

**MINISTRY OF EDUCATION**  
**MANDALAY TECHNOLOGICAL UNIVERSITY**  
**Department of Mechatronic Engineering**  
**2017-2018 Academic Year**

**Fourth Year**

**Second Semester Examination**

**Date: 26.9.2018(TUE)**

**Time: 9:00 to 12:00 noon**

II. Solution & Marking of McE.42077 (Control Engineering II)

Ques No.	Solution	
1.(a.)	<p>Solution: The closed-loop transfer function is</p> $\phi(s) = \frac{G(s)}{1 + G(s)} = \frac{5K_A}{s^2 + 34.5s + 5K_A}$ $K_A = 200, \therefore \phi(s) = \frac{1000}{s^2 + 34.5s + 1000}$ $\therefore \omega_n^2 = 1000, \quad 2\zeta\omega_n = 34.5$ $\therefore \omega_n = 31.6(\text{rad} / \text{s}), \zeta = \frac{34.5}{2\omega_n} = 0.545$ $t_p = \frac{\pi}{\omega_n \sqrt{1 - \zeta^2}} = 0.12(\text{sec})$ $t_s \approx \frac{3}{\zeta\omega_n} = 0.174(\text{sec})$ $\sigma\% = e^{-\pi\zeta / \sqrt{1 - \zeta^2}} \times 100\% = 13\%$	3 Marks
	<p>If <math>K_A = 200</math>, then <math>\omega_n = 34.5(\text{rad} / \text{s})</math>; <math>\zeta = 0.545</math></p> <p><math>\therefore t_p = 0.12(\text{s})</math>, <span style="border: 1px solid black; padding: 2px;"><math>t_s = 0.23\text{s}</math></span>, <math>\sigma\% = 13\%</math></p>	
	<p>If <math>K_A = 1500</math>, then <math>\omega_n = 86.2(\text{rad} / \text{s})</math>; <math>\zeta = 0.2</math></p> <p><math>\therefore t_p = 0.037(\text{s})</math>, <span style="border: 1px solid black; padding: 2px;"><math>t_s = 0.23\text{s}</math></span>, <math>\sigma\% = 52.7\%</math></p>	3 Marks
	<p>Thus, the greater the <math>K_A</math>, the less the <math>\zeta</math>, the greater the <math>\omega_n</math>, the less the <math>t_p</math>, the greater the <math>\sigma\%</math>, while the settling time <math>t_s</math> has no change.</p>	
	<p><math>K_A = 13.5</math></p> <p>When <math>K_A = 13.5</math>, <math>\omega_n = 8.22(\text{rad} / \text{s})</math>, <math>\zeta = 2.1</math></p>	3 Marks
	<p><math>\zeta &gt; 1</math> , Overdamped</p>	
	<p>When system is over-damped, there is no peak time, overshoot and oscillation.</p>	1 Mark

When  $K_A$  increases,  $t_p$  decreases,  $t_r$  decreases, the speed of response increases, meanwhile, the overshoot increases.

1.(b.) For a zero steady-state error:

(a.) when the input is a step, one integration is needed,  
or a type 1 system.

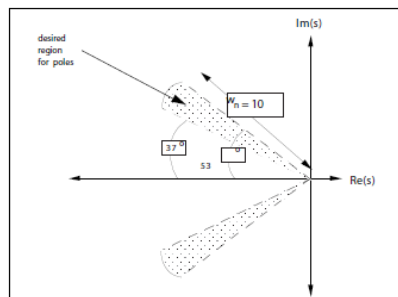
3 Mark

(b.) A type 2 system is required for  $e_{ss} = 0$  for a ramp input.

