

1. Population and Sample

Population: The whole set of individuals about which we attempt to draw conclusions.

Sample: A part of the population which is observed. Sample space (所有可能)

Relationship: Probability: Reasoning from Population → Sample. 能结果

Inferential Statistics: Reasoning from Sample → Population. 不是 Population 推

2. Probability Basics & Counting

Definitions

Experiment: Any action that generates observations.

Sample Space (S): Set of all possible outcomes.

Event: A subset of outcomes in S.

Probability: P(A) = (# of outcomes in A) / (Total # of outcomes in S)

Counting Techniques

Product Rule: Experiment 1 (m outcomes) followed by Experiment 2 (n outcomes)

Permutation (Ordered): Number of ways to arrange k objects from n distinct objects.

Formula: P = n! / (n-k)!

Combination (Unordered): Number of ways to select k objects from n distinct objects.

Formula: C = n! / (k!(n-k)!)

Complement: P(A') = 1 - P(A).

Mutually Exclusive: If A ∩ B = ∅, then P(A ∩ B) = 0.

Addition Rule: P(A ∪ B) = P(A) + P(B) - P(A ∩ B)

Three Events:

P(A ∪ B ∪ C) = P(A) + P(B) + P(C) - [P(AB) + P(AC) + P(BC)] + P(ABC)

Conditional Probability & Bayes

Conditional Probability: P(A|B) = P(A ∩ B) / P(B)

Multiplication Rule: P(A ∩ B) = P(A|B)P(B)

Independence: A and B are independent if P(A ∩ B) = P(A)P(B) or P(A|B) = P(A).

Bayes Theorem:

Random variable is any characteristic whose value change from one individual to another.

Mean: Variability: Variance, Standard deviation.

Graphical: Histogram (Density/Frequency), Pie chart.

Boxplot: Visualizes Median, 1st/3rd Quartiles, and Outliers.

6. Random Variables (R.V.)

PMF: P(X) = P(X ∈ S, X ∈ X)

Expectation: E(X) = Σ xP(x)

Common Distributions:

Binomial: C(n, k) p^k (1-p)^(n-k)

Poisson: P(X) = e^-λ λ^x / x!

6.2 Continuous R.V.

PDF f(x): Probability is area under curve. P(X = x) = 0.

CDF: F(x) = ∫\_(-∞)^x f(t) dt.

5.1 Regression (MSE) mean square error.

Measure: MSE(f) = E(Y - f(X))^2.

Optimal Solution: The Conditional Expectation f\*(X) = E(Y|X) minimizes MSE.

5.2 Classification (MSE)

Measure: Misclassification Error E(I(Y ≠ f(X)))

Optimal Solution: Bayes Rule f\*(X) = argmax\_y P(y = k|X)

5.3 Training vs Test

Training error underestimates true error.

We need Test error (from independent data).

6. Bias-Variance Decomposition

Test MSE decomposition: Bias^2(f) + Var(f) + R^2(f)

Bias: Error from simplifying assumptions (High in simple models).

Variance: Sensitivity to training set fluctuations (High in complex models).

Trade-off: Complexity ↑ → Bias ↓, Variance ↑.

7. Cross Validation (CV) & Estimation

Alternative to Test Set

Adjustment: Adjust training error using AIC, BIC, Covariance penalty.

Resampling Methods:

Validation Set

Split data randomly into training and validation parts.

Cons: High variance in result, overestimates error (less training data).

Adv: Simple idea, easy to implement, intuitive.

Leave-One-Out CV (LOOCV) MSE = averaged MSE

Train on n-1, Test on 1. Repeat n times.

Cons: Low Bias.

Cons: Computational cost.

K-Fold CV

Split into K folds.

CV = Average of E\_k.

Comparison

Bias: LOOCV < K-Fold.

Variance: LOOCV > K-Fold.

Choice: K = 5 or 10 provides the best compromise.

Expectation: E(X) = ∫\_(-∞)^∞ xf(x) dx.

Common Distributions:

Uniform: f(x) = 1/(b-a) for x ∈ [a, b]

Exponential: f(x) = λe^-λx for x > 0.

