

Quiz 2, STATS/DATASCI 531/631 W25

In class on 4/16, 2:30pm to 3:00pm

This document produces different random quizzes each time the source code generating it is run. The actual quiz will be a realization generated by this random process, or something similar.

This version lists all the questions currently in the quiz generator. The actual quiz will have one question sampled from each of the 6 question categories.

Instructions. You have a time allowance of 30 minutes. The quiz may be ended early if everyone is done. The quiz is closed book, and you are not allowed access to any notes. Any electronic devices in your possession must be turned off and remain in a bag on the floor.

For each question, circle one letter answer and provide some supporting reasoning.

Q1. Foundations of POMP models

Q8-01.

Consider a model $Y_{1:N}$ for data $y_{1:N}^*$, with a latent variable $X_{0:N}$, and a statistical model defined by a joint density $f_{X_{0:N}, Y_{1:N}}(x_{0:N}, y_{1:N}; \theta)$. The likelihood function is

$$L(\theta) = f_{Y_{1:N}}(y_{1:N}^*; \theta).$$

Are the following identities (A) true for all statistical models; (B) true for general POMP models but not all models; (C) true for linear Gaussian POMP models but not general POMP models; (D) generally false.

$$L(\theta) = \int f_{Y_{1:N}|X_{0:N}}(y_{1:N}^*|x_{0:N}; \theta) f_{X_{0:N}}(x_{0:N}; \theta) dx_{0:N} \quad (1)$$

$$L(\theta) = \prod_{n=1}^N f_{Y_n|Y_{1:n-1}}(y_n^*|y_{1:n-1}^*; \theta) \quad (2)$$

$$\text{Var}\{X_{n+1} | Y_{1:n}\} = E[\text{Var}\{X_{n+1} | X_n\} | Y_{1:n}] + \text{Var}\{E[X_{n+1} | X_n] | Y_{1:n}\} \quad (3)$$

$$L(\theta) = \int \left[\prod_{n=1}^N f_{Y_n|X_n}(y_n^*|x_n; \theta) \right] f_{X_{0:N}}(x_{0:N}; \theta) dx_{0:N} \quad (4)$$

Solution. 1(A), 2(A), 3(B), 4(B)

For part 3, we have in general that

$$\text{Var}\{U\} = E[\text{Var}\{U|V\}] + \text{Var}E[U|V]. \quad (5)$$

Such identities hold when everything is conditioned on another variable, so we have

$$\text{Var}\{U|Z\} = E[\text{Var}\{U|V, Z\}|Z] + \text{Var}\{E[U|V, Z]|Z\}. \quad (6)$$

Setting $U = X_{n+1}$, $V = X_n$, $Z = Y_{1:n}$, we have

$$\text{Var}\{X_{n+1} | X_n, Y_{1:n}\} = E[\text{Var}\{X_{n+1} | X_n, Y_{1:n}\} | X_n] + \text{Var}\{E[X_{n+1} | X_n, Y_{1:n}] | X_n\}. \quad (7)$$

The POMP model structure assumes X_{n+1} and $Y_{1:n}$ are conditionally independent given X_n and so

$$\text{Var}\{X_{n+1} | X_n\} = E[\text{Var}\{X_{n+1} | X_n\} | X_{1:n}] + \text{Var}\{E[X_{n+1} | X_n] | X_{1:n}\}. \quad (8)$$

Q8-02.

Which of the following linear Gaussian POMP model have an observable variable Y_n with distribution matching an ARMA(1,1) model? Here, ϵ_n and η_n are Gaussian white noise. X_n is 1-dimensional in (1) and 2-dimensional in (2) and (3).

- (A) Only (3)
- (B) (1) and (2) but not (3)
- (C) (2) and (3) but not (1)
- (D) (1) and (3) but not (2)
- (E) (1), (2) and (3)

$$\left. \begin{aligned} X_n &= aX_{n-1} + \epsilon_n \\ Y_n &= X_n + \eta_n \end{aligned} \right\} \quad (9)$$

$$\left. \begin{aligned} X_n &= \begin{pmatrix} a & 1 \\ 0 & 0 \end{pmatrix} X_{n-1} + \begin{pmatrix} 0 \\ 1 \end{pmatrix} \epsilon_n \\ Y_n &= (1, 0) X_n + \eta_n \end{aligned} \right\} \quad (10)$$

$$\left. \begin{aligned} X_n &= \begin{pmatrix} a & 1 \\ 0 & 0 \end{pmatrix} X_{n-1} + \begin{pmatrix} 1 \\ b \end{pmatrix} \epsilon_n \\ Y_n &= (1, 0) X_n \end{aligned} \right\} \quad (11)$$

Solution. (A)

