

# Generative Adversarial Networks for Social Scientists

Social Science Data Lab

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# These Cats Do Not Exist!



Figure 1: Cats from [thiscatdoesnotexist.com](http://thiscatdoesnotexist.com)

## These Persons Do Not Exist!



Figure 2: Persons from [thispersondoesnotexist.com](http://thispersondoesnotexist.com)

# These Voices Never Said These Words!

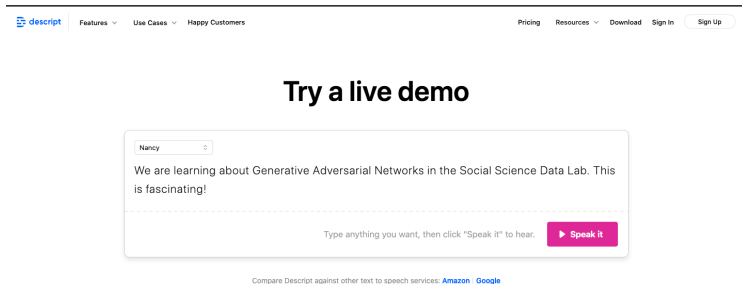


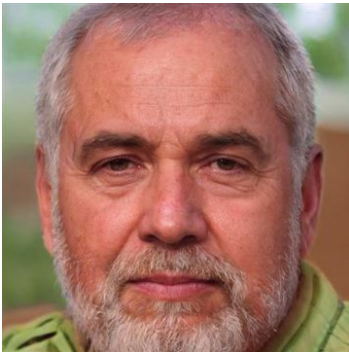
Figure 3: Voices from descript.com

Why We Should Care!

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## Fake Persons are Used to Spread Misinformation.

“How a fake persona laid the groundwork for a Hunter Biden conspiracy deluge”  
(NBC News, Oct. 29, 2020)



**Figure 4:** “ ‘Martin Aspen’, a fake identity whose profile picture was created by artificial intelligence.”

# Deep Fakes Can Make the Detection of Misinformation Really Hard.

Can we still trust audio visual sources?

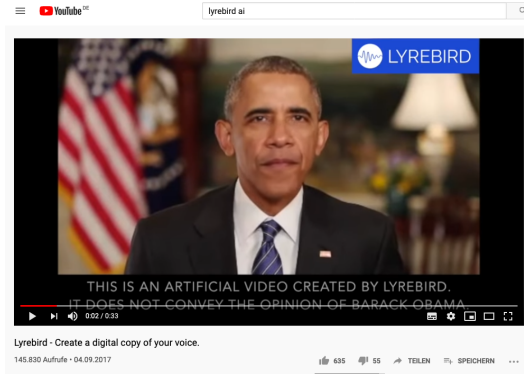


Figure 5: A Deep Fake (three years ago...).

What I will talk about today:

- GANs for Multiple Imputation.
- GANs for Small Area Estimation
- GANs for Privacy Protective Synthetic Data
- ...



## A Quick Introduction to Generative Adversarial Networks.

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# Generative Adversarial Nets Are Surprisingly Simple.

- Generative Adversarial Nets (GANs), introduced by Goodfellow et al. (2014), allow it to sample from arbitrary joint (continuous) distributions.
- At its core, a GAN is a minimax game with two competing actors—a discriminator (D) trying to tell real from synthetic samples and a generator (G) to produce realistic synthetic samples from random noise.
- Formally, this two-player minimax game can be written as:

$$\min_G \max_D \mathbb{E}_{x \sim p_X} [f(D(x))] + \mathbb{E}_{z \sim p_z} [f(1 - D(G(z)))] \quad (1)$$

where  $f: [0, 1] \rightarrow \mathbb{R}$  is a monotone function. For example, in standard GAN,  $f(a) = \log(a)$ , and in Wasserstein GAN (Arjovsky et al., 2017),  $f(a) = a$ .

$p_{data}(x)$  is the distribution of the real data,  $X$  is a sample from  $p_{data}(x)$ . The generator network  $G(z)$  takes as input  $z$  from  $p(z)$ , where  $z$  is a random sample from a probability distribution  $p(z)$ .