Normal: X ~ N(μ, σ^2). f(x) = 1/√(2πσ^2) \* exp(-(x-μ)^2/(2σ^2))

7. Joint Distribution

Joint PDF: P((X,Y) ∈ A) = ∫\_A f(x,y) dx dy

Independence: f(x,y) = f\_x(x)f\_y(y)

Correlation: Corr(X,Y) = Cov(X,Y) / (σ\_X σ\_Y)

Random Sample: X\_1, ..., X\_n are i.i.d. (independent and identically distributed).

Sampling Distribution of Mean: If X\_i ~ N(μ, σ^2), then X-bar ~ N(μ, σ^2/n)

Central Limit Theorem (CLT): For large n, regardless of population distribution:

Linear Combination: If X\_i are independent Normals, Σ a\_i X\_i is Normal.

Maximum Likelihood (MLE): Find θ that maximizes likelihood L(θ) = f(x\_1, ..., x\_n; θ)

10. Confidence Interval (CI)

Definition: A random interval that contains the true parameter with prob 1-α.

Interpretation: In repeated sampling, 100(1-α)% of intervals cover μ.

Formulas (for Mean):

Known σ: X-bar ± z\_{α/2} (σ/√n)

Unknown σ: X-bar ± t\_{α/2, n-1} (s/√n)

General Approx CI: X-bar ± z\_{α/2} (σ/√n)

A hypothesis test is a claim about a characteristic of a probability distribution (population parameter).

A hypothesis test uses sample data to choose between two competing claims.

Null hypothesis: H\_0 assumed true initially. Alternative hypothesis: H\_a: competing claim contradicting H\_0.

A test procedure is a data-based rule for deciding whether to reject H\_0 defined via a test statistic.

(a function of the sample) and a rejection region (values for which H\_0 is rejected).

Type I error: reject H\_0 when H\_0 is true. probability = α (significance level).

Type II error: fail to reject H\_0 when H\_a is true. probability = β.

Power: 1 - β. Typically, increasing n increases power.

Goal: minimize subject to pre-specified α. P-value: Probability of observing data as extreme as actual, assuming H\_0 is true.

4. What Is Data? Collection of data objects and their attributes.

Object: record, point, sample, entity, instance.

Attribute: property/characteristic (e.g., age, height). Also called variable, field, feature.

2. Types of Variables

Continuous: length, time, weight.

Nominal (Categorical): race, sex, eye color.

Ordinal: age group, grade, satisfaction rating (ordered).

Interval: temperature, salary range.

3. Types of Data

Data Matrix Points in multi-dimensional space.

Text Data: Document = vector of terms. Element = term frequency (counts).

Transaction Data: Each record = a set of items (e.g., Market basket).

Graph Data: Social networks, molecular structures.

4. Data Quality

Issues affecting subsequent analysis

Noise: Perturbation of values.

Outliers: Observations considerably different from others.

Missing Values

Reasons: Not collected or not applicable.

Handling: Eliminate, impute, or incorporate partial info.

Sampling Bias: Sample ≠ Population.

Causes: Convenience sampling, Class imbalance.

5. Data Exploration (EDA)

Goal: Preliminary understanding. Select right tools.

Techniques

Summary Statistics

Visualization

(Clustering/Anomaly detection are also exploratory).

6. Summary Statistics

Frequency/Mode

Location: Mean, Median, Trimmed mean, Percentile.

Spread: Range, Variance, Standard deviation.

Skewness

7. Visualization Techniques

Histogram: Distribution of a variable. (2D Histogram for joint distribution).

Boxplot: Median, quartiles, outliers. Good for comparing distributions.

Scatter Plot: Relationship between 2 variables.

Matrix Plot: Visualizes data/similarity matrix using colors. Variables often normalized.

Parallel Coordinates

Parallel axes for variables.

Object = Line connecting axes.

Variable ordering matters.

Star Plots: Axes radiate from center. Object = Polygon.

Chernoff Faces: Variables mapped to facial features. Object = Face.

1. Terminology

Statistics ↔ Machine Learning

Classification/Regression ↔ Supervised Learning

Clustering ↔ Unsupervised Learning

Covariates ↔ Features

Sample ↔ Training set

Statistical Model ↔ Learner

Model classification/Prediction error → Generalization error

Models & Assumptions

Assumption 19: Y = f(X) + ε, where E(ε) = 0 and is independent of X.

Model Types 20

Parametric (Strong assumption on f): Linear/Polynomial regression, GLM, Fisher's discriminant, Logistic regression, Deep learning.

Nonparametric (Flexible form): Local smoothing, Smoothing splines, Trees/Random Forest/Boosting, SVM.

