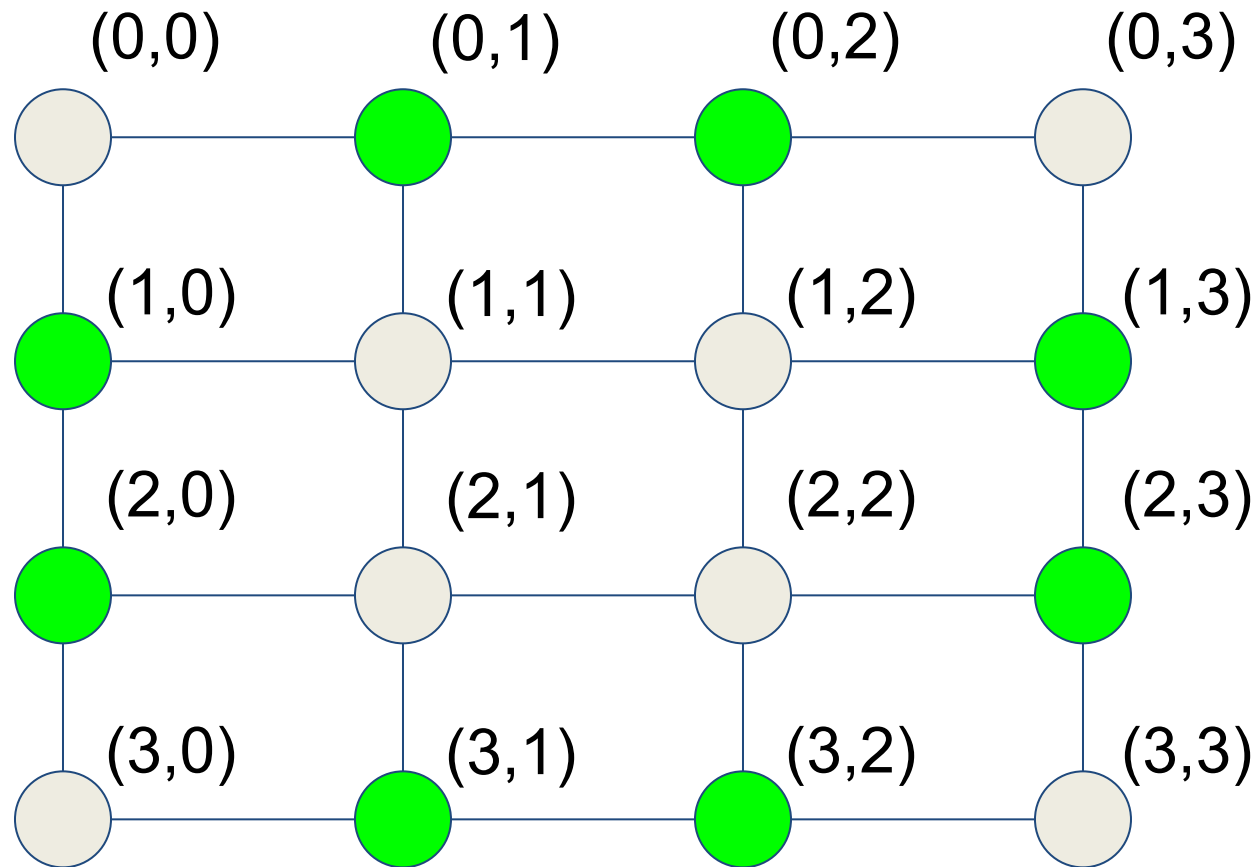
Finite Elements

- At each time step, update vertical displacement of each element in **interior**:



