

1 Field Theory

1.1 Definition

First, let us define scalar field φ as $\varphi = \varphi(\mathbf{r}, t) = \varphi(x, y, z, t)$ and vector field \mathbf{a} as $\mathbf{a} = \mathbf{a}(\mathbf{r}, t) = \mathbf{a}(x, y, z, t)$.

Then grad φ of scalar φ would be

$$\text{grad } \varphi = \frac{\partial \varphi}{\partial x} \mathbf{i} + \frac{\partial \varphi}{\partial y} \mathbf{j} + \frac{\partial \varphi}{\partial z} \mathbf{k} \quad (1.1.1)$$

Given a vector field \mathbf{a} , choose any point in the field and wrap it in volume V . We define divergence of the field as:

$$\text{div } \mathbf{a} = \lim_{V \rightarrow 0} \frac{\oint_S \mathbf{a} \cdot d\mathbf{S}}{V} \quad (1.1.2)$$

By Остроградский-Gauss formula, We can deduce:

$$\text{div } \mathbf{a} = \frac{\partial a_x}{\partial x} + \frac{\partial a_y}{\partial y} + \frac{\partial a_z}{\partial z} \quad (1.1.3)$$

We define projection along a direction \mathbf{n} of curl of the vector field as:

$$\text{rot}_n \mathbf{a} = \lim_{S \rightarrow 0} \frac{\oint_L \mathbf{a} \cdot d\mathbf{r}}{S} \quad (1.1.4)$$

where we choose any point in the field and choose an infinitely small closed curve L on the curved surface S and direction of normal line of the curved surface is as same as \mathbf{n} .

By Stoke formula, we can deduce:

$$\text{rot } \mathbf{a} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ a_x & a_y & a_z \end{vmatrix} \quad (1.1.5)$$

We define Hamiltonian as:

$$\nabla = \mathbf{i} \frac{\partial}{\partial x} + \mathbf{j} \frac{\partial}{\partial y} + \mathbf{k} \frac{\partial}{\partial z} \quad (1.1.6)$$

and read it as nabla.

We define Laplace Operator as:

$$\Delta = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \quad (1.1.7)$$

1.2 Basic formula

Let us deduce basic formula!

(1) Derivation formula

$$\text{grad}(\varphi + \psi) = \text{grad} \varphi + \text{grad} \psi \quad (1.2.1)$$

Proof:It is as same as derivation.

$$\text{grad}(\varphi\psi) = \psi\text{grad}\varphi + \varphi\text{grad}\psi \quad (1.2.2)$$

Proof:It is as same as derivation.

$$\text{grad}F(\varphi) = F'(\varphi)\text{grad}\varphi \quad (1.2.3)$$

Proof:It is as same as derivation.

$$\text{div}(\mathbf{a} + \mathbf{b}) = \text{div}\mathbf{a} + \text{div}\mathbf{b} \quad (1.2.4)$$

Proof:It is as same as derivation.

$$\text{div}(\varphi\mathbf{a}) = \varphi\text{div}\mathbf{a} + \mathbf{a} \cdot \text{grad}\varphi \quad (1.2.5)$$

Proof:

$$\text{div}(\varphi\mathbf{a}) = \frac{\partial\varphi a_x}{\partial x} + \frac{\partial\varphi a_y}{\partial y} + \frac{\partial\varphi a_z}{\partial z} = \varphi\text{div}\mathbf{a} + \mathbf{a} \cdot \text{grad}\varphi$$

$$\text{div}(\mathbf{a} \times \mathbf{b}) = \mathbf{b} \cdot \text{rota} - \mathbf{a} \cdot \text{rot}\mathbf{b} \quad (1.2.6)$$

Proof:

$$\begin{aligned} \text{div}(\mathbf{a} \times \mathbf{b}) &= \text{div}((a_y b_z - b_y a_z)\mathbf{i} + (a_z b_x - a_x b_z)\mathbf{j} + (b_y a_x - a_y b_x)\mathbf{k}) \\ &= \left(a_y \frac{\partial b_z}{\partial x} + b_z \frac{\partial a_y}{\partial x} - b_y \frac{\partial a_z}{\partial x} - a_z \frac{\partial b_y}{\partial x} \right) \\ &\quad + \left(a_z \frac{\partial b_x}{\partial y} + b_x \frac{\partial a_z}{\partial y} - a_x \frac{\partial b_z}{\partial y} - b_z \frac{\partial a_x}{\partial y} \right) \\ &\quad + \left(b_y \frac{\partial a_x}{\partial z} + a_x \frac{\partial b_y}{\partial z} - a_y \frac{\partial b_x}{\partial z} - b_x \frac{\partial a_y}{\partial z} \right) \\ &= \mathbf{b} \cdot \text{rota} - \mathbf{a} \cdot \text{rot}\mathbf{b} \end{aligned}$$

$$\text{rot}(\mathbf{a} + \mathbf{b}) = \text{rota} + \text{rot}\mathbf{b} \quad (1.2.7)$$

Proof:It is eazy to prove.

