

Introduction

Events and message queues present us ample room to create asynchronous systems that effectively are *reactionary* by nature. For numerous problems this approach presents an ideal solution, however when creating these systems *internal* knowledge of the events used as well as access to the relevant message queue is paramount. In this lecture we will inspect two different design approaches that try and lower the coupling between *sender* and *receiver*. In the first design the *sender* knows who it wants to send its event to, whereas in the second design it *does not care*. Secondly, in order to design/implement these two solutions 3 specific design patterns are named and used.

Content and reflection

Themes

- Message Designs
 - Specific receiver design[1]
 - Broadcasting design[1]
- GOF Design patterns
 - Singleton pattern[2][1]
 - Observer pattern[3][1]
 - Mediator pattern[4][1]
- Fundamental variable info
 - Static members in C++[5]

Do note that the two designs described in the slides can ONLY be found IN SAID slides - thus the slides are extremely important!

Questions

- Designs
 - Specific receiver
 - * Which classes are involved and how
 - * What is it that a *sender* needs to know to send an event to a *receiver*
 - * In what way does this design reduce coupling
 - * Which design patterns take part
 - Broadcast - receiver is *irrelevant*
 - * Which classes are involved and how
 - * What is it that a *sender* needs to know to send an event to a *receiver*
 - * Which design patterns take part
 - * *LOCAL* and *GLOBAL* IDs - what's this - *VERY IMPORTANT* to understand these two concepts

- Patterns
 - Singleton
 - * What is the concept behind it
 - * From an implementation point of view, how is this achieved
 - Observer
 - * What is the concept behind it
 - * How do the classes involved interact
 - * What is the difference between *observer* & *publisher/subscriber* (last part requires a google search)
 - Mediator
 - * What is the concept behind it
 - * How do the classes involved interact conceptually

Material

Slides

- [1] S. Hansen, *A message system*, Slides - see course repos.

Local repository

- [2] R. J. Erich Gamma Richard Helm and J. Vlissides, *Gof singleton pattern*, Chapter, From the GOF book, found in <https://redweb.ece.au.dk/courses/projects/sw3isu/repository>, 1994.
- [3] R. J. Erich Gamma Richard Helm and J. Vlissides, *Gof observer pattern*, Chapter, From the GOF book, found in <https://redweb.ece.au.dk/courses/projects/sw3isu/repository>, 1994.
- [4] R. J. Erich Gamma Richard Helm and J. Vlissides, *Gof mediator pattern*, Chapter, From the GOF book, found in <https://redweb.ece.au.dk/courses/projects/sw3isu/repository>, 1994.

Online

- [5] Alex. "Static member variables." (), [Online]. Available: <http://www.learncpp.com/cpp-tutorial/811-static-member-variables>.