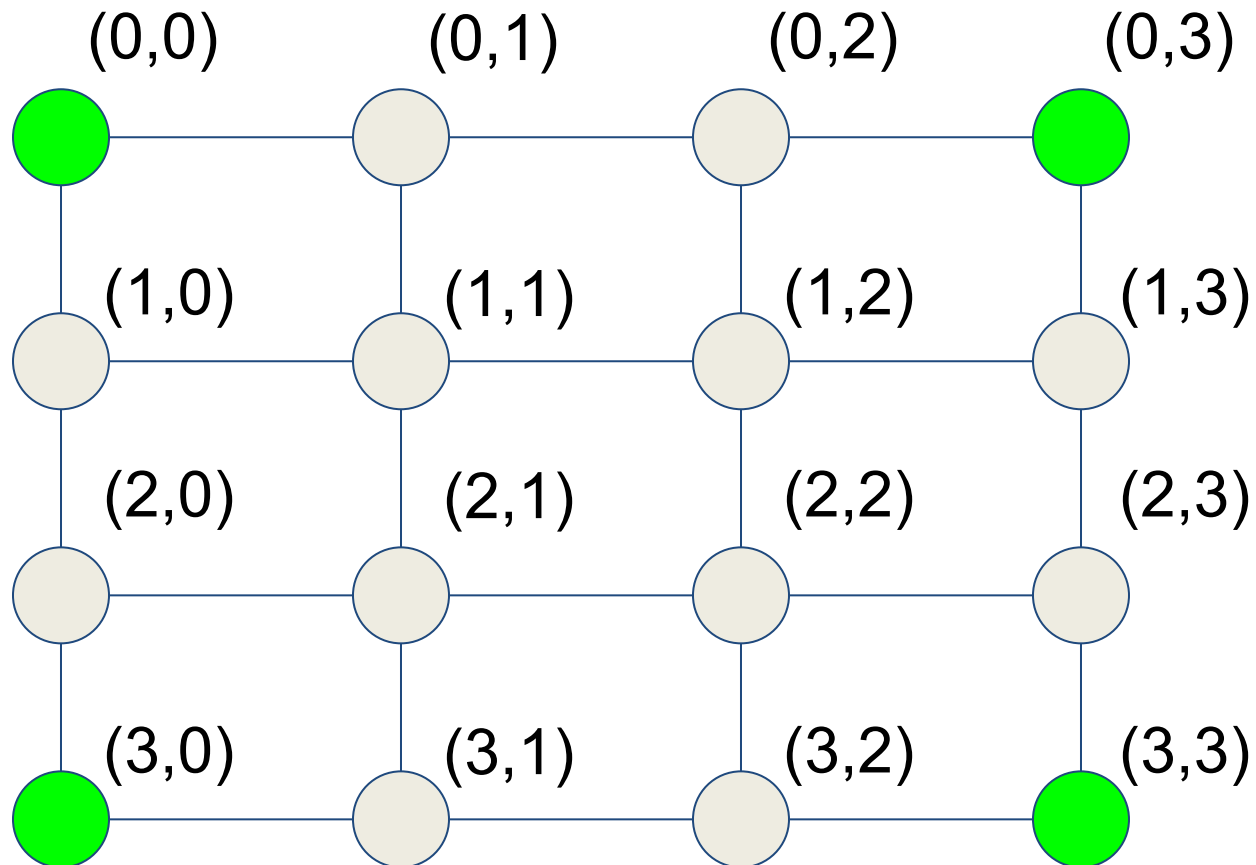
Finite Elements

- Then, update elements in the **sides**:



