

# MATH 629 Homework 1

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## Problem 1

The weights and biases are given by

$$\begin{aligned}\mathbf{W}^{(1)} &= \begin{bmatrix} -1 & 1 & 0 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 0 & -1 & 1 \end{bmatrix} \\ \mathbf{b}^{(1)} &= [0 \quad 0 \quad 0] \\ \mathbf{W}^{(2)} &= [1 \quad 1 \quad 1] \\ b^{(2)} &= -2.4\end{aligned}$$

## Problem 2

The dimensions of  $X, Y, W, B$  are as follows (assuming that the number of features is  $d$ ):

- $X \in \mathbb{R}^{N \times d}$
- $Y = [y_1, y_2, \dots, y_N]^T \in \mathbb{R}^{N \times 1}$
- $W \in \mathbb{R}^{d \times 1}$
- $B \in \mathbb{R}^{N \times 1}$

With the notations above, we can define  $\mathcal{L}(Y, T)$  as

$$\mathcal{L}(Y, T) := [\mathcal{L}(y_1, t_1), \mathcal{L}(y_2, t_2), \dots, \mathcal{L}(y_N, t_N)]^T \in \mathbb{R}^{N \times 1}$$

Accordingly, we have that

$$\mathcal{E} = \frac{1}{N} \mathcal{L}(Y, T)^T \cdot e^{N \times 1}$$

and, obviously,

$$Y = XW + B$$

Therefore, the derivatives are computed as

$$\begin{aligned}\frac{\partial \mathcal{E}}{\partial Y} &= \frac{1}{N} \sin(Y - T) \\ \frac{\partial \mathcal{E}}{\partial W} &= \frac{\partial \mathcal{E}}{\partial Y} \frac{\partial Y}{\partial W} = \frac{1}{N} X^T \sin(Y - T) \\ \frac{\partial \mathcal{E}}{\partial B} &= \frac{\partial \mathcal{E}}{\partial Y} \frac{\partial Y}{\partial B} = \frac{1}{N} \sin(Y - T)\end{aligned}$$

## Problem 3

We start with showing that the absolute loss is indeed a squared loss with reassigned weights.

$$\sum_{n=1}^N |y_n - \mathbf{X}_n \beta| = \sum_{n=1}^N \frac{1}{|y_n - \mathbf{X}_n \beta|} (y_n - \mathbf{X}_n \beta)^2 =: \sum_{n=1}^N s_n (y_n - \mathbf{X}_n \beta)^2 \quad (1)$$

In order to estimate the  $s_n$ 's, we can utilize the following algorithm:

- Initialize OLS weights,  $\beta^0$
- Compute residuals  $|y_n - \mathbf{X}_n\beta|$
- Update weights  $w_n^i$  with  $w_n^i = \frac{1}{|y_n - \mathbf{X}_n\beta|}$
- Solve the WLS problem,  $\beta^{i+1} = \operatorname{argmin} \sum_n w_n^i (y_n - X_n\beta^i)$
- Stop when  $|\beta^{i+1} - \beta^i| < \epsilon$ , where  $\epsilon$  is a pre-determined threshold.

## Problem 4

Figure 1: Implementation of XOR