2 Mark

1.(c.)

i.  $0.6 \leq \zeta \leq 0.8$ ,  $\omega_n \leq 10$  ,  
 $\zeta = 0.6$ ,  $\theta = 53.13^\circ$        $\zeta = 0.8$ ,  $\theta = 36.87^\circ$

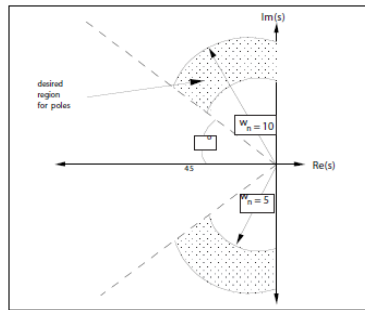


2 Marks

ii.  $\zeta \leq 0.707$  ,  $5 \leq \omega_n \leq 10$ ,

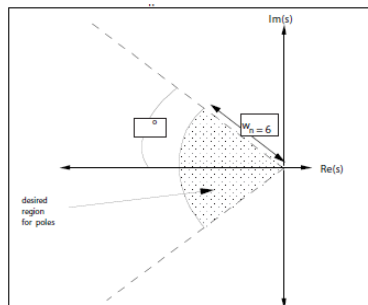
$\zeta = 0.707$ ,  $\theta = 45^\circ$        $\zeta = 0.8$ ,  $\theta = 36.87^\circ$

1.5 marks



iii.  $\zeta \geq 0.6$  ,  $\omega_n \leq 0.6$ ,  
 $\zeta = 0.6$ ,  $\theta = 53.13^\circ$

1.5 marks



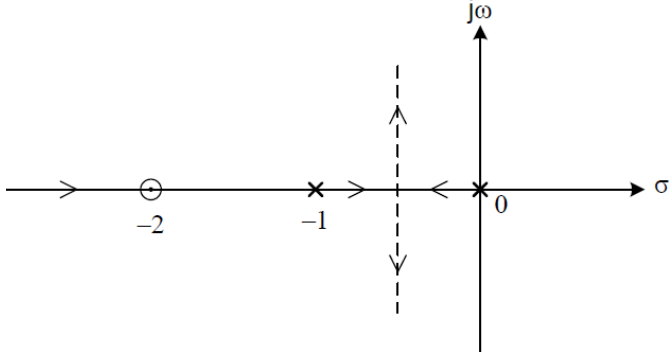
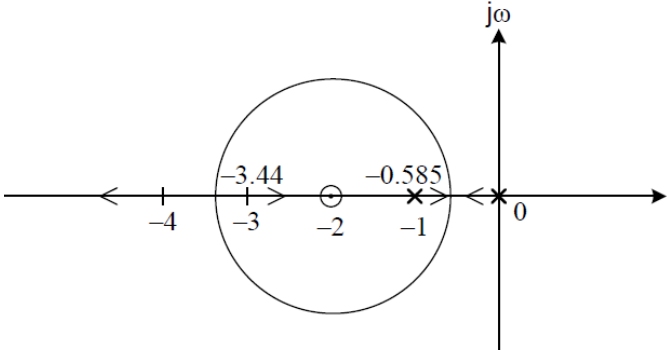
Ques No	Solution	Marks
2.	<p style="text-align: center;"><math>P.O \leq 10 \%</math></p> $100 e^{-\pi\zeta/\sqrt{1-\zeta^2}} \leq 10$ $e^{-\pi\zeta/\sqrt{1-\zeta^2}} \leq 0.1$ $\frac{-\pi\zeta}{\sqrt{1-\zeta^2}} \leq \ln 0.1$ $\frac{-\pi\zeta}{\sqrt{1-\zeta^2}} \leq -2.302583$ $\frac{\pi\zeta}{\sqrt{1-\zeta^2}} \geq 2.302583$ <p style="text-align: center;">Squaring both sides,</p> $\frac{\pi^2\zeta^2}{1-\zeta^2} \geq 5.301898$ $1.8615\zeta^2 \geq 1-\zeta^2$ $2.8615\zeta^2 \geq 1$ $\zeta \geq 0.59$ $T(s) = \frac{12K}{s^2+12s+12K}$ <p>Compare with,</p> $T(s) = \frac{\omega_n^2}{s^2+2\zeta\omega_n s+\omega_n^2}$ $2\zeta\omega_n = 12$ $\zeta\omega_n = 6$ $\omega_n = 10.169$ $\omega_n^2 = 12K$ $K = \frac{\omega_n^2}{12} = 8.6$ <p>(b.) <math>K=10, S_K^T=?</math></p> $S_K^T = \frac{\partial T}{\partial K} \times \frac{K}{T}$ $S_K^T = \frac{\partial}{\partial K} \left[ \frac{12K}{s^2+12s+12K} \right] \times \frac{K}{\left[ \frac{12K}{s^2+12s+12K} \right]}$	<p style="text-align: center;">3 Marks</p> <p style="text-align: center;">2 Marks</p>

