

# Build firmware Marlin 2.0.7.2 for BigTreeTech E3 RRF

**download in source firmware : MARLIN 2.0.7.2**

1 : Create folder Marlin in your directory « [C:\](#)  
exemple: [C:\marlin](#)

2 : unzip [Marlin-2.0.7.2.x-E3-RRF.rar](#) and copy the extract folder to « [C:\marlin](#)

3 : open Vscode and go to platformio extensions. With platformio add folder from your [C:\marlin\ Marlin-2.0.7.2.x-E3-RRF](#)

4 : Now you can configure your files configuration.h and configuration\_adv.h as you wish, with or without bltouch, neopixel, filament sensor etc ....

IMPORTANT : before build your marlin you need to have these settings to enable the wifi module

## configuration.h

```
95 // @section machine
96
97 /**
98  * Select the serial port on the board to use for communication with the host.
99  * This allows the connection of wireless adapters (for instance) to non-default port pins.
100  * Serial port -1 is the USB emulated serial port, if available.
101  * Note: The first serial port (-1 or 0) will always be used by the Arduino bootloader.
102  *
103  * :[-1, 0, 1, 2, 3, 4, 5, 6, 7]
104  */
105 #define SERIAL_PORT 3
106
107 /**
108  * Select a secondary serial port on the board to use for communication with the host.
109  * Currently Ethernet (-2) is only supported on Teensy 4.1 boards.
110  * :[-2, -1, 0, 1, 2, 3, 4, 5, 6, 7]
111  */
112 #define SERIAL_PORT_2 -1
113
114 /**
115  * This setting determines the communication speed of the printer.
116  *
117  * 250000 works in most cases, but you might try a lower speed if
118  * you commonly experience drop-outs during host printing.
119  * You may try up to 1000000 to speed up SD file transfer.
120  *
121  * :[2400, 9600, 19200, 38400, 57600, 115200, 250000, 500000, 1000000]
122  */
123 #define BAUDRATE 115200
124
125 // Enable the Bluetooth serial interface on AT90USB devices
126 //#define BLUETOOTH
127
128 // Choose the name from boards.h that matches your setup
129 #ifndef MOTHERBOARD
130   #define MOTHERBOARD BOARD_BTT_E3_RRF
131 #endif
132
```

be sure to

```
#define SERIAL_PORT 3
#define SERIAL_PORT_2 -1
#define BAUDRATE 115200
```

## configuration\_adv.h

```
3635  /**
3636   * Ethernet. Use M552 to enable and set the IP address.
3637   */
3638  #if HAS_ETHERNET
3639   #define MAC_ADDRESS { 0xDE, 0xAD, 0xBE, 0xEF, 0xF0, 0x0D } // A MAC address unique to your network
3640 #endif
3641
3642  /**
3643   * WiFi Support (Espressif ESP32 WiFi)
3644   */
3645  // #define WIFISUPPORT // Marlin embedded WiFi management
3646  // #define ESP3D_WIFISUPPORT // ESP3D Library WiFi management (https://github.com/luc-github/ESP3DLib)
3647
3648  #if EITHER(WIFISUPPORT, ESP3D_WIFISUPPORT)
3649   #define WEBSUPPORT // Start a webserver (which may include auto-discovery)
3650   #define OTASUPPORT // Support over-the-air firmware updates
3651   #define WIFI_CUSTOM_COMMAND // Accept feature config commands (e.g., WiFi ESP3D) from the host
3652
3653   /**
3654    * To set a default WiFi SSID / Password, create a file called Configuration_Secure.h with
3655    * the following defines, customized for your network. This specific file is excluded via
3656    * .gitignore to prevent it from accidentally leaking to the public.
3657    *
3658    * #define WIFI_SSID "WiFi SSID"
3659    * #define WIFI_PWD "WiFi Password"
3660    */
3661   #include "Configuration_Secure.h" // External file with WiFi SSID / Password
3662 #endif
```

be sure don't uncomment

```
// #define WIFISUPPORT
#define ESP3D_WIFISUPPORT
```

5 : Now you can build your firmware and have success compil

6 : the firmware is located in the folder C:\marlin\Marlin-2.0.7.2.x-E3-RRF\.pio\build\BIGTREE\_E3\_RRF

!! Be sure the firmware must absolutely be called firmware.bin before you copy into your board.

7 : when the file is in your Sdcard you have to put into your board and turn on your printer. Wait a moment and firmware is upload !

now we need to activate the wifi module so that it can communicate with your networks. Please refer to TUTORIAL ESP3D.

Create by So'6 Rallye