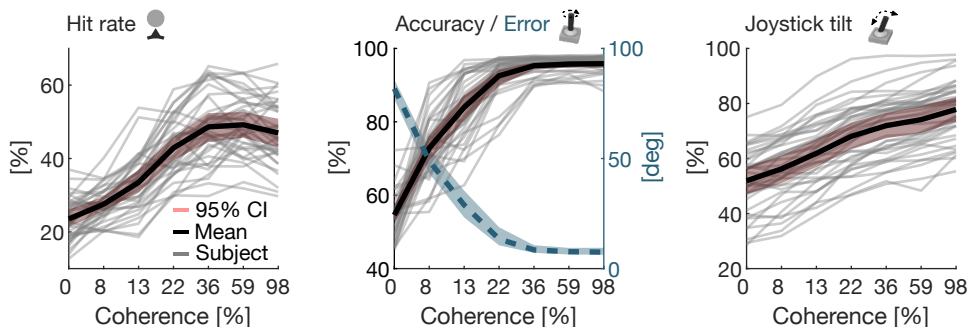
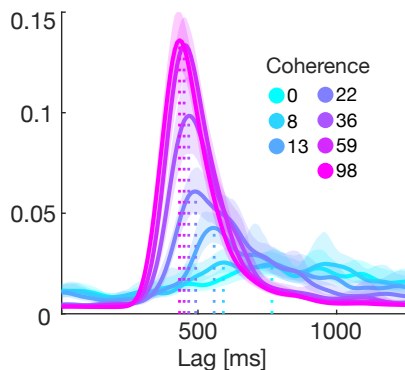


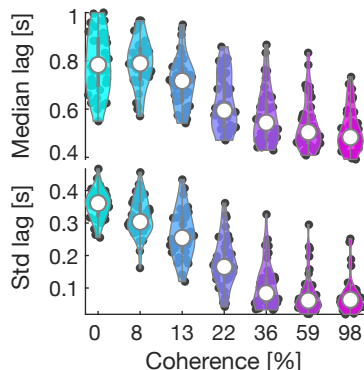
# a) Average solo behavior



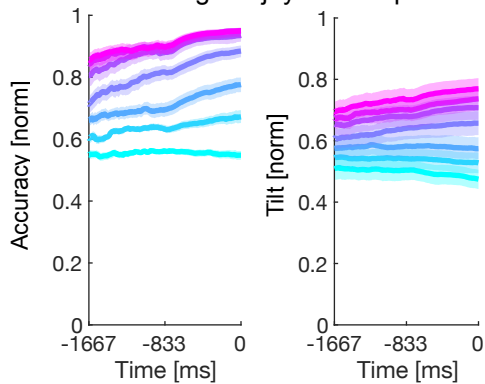
## b) Example subject: response lag



## c) Population: response lags and variability



## d) Continuous change of joystick response



## e) Changes in tilt follow changes in accuracy