3. Prediction vs Inference

Prediction: Minimize E((Ŷ - Y)^2) = Reducible Error + Irreducible Error Var(ε).

Inference: Understand relationship between X and Y.

Trade-off: Linear models (High Inference, Low Prediction accuracy) vs Non-linear models (Low Inference, High Prediction).

4. Classification Models Detail

Task: Estimate P(Y = k | X)

Model 1: Linear Regression

Method: Fit Y(0 or 1) using LSE β = (X^T X)^-1 X^T Y

Decision: φ(X) = I(X^T β > 0.5)

(Added) Trivial classifier example: I(feature > C\_j23)

Model 2: K-Nearest Neighbors (KNN)

Method: ŷ(X) = Σ\_{i=1}^K y\_i / K

Decision: Majority vote.

Effective Parameters: n, k

k = 1: 0 training error (Overfitting), rough boundary.

Large k: Smoother boundary.

5. Model Assessment

1. Sparse Regression & Motivation Basic Setup 1

Given training set (x\_i, y\_i), assume the linear model:

Sparsity: It is assumed that p\_0 < p, where p is the dimension of independent predictors.

Goal: Correctly detect the set of informative predictors A' from the total set of variables.

Why Do We Care? 2. Sparse Regression

Multicollinearity: Can mask significance and inflate variance.

Prediction Accuracy: When p is large, accuracy deteriorates due to overfitting ("curse of dimensionality").

Interpretability: Models are unnecessarily complicated if irrelevant variables are included.

Popular Techniques

Sequential selection (Forward/Backward):

Shrinkage methods (Lasso, Ridge):

Dimension reduction (PCA):

2. Subset Selection Algorithms

Let M\_0 be the null model (no predictors).

For k = 1, 2, ..., p:

Fit all p models with exactly k predictors.

Pick the best one (smallest RSS or largest R^2), call it M\_k.

Select the single best model from M\_0, ..., M\_p using cross-validation, C\_p, AIC, or BIC.

Note: Computationally expensive for large p.

2.2 Model Selection Criteria 5

Used to select the final model size (d predictors).

Mallov's Cp:

AIC (Akaike Information Criterion):

BIC (Bayesian Information Criterion):

Note: BIC penalizes complexity more heavily than AIC.

2.3 Sequential Variable Selection 6

Forward Stepwise Selection:

Start with null model M\_0.

For k = 0, ..., p-1: Consider all p-k models that add one predictor to M\_k.

Select best model among M\_{k+1}, ..., M\_p using criteria (AIC/BIC).

Backward Selection: Starts with full model M\_p and iteratively deletes predictors.

Stagewise Selection: Mixes forward addition and backward deletion in each step.

Remarks: Computationally more efficient than Best Subset selection.

Greedy Algorithm: No guarantee of finding the globally best model, but performs well in practice.

3. Shrinkage Methods (Regularization) RSS = Σ (y\_i - ŷ\_i)^2

Generalization 8 (β\_0, β) = argmin Σ (y\_i - β\_0 - x\_i^T β)^2 + λ J(β)

A: Tuning parameter controlling the trade-off between fitting and shrinkage.

Through this optimization problem, SVM seeks the best hyperplane that classifies the data with maximum margin while allowing some margin violations through the slack variables.

调参 (C): C controls the trade-off between maximizing the margin and minimizing the misclassification error.

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### 3.1 Ridge Regression 9

Penalty:  $L_2$ -norm penalty ( $J(\beta) = ||\beta||_2^2 = \sum \beta_i^2$ )  
Objective:  $\beta^{ridge} = \argmin(y - X\beta)^T(y - X\beta) + \lambda ||\beta||_2^2$   
 $\rightarrow \argmin(y - X\beta)^T(y - X\beta) + \lambda ||\beta||_2^2$

Solution (Closed-form exists):  
 $\beta^{ridge} = (X^T X + \lambda I)^{-1} X^T y$

Properties:  $||\beta||_2^2$  is a shrinkage penalty shrinks estimates of  $\beta \rightarrow 0$   
Shrinks coefficients towards zero but not exactly to zero (does not perform variable selection)

If  $\lambda = 0$ , result is OLS (Least Squares). If  $\lambda \rightarrow \infty$ ,  $\beta \rightarrow 0$ .  
Bias-Variance Trade-off: Ridge is a biased estimator but may have smaller MSE than OLS by reducing variance

### 3.2 Lasso (Least Absolute Shrinkage and Selection Operator) 11

Penalty:  $L_1$ -norm penalty ( $J(\beta) = ||\beta||_1 = \sum |\beta_i|$ )  
Objective:  $\beta^{lasso} = \argmin(y - X\beta)^T(y - X\beta) + \lambda ||\beta||_1$

Solution: No explicit closed-form solution (requires Quadratic Programming).