Ques No	Solution	Marks
2.	$= \frac{12s^2 + 144s + 144K - 144K}{s^2 + 12s + 12K} \times \frac{1}{12}$ $S_K^T = \frac{s^2 + 12s}{s^2 + 12s + 12K}$ $S_K^T = \frac{s(s + 12)}{s(s + 12) + 12K}$ $= \frac{s(s + 12)}{s(s + 12) + 120}$ <p>(c.) <math>s=0, S_K^T = ?</math></p> $S_K^T = \frac{s(s + 12)}{s(s + 12) + 120} = \frac{0}{120} = 0$ <p>(d.) <math>\frac{60 \text{ beats}}{\text{minute}} = \frac{60 \text{ beats}}{60 \text{ secs}} = \frac{1 \text{ beat}}{1 \text{ sec}} = j2\pi</math></p> $S_K^T (j2\pi) = ?$ $s = j2\pi \times \frac{1 \text{ beat}}{1 \text{ sec}} = j2\pi$ $S_K^T = \frac{s(s + 12)}{s(s + 12) + 120}$ $S_K^T = \frac{j2\pi (j2\pi + 12)}{j2\pi (j2\pi + 12) + 120}$ $S_K^T = \frac{j2\pi (j2\pi + 12)}{j2\pi (j2\pi + 12) + 120}$ $= \frac{-39.478 + j 75.398}{-39.478 + j 75.398 + 120}$ $S_K^T = \frac{-39.478 + j 75.398}{80.522 + j 75.398}$ $= \frac{85.11 \angle 117.6}{110 \angle 43.12} = 0.771 \angle 74.48$ $S_K^T = 0.771$	<p>5 Marks</p> <p>2 Marks</p> <p>1 Mark</p> <p>1 Mark</p> <p>6 Marks</p>

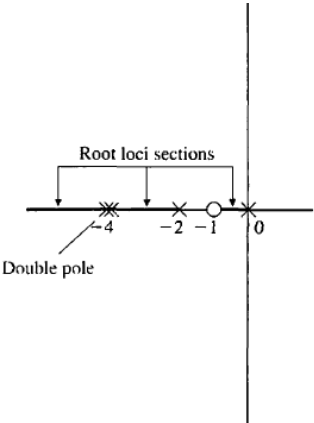
3.	$G(s) = \frac{K(s+2)}{(s+10)} \times \frac{1}{s(s-1)}, H(s) = 1$ $= \frac{K(s+2)}{(s+10)(s-1)s}$ <p>(a.) Characteristics Equation,</p> $1 + H(s)G(s) = 0$ $1 + \frac{K(s+2)}{(s+10)(s-1)s} = 0$ $\frac{(s+10)(s-1)s + K(s+2)}{(s+10)(s-1)s} = 0$ $(s+10)(s-1)s + K(s+2) = 0$ $s^3 + 9s^2 - 10s + Ks + 2K = 0$ <p>Using Routh-hurwitz,</p> <table border="0" style="margin-left: 40px;"> <tr> <td><math>S^3</math></td><td>1</td><td>K-10</td></tr> <tr> <td><math>S^2</math></td><td>9</td><td>2K</td></tr> <tr> <td><math>S^1</math></td><td><math>\frac{9K-90-2K}{9}</math></td><td>0</td></tr> <tr> <td><math>S^0</math></td><td>2K</td><td>0</td></tr> </table> <p>For the system to be stable,</p> $\frac{7K-90}{9} > 0$ $7K - 90 > 0$ $K > \frac{90}{7}$ $2K > 0$ $K > 0$ <p>(b.) When <math>K = \frac{90}{7}</math></p> <p>The system is marginally stable,</p> <p><math>S^2</math> row ..... <math>q(s) = 9s^2 + 2K = 0</math></p> $9s^2 + 2\left(\frac{90}{7}\right) = 0$ $9s^2 = -\frac{180}{7}$	$S^3$	1	K-10	$S^2$	9	2K	$S^1$	$\frac{9K-90-2K}{9}$	0	$S^0$	2K	0	<p>2 Marks</p> <p>3 Marks</p> <p>4 Marks</p> <p>4 Marks</p> <p>5 Marks</p>
$S^3$	1	K-10												
$S^2$	9	2K												
$S^1$	$\frac{9K-90-2K}{9}$	0												
$S^0$	2K	0												



