# SMT Encoding of Maximal Causual Model for Race Detection

#### 1 SMT Encoding of Maximal Causal Model

$$\Phi_{\tau} = \Phi_{mhb} \wedge \Phi_{lock} \wedge \bigwedge_{e \in \tau} \Phi_{e} \tag{1}$$

where:

 $\tau = \text{trace of events}$ 

 $\Phi_{mhb} = \text{intra-thread program order}$  and inter-thread synchronization constraints

 $\Phi_{lock} = \text{lock}$  mutual exclusion constraint

 $\Phi_e$  = feasibility constraint of event e

$$\Phi_e = (O_e > M) \vee \Phi_e^{conc} \vee (\Phi_e^{abs} \wedge O_{next(e)} > M)$$
 (2)

where:

 $O_e$  = order variable of event e

M =order variable representing infinity

 $\Phi_e^{conc} = \text{concrete feasitibility constraint of event } e$ 

 $\Phi_e^{abs} = \text{data-abstract feasitibility constraint of event } e$ 

next(e) = event that immediately follows e within the thread

$$\Phi_e^{abs} = \bigwedge_{r \in dep(e)} \Phi_r^{conc} \tag{3}$$

where:

dep(e) = all read events that precede event e within the thread

$$\Phi_e^{conc} = \begin{cases}
\Phi_e^{abs} & \text{if } op(e) \neq read \\
\Phi_e^{abs} \wedge \Phi_e^{sc} & \text{if } op(e) = read.
\end{cases}$$
(4)

where:

 $\Phi_e^{sc} = {\rm read}$  value observability constraint under sequential consistency memory model

$$\Phi_r^{sc} = \left(initVal(x) = v \wedge \bigwedge_{w \in W_-^x} O_w > O_r\right) \vee$$

$$\bigvee_{w \in W_v^x} \left(\Phi_w^{conc} \wedge O_r > O_w \wedge \bigwedge_{\substack{w' \in W_-^x \\ w \neq w^{\bar{f}}}} (O_{w'} > O_r \vee O_{w'} < O_w)\right), \quad (5)$$
if  $r = (read, x, v, tid)$ 

where:

initVal(x) = initial value stored in memory location x  $W_v^x = \text{set of write events that write value } v \text{ to memory location } x$ 

Note: initVal(x) is known upfront at the time when the formula is built so initVal(x) = v does not appear in the implementation. And the problem stays in the "boolean formula over partial-orders" fragment.

### 2 Optimizations

#### 2.1 Simplify $\Phi_e^{abs}$

$$\Phi_e^{abs} = \bigwedge_{r \in dep(e)} \Phi_r^{conc} = \begin{cases} true & \text{if } dep(e) = \varnothing \\ \Phi_{lastRead(e)}^{conc} & otherwise. \end{cases}$$
 (6)

where:

lastRead(e) = last read event that precedes event e within the thread

## 2.2 Simplify $\bigwedge_{e \in \tau} \Phi_e$

$$\bigwedge_{e \in \tau} \Phi_e = \bigwedge_{\substack{e \in \tau, \\ op(e) = read}} \Phi_e$$
(7)

*Proof sketch:* If  $lastRead(w) = \bot$ , then  $\Phi_w = true$ . Otherwise,  $\Phi_w = (O_w > M) \lor (O_w < M \land \Phi_{lastRead(e)}^{conc})$  and  $\Phi_{lastRead(w)} \Longrightarrow \Phi_w$ . Therefore,  $\Phi_w$  is always redundant.

### 3 SMT Encoding of Race Condition

$$\Phi_{cop(e_1, e_2)} = (O_{e_1} = O_{e_2} < M) \tag{8}$$

where:

 $cop(e_1, e_2) = conflicting pair consisting of event <math>e_1$  and  $e_2$