A nice way to see (1) is in the frequency domain. X_n is AR(1) and so has spectrum $\sigma_\epsilon^2 / |1 - a \exp i\omega|^2 = \sigma_\epsilon^2 / (1 + a^2 - 2a \cos(\omega))$. η_n has spectrum σ_η^2 , and so Y_n has spectrum

$$\sigma_\eta^2 + \frac{\sigma_\epsilon^2 \text{psilon}}{1 + a^2 - 2a \cos(\omega)} = \frac{\sigma_\eta^2(1 + a^2) + \sigma_\epsilon^2 - 2a\sigma_\epsilon^2 \cos(\omega)}{1 + a^2 - 2a \cos(\omega)} \quad (12)$$

$$= \sigma^2 \frac{(1 + b^2) - 2b \cos(\omega)}{1 + a^2 - 2a \cos(\omega)} \quad (13)$$

where σ and b solve

$$\sigma^2(1 + b^2) = \sigma_\eta^2(1 + a^2) + \sigma_\epsilon^2, \quad (14)$$

$$\sigma^2 b = a\sigma_\epsilon^2 \cos(\omega) \quad (15)$$

(2) is the same set of equations as (1), as seen by setting $X'_n = \begin{pmatrix} X_n \\ \epsilon_n \end{pmatrix}$.

(3) is the ARMA(1,1) case of the LG-POMP representation of a general ARMA model given in Chapter 11. Specifically, set $X_n = \begin{pmatrix} Y_n \\ b\epsilon_n \end{pmatrix}$, and see that the process model becomes

$$\begin{pmatrix} Y_n \\ b\epsilon_n \end{pmatrix} = \begin{pmatrix} aY_{n-1} + b\epsilon_{n-1} + \epsilon_n \\ b\epsilon_n \end{pmatrix}.$$

Q8-03.

Scientifically, our conclusions should not depend on the units of measurement we use, but we can make errors if we don't get the details right. Suppose our data are two years of weekly aggregated case reports of a disease and we have a continuous-time model solved numerically by an Euler timestep of size dt . Which of the following is a correct explanation of our options for properly implementing this in a pomp object called `po`?

- A. The measurement times, `time(po)`, should be in units of weeks, such as 1, 2, ..., 104. The latent process can be modeled using arbitrary time units, say days or weeks or years. The units of dt should match the time units of the **latent** process.
- B. The measurement times, `time(po)`, should be in units of weeks, such as 1, 2, ..., 104. The latent process can be modeled using arbitrary time units, say days or weeks or years. The units of dt should be in weeks (in practice, usually a fraction of a week) to match the units of the **measurement** times.
- C. The measurement times do not have to be in units of weeks. For example, we could use `time(po)=1/52, 2/52, ..., 2`. The latent process and dt should use the same units of time as the measurement times.
- D. The measurement times do not have to be in units of weeks. For example, we could use `time(po)=1/52, 2/52, ..., 2`. The latent process can also use arbitrary units of time, which do not necessarily match the units of the measurement times. The units of dt should match the units used for the **latent** process.
- E. The measurement times do not have to be in units of weeks. For example, we could use `time(po)=1/52, 2/52, ..., 2`. The latent process can also use arbitrary units of time, which do not necessarily match the units of the measurement times. The units of dt should match the units used for the **measurement** times.

Solution. (C)

For scientific calculations, you generally have to pick an arbitrary set of units and use it consistently. In `pomp`, this means that you have to use the same units for measurement times and within the latent process. For example, if your measurement times are in days (7,14,...) then rate parameters should have units day^{-1} . A latent transition with mean duration 1 week would have corresponding rate $1/7\text{day}^{-1}$.

Q8-04.

Let V_n be a Markov process and let $W_n = h(V_n)$ for some function h . Which of the following statements are true?

- i. W_n is a Markov process for all choices of h .
- ii. W_n is a Markov process for some choices of h .
- iii. W_n is not a Markov process for any choice of h .
- iv. If $V_n = (X_n, Y_n)$ where X_n and Y_n are a POMP, and $h(X_n, Y_n) = X_n$ then W_n is a Markov process.
- v. If $V_n = (X_n, Y_n)$ where X_n and Y_n are a POMP, and $h(X_n, Y_n) = Y_n$ then W_n is a Markov process.

A: i,iv,v

B: ii,iv

C: ii,v

D: iii

E: Some combination other than those listed above

Solution. (B)

(iv) is true by definition of a POMP model, and this rules out (iii). To see that (v) is not generally true, consider a Markov chain, X_n on $\{1,2,3\}$ which cycles $1 \rightarrow 2 \rightarrow 3 \rightarrow 1$, with X_0 being uniform on $\{1,2,3\}$. Let $Y_n = A$ if $X_n \in \{1, 2\}$ and $Y_n = B$ if $X_n = 3$. Then, $P(Y_{n+1} = B | Y_n = A) = 1/2$ which is not equal to $P(Y_{n+1} = B | Y_n = A, Y_{n-1} = A) = 1$. This example also rules out (i). (ii) is clearly satisfied by the identity function, $h(x) = x$, so we are left with (ii) and (iv).

Q2. Likelihood evaluation; the particle filter

Q9-01.