Ques N0	Solution	Marks
4.	<p>(i) Breakaway point , <math>s = -0.59</math></p> <p>(ii) Entry point , <math>s = -3.414</math></p> <p>(b) <math>K = ?</math> , <math>s = ?</math> at real part = -2</p> <p><math>1 + KG(s) = 0</math></p> $1 + \frac{K(s+2)}{s(s+1)} = 0$ <p>Compare with <math>as^2 + bs + c = 0</math></p> $s = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a} , a = 1 , b = K+1 , c = 2K$ $s = \frac{-(K+1) \pm \sqrt{(K+1)^2 - 4(1)(2K)}}{2 \times 1}$ $s = \frac{-(K+1)}{2} \pm \frac{\sqrt{(K+1)^2 - 4(1)(2K)}}{2}$ $\frac{-(K+1)}{2} = -2$ <p><math>K = 3</math></p> <p>When <math>K = 3</math> ,</p> $s^2 + (K+1)s + 2K = 0$ $s^2 + 4s + 6 = 0$ $s = -2 \pm j1.44$ <p>The roots are <math>s = -2 + j1.44</math> and <math>s = -2 - j1.44</math> .</p> <p>(b.) Sketch the root,</p> <p><math>1 + KG(s) = 0</math></p> $1 + \frac{K(s+2)}{s(s+1)} = 0$	

Ques N0	Solution	Marks
4.	<p> <math display="block">1 + \frac{K(s+2)}{s(s+1)} = 0</math> <math display="block">s(s+1) + K(s+2) = 0</math> <math display="block">n_p = 2, s = 0, s = -1</math> <math display="block">n_z = 1, s = -2</math> </p>  <p>             Segments are <math>s = 0</math> and <math>s = -1</math>  <math>s = -2</math> and <math>s = -\infty</math> </p> <p>no of Separate root loci, <math>n_p = 2</math></p> <p>The root loci are symmetric with respect to the real axis</p> <p>Center of Asymptotes,</p> $\phi_A = \frac{2q+1}{n_p + n_z} \times 180^\circ, q = n - m - 1 = 2 - 1 - 1 = 0$ <p>When <math>q = 0</math>, <math>\phi_A = \frac{2(0)+1}{2-1} \times 180^\circ = 180^\circ</math></p> <p>Breakaway point, <math>s = -0.59, -3.414</math></p> 	



Ques N0	Solution	Marks
5.(a.)	<p>The characteristic equation is,</p> $1 + GH(s) = 1 + \frac{K(s + 1)}{s(s + 2)(s + 4)^2}.$ $1 + GH(s) = 1 + \frac{K(s + 1)}{s(s + 2)(s + 4)^2} = 0$ <p>When <math>K = 0</math>, the pole at <math>s = 0, s = -2, s = -4, s = -4</math>  <math>\therefore n_p = 4</math></p> <p>When <math>K = \infty</math>, the zeros at <math>s = -1</math>,  <math>\therefore n_z = 1</math></p>  <p>No of separate loci, <math>SL = n_p = 4, n=4, M=1</math></p> <p>The root loci are symmetric with respect to horizontal real axis.</p> <p>The segment of Root Locus has at <math>s=0</math> and <math>s=-1, s=-2</math> and <math>s=-4</math>,  <math>s=-4</math> and <math>\infty</math></p> <p>Angle of Asymptotes,</p> $\phi_A = \frac{2q+1}{n_p - n_z} \times 180^\circ, \quad q = n - m - 1 = 4 - 1 - 1 = 2$ <div style="display: flex; align-items: center; margin-top: 10px;"> <div style="border: 1px solid black; padding: 5px; margin-right: 10px;"> <p>When <math>q = 0,</math>  <math>q = 1,</math>  <math>q = 1,</math></p> </div> <div> <p><math>\phi_A = +60^\circ \quad (k = 0),</math>  <math>\phi_A = 180^\circ \quad (k = 1), \text{ and}</math>  <math>\phi_A = 300^\circ \quad (k = 2),</math></p> </div> </div> <p>Centre of Asymptotes,</p> $\sigma_A = \frac{\sum(-p) - \sum(-z)}{n_p - n_z}$	10 Marks