Key Property: 变量选择 会自动把不重要的变量系数变为0

Sparse Solution: Some coefficients become exactly zero. Lasso performs continuous variable selection

Geometry: The constraint region ( $\sum |\beta_i| \leq s$ ) is diamond/polygone. The contours of RSS (when coefficients are zero) 13.

### 3.3 Comparison: Ridge vs. Lasso 14

Both introduce bias to reduce variance. 稳定性

Lasso produces simpler, interpretable models (subset of predictors).

Ridge keeps all variables. (更加稳定)

Prediction accuracy depends on the true underlying model.

### 3.4 Special Simple Case (n = p, X = I) 15

If the design matrix is orthogonal ( $X = I_p$ ):

OLS Estimate:  $\beta^{ols} = y$

Ridge Estimate: Scaling,  $\beta^{ridge} = y/(1 + \lambda)$

Lasso Estimate: Soft-thresholding / Truncation,  $\beta^{lasso} = \text{sign}(y) (|y| - \lambda/2)^+$

### 4. Extensions of Shrinkage Methods

#### 4.1 Ridge Estimators 16

General penalty  $L_\alpha(\beta) = \sum |\beta_j|^\alpha$

Cases:  $\alpha = 0$ : Hard thresholding (subset selection).  
 $\alpha = 1$ : Lasso.  
 $\alpha = 2$ : Ridge.  
 $\alpha = \infty$ : Maximum absolute value.  $L_\infty(\beta) = \max |\beta_j|$

#### 4.2 Nonnegative Garrote 17

$L_1 + L_2$  norm. Starts with OLS estimates and shrinks them.

Formula:  $\min_{\beta} ||y - X\beta||_2^2 + \lambda_1 ||\beta||_1 + \lambda_2 ||\beta||_2^2$

Property: Almost unbiased for large coefficients, shrinks small ones to zero.

#### 4.3 Other Variants 18

Group Lasso: If variables are partitioned into groups, it includes/excludes whole groups (uses  $L_2$  norm of the group vector).

Elastic Net: Combination of  $L_1$  and  $L_2$  penalties.

### 1. Polynomial Regression (非线性回归)

Concept: Extends linear regression by replacing the linear function with a polynomial. It is a special case of multiple linear regression.

Formula:  $y_i = \beta_0 + \beta_1 x_i + \beta_2 x_i^2 + \dots + \beta_d x_i^d + \epsilon_i$

Practice: Degree  $d$  usually 2, 3, or 4.

Centered predictors ( $\bar{x}_i = x_i - \bar{x}$ ) used to reduce correlation between terms.

### Polynomial Logistic Regression

Used for binary responses.

Formula:  $\logit(\Pr(y_i > c | x_i)) = \beta_0 + \beta_1 x_i + \dots + \beta_d x_i^d$

### 2. Step Functions 19

Idea: 局部逼近非线性结构 连续  $\rightarrow$  二元

Approximates nonlinear structure locally by converting a continuous variable into an ordered binary variable.

Uses  $K$  thresholds,  $c_1, \dots, c_K$  to define intervals.

### Model Breaks Points

Construct  $K + 1$  indicator variables:

$G_0(X) = I(X < c_1)$   
 $G_1(X) = I(c_1 \leq X < c_2)$   
 $\dots$   
 $G_K(X) = I(X \geq c_K)$

Formula:  $y_i = \beta_0 + \beta_1 G_1(x_i) + \dots + \beta_K G_K(x_i) + \epsilon_i$

This results in a piecewise constant function.

### 3. Interaction Regression Model 交互效应

Used when the effect of one predictor depends on the value of another predictor.

Formula:  $y_i = \beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \beta_3 x_{i1} x_{i2} + \epsilon_i$

The mean response per unit change in each variable now depends on other variables.