Suppose that 10 replications of a particle filter, each using 10^3 particles, runs in 15 minutes with no parallelization. To look for a more precise likelihood evaluation, you consider running 20 replicates, each with 10^4 particles. Approximately how many minutes will this take, if you distribute the calculation across 4 cores?

- A: 50
- B: 60
- C: 75
- D: 120
- E: 300

Solution. C.

Using the linear dependence, also called proportionality, of the computing effort on various algorithmic parameters, we calculate

$$5 \times (10000/1000) \times (20/10) \times (1/4) = 75.$$

Q9-02.

A particle filter is repeated 5 times to evaluate the likelihood at a proposed maximum likelihood estimate, each time with 10^4 particles. Suppose the log likelihood estimates are -2446.0 , -2444.0 , -2443.0 , -2442.0 , -2440.0 . Which of the following is an appropriate estimate for the log likelihood at this parameter value and its standard error.

- A: Estimate = -2443.0 , with standard error 1.0
- B: Estimate = -2443.0 , with standard error 2.2
- C: Estimate = -2443.0 , with standard error 5.0
- D: Estimate = -2441.4 , with standard error 2.2
- E: Estimate = -2441.4 , with standard error 1.4

Solution. E.

Answers A, B and C estimate using a mean on the log scale. However, the particle filter provides an unbiased likelihood estimate on a natural scale but not on a log scale. Note that the particle filter also has some bias for most quantities on a natural scale, which reduces to zero as the number of particles tends to infinity, but it happens to be unbiased for the likelihood. The standard error for the log of the mean of the likelihoods can be computed by the delta method or a jack-knife, for example using the `logmeanexp` function in `pomp`.

```
l1 <- c(-2446, -2444, -2443, -2442, -2440)
mean(l1)
```

```
## [1] -2443
```

```
sd(l1)
```

```
## [1] 2.236068
```

```
sd(l1)/sqrt(length(l1))
```

```
## [1] 1
```

```
pomp::logmeanexp(l1, se=TRUE)
```

```
##           est           se
## -2441.422198    1.380688
```

Q9-03.

Effective sample size (ESS) is one of the main tools for diagnosing the success of a particle filter. If you plot an object of class `pfilterd_pomp` (created by applying `pfilter` to a `pomp` object), the ESS is displayed.

Suppose one or more time points have low ESS (say, less than 10) even when using a fairly large number of particles (say, 10^4). What is the proper interpretation?

A: There is a problem with data, perhaps an error recording an observation.

B: There is a problem with the model which means that it cannot explain something in the data.

C: The model and data have no major problems, but the model happens to be problematic for the particle filter algorithm.

D: At least one of A, B, and C.

E: Either A or B or both, but not C. If the model fits the data well, the particle filter is guaranteed to work well.

Solution. D.

An example of a situation where the model fits the data well, but filtering is hard, arises when the measurement error is small relative to the process noise. In this case, the particles are scattered by the process noise and very few of them are compatible with the data due to the precise measurement. Thus, almost all the particles must be discarded as unfeasible given the data, corresponding to a low ESS.

Q3. Likelihood maximization; iterated filtering

Q10-01.

When carrying out inference by iterated particle filtering, the likelihood increases for the first 10 iterations or so, and then steadily decreases. Testing the inference procedure on simulated data, this does not happen and the likelihood increases steadily toward convergence. Which of the following is the best explanation for this?

A: One or more random walk standard deviation is too large.

B: One or more random walk standard deviations is too small.

C: The model is misspecified, so it does not fit the data adequately.

D: A combination of the parameters is weakly identified, leading to a ridge in the likelihood surface.

E: Too few particles are being used.

Solution. C.

A test on simulated data, when the truth is known, can help pin down an optimization problem. All the issues other than C can cause inference problems, but likely would cause similar problems on simulated data.

When there is a reproducible and stable phenomenon of decreasing likelihood, it generally indicates that the unperturbed model is a worse fit to the data than the perturbed model. Recall that the likelihood calculated by iterated filtering at each iteration corresponds to the model with perturbed parameters rather than the actual postulated model with fixed parameters. If the perturbed model has higher likelihood, it may mean that the data are asking to have time-varying parameters. It may also be a signature of any other weakness in the model that can be somewhat accommodated by perturbing the parameters.

Q10-02.

People sometimes confuse likelihood profiles with likelihood slices. When you read a report claiming to have computed a profile it can be worth checking whether it is actually computed as a slice. Suppose you read a figure which claims to construct a profile confidence interval for a parameter ρ in a POMP model with four unknown parameters. Which of the following confirms that the plot is, or is not, a properly constructed profile confidence interval.

A: The CI is constructed by obtaining the interval of ρ values whose log likelihood is within 1.92 of the maximum on a smoothed curve of likelihood values plotted against ρ .

B: The code (made available to you by the authors as an Rmarkdown file) involves evaluation of the likelihood but not maximization.

C: The points along the ρ axis are not equally spaced.

D: The smoothed line shown in the plot is close to quadratic.