# Generative Adversarial Nets Are Surprisingly Simple.

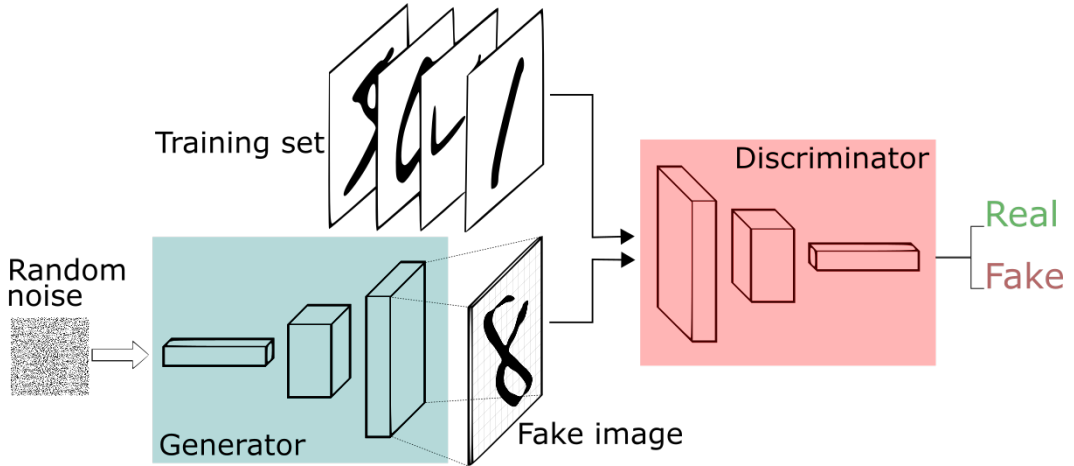


Figure 6: The architecture of a GAN. Source: Freecodecamp.org, Thalles Silva

Let's Look at Some Code.

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## Social Science Applications of GANs.

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- For imputation we only want to sample imputations for missing values from the underlying joint distribution.
- Yoon et al. (2018) and Li et al. (2019) propose a straightforward extensions to the basic GAN architecture for imputation.

# GAN Architectures for Imputation.

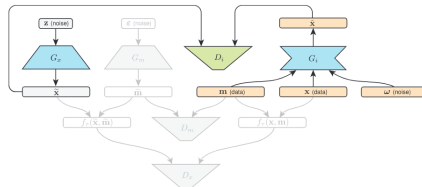
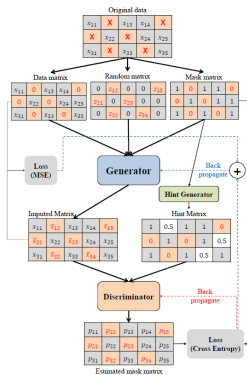


Figure 7: GAN architectures for Imputation. Left: Yoon et al., 2018, Right: Li et al., 2019.

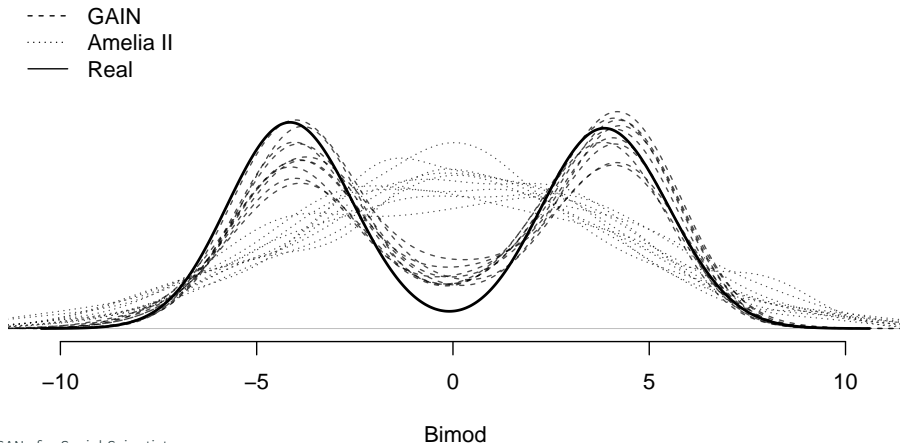
**Table 1:** Overview of one generated data set for experiment 1

Variable	Type	Missing	Description
Y	Continuous	0	Dependent Variable
X	Continuous	320	Independent Variable 1 for the regression.
Bin	Binary	317	Independent Variable 2 for the regression.
Bimod	Continuous	270	Bi-modal variable.
Categ	Unordered Categorical	271	Categorical Variable.

Y is generated by:  $Y = X + 2 \cdot \text{Bin} + 3 \cdot \text{Bin} \cdot X + \epsilon$ .



