Estimating and correcting for measurement error using hidden Markov models

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October 16, 2023



Overview

- 1. Measurement error
- 2. Hidden Markov models (HMMs)
- 3. HMMs in R
- 4. HMMs in Latent Gold
- **5. Concluding remarks**

Measurement error

Definition

- Occurs when the observed/measured value differs from the true value of a variable
- Can be random (by chance) or systematic (according to some pattern)
- In categorical data referred to as misclassification

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Effects

- Can bias estimates
- Lead to incorrect research findings
- Usually, systematic error worse than random error

Sources of measurement error

Surveys

- Self-reported measures affected by cognitive processes
 - Recall bias
 - Social desirability bias
- Poor questions or questionnaire design
 - Misunderstanding, wrong interpretation
 - Respondent fatigue

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Digital trace data

- Incomplete data from tracking apps
 - Not installed on all devices
 - Temporarily switched off
- Data not representing individual usage
 - Multiple HH members using same device/accoung

Hidden Markov models (HMMs)

Background

- Latent class models used to correct for error in categorical, longitudinal data
- Do not require any data source to be error-free
- Use repeated measures of indicator(s) to extract information about the error from the data

Hidden Markov models (HMMs)

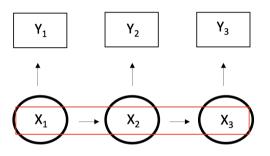
Background

- Latent class models used to correct for error in categorical, longitudinal data
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The standard HMM

- Markov assumption: true state at time t only depends on true state at time t-1
- Local independence assumption: observed state at time t only depends on true state at time t

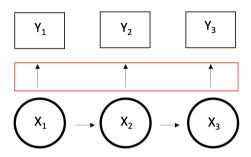
Standard HMM - Markov assumption



$$Pr(X_t = x_t | X_1 = x_1, ..., X_{t-1} = x_{t-1}) = Pr(X_t = x_t | X_{t-1} = x_{t-1})^1$$

¹where $Pr(X_t = x_t)$ denotes the probability of the latent state X_t taking on a specific value x_t out of k possible categories.

Standard HMM - local independence assumption



$$Pr(A_1 = a_1, ..., A_T = a_T | X_1 = x_1, ..., X_T = x_T) = \prod_{t=1}^T Pr(A_t = a_t | X_t = x_t)^2$$

²where $Pr(A_1 = a_1, ..., A_T = a_T)$ denotes the probability of observing a specific sequence of states, where each state $-A_1$, ..., A_T – takes on a specific value $-a_1$, ..., a_T – out of k possible categories.

Standard HMM

Full HMM

Combining the Markov and local independence assumptions leads to the following probability of observing a certain path $A = (A_1, ..., A_T)$ in the data:

$$Pr(A = a) = \sum_{x_0=1}^{k} \cdots \sum_{x_t=1}^{k} Pr(X_0 = x_0) \prod_{t=1}^{T} Pr(X_t = x_t | X_{t-1} = x_{t-1})$$

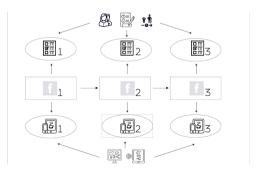
$$\prod_{t=1}^{T} Pr(A_t = a_t | X_t = x_t)$$

- $Pr(X_0 = x_0)$ represents the initial state latent probabilities
- $Pr(X_t = x_t | X_{t-1} = x_{t-1})$ represents the latent transition probabilities, which follow a Markov process
- $Pr(A_t = a_t | X_t = x_t)$ denotes the classification error (or emission) probabilities, which satisfy the local independence assumption

Extended HMMs

Multiple indicator HMMs

- Correct for error in all sources simultaneously
- Allow to relax the local independence assumption
 - Model more realistic error scenarios, e.g., systematic error



HMMs in R

Available packages

- HMM (http://CRAN.R-project.org/package=HMM)
- hmm.discnp (http://CRAN.R-project.org/ package=hmm.discnp)
- msm (https://doi.org/10.18637/jss.v038.i08)
- depmixS4 (https://doi.org/10.18637/jss.v036.i07)
- mhsmm (https://doi.org/10.18637/jss.v039.i04)
- LMest (http://CRAN.R-project.org/package=LMest)
- seqHMM (https://doi.org/10.18637/jss.v088.i03)

HMMs in R

Package limitations

- Only standard HMMs are allowed (no covariates, one indicator)
- Only continuous time processes
- Must specify starting values
- Cannot handle missing values
- Cannot properly use a three-step approach