E: A and D together.

Solution. B.

If the researchers calculate a sliced likelihood through the MLE and tell you it is a profile, but you are concerned they might have constructed a slice by mistake, it is hard to know without looking at the code. (A) is the proper construction of a profile if the points are maximizations over the remaining parameters for a range of fixed values of ρ . However, if the code does not involve maximization over other parameters at each value of ρ , it cannot be a proper profile. It could be a slice accidentally explained to be a profile, and with a confidence interval constructed as if it were a profile.

If there is only one unknown parameter then a slice and a profile are the same thing, and no maximization is required. This is an unusual situation; there is usually more than one unknown parameter.

Q10-03.

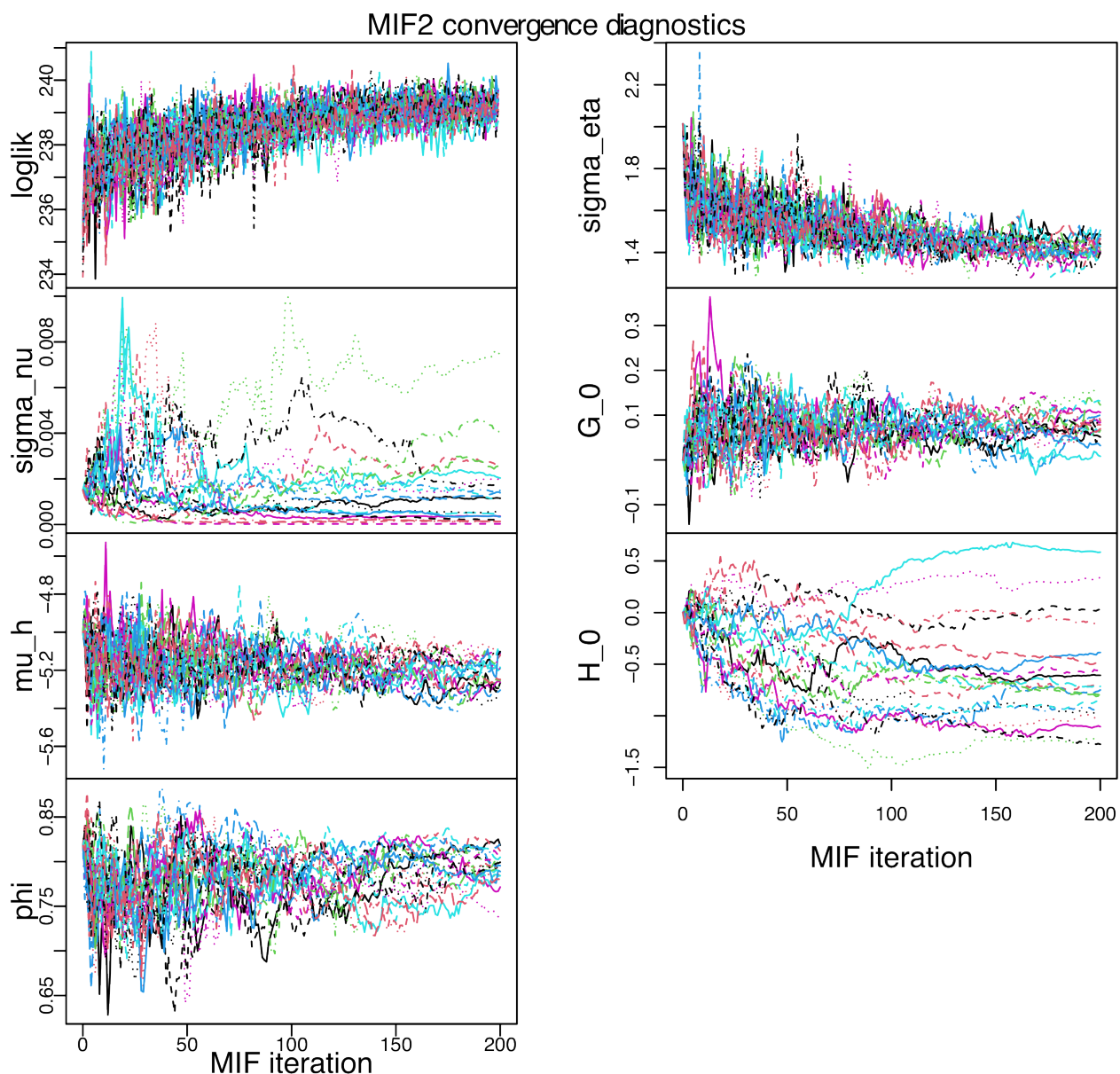


Figure 1: Diagnostic plot

The iterated filtering convergence diagnostics plot shown above come from a student project. What is the best interpretation?

A: Everything seems to be working fine. The likelihood is climbing. The replicated searches are giving consistent runs. The spread of convergence points for σ_ν and H_0 indicates weak identifiability, which is a statistical fact worth noticing but not a weakness of the model.