### Density of the imputed values for the bi-modal variable.



## Multiple Imputation for Small Area Estimation.

$$\left( \begin{array}{c} \text{complete survey data} \\ \text{incomplete survey data} \\ \text{Census data} \end{array} \right) \begin{array}{cccc} obs & s & d & y \\ 1 & 1 & 0 & 3 \\ 2 & 1 & 1 & 1 \\ 3 & 1 & 1 & 2 \\ 4 & 2 & 0 & 3 \\ \vdots & \vdots & \vdots & \vdots \\ n-m-2 & k & 0 & 2 \\ n-m-1 & k & 1 & 1 \\ n-m & k & 1 & 3 \\ n-m+1 & 1 & NA & 2 \\ \vdots & \vdots & \vdots & \vdots \\ n-1 & k & NA & 1 \\ n & k & NA & 3 \\ n+1 & 1 & 0 & NA \\ n+2 & 1 & 1 & NA \\ n+3 & 1 & 1 & NA \\ n+4 & 1 & 1 & NA \\ n+5 & 2 & 0 & NA \\ \vdots & \vdots & \vdots & \vdots \\ n+N-4 & k-1 & 1 & NA \\ n+N-3 & k & 0 & NA \\ n+N-2 & k & 1 & NA \\ n+N-1 & k & 1 & NA \\ n+N & k & 1 & NA \end{array} \Rightarrow \left( \begin{array}{cccc} obs & s & d & y \\ 1 & 1 & 0 & 3 \\ 2 & 1 & 1 & 1 \\ 3 & 1 & 1 & 2 \\ 4 & 2 & 0 & 3 \\ \vdots & \vdots & \vdots & \vdots \\ n-m-2 & k & 0 & 2 \\ n-m-1 & k & 1 & 1 \\ n-m & k & 1 & 3 \\ n-m+1 & 1 & 0.2 & 2 \\ \vdots & \vdots & \vdots & \vdots \\ n-1 & k & 0.9 & 1 \\ n & k & 0.8 & 3 \\ n+1 & 1 & 0 & 1.6 \\ n+2 & 1 & 1 & 2.1 \\ n+3 & 1 & 1 & 2.0 \\ n+4 & 1 & 1 & 2.2 \\ n+5 & 2 & 0 & 1.2 \\ \vdots & \vdots & \vdots & \vdots \\ n+N-4 & k-1 & 1 & 1.3 \\ n+N-3 & k & 0 & 1.9 \\ n+N-2 & k & 1 & 2.3 \\ n+N-1 & k & 1 & 2.1 \\ n+N & k & 1 & 2.2 \end{array} \right) \left. \begin{array}{l} \bar{y}_{s=1} = 1.98 \\ \bar{y}_{s=k} = 2.05 \end{array} \right\}$$

**Figure 9: Multiple Imputation for SAE.** Source: Honaker & Plutzer 2016.

# Multilevel Regression with Post-Stratification.

$$\begin{pmatrix}
 \begin{matrix} obs & s & d & y \end{matrix} \\
 \begin{matrix} 1 & 1 & 0 & 3 \\ 2 & 1 & 1 & 1 \\ 3 & 1 & 1 & 2 \\ 4 & 2 & 0 & 3 \\ \vdots & \vdots & \vdots & \vdots \\ n-m-2 & k & 0 & 2 \\ n-m-1 & k & 1 & 1 \\ n-m & k & 1 & 3 \end{matrix}
 \end{pmatrix}
 \Rightarrow
 \begin{pmatrix}
 \begin{matrix} obs & s & d & \hat{y} \end{matrix} \\
 \begin{matrix} 1 & 1 & 0 & 2.7 \\ 2 & 1 & 1 & 1.9 \\ 3 & 2 & 0 & 1.2 \\ 4 & 2 & 1 & 1.7 \\ 5 & 3 & 0 & 1.5 \\ 6 & 3 & 1 & 2.3 \\ \vdots & \vdots & \vdots & \vdots \\ 2k-3 & k-1 & 0 & 2.1 \\ 2k-2 & k-1 & 1 & 1.4 \\ 2k-1 & k & 0 & 1.9 \\ 2k & k & 1 & 2.6 \end{matrix}
 \end{pmatrix}
 \Rightarrow
 \begin{pmatrix}
 \begin{matrix} obs & s & \hat{y} & w \end{matrix} \\
 \begin{matrix} 1 & 1 & 2.7 & 4 \\ 2 & 1 & 1.9 & 7 \\ 3 & 2 & 1.2 & 3 \\ 4 & 2 & 1.7 & 9 \\ 5 & 3 & 1.5 & 3 \\ 6 & 3 & 2.3 & 6 \\ \vdots & \vdots & \vdots & \vdots \\ 2k-3 & k-1 & 2.1 & 2 \\ 2k-2 & k-1 & 1.4 & 8 \\ 2k-1 & k & 1.9 & 4 \\ 2k & k & 2.6 & 7 \\ \hline & & \sum w = N & \end{matrix}
 \end{pmatrix}
 \begin{matrix}
 \left. \begin{matrix} \\ \\ \\ \end{matrix} \right\} \bar{y}_{s=1} = 2.19 \\
 \left. \begin{matrix} \\ \\ \end{matrix} \right\} \bar{y}_{s=2} = 1.58 \\
 \left. \begin{matrix} \\ \end{matrix} \right\} \bar{y}_{s=3} = 2.03 \\
 \\ \\
 \left. \begin{matrix} \\ \end{matrix} \right\} \bar{y}_{s=k-1} = 1.40 \\
 \left. \begin{matrix} \\ \end{matrix} \right\} \bar{y}_{s=k} = 2.36
 \end{matrix}$$