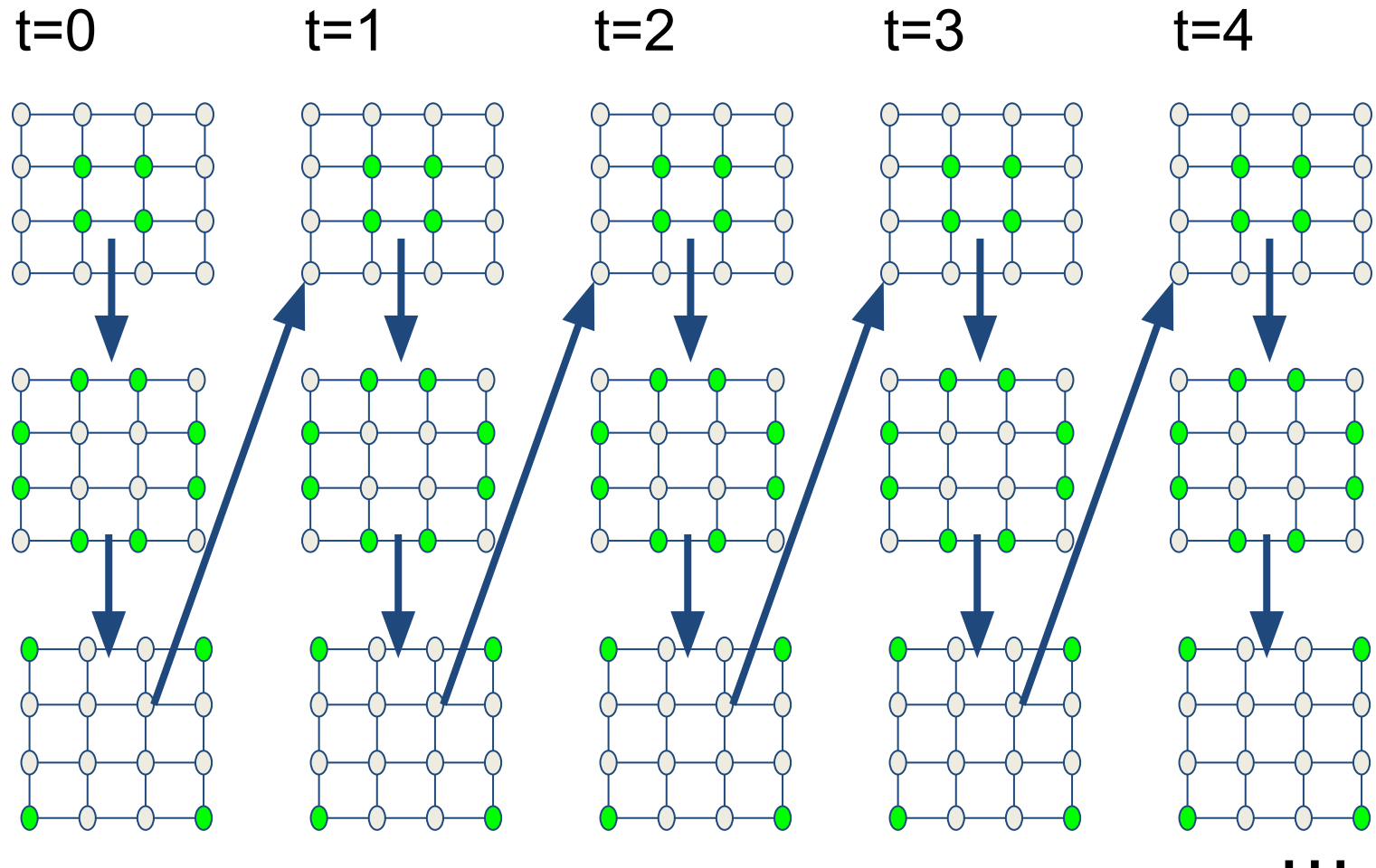
Finite Elements

- Finally, update elements in the **corners**:



Finite Elements

- Once all displacements are updated, repeat:



Finite Elements

- **Interior** update equation:

$$u(i, j) = \frac{\rho(u1(i-1, j) + u1(i+1, j) + u1(i, j-1) + u1(i, j+1) - 4u1(i, j)) + 2u1(i, j) - (1 - \eta)u2(i, j)}{1 + \eta}$$

$$1 < i < N - 1, 1 < j < N - 1$$

- where **u** = vertical displacement
- **u1** = previous displacement
- **u2** = previous previous displacement
- **ρ (rho)** = physical constant related to pitch
- **η (eta)** = physical constant related to damping



Finite Elements

- Each element of u depends only on u_1 and u_2 , and not on other elements of u
- Each element can be updated in parallel!