B: The consistently climbing likelihood is promising, but the failure of σ_ν and H_0 to converge needs attention. Additional searching is needed, experimenting with **larger** values of the random walk perturbation standard deviation for these parameters to make sure the parameter space is properly searched.

C: The consistently climbing likelihood is promising, but the failure of σ_ν and H_0 to converge needs attention. Additional searching is needed, experimenting with **smaller** values of the random walk perturbation standard deviation for these parameters to make sure the parameter space is properly searched.

D: The consistently climbing likelihood is promising, but the failure of σ_ν and H_0 to converge needs attention. This indicates weak identifiability which cannot be solved by improving the searching algorithm. Instead, we should change the model, or fix one or more parameters at scientifically plausible values, to resolve the identifiability issue before proceeding.

E: Although the log likelihood seems to be climbing during the search, until the convergence problems with σ_ν and H_0 have been addressed we should not be confident about the successful optimization of the likelihood function or the other parameter estimates.

Solution. A.

All searches are finding parameters with consistent likelihood. The discrepancies of a few log likelihood units put the parameter values within statistical uncertainty according to Wilks's Theorem. Therefore, the spread in the parameter estimates reflects uncertainty about the parameter given the data, rather than a lack of convergence.

That perspective suggests that the goal of the Monte Carlo optimizer is to get close to the MLE, measured by likelihood, rather than to obtain it exactly. Independent Monte Carlo searches can be combined via a profile likelihood to get a more exact point estimate and a confidence interval.

Wide confidence intervals, also called weak identifiability, are not necessarily a problem for the scientific investigation. Some parameters may be imprecisely estimable, while others can be obtained more precisely, and part of the analysis is to find which is in each category. It may also be of interest to investigate what extra precision can be obtained on one parameter by making assumptions about the value of another, as in D, but this is not mandatory for proper inference.

Overall, the convergence plots here look good. The plots show that the searches are all started from a single high likelihood starting point. Now this has been done successfully, a natural next step would be to start some searches from more diverse starting points to look for any global features missed by this local search.

Q10-04.

The iterated filtering convergence diagnostics plot shown above come from a student project, calculated using 10^3 particles. What is the best interpretation?

A: Everything seems to be working fine. There is a clear consensus from the different searches concerning the highest likelihood that can be found. Therefore, the search is doing a good job of maximization. Occasional searches get lost, such as the purple line with a low likelihood, but that is not a problem.

B: The searches obtain likelihood values spread over thousands of log units. We would like to see consistent convergence within a few log units. We should use more particles and/or more iterations to achieve this.

C: The searches obtain likelihood values spread over thousands of log units. We would like to see consistent convergence within a few log units. We should compare the best likelihoods obtained with simple statistical models, such as an auto-regressive moving average model, to look for evidence of model misspecification.

D: The searches obtain likelihood values spread over thousands of log units. We would like to see consistent convergence within a few log units. We should look at the effective sample size plot for the best fit we have found yet, to see whether there are problems with the particle filtering.

