

Name: _____

Roll Number: _____

Quiz-2

Max. Time: 20 min

Max. Points: 20

Note: Solve all parts. Limit your written responses to the provided space.

Q.1. [8] Choose by putting a check mark on the most appropriate option. Note: No cutting/overwriting allowed.

i. When two linear transformations are performed one after another, the combined effect may not always be linear.

(A) True (B) **False**

ii. A mapping $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is onto \mathbb{R}^m if every vector \mathbf{x} in \mathbb{R}^n maps onto some vector in \mathbb{R}^m .

(A) True (B) **False**

iii. If \mathbf{A} is 3×2 matrix, then the transformation from \mathbf{x} to \mathbf{Ax} cannot be one-to-one.

(A) True (B) **False**

iv. The columns of the standard matrix for a linear transformation $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ are the images of the columns of I_n .

(A) **True** (B) False

v. Every elementary matrix is not invertible.

(A) True (B) **False**

vi. Product of invertible matrices is invertible and is given by the product of their inverses in the same order.

(A) True (B) **False**

vii. If a matrix cannot be row reduced to identity matrix, then its inverse does not exist.

(A) **True** (B) False

viii. An $n \times n$ matrix is invertible if it has at most n pivots.

(A) True (B) **False**

Q.2. [6+6]

a) Determine the standard matrix of linear transformation for the following:

i) $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ first reflects points through the horizontal x_1 axis and then reflects points through the line $x_2 = x_1$.

Solution: $T(\mathbf{e}_1) = \mathbf{e}_2, T(\mathbf{e}_2) = -\mathbf{e}_1$. Therefore, $[T(\mathbf{e}_1) \ T(\mathbf{e}_2)] = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$

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ii) $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ is a horizontal shear transformation that leaves the unit vector \mathbf{e}_1 for horizontal axis unchanged and maps the unit vector for the vertical axis \mathbf{e}_2 to $\mathbf{e}_2 + 3\mathbf{e}_1$

Solution:

$$T(\mathbf{e}_1) = \mathbf{e}_1; , T(\mathbf{e}_2) = \begin{bmatrix} 0 \\ 1 \end{bmatrix} + 3 \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 3 \\ 1 \end{bmatrix}$$

$$[T(\mathbf{e}_1) \ T(\mathbf{e}_2)] = \begin{bmatrix} 1 & 3 \\ 0 & 1 \end{bmatrix}$$

b) Determine if the following matrix is invertible.

$$A = \begin{bmatrix} -1 & -3 & 0 & 1 \\ 3 & 5 & 8 & -3 \\ -2 & -6 & 3 & 2 \\ 0 & -1 & 2 & 1 \end{bmatrix}$$

Solution: Row reduce A to echelon form to check the number of pivot positions, which should be 4 if the matrix is invertible.

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$$A = \begin{bmatrix} -1 & -3 & 0 & 1 \\ 3 & 5 & 8 & -3 \\ -2 & -6 & 3 & 2 \\ 0 & -1 & 2 & 1 \end{bmatrix} \sim \begin{bmatrix} -1 & -3 & 0 & 1 \\ 0 & -4 & 8 & 0 \\ 0 & 0 & 3 & 0 \\ 0 & -1 & 2 & 1 \end{bmatrix} \sim \begin{bmatrix} -1 & -3 & 0 & 1 \\ 0 & -4 & 8 & 0 \\ 0 & 0 & 3 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Since A has 4 pivots, it is invertible.