Piecewise Polynomials & Splines 4.1 Basics  $y_i = \beta_0 + \beta_1 x_i + \dots + \beta_d x_i^d + \epsilon_i$

Piecewise Polynomials: Fit separate low-degree polynomials over different regions defined by knots.

Issue: Discontinuous (jumps) at knots if unconstrained.

### 4.2 Constraints 22 平滑

1. To fix discontinuity, require the fitted curve to be continuous.

2. Furthermore, require continuous 1st and 2nd derivatives are continuous.

### 4.3 Cubic Spline 三次样条

Definition: Continuous piecewise polynomials with continuous 1st and 2nd order derivatives.

Basis Functions: Uses Truncated Power Basis  $B(x; \xi)$ .

### Fused Lasso: Penalizes differences between adjacent coefficients

Formula:  $\min_{\beta} ||y - X\beta||_2^2 + \lambda ||\beta||_1 + \gamma ||\beta - \beta_{adj}||_1$

### 5. Dimension Reduction Methods

#### 5.1 Principal Component Analysis (PCA)

Definition 19:

Find linear combinations  $U_j = a_j^T X$  (Principal Components) such that:

Variance is maximized:  $\text{Var}(U_j)$  is as large as possible.

Uncorrelated:  $\text{Cov}(U_j, U_k) = 0$ .

Normalized:  $||a_j|| = 1$ .

Calculation 20: 特征值分解

Based on Eigen-decomposition of the covariance matrix  $\Sigma$ .

Eigenvalues:  $\lambda_1 \geq \lambda_2 \geq \dots \geq 0$ .

PC loadings:  $a_j$  are the eigenvectors  $e_j$ .

Variance of  $j$ -th PC is  $\lambda_j$ .

#### Dimension Reduction:

Choose  $k \ll p$  such that the first  $k$  components explain a large proportion of the total variance.

#### 5.2 Projection Pursuit (PP) 22

Motivation: PCA finds max variance (often Gaussian) directions that are non-normal.

Indices: Measures of non-normality (e.g., using cumulants  $k_3, k_4$ ).

#### 5.3 Principal Component Regression (PCR) 23

Algorithm 23:  $\hat{y} = \hat{\beta}^T X$

Compute Principal Components  $Z_1, \dots, Z_m$  from  $X$ .

Regress response  $y$  on these derived components  $Z_j$ .

Since  $X$  is orthogonal, this is a sum of univariate regressions.

#### Remarks 24:

Unsupervised: PCA is performed on  $X$  without knowing  $y$ .

No Variable Selection: Each PC is a linear combination of all original predictors.

Standardization: Recommended to standardize predictors first.

Works well when the first few PCs capture the variation relevant to  $y$ .

#### 5.4 Partial Least Squares (PLS) 25

PLS is Supervised. It uses both  $X$  and  $Y$  to construct the directions.

#### Algorithm Concept 26:

Calculate univariate regression coefficient of  $y$  on each  $x_j$ .

Use these coefficients to weight inputs and construct the first direction  $Z$ .

Regress  $y$  on  $Z$ .

Orthogonalize  $X$  w.r.t  $Z$  (remove effect of  $Z$ ) and repeat to find subsequent directions.

#### Properties 27:

If  $J$  is  $p$  directions are used, it equals the OLS solution.

Uses  $J < p$  for dimension reduction.

The inputs are weighted by the strength of their univariate effect on  $y$ .

Where  $(x - \bar{x}_k)^3$  is  $(x - \bar{x}_k)^3$  if  $x > \bar{x}_k$ , else 0.

#### 4.4 Natural Cubic Spline = max $(x - \bar{x}_k, 0)$

Motivation: Regular splines have high variance at the boundaries.

Definition: A spline *require the model to be linear at boundary*.

Benefit: More stable estimates at boundaries.

#### 4.5 Determining Knots 28

Uniform fashion: At percentiles of the predictor (e.g., 25th, 50th, 75th).

Number: Determines complexity (Degrees of Freedom). Chosen via Cross Validation.

#### 5. Smoothing Spline

Objective Function

Find  $\hat{g}$  that minimizes:

$\int_0^1 (y - g(x))^2 dx + \lambda \int_0^1 (g'(x))^2 dx$

Loss: Fits the data.

Properties: Linear in the region outside.

The minimizer  $\hat{g}(x)$  is a Natural Cubic Spline.

Knots: Every unique observation  $x_i$  is a knot.

It is a shrunken version of the natural cubic spline.