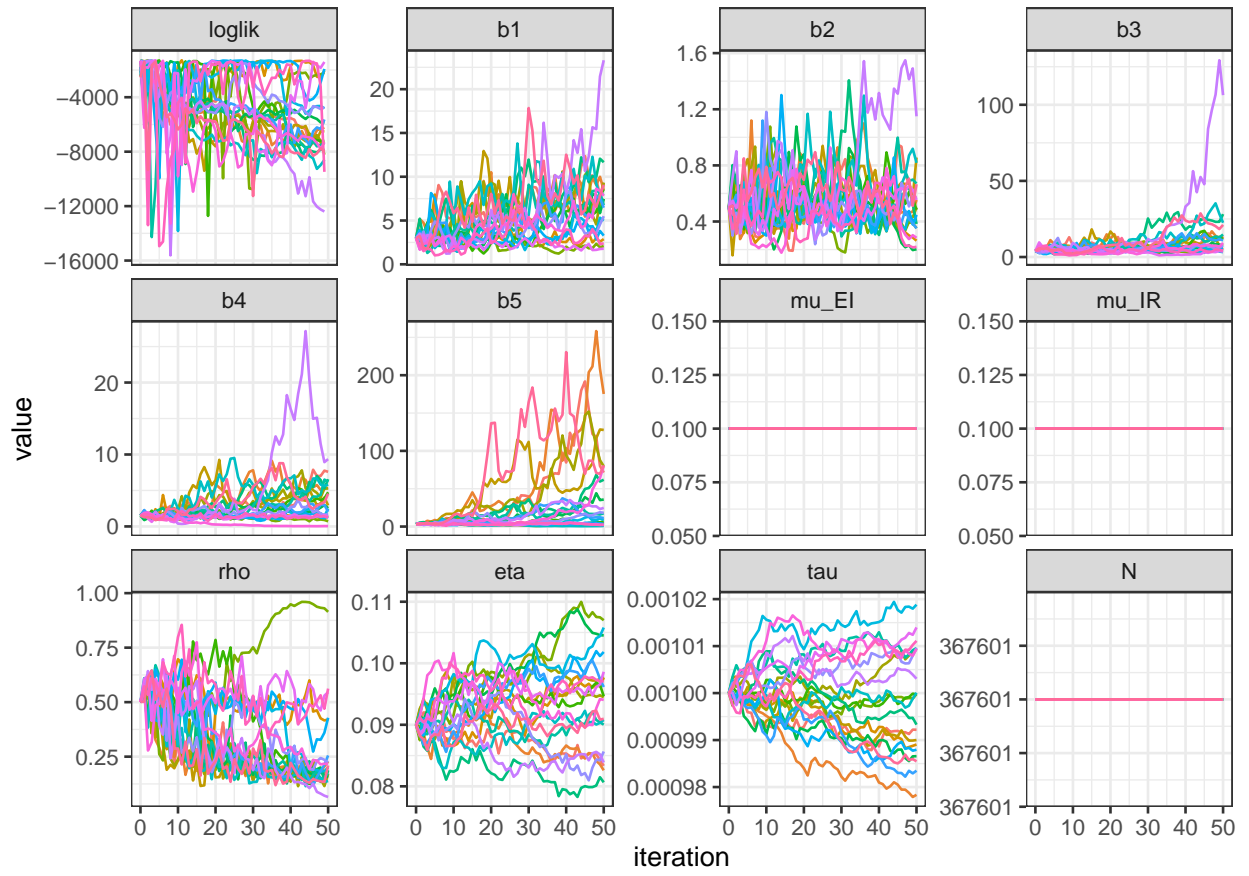


Figure 2: Diagnostic plot

E: All of B, C, and D.

Solution. E.

This project team were able to show evidence of adequate global maximization for their model, but their maximized likelihood was 47 log units lower than ARMA model. The wide spread in likelihood, thousands of log units, shown in this convergence plot suggests that the numerics are not working smoothly. This could mean that more particles are needed: 10^3 particles is relatively low for a particle filter. However, if the model fit is not great (as revealed by comparison against a benchmark) this makes the filtering harder as well as less scientifically satisfactory. If the model is fitting substantially below ARMA benchmarks, it is worth considering some extra time on model development. Identifying time points with low effective sample size can help to identify which parts of the data are problematic for the model to explain.

Q4. Data analysis: epidemiological models

Q11-01.

Two models are fitted to case counts on an epidemic. Model 1 is an SIR POMP model with a negative binomial measurement model, and model 2 is a linear regression model estimating a cubic trend. The log likelihoods are $\ell_1 = -2037.91$ and $\ell_2 = -2031.28$ respectively. Which of the following do you agree with most?

A: We should not compare the models using these likelihoods. They correspond to different model structures, so it is an apples-to-oranges comparison.

B: We can compare them, but the difference is in the 4th significant figure, so the likelihoods are statistically indistinguishable.

C: The linear model has a noticeably higher likelihood. Our mechanistic model needs to be updated to beat this benchmark before we can responsibly interpret the fitted model. If a simple regression model has higher likelihood than a more complex mechanistic model, one should prefer the simpler model.

D: The linear model has a noticeably higher likelihood. The mechanistic model is somewhat validated by being not too far behind the simple regression model. We are justified in cautiously interpreting the mechanistic model, while continuing to look for further improvements.

E: The log likelihoods cannot properly be compared as presented, but could be if we used a Gaussian measurement model for the POMP (or a negative binomial generalized linear model instead of least squares for the regression).

Solution. D.

Why not A? Likelihoods of different models for the same data can be compared. Likelihood ratio tests using Wilks's theorem specifically require nested models, but in other contexts (such as AIC and the Neyman-Pearson lemma) the models being compared by likelihood do not need to have any particular relationship.

Why not B? Likelihood ratios have statistical meaning, which corresponds to differences of log likelihoods. The likelihood is a dimensional quantity, whereas the likelihood ratio is dimensionless. The units used correspond to a scientifically arbitrary additive constant to the log likelihood, which disappears after taking differences.

Why not C? If our only goal were to find a predictive model, then (C) could be a reasonable position. Usually, we want to find a model that also has interpretable structure, leading to understanding of the system or estimating the effect of interventions. A simple regression model cannot do those things, even if it fits a bit better. If the mechanistic model fits much worse than simple alternatives, it is not providing a reasonable explanation of the data, suggesting that there may be important things missing from the model specification.

Quite likely, with some persistence, a mechanistic specification will beat a simple off-the-shelf statistical model.

Q11-02.

A compartment model is first implemented as a system of ordinary differential equations (ODEs). This leads to qualitatively reasonable trajectories, but poor likelihood values. The researchers add stochasticity in an attempt to improve the fit of the model by interpreting the ODEs as rates of a Markov chain. The likelihood, maximized by iterated particle filtering, remains poor compared to ARMA benchmarks. In addition, the effective sample size for the particle filtering is low at many time points despite even using as many as 10^4 particles. Which of the following is the most promising next step?

