Gausian Elimination vislant pirating (1) Compute Ly factorization of matrix AER^x 2) Use the factorization to Solve System of linear equations Ax=6 1) Reduce A to upper transplan form using n-1 Gauss transforms Li 47 L; annihilates all elements on i-th column of A under element a: ⇒ We have Ln-1 Ln-2 ... L2L, A= U > A= Li Lz ... Ln-z Ln-1 where L=L; L2 ... Ln-2 Ln-1 => A = LV poto calculate individual inverses Compute L by toggling the signs and combining the elements under the diagonal matrix multiplication 2) Now that we have Lond U, solve Ax=6 by: Ax=b (=> LUx=b i) solve []=b for d (forward substitution) ii) solve Ux=3 for x (backward substitution) motivation: much easier to solve due to the tringular forms of Land V.

More efficient to solve

Ax=b,

Ax=b,

Ax=b,

Since we can reuse the LU factorization as opposed to computing

 $X = A^{-1}b_1$   $X = A^{-1}b_2$   $X = A^{-1}b_3$ 

General Algo (given A and b) to compute Li:

for (=1,..., N-1

1. Compute Li

is I dentity matrix and elements under  $l_{ii}$  are  $-\frac{\alpha_{ij}}{\alpha_{ij}}$  for j > i

2. A - L; A

Loonly akij krijsi need to be calculated and aij jri become o

Lowe this new matrix for the next iteration

exi solve 
$$Ax = b$$
 $A = \begin{bmatrix} 2 & 2 & 2 \\ 2 & 2 & 2 \\ -2 & 2 & 2 \end{bmatrix}$ 
 $b = \begin{bmatrix} 8 \\ 7 \\ 0 & 3 & 2 \end{bmatrix}$ 
 $L_1 = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 0 & 1 \end{bmatrix}$ 
 $L_2 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 1 \end{bmatrix}$ 
 $L_2 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 1 \end{bmatrix}$ 
 $L_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 1 \end{bmatrix}$ 

We have  $L_2 L_1 A = U \Leftrightarrow A = \begin{bmatrix} 2 & -1 & 1 \\ 0 & 3 & 1 \\ 0 & 0 & 1 \end{bmatrix}$ 

We have  $A_1 = A_2 = A_3 = A_4 = A_4 = A_5 = A_5 = A_7 =$