The seqHMM package - preparing data

Data

Data tracking app

Frequency of FB use in 3 time points (3 survey waves and corresponding periods from tracking apps).

```
# Data survey
head(data.fb.wide.survey)
new.id fb.survev1
                              fb.survev2
                                                     fb.survev3
      1. several times a day
                              2.dailv
                                                     1.several times a day
      2.daily
                              2.daily
                                                     2.dailv
      2.daily
                              3.weeklv
                                                     2.daily
      5.less than monthly
                              5.less than monthly
                                                     5.less than monthly
     1.several times a day
                              2.daily
                                                   1.several times a day
```

```
head(data.fb.wide.trackig)
new.id fb.tracking1
                               fb.tracking2
                                                      fb.tracking3
      1.several times a day
                               1.several times a day 1.several times a day
      2.dailv
                               2.dailv
                                                      2.dailv
      5.less than monthly
                               5.less than monthly
                                                      5.less than monthly
      4.monthly
                               3.weeklv
                                                      4.monthly
      2.dailv
                               2.dailv
                                                       3.weeklv
```

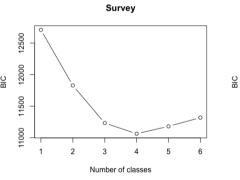
Running HMMs with varying k

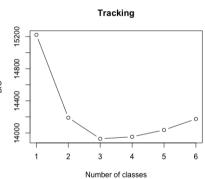
Model selection

Three criteria: model fit (BIC/AIC), class sizes, intepretative value (unless fixed cat.).

```
data.fb.seq.survey <- segdef(data.fb.wide.survey[,2:4], start=1)</pre>
results <- NA
for(i in 2:7) {
    model.class <- build.hmm(observations=data.fb.seq.survey, n.states=i)
    model.fit <- fit.model(model.class.
                            control.em=list(restart=list(times = 5)))
    results <- append(results, BIC(model.fit$model))
plot(results[-1], type="b")
data.fb.seq.tracking <- segdef(data.fb.wide.tracking[.2:4]. start=1)
results.tracking <- NA
for(i in 2:7)
    model.class.tracking <- build.hmm(observations=data.fb.seg.tracking, n.states=i)
    model.fit.tracking <- fit.model(model.class.tracking.
                             control.em=list(restart=list(times = 5)))
    results.tracking <- append(results.tracking, BIC(model.fit.tracking$model))
plot(results.tracking[-1], type="b")
```

Selecting HMM





Running selected HMM

Results selected HMM - survey data

```
$model
Initial probabilities :
         State 2 State 3 State 4
State 1
 0.323 0.207 0.164 0.306
Transition probabilities :
       State 1 State 2 State 3 State 4
State 1 0 95898 0 0000 0 0000 0 0410
State 2 0.00020 0.9134 0.0116
                                0.0748
State 3 0 00000 0 0000 1 0000 0 0000
State 4 0 03668 0 0374 0 0000 0 9259
Emission probabilities :
state names 1.several times a day 2.daily 3.weekly 4.monthly 5.less than monthly
State 1
                        0.92096 0.0754 0.0036
                                                0.00000
                                                                    0.00000
State 2
                        0.00656
                                0.0503
                                       0.8063
                                                0.13676
                                                                    0.00000
State 3
                        0.00000
                                0.0000
                                       0.0235 0.43569
                                                                    0.54079
                        0.10774 0.8260 0.0607 0.00246
                                                                    0.00308
State 4
```

Results selected HMM - survey data

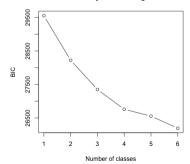
```
logLik
-5484 077
$em results
$em_results$logLik
-5484.077
$em_results$iterations
490
$em_results$change
9.926655e-11
$em_results$best_opt_restart
-5484.077 -5484.077 -5484.077 -5484.077 -5484.077
$global_results
NUILI.
$local_results
NULT.
$call
fit model (model = model 4class. control em = list(restart = list(times = 5)))
```

Results selected HMM - tracking data

```
$model
Initial probabilities :
State 1 State 2 State 3 State 4
 0.249 0.262 0.419 0.070
Transition probabilities :
      State 1 State 2 State 3 State 4
State 1 0.8930 0.0951 0.0000 0.0123
State 2 0 0352 0 9648 0 0000 0 0000
State 3 0.0114 0.0346 0.9360 0.0175
State 4 0.0000 0.0000
                      0.0300 0.9700
Emission probabilities :
state names 1.several times a day 2.daily 3.weekly 4.monthly 5.less than monthly
State 1
                       0.03431
                               0.00000 0.5538
                                                 0.2400
                                                                   0.17176
State 2
                     0 90190 0 00000 0 0898
                                                 0.0000
                                                                   0.00823
State 3
                     0.00243 0.00291 0.0354 0.1010
                                                                   0.85812
                       0.00000 0.61530 0.3664 0.0115
                                                                   0.00686
State 4
```