- A: Increase to 10^5 particles, moving the computations to a cluster if necessary.
- B: Add noise to one or more rates to allow for overdispersion.
- C: Try adding extra features to the model to capture scientific details not present in the original model.
- D: Experiment with variations in the iterated filtering procedure; maybe more iterations, or a different cooling schedule.
- E: To address the possibility of reporting errors, see if the model fits better when the most problematic data points are removed.

Solution. B.

All the possibilities are worth consideration. However, adding noise in rates to give flexibility in mean-variance relationships is commonly an important part of developing a stochastic model. The simple compartment model interpretation of a ODE as a Markov chain is determined by the rates and therefore does not have free parameters to describe variance. There is some variance inherent in the Markov chain (demographic stochasticity) but additional variability may be needed. It will be hard to investigate the other possibilities if the model has not been given enough stochasticity to explain the variability in the data, so including overdispersion should be an early step. Note that overdispersion can be included in both the process model and the measurement model.

Q11-03. You fit an SEIR model to case reports of an immunizing disease from a city. The resulting confidence interval for the mean latent period is 12–21 days, but clinical evidence points to a latent period averaging about 7 days. Which of the following is the most appropriate response to this discrepancy?

- A: The latent period may be confounded with some unmodeled aspect of the system, such as spatial or age structure. The model estimates an effective latent period at the population level, which may not perfectly match what is happening at the scale of individuals.
- B: The discrepancy shows that something is substantially wrong with the model. Extra biological detail must be introduced with the goal of bringing the estimated parameter back in line with the known biology of the system.
- C: The discrepancy is problematic, but fortunately can readily be fixed. Since we know the clinical value of this parameter with reasonable accuracy, we should simply use this value in the model rather than estimating it.
- D: If the model fits the data statistically better than any known alternative model, then we have to take the estimated parameter at face value. It is certainly possible that the estimates in the literature correspond to some different population, or different strain, or have some other measurement bias such as corresponding to severe cases resulting in hospitalization. The discrepancy does not show that our model was wrong.
- E: This discrepancy suggests that we should take advantage of both C and D above by putting a Bayesian prior on the latent period. By quantifying the degree of our skepticism about the previously established clinical value of 7 days, we can optimally combine that uncertainty with the evidence from this dataset.

Solution. A.

Transferring parameter estimates between scales is hard. An example is the difficulty of reconciling micro and macro economics. It is generally not possible to guarantee that a parameter means exactly the same thing in models at different scales. (A) acknowledges this. The other answers, in various ways, assume that there should be a single parameter value that describes the system at all scales. There is some merit also to (D), since it is reasonable to try to gain biological understanding by investigating why the fitted model is successful at explaining the data. However, this is an observational study and so we should be cautious of making a causal interpretation of models fitted to data due to the possibility of confounding. Only (A)

addresses this concern.

Q5. Data analysis: financial models

Q12-01.

To do: A question on volatility modeling using POMP models

Solution. .

To do.

Q6. Computing with POMP models

Q13-01.

Suppose you obtain the following error message when you build your pomp model using C snippets.

```
##
## Error: in 'simulate': error in building shared-object library from C snippets: in 'Cbuilder':
## compilation error: cannot compile shared-object library
## '/tmp/RtmpFkkeCQ/24104/pomp_4fc43714a7a9ebddf896bbc51635d211.so': status = 1
## compiler messages:
## gcc -I"/usr/local/apps/R/ubuntu_20.04/4.2.1/lib64/R/include" -DNDEBUG
## -I'/home/kingaa/R/x86_64-pc-linux-gnu-library/4.2/pomp/include' -I'/home/kingaa/teach/sbied'
## -I/usr/local/include -fpic -g -O2 -Wall -pedantic -c
## /tmp/RtmpFkkeCQ/24104/pomp_4fc43714a7a9ebddf896bbc51635d211.c
## -o /tmp/RtmpFkkeCQ/24104/pomp_4fc43714a7a9ebddf896bbc51635d211.o
## In file included from /home/kingaa/R/x86_64-pc-linux-gnu-library/4.2/pomp/include/pomp.h:9,
## from /tmp/RtmpFkkeCQ/24104/pomp_4fc43714a7a9ebddf896bbc51635d211.c:5:
## /tmp/RtmpFkkeCQ/24104/pomp_4fc43714a7a9ebddf896bbc51635d211.c: In function '__pomp_rmeasure':
## /usr/local/apps/R/ubuntu_20.04/4.2.1/lib64/R/include/Rmath.h:333:16: error:
## too many arguments to function 'Rf_rnorm'
## In addition: Warning message:
## In system2(command = R.home("bin/R"), args = c("CMD", "SHLIB", "-c", :
## running command 'PKG_CPPFLAGS="-I'/home/kingaa/R/x86_64-pc-linux-gnu-library/4.2/pomp/include'
## -I'/home/kingaa/teach/sbied'" '/usr/local/apps/R/ubuntu_20.04/4.2.1/lib64/R/bin/R' CMD SHLIB -c
## -o /tmp/RtmpFkkeCQ/24104/pomp_4fc43714a7a9ebddf896bbc51635d211.so
## /tmp/RtmpFkkeCQ/24104/pomp_4fc43714a7a9ebddf896bbc51635d211.c 2>&1' had status 1
```

Which of the following is a plausible cause for this error?