Figure 10: MRP for SAE. Source: Honaker & Plutzer 2016.

## Results of GAIN for Small Area Estimation.

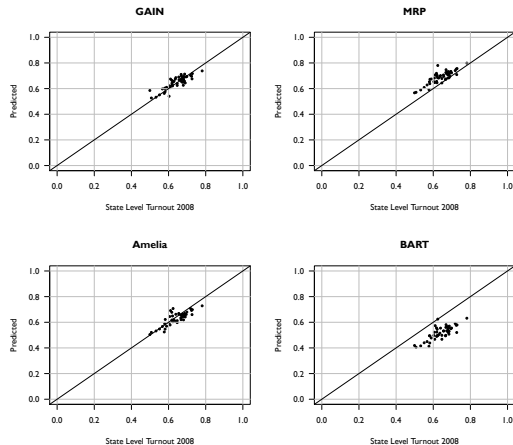


Figure 11: State Level Estimates of Turnout in the US Election 2008.

**Table 2:** RMSE and Correlation of State Level Predictions and Turnout 2008.

	RMSE	Correlation
GAIN	<b>0.0303</b>	<b>0.8514</b>
MRP	0.0561	0.8375
Amelia	0.0343	0.8286
BART	0.1280	0.7774

# Private Post-GAN Boosting for Synthetic Data. (Neunhoffer, Wu & Dwork)

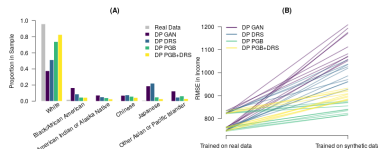
## Motivation

- A recent line of work (Beaulieu-Jones et al., 2019; Xie et al., 2018; Yoon et al., 2019) studies how one can generate synthetic data by incorporating differential privacy into *generative adversarial networks* (GANs) (Goodfellow et al., 2014).
- Due to the noise, the **convergence of GANs becomes even more elusive**. This often leads to poor utility at the end of training.
- We propose *Private post-GAN boosting* (*Private PGB*), a differentially private method that **combines samples produced by the sequence of generators** during GAN training to create a **high-quality synthetic dataset**.
- We leverage the **Private Multiplicative Weights method** (Hardt & Rothblum, 2010; Hardt et al., 2012) to reweight generated samples.

## Results



- Real samples from 25 multivariate normal distributions, synthetic examples without privacy from a GAN and Non-Private PGB, and synthetic examples from a GAN with differential privacy and Private PGB.



- Specific Utility of Synthetic 1940 American Census Data. Panel (A): Distribution of Race Membership in Synthetic Samples. Panel (B): Regression RMSE with Synthetic Samples.

## Algorithm

**Require:** a private dataset  $X \in \mathcal{X}^n$ , a synthetic dataset  $B$  generated by the set of generators  $\mathcal{G}$ , a collection of discriminators  $\{D_1, \dots, D_N\}$ , number of iterations  $T$ , per-round privacy budget  $\epsilon_0$ , learning rate parameter  $\eta$ .

**Initialize**  $\phi^1$  to be the uniform distribution over  $B$

**for**  $t = 1, \dots, T$  **do**

**Distinguisher player:** Run exponential mechanism  $\mathcal{M}_E$  to select a discriminator  $D^t$  using quality score  $q(X, D_j) = U(\phi^t, D_j)$  and privacy parameter  $\epsilon_0$ .

**Synthetic data player:** Multiplicative weights update on the distribution over  $B$ : for each example  $b \in B$ :

$$\phi^{t+1}(b) \propto \phi^t(b) \exp(\eta D^t(b))$$

Let  $\bar{D}$  be the discriminator defined by the uniform average over the set  $\{D^1, \dots, D^T\}$ , and  $\bar{\phi}$  be the distribution defined by the average over the set  $\{\phi^1, \dots, \phi^T\}$

Thank you for your attention!

Any Questions?



## References

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