

DOCUMENTATION FOR  
QUESTION 2:

**PART 1:**  
**Converting CFG to PDA :**

The PDA will have only one state  $\{q\}$ .

The start symbol of CFG will be the start symbol in the PDA.

All non-terminals of the CFG will be the stack symbols of the PDA and all the terminals of the CFG will be the input symbols of the PDA.

*Example :*

Suppose the given CFG is :

$S \rightarrow aSa \mid bSb \mid A \mid bB$

$A \rightarrow a \mid \wedge$

$B \rightarrow b \mid \wedge$

Then its corresponding PDA will be,

$d(q, \wedge, S) \rightarrow (q, aSa)$

$d(q, \wedge, S) \rightarrow (q, bSb)$

$d(q, \wedge, S) \rightarrow (q, A)$

$d(q, \wedge, S) \rightarrow (q, bB)$

$d(q, \wedge, A) \rightarrow (q, a)$

$d(q, \wedge, A) \rightarrow (q, \wedge)$

$d(q, \wedge, B) \rightarrow (q, b)$

$d(q, \wedge, B) \rightarrow (q, \wedge)$

$d(q, a, a) \rightarrow \wedge$

$d(q, b, b) \rightarrow \wedge$

*Solution approach:*

The contents of the file are stored in 'rules' & for all the productions of each non-terminal, the corresponding delta function is displayed.

In the end, for all the terminals, popping operation is done.

**PART 2:**  
**Converting PDA TO CFG:**

*Example:*

Transition Table for the PDA :

Move number	State	Input	Stack Symbol	Move(s)
1	$q_0$	a	Z	$(q_0, AZ)$

2	q0	b	Z	(q0,BZ)
3	q0	a	A	(q0,AA)
4	q0	b	A	(q0,BA)
5	q0	a	B	(q0,AB)
6	q0	b	B	(q0,BB)
7	q0	c	Z	(q1,Z)
8	q0	c	A	(q1,A)
9	q0	c	B	(q1,B)
10	q1	a	A	(q1,^)
11	q1	b	B	(q1,^)
12	q1	^	Z	(q1,^)

The CFG would be

$S \rightarrow [q_0, Z, x_i]$

$[q_0, Z, x_0] \rightarrow a [q_0, A, x_1] [x_1, Z, x_0]$

$[q_0, Z, x_0] \rightarrow b [q_0, B, x_1] [x_1, Z, x_0]$

$[q_0, A, x_0] \rightarrow a [q_0, A, x_1] [x_1, A, x_0]$

$[q_0, A, x_0] \rightarrow b [q_0, B, x_1] [x_1, A, x_0]$

$[q_0, B, x_0] \rightarrow a [q_0, A, x_1] [x_1, B, x_0]$

$[q_0, B, x_0] \rightarrow b [q_0, B, x_1] [x_1, B, x_0]$

$[q_0, Z, x_0] \rightarrow c [q_1, Z, x_0]$

$[q_0, A, x_0] \rightarrow c [q_1, A, x_0]$

$[q_0, B, x_0] \rightarrow c [q_1, B, x_0]$

$[q_1, A, q_1] \rightarrow a$

$[q_1, B, q_1] \rightarrow b$

$[q_1, Z, q_1] \rightarrow ^$

The total no. of productions for the above CFG are 35 allowing all combinations of  $x_i$ .

They are computed as follows :

Productions for start symbol = no. of states in the PDA

$$= 2$$

Productions for moves with two terms =  $6 \cdot (2^2)$

Productions for moves with one term =  $3 \cdot (2^1)$

Productions for moves with one term which is  $^ = 3 \cdot 1$

Adding all we get, total\_num\_productions =  $2 + 24 + 6 + 3$

$$= 35$$

Note : Here  $x_i$  indicates the total no. of states in the PDA. In the above eg. there only 2 states  $q_0$  &  $q_1$ . So,  $x_0$  can be  $q_0$  &  $x_1$  can be  $q_1$ . And then we consider all of their combinations.

Let  $P$  be productions in grammar  $G = (V, \Sigma, S, P)$

The set  $P$  contains the following productions & only these:

1. For every  $q \in Q$ , the productions  $S \rightarrow [q_0, Z, q]$  is in  $P$ .
2. For every  $q, q_1 \in Q$ , if  $d(q, a, A)$  contains  $(q_1, ^\wedge)$ , then the production  $[q, A, q_1] \rightarrow a$  is in  $P$ .
3. For every  $q, q_1 \in Q$ , if  $d(q, a, A)$  contains  $(q_1, B_1, B_2, B_3, \dots, B_m)$ , then for every choice of  $q_2, \dots, q_{m+1} \in Q$ , the production  
 $[q, A, q_{m+1}] \rightarrow a[q_1, B_1, q_2][q_2, B_2, q_3] \dots [q_m, B_m, q_{m+1}]$   
 is in  $P$ .

*Solution approach:*

The data (pda transition table) is stored from the file in pda 2D vector.

Then for every move, the template is displayed & productions are computed allowing all combinations of the  $x_i$ .