$$\sigma_A = \frac{(-2) + 2(-4) - (-1)}{4 - 1} = \frac{-9}{3} = -3.$$

Characteristics Equation is,

$$s(s+2)(s+4)^2 + K(s+1) = 0$$

$$(s^2+2s)(s+4)^2 + K(s+1) = 0$$

$$(s^2+2s)(s^2+8s+16) + K(s+1) = 0$$

$$s^4+10s^3+32s^2+(K+32)s+K=0$$

By applying the Routh-Hurwitz criterion,

$s^4$	1	32	K
$s^3$	10	K+32	0
$s^2$	$\frac{288-K}{10}$	K	0
$s^1$	$\frac{9216+156K-K^2}{288-K}$	0	0
$s^0$	K	0	0

The system to be stable,

$$\frac{9216 + 156K - K^2}{288 - K} = 0$$

$$9216 + 156K - K^2 = 0$$

$$K = 201.7 \quad \text{or} \quad K = -45.7 \quad (\text{impossible})$$

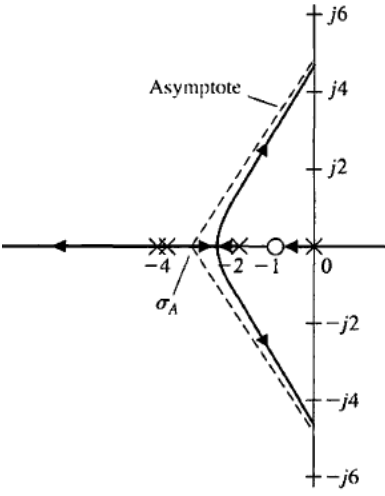
$$\frac{288-K}{10} s^2 + K = 0$$

When  $K = 201.7$ ,

$$\frac{288-201.7}{10} s^2 + 201.7 = 0$$

$$s = \pm j 4.83$$

$$G(s) = \frac{K}{(s+2)(s+4)}, \quad 1 + G(s) = 1 + \frac{K}{(s+2)(s+4)} = 0.$$

	<p>Breakaway point,</p> $1 + GH(s) = 1 + \frac{K(s + 1)}{s(s + 2)(s + 4)^2}$ $K = \frac{-[s^4 + 10s^3 + 32s^2 + 32s]}{s + 1}$ $\frac{dK}{ds} = \frac{d}{ds} \frac{-[s^4 + 10s^3 + 32s^2 + 32s]}{s + 1}$ <p>Breakaway point = - 2.6</p> 	<p>10 Marks</p>
<p>5.(b.)</p>	<p><math>K = ?</math>, <math>H(s) = 1</math></p> $G(s) = \frac{K(s + 20)}{s(s + 10)^2}$ <p>The characteristic equation,</p> $1 + G(s)H(s) = 0$ $1 + \frac{K(s + 20)}{s(s + 10)^2} = 0$ $s(s + 10)^2 + K(s + 20) = 0$ $s(s + 10)^2 + Ks + 20K = 0$ $s(s^2 + 100 + 20s) + Ks + 20K = 0$ $s^3 + 20s^2 + s(100 + K) + 20K = 0$	

	<p>Using the Routh-Hurwith Criterion,</p> $\begin{array}{ccc} S^3 & 1 & (100+K) \\ S^2 & 20 & 20K \\ S^1 & \frac{20K+2000-20K}{20} = 100 & 0 \\ S^0 & 20K & \end{array}$ <p>For the system to bestable,</p> $20K > 0$ $K > 0$	
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