$$\text{rot}(\varphi\mathbf{a}) = \varphi\text{rota} + \text{grad}\varphi \times \text{rota} \quad (1.2.8)$$

Proof:Expand it and prove it.

$$\text{rot}(\mathbf{a} \times \mathbf{b}) = (\mathbf{b} \cdot \nabla)\mathbf{a} - (\mathbf{a} \cdot \nabla)\mathbf{b} + \mathbf{a}\text{div}\mathbf{b} - \mathbf{b}\text{div}\mathbf{a} \quad (1.2.9)$$

Proof:

$$\operatorname{rot}(\mathbf{a} \times \mathbf{b}) = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ a_y b_z - b_y a_z & a_z b_x - a_x b_z & b_y a_x - a_y b_x \end{vmatrix}$$

$$\operatorname{grad}(\mathbf{a} \cdot \mathbf{b}) = (\mathbf{b} \cdot \nabla) \mathbf{a} + (\mathbf{a} \cdot \nabla) \mathbf{b} + \mathbf{b} \times \operatorname{rot} \mathbf{a} + \mathbf{a} \times \operatorname{rot} \mathbf{b} \quad (1.2.10)$$

Proof:I have not prove yet.

$$\operatorname{grad} \left(\frac{a^2}{2} \right) = (\mathbf{a} \cdot \nabla) \mathbf{a} + \mathbf{a} \times \operatorname{rot} \mathbf{a} \quad (1.2.11)$$

Proof:I have not prove yet.

$$\operatorname{div} \operatorname{grad} \varphi = \Delta \varphi \quad (1.2.12)$$

Proof:I have not prove yet.

$$\operatorname{div} \operatorname{rot} \mathbf{a} = 0 \quad (1.2.13)$$

Proof:I have not prove yet.

$$\operatorname{rot} \operatorname{grad} \varphi = 0 \quad (1.2.14)$$

Proof:I have not prove yet.

$$\operatorname{rot} \operatorname{rot} \mathbf{a} = \operatorname{grad} \operatorname{div} \mathbf{a} - \Delta \mathbf{a} \quad (1.2.15)$$

Proof:I have not prove yet.

$$\operatorname{div}(\varphi \operatorname{grad} \psi) = \varphi \Delta \psi + \operatorname{grad} \varphi \cdot \operatorname{grad} \psi \quad (1.2.16)$$

Proof:I have not prove yet.

$$\Delta(\varphi \psi) = \psi \Delta \varphi + \varphi \Delta \psi + 2 \operatorname{grad} \varphi \cdot \operatorname{grad} \psi \quad (1.2.17)$$

Proof:I have not prove yet.

(2) Integral formula

$$\int_V \operatorname{grad} \varphi \, dV = \int_S \mathbf{n} \varphi \, dS \quad (1.2.18)$$

Proof:I have not prove yet.

Остроградский-Gauss formula

$$\int_V \operatorname{div} \mathbf{a} \, dV = \int_S \mathbf{n} \cdot \mathbf{a} \, dS \quad (1.2.19)$$

Proof: I have not prove yet.

$$\int_V \operatorname{rot} \mathbf{a} \, dV = \int_S \mathbf{n} \times \mathbf{a} \, dS \quad (1.2.20)$$

Proof: I have not prove yet.

$$\int_V (\mathbf{v} \cdot \nabla) \mathbf{a} \, dV = \int_S (\mathbf{v} \cdot \mathbf{n}) \mathbf{a} \, dS \quad (1.2.21)$$

\mathbf{v} is a constant vector.

Proof: I have not prove yet.

$$\int_V \Delta \varphi \, dV = \int_S \frac{\partial \varphi}{\partial n} \, dS = \int_S \mathbf{n} \cdot \nabla \varphi \, dS \quad (1.2.22)$$

Proof: I have not prove yet.

$$\int_V \Delta \mathbf{a} \, dV = \int_S \frac{\partial \mathbf{a}}{\partial n} \, dS = \int_S (\mathbf{n} \cdot \nabla) \mathbf{a} \, dS \quad (1.2.23)$$

Proof: I have not prove yet.

First Green formula

$$\int_V (\varphi \Delta \psi + \operatorname{grad} \varphi \cdot \operatorname{grad} \psi) \, dV = \int_S \varphi \frac{\partial \psi}{\partial n} \, dS \quad (1.2.24)$$

and V is a simply connected domain.

Proof: I have not prove yet.

Second Green formula.

$$\int_V (\varphi \Delta \psi - \psi \Delta \varphi) \, dV = \int_S \left(\varphi \frac{\partial \psi}{\partial n} - \psi \frac{\partial \varphi}{\partial n} \right) \, dS \quad (1.2.25)$$

and V is a simply connected domain.

Proof: I have not prove yet.

$$\int_V (\text{grad} \varphi)^2 \, dV = \int_S \varphi \frac{\partial \varphi}{\partial n} \, dS \quad (1.2.26)$$

and $\Delta \varphi = 0$, V is a simply connected domain.

Proof: I have not prove yet.