- A: Using R syntax within a C function that has the same name as an R function.
- B: A parameter is missing from the `paramnames` argument to `pomp`.
- C: Indexing past the end of an array because C labels indices starting at 0.
- D: Using `beta` as a parameter name when it is a declared C function.
- E: A missing semicolon at the end of a line.

Solution. A.

The code producing the error is below. Within C snippets, the C versions of R distribution functions are available but they have slightly different syntax from their more familiar R children. A complete reference guide to R's C interface is available as part of R's documentation. In particular, the C form of R's distribution functions is useful for writing C snippets.

```
sir4 <- simulate(
  sir1,
  statenames=c("S", "I", "R", "cases", "W"),
  paramnames=c(
```

```

    "gamma", "mu", "iota",
    "beta1", "beta_sd", "pop", "rho",
    "S_0", "I_0", "R_0"
  ),
  rmeasure=Csnippet("
    double mean, sd;
    double rep;
    mean = cases*rho;
    sd = sqrt(cases*rho*(1-rho));
    rep = nearbyint(rnorm(1,mean,sd));
    reports = (rep > 0) ? rep : 0;"
  )
)

```

Q13-02. Suppose you obtain the following error message when you build your pomp model using C snippets.

```

##
## Error: error in building shared-object library from C snippets: in 'Cbuilder': compilation error:
## cannot compile shared-object library
## '/tmp/RtmpFkkeCQ/24104/pomp_068eedfc62b1e391363bbdd99fbe8c.so': status = 1
## compiler messages:
## gcc -I"/usr/local/apps/R/ubuntu_20.04/4.2.1/lib64/R/include" -DNDEBUG
## -I'/home/kingaa/R/x86_64-pc-linux-gnu-library/4.2/pomp/include' -I'/home/kingaa/teach/sbied'
## -I/usr/local/include -fpic -g -O2 -Wall -pedantic
## -c /tmp/RtmpFkkeCQ/24104/pomp_068eedfc62b1e391363bbdd99fbe8c.c
## -o /tmp/RtmpFkkeCQ/24104/pomp_068eedfc62b1e391363bbdd99fbe8c.o
## /tmp/RtmpFkkeCQ/24104/pomp_068eedfc62b1e391363bbdd99fbe8c.c:
## In function '__pomp_rinit':
## /tmp/RtmpFkkeCQ/24104/pomp_068eedfc62b1e391363bbdd99fbe8c.c:38:13:
## error: called object is not a function or function pointer
##    38 |     cases = 0
##       |         ^
## make: *** [/usr/local/apps/R/ubuntu_20.04/4.2.1/lib64/R/etc/Makeconf:168:
## /tmp/RtmpFkkeCQ/24104/pomp_068eedfc62b1e391363bbdd99fbe8c.o] Error 1
## In addition: Warning message:
## In system2(command = R.home("bin/R"), args = c("CMD", "SHLIB", "-c", :
## running command 'PKG_CPPFLAGS="-I'/home/kingaa/R/x86_64-pc-linux-gnu-library/4.2/pomp/include'
## -I'/home/kingaa/teach/sbied'" '/usr/local/apps/R/ubuntu_20.04/4.2.1/lib64/R/bin/R' CMD SHLIB -c
## -o /tmp/RtmpFkkeCQ/24104/pomp_068eedfc62b1e391363bbdd99fbe8c.so
## /tmp/RtmpFkkeCQ/24104/pomp_068eedfc62b1e391363bbdd99fbe8c.c 2>&1' had status 1

```

Which of the following is a plausible cause for this error?

- A: Using R syntax within a C function that has the same name as an R function.
- B: A parameter is missing from the `paramnames` argument to `pomp`.
- C: Indexing past the end of an array because C labels indices starting at 0.
- D: Using `beta` as a parameter name when it is a declared C function.
- E: A missing semicolon at the end of a line.

Solution. E.

The error message was produced by the code below. `pomp` passes on the C compiler error message for you to inspect. Note the missing semicolon in the next-to-last line.

```

sir1 <- sir()
sir2 <- pomp(
  sir1,

```

```

statenames=c("S","I","R","cases","W"),
paramnames=c(
  "gamma","mu","iota",
  "beta1","beta_sd","pop","rho",
  "S_0","I_0","R_0"
),
rinit=Csnippet("
double m = pop/(S_0+I_0+R_0);
S = nearbyint(m*S_0);
I = nearbyint(m*I_0);
R = nearbyint(m*R_0);
cases = 0
W = 0;"
)
)

```

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