#### Tuning Parameter $\lambda$

Controls bias-variance trade-off.

$\lambda = 0$ : Interpolates data (high variance).

$\lambda \rightarrow \infty$ : Simple linear regression.

Optimal: Determined by Cross Validation.

#### 6. Local Linear Regression

Algorithm

Goal: Fit at a specific point  $x_0$ .

Selection: Find the  $s$ -nearest training points.

Weighting: Assign weights  $K_{ij} = K((x_i - x_0)/h)$  (Decreases with distance; 0 if not in neighbor set).

Fit: Minimize Weighted Least Squares:  $\min_{\beta} \sum_{i=1}^s K_{ij} (y_i - \beta_0 - \beta_1(x_i - x_0))^2$

Predict:  $\hat{f}(x_0) = \beta_0 + \beta_1 x_0$ .

Span  $s$ : Controls flexibility of the non-linear fit.

Small  $s$ : Local, wiggly fit.

Large  $s$ : Global fit (approaches linear regression).

$s$  can be fixed by cross validation.

$f_j$  can be estimated by any non-linear model.

Pros & Cons:  $f_j$  is additive in nature. Can examine effect of each individual.

Pros: Automatically model non-linearities. Interpretable (examining effect of  $X_j$  holding others fixed).

Cons: Misses interactions between variables (unless explicitly added (e.g.,  $f_{jk}(X_j, X_k)$ )).

### 1. 分类问题概述 (Classification Overview) 基本定义 1

设定: 输入  $X \in R^p$ , 输出  $Y \in \{1, \dots, K\}$  (定性变量/类别).

分类器: 函数  $G: R^p \rightarrow \{1, \dots, K\}$ .

目标: 最小化误分率 (Misclassification Error).

定义 1: 分类函数  $h_k(x)$  (针对第  $k$  类).

决策规则: 选择得分最高的类.

分类边界:  $\{x: h_k(x) = h_l(x)\}$  得分相等.

二元分类特例 (Binary Case):  $K = 2$ , 类别编码为  $\{0, 1\}$  或  $\{-1, 1\}$ .

决策:  $G(x) = I(h(x) > 0.5)$  或  $G(x) = \text{sign}(h(x))$ .

边界:  $\{x: h(x) = 0.5\}$  或  $\{x: h(x) = 0\}$ .

3. 线性回归用于分类 (Linear Regression for Classification)

分类: 将类别编码为  $\{0, 1\}$ . 拟合线性回归  $Y = X^T \beta$ .

多分类问题: 常用的做法 (使用 2, 2, 2) 强化了类别的顺序和距离. 这是不合理的.

解决方法: 使用虚拟变量 (Dummy Variables) 编码  $0, 1$ .

创建  $K$  个指示变量 (Indicator Response Matrix).

对每一列拟合线性回归  $h_k(x)$ .

局限性: 预测值可能  $< 0$  或  $> 1$  (Missing problem) 无法区分 (many-way problem).

4. 贝叶斯规则 (Bayes Rule) 1.2 贝叶斯规则: 最小化误分率的分类器.

公式: 选择后验概率最大的类.

两种策略: 估计  $p_k(X)$  (如 LDA, QDA, Logistic Regression).

直接估计边界  $G(X)$  (如 SVM, Boosting, AdaBoost).

贝叶斯定理 9:  $P(Y = k | X) = \frac{p_k(X) P(Y = k)}{\sum_{l=1}^K p_l(X) P(Y = l)}$

$f_k(X)$ : 第  $k$  类的 (Class-conditional density). 比较  $p_k(X)$  等价于比较  $\pi_k f_k(X)$ .

5.1 线性判别分析 (LDA) (Discriminant Analysis)

假设:  $X \sim N(\mu_k, \Sigma_k)$  (各类协方差矩阵相同).

判别函数:  $\log \pi_k f_k(X) = \log \left( \frac{1}{(2\pi)^{p/2} |\Sigma_k|} \exp \left( -\frac{1}{2} (X - \mu_k)^T \Sigma_k^{-1} (X - \mu_k) \right) \right)$

这是一个关于  $X$  的线性函数.

决策: 分类到  $\delta_k(X)$  最大的类.

参数估计:  $\hat{\mu}_k = \bar{x}_k$ ,  $\hat{\Sigma}_k = \frac{1}{n_k} \sum_{i \in S_k} (x_i - \bar{x}_k)(x_i - \bar{x}_k)^T$

$\delta_k(X)$  类均值 (Centroid).