Running two-indicator HMM

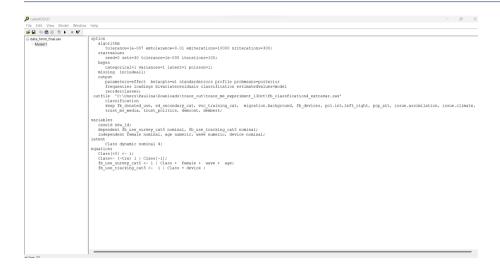
survey and tracking

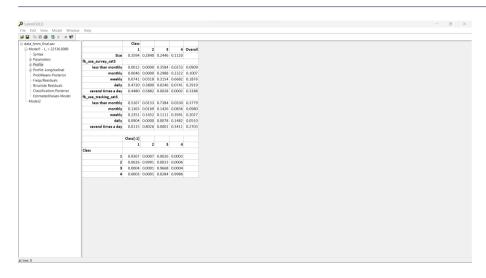


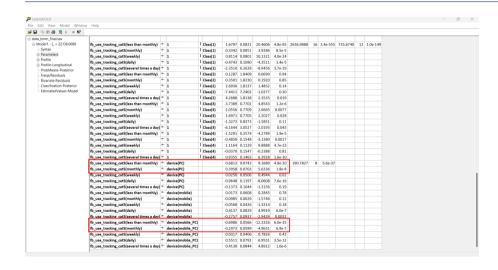
Running two-indicator HMM

Results two-indicator HMM

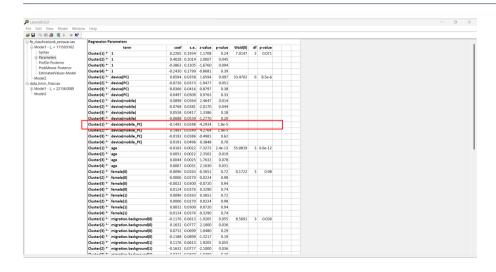
```
$model
Initial probabilities :
State 1 State 2 State 3 State 4
 0.189 0.332 0.303 0.176
Transition probabilities :
       State 1
                 State 2
                          State 3 State 4
State 1 0 99356 0 00000
                         0.00644
                                  0.0000
State 2 0.00438 0.90001
                         0.07024
                                  0.0253
State 3 0.00000 0.00298
                         0.99702
                                  0.0000
State 4 0.00000 0.00000
                         0.00000 1.0000
Emission probabilities :
Survey:
state names 1.several times a day 2.daily 3.weekly 4.monthly 5.less than monthly
State 1
                         0.0000 0.0000
                                        0.1020 0.4318
                                                                    0.4662
State 2
                        0.3560 0.3830
                                        0.2530
                                                0.0060
                                                                    0.0030
State 3
                        0.5040 0.3450
                                        0.1250
                                                0.0221
                                                                    0.0035
State 4
                        0.3250 0.3610
                                        0.2630 0.0499
                                                                    0.0014
Tracking:
state names 1.several times a day 2.daily 3.weekly 4.monthly
                                                           5.less than monthly
State 1
                        0.0018 0.0270
                                        0.1439
                                               0.1389
                                                                    0.6884
State 2
                        0.0057 0.0013
                                        0.0766
                                                0.1310
                                                                    0.7853
State 3
                        0.8196
                                0.0000
                                        0 1475
                                                 0.0173
                                                                    0.0156
                         0.0122 0.2399
                                        0 5491
                                                 0 1423
                                                                    0.0565
State 4
```

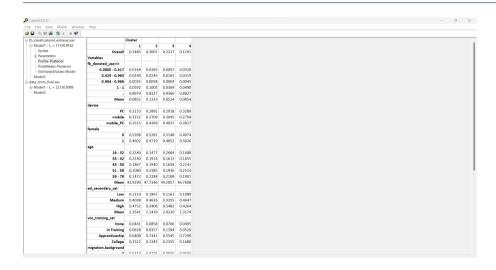












Concluding remarks

• HMMs potentially a powerful tool to correct for measurement error

But...

- Difficult to use
 - No comprehensive R packages
 - Important to know data generating process

Thank you!

