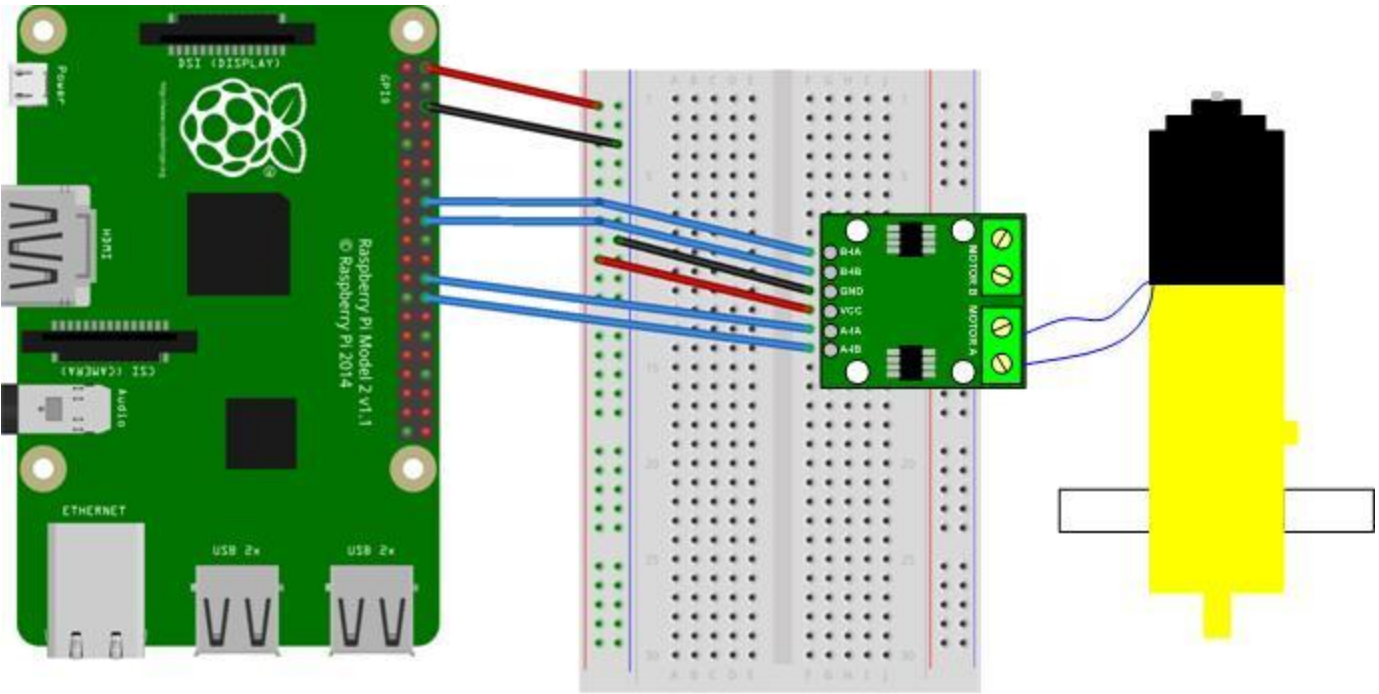


# Controlling Motors



# Let's get programming