假设:  $X | Y = k \sim N(\mu_k, \Sigma_k)$  (各类协方差矩阵不同). 判别函数:

$\delta_k(X) = \log(\pi_k) - \frac{1}{2} \log |\Sigma_k| - \frac{1}{2} (X - \mu_k)^T \Sigma_k^{-1} (X - \mu_k)$

包含  $X$  的二次项. 特点: 决策边界是二次曲线.

5.3 朴素贝叶斯 (Naive Bayes) 与独立性

假设: 特征变量  $X_1, \dots, X_p$  相互独立.

优点: 简化了估计任务 (只需估计变量密度).

Variance Trade-off: (在高维数据下通常表现不错).

逻辑回归 (Logistic Regression) 6.1 逻辑回归

模型: 使用逻辑函数 (Logistic/Sigmoid function) 建模  $P(Y = 1 | X)$ .

Logit (对数几率):  $\logit(p) = \log \left( \frac{p}{1-p} \right) = \beta_0 + \beta^T X$

解释:  $\beta$  表示  $X$  每增加 1 个单位, 对数几率 (Log-odds) 增加  $\beta_j$  (几率乘以  $e^{\beta_j}$ ).

参数估计 (MLE) 14 极大似然估计: 最大化对数似然函数  $l(\beta)$ .

求解算法: IRLS (迭代加权最小二乘法), 即 Newton-Raphson 方法 15.

### 1. Tree-based Methods Basics

Core Concepts

Prediction: Use mean or mode of training observations in that region.

Properties: Region-wise constant, completely nonparametric.

2. Notations & Structure

$X$ : Input vector.  $y$ : Output vector.

Nodes: Root/Terminal/Leaf. Parent/Child. Internal/Leaf nodes.

Split:  $s$ : A partition of the parent node into two child nodes.

3. Key Elements of Tree Construction

Stopping Criteria: Binary splits.

Stopping Rule: When to stop splitting.

3.1 Standard Set of Questions

Depends on only one variable.

Continuous: Is  $x_j \leq c$ ?  $c \in (-\infty, \infty)$ .

Categorical: Is  $x_j$  in a subset of categories?

4. Goodness of Split & Impurity

Impurity Functions  $G(t)$ : Let  $p_k$  be proportion of class  $k$  in node  $t$ .

Misclassification Error:  $1 - \max_k p_k$ .

Gini Index:  $1 - \sum_k p_k^2$ .

Cross Entropy:  $-\sum_k p_k \log(p_k)$ .

Criterion: Maximize impurity reduction.

$\phi(s, t) = G(t) - p_k G(t_k) - (1 - p_k) G(t_k)$

### 迭代更新:

6.2 多元逻辑回归 16

选取一个基准类 (如第  $K$  类), 建立  $K-1$  个 Logit 模型.

Logit 模型:  $\log(p_k(X)/p_K(X)) = X^T \beta_k$

### 6.3 Probit 模型 17

使用标准正态分布的 CDF  $\Phi$  代替逻辑函数.

$p(X) = \Phi(\beta_0 + \beta^T X)$

### 6.4 Logistic Regression vs LDA 18

两者都有线性的 Logit 形式.

区别: 拟合过程不同.

Logistic: 最大化条件似然 (MLE).

LDA: 基于正态分布假设估计均值和方差 (最大化联合似然).

### 7. 分离超平面 (Separating Hyperplane) 19

思想: 在特征空间中寻找一个超平面, 将不同类别的点完全分开.

几何表示: 超平面方程  $f(x) = \beta_0 + \beta^T x = 0$ .

法向量:  $\beta = \beta_0 / ||\beta||$ .

到平面的距离:  $(\beta^T x + \beta_0) / ||\beta||$ .

优化问题:  $\max_{\beta} \min_{x \in S} \beta^T x$

subject to:  $\beta^T x \geq 1, \forall x \in S$

等价形式 (标准形式) 22:

subject to:  $\beta^T x \geq 1, \forall x \in S$

使用 Lagrange 乘子法, 转换为二次规划 (Quadratic Programming, QP) 问题求解.

### 9. 分类模型评估 (Evaluation) 24

基础指标: 误分率 (Test Error).

Advanced metrics: 混淆矩阵 (Confusion Matrix): TN, FP, FN, TP.