## Testing with Docker

Tom Buskens June 22, 2019

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## 1 Docker CI

In our repositories we wanted to use a CI tool to build our docker images with an automated test build. To accomplish this we used the GitLab CI/CD Runners running in a docker image. Because we wanted to use the docker build tools we need to run the dind image, which stands for Docker in Docker. This environment is totally save and you cannot access the host docker system because the runners are not running in a privileged environment but still using the host docker socket. When this is all setup, we can begin using our runner and continue creating our CI file.

```
Running with gitlab-runner 11.11.2 (ac2a293c)

on Shared-01 P-JLjMku

ERROR: Preparation failed: Cannot connect to the Docker daemon at unix:///var/run/docker.sock. Is the docker daemon running?
(executor_docker.go:969:08)

Will be retried in 3s ...

ERROR: Preparation failed: Cannot connect to the Docker daemon at unix:///var/run/docker.sock. Is the docker daemon running?
(executor_docker.go:969:08)

Will be retried in 3s ...

ERROR: Preparation failed: Cannot connect to the Docker daemon at unix:///var/run/docker.sock. Is the docker daemon running?
(executor_docker.go:969:08)

Will be retried in 3s ...

ERROR: Job failed (system failure): Cannot connect to the Docker daemon at unix:///var/run/docker.sock. Is the docker daemon running?
(executor_docker.go:969:08)
```

Figure 1: Running the Gitlab Runner without the Docker socket mounted.

Figure 2: The correct docker-compose.yml setup for the Gitlab Runner.

## 2 Docker build

Now we have setup our Gitlab Runner, we can use this to build our custom docker images with. To do this we need to create a .gitlab-ci.yml which contains the docker commands to run the test. First we build the image and if you want to, you can create a script to test the features of your image. This is something we didn't implement yet because all of our images are build for an Raspberry Pi, but the VPS server containing the Gitlab Runner is using a AMD64 processer and doesn't have the ina sensor, so we can not run the Raspberry Pi image.

```
image: docker:stable

variables:
    # For non-Kubernetes executors, we use tcp://docker:2375/
    DOCKER_HOST: tcp://docker:2375/
    # When using dind, it's wise to use the overlayfs driver for
    # improved performance.
    DOCKER_DRIVER: overlay2

services:
    - docker:dind

before_script:
    - docker info

build:
    stage: build
    script:
    - docker build -t registry.twizzel.net/hva/sfs-power-monitoring/prometheus-powermeter-build .
    - docker ps
```

Figure 3: Our .gitlab-ci.yml to build and run the image.

```
$ docker build -t registry.twizzel.net/hva/sfs-power-
monitoring/prometheus-powermeter-build .
Sending build context to Docker daemon 69.12kB
Step 1/12 : FROM arm32v7/python:3.6-slim-stretch
3.6-slim-stretch: Pulling from arm32v7/python
5155b41fe73a: Pulling fs layer
5d431f802675: Pulling fs layer
f65f7c6b7d6d: Pulling fs layer
c384daa176c5: Pulling fs layer
f7633e7e4d6c: Pulling fs layer
c384daa176c5: Waiting
f7633e7e4d6c: Waiting
5d431f802675: Verifying Checksum
5d431f802675: Download complete
5155b41fe73a: Download complete
c384daa176c5: Verifying Checksum
c384daa176c5: Download complete
f65f7c6b7d6d: Verifying Checksum
f65f7c6b7d6d: Download complete
f7633e7e4d6c: Verifying Checksum
f7633e7e4d6c: Download complete
5155b41fe73a: Pull complete
5d431f802675: Pull complete
f65f7c6b7d6d: Pull complete
c384daa176c5: Pull complete
f7633e7e4d6c: Pull complete
Digest:
sha256:9a8ad0bfefd822d21a26abcc44271e08dbf8d3e57567da582212c9d92a350f1d
Status: Downloaded newer image for arm32v7/python:3.6-slim-stretch
---> 63aeec0788cd
Step 2/12 : MAINTAINER Tom Buskens <t.buskens@twizzel.net>
 ---> Running in Ocellfa73144
Removing intermediate container Ocellfa73144
---> bb0c2c7cfc93
Step 3/12 : RUN apt-get update -y
---> Running in 486d960fd77a
```

Figure 4: First build of our prometheus-powermeter image.

```
$ docker run registry.twizzel.net/hva/sfs-power-monitoring/prometheus-
powermeter-build
Traceback (most recent call last):
  File "metric_ina.py", line 61, in <module>
    inamodule = INA219(0.1, 2.0)
  File "/usr/local/lib/python3.6/site-packages/ina219.py", line 106, in
init
    self._i2c = I2C.get_i2c_device(address=address, busnum=busnum)
  File "/usr/local/lib/python3.6/site-packages/Adafruit_GPI0/I2C.py",
line 63, in get_i2c_device
    busnum = get_default_bus()
  File "/usr/local/lib/python3.6/site-packages/Adafruit_GPI0/I2C.py",
line 55, in get default bus
    raise RuntimeError('Could not determine default I2C bus for
platform.')
RuntimeError: Could not determine default I2C bus for platform.
ERROR: Job failed: exit code 1
```

Figure 5: Docker run works but fails because of a missing I2C bus.