Finite Elements

- Equation breakdown:

$$u(i, j) = \frac{\rho(u1(i-1, j) + u1(i+1, j) + u1(i, j-1) + u1(i, j+1) - 4u1(i, j))}{1 + \eta} + 2u1(i, j) - (1 - \eta)u2(i, j)$$

- Sum of (top, bottom, left, right) neighbors' previous displacements and this element's previous displacement multiplied by rho
- This element's previous displacement multiplied by 2
- This element's previous previous displacement multiplied by (1-eta)



Finite Elements

- **Side** update equations:

$$u(0, i) = Gu(1, i)$$

$$u(N - 1, i) = Gu(N - 2, i)$$

$$u(i, 0) = Gu(i, 1)$$

$$u(i, N - 1) = Gu(i, N - 2)$$

$$1 < i < N - 1$$

- where **G** = boundary gain (whether the edge of the drum is taut or loose)



Finite Elements

- Note: side u element updates depend on interior u elements (not u_1 or u_2)
→ must happen after interior points updated



Finite Elements

- **Corner** update equations:

$$u(0, 0) = Gu(1, 0)$$

$$u(N - 1, 0) = Gu(N - 2, 0)$$

$$u(0, N - 1) = Gu(0, N - 2)$$

$$u(N - 1, N - 1) = Gu(N - 1, N - 2)$$

- Must happen after side points updated



Finite Elements

- Example using a 4x4 grid for $T=2$ iterations:



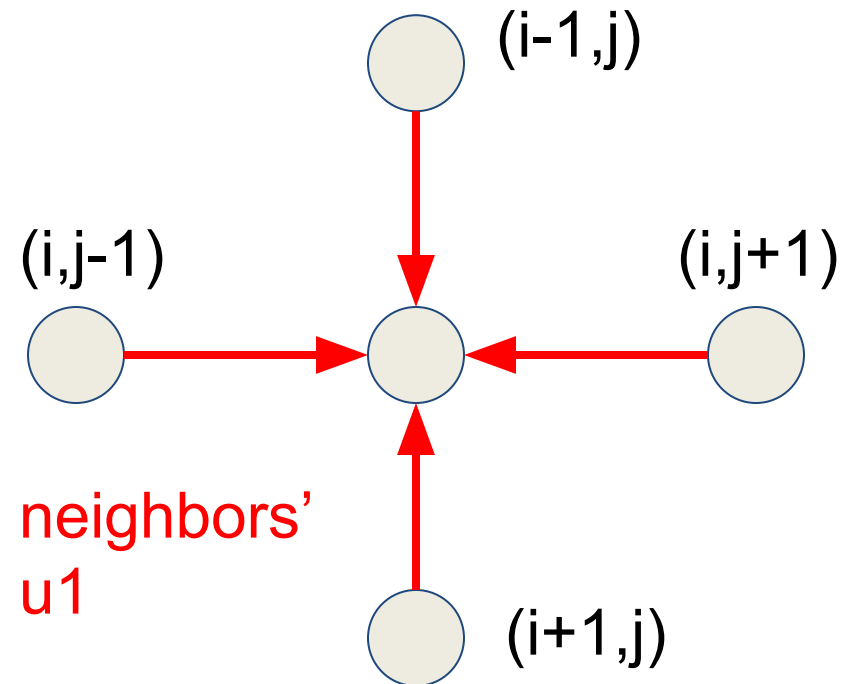
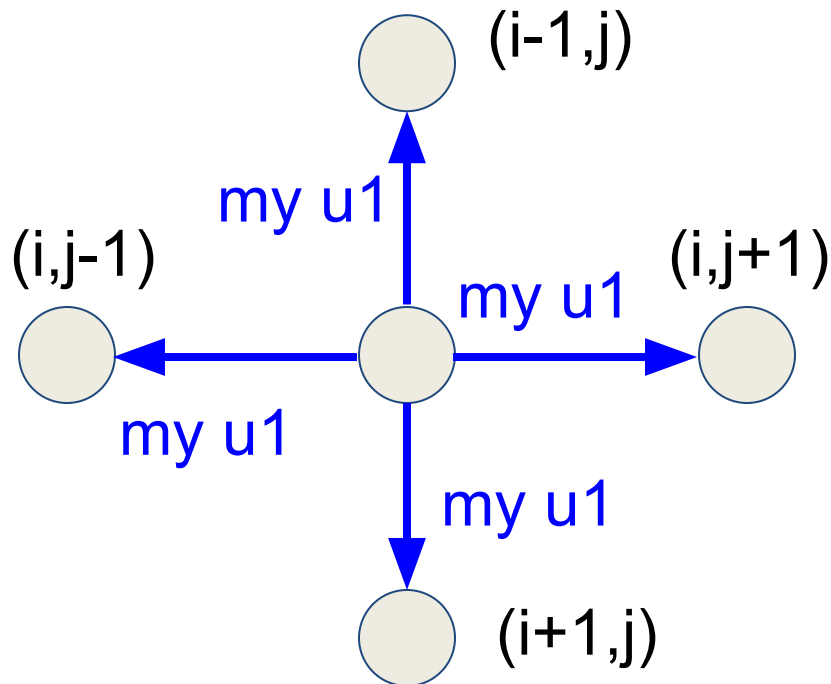
Lab 2

