

# OBJECT DETECTION AND TRACKING

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## UNDERSTANDING THE PROBLEM

#### What is Object Detection?

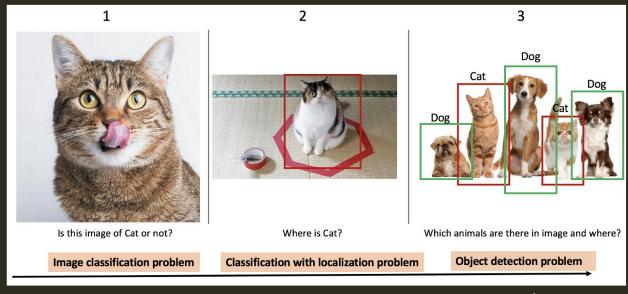
- A computer vision technology that identifies objects in images or videos.

#### Why is it Important?

- Powers applications in security, autonomous vehicles, and retail.

#### **Challenges:**

- High false positives/negatives.
- Poor performance in diverse environments.
- Difficulty tracking objects across video frames.
- Need for real-time results.



## OUR SOLUTION

#### What Are We Offering?

A smart Al-based object detection system with:

- High precision and recall
- Real-time tracking capabilities
- Robust performance in diverse environments

### **Applications:**

- Surveillance: Detect intruders or suspicious activities
- Autonomous Driving: Identify pedestrians, vehicles, and road signs
- Retail: Track inventory and analyze customer behavior

GitHub Repository: Link (Currently Working)



### REAL-TIME OBJECT DETECTION & TRACKING (Inspired By Tesla & Architecture)

#### 1. Learning from Tesla:

- Multi-camera systems for broader coverage.
- Sensor fusion (integrating visual and radar data).
- High-speed, real-time processing for autonomous vehicles.

#### 2. Our Implementation:

- Object tracking with bounding boxes using SORT/DeepSORT.
- Optimizations for real-time applications with hardware acceleration.

### PIPELINE:

Image Input

**Detection Model** 

Post – Processing

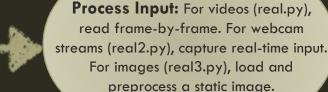
Display results

### TECHNOLOGIES USED

- Pre-trained Model: SSD MobileNet V2 trained on Open Images Dataset V4.
- Processing Framework: TensorFlow Hub for model loading and TensorFlow for inference, with OpenCV handling image and video processing.
- **Post-Processing:** Non-Max Suppression (NMS) for bounding box refinement and confidence thresholding for accurate detections.

### **WORKFLOW:**

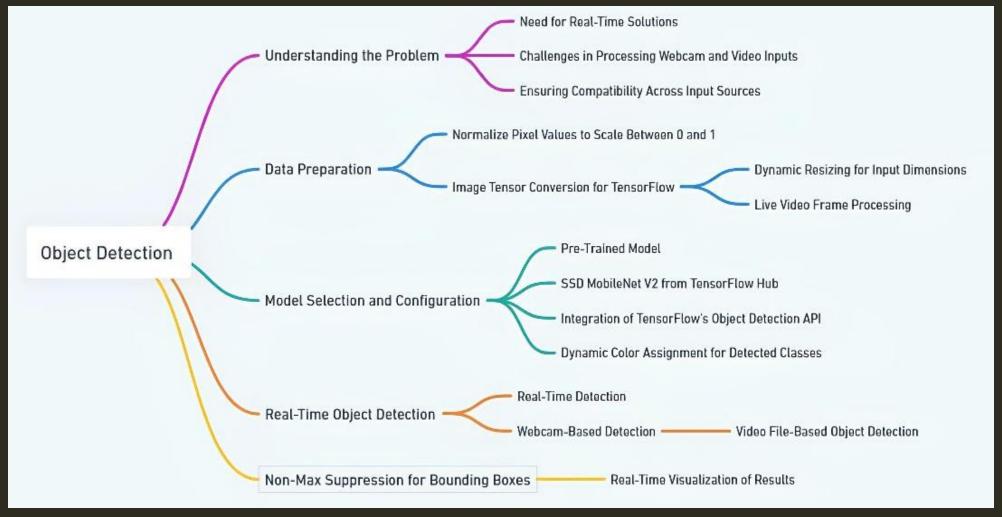
Load Pre-trained Model: Use
TensorFlow Hub to load the SSD
MobileNet V2 model trained on
Open Images Dataset V4 for object
detection.





Detect and Visualize: Perform inference using TensorFlow, apply Non-Max Suppression to refine bounding boxes, and use OpenCV to draw bounding boxes, labels, and confidence scores on the input.

### **COMPLETE ROADMAP**



## THE VALUE OF OUR SOLUTION

#### **Key Benefits:**

- Accurate Detection: High precision and recall
- Real-Time Performance: Practical for real-world use
- Versatile Applications: Security, transportation, retail
- Robustness: Works in difficult conditions

#### **Use Cases:**

- Surveillance: Enhanced monitoring
- Autonomous Vehicles: Safer navigation
- Retail: Efficient inventory tracking