- Use MPI to parallelize computation and send messages between elements
- Part 1:
 - Small grid
 - One MPI process per element
- Part 2:
 - Large grid
 - Multiple elements assigned to each MPI process



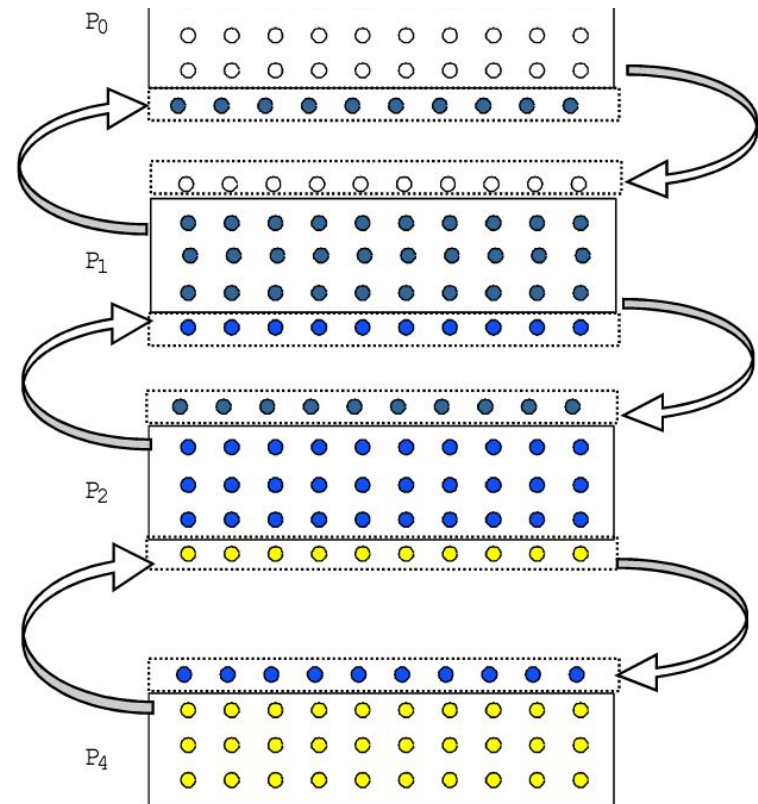
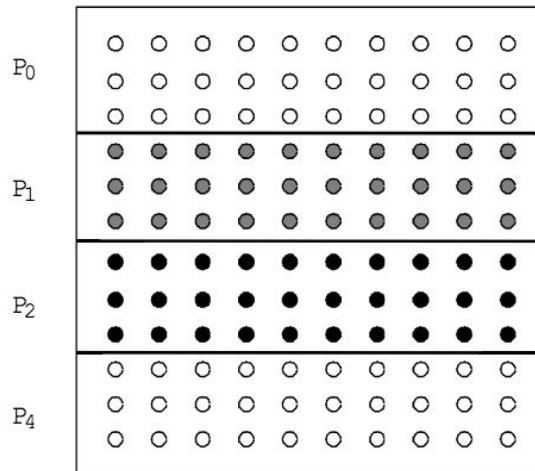
Lab 2, Part 1

- Use MPI communication to send u_1 to neighbors, receive u_1 , update u , repeat



Lab 2, Part 2

- Use row decomposition:



Data partition allocated per processor

Add ghost rows to hold boundary data

Send edges to neighbors

Receive into ghost rows

Compute as in sequential program