Medical Image Computing

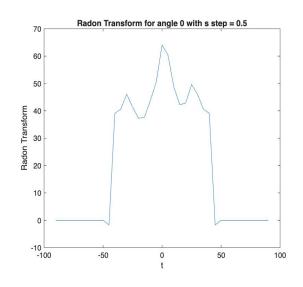
Assignment 2

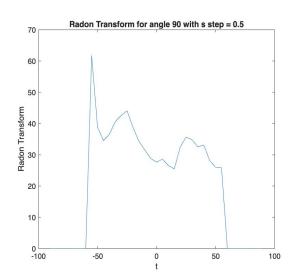
Shreyas Grampurohit (21D070029) Soham Nivargi (21D070074)

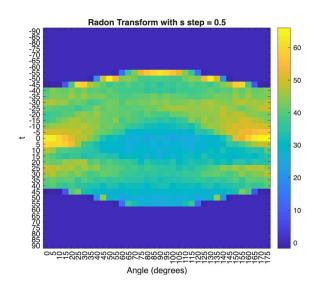
Q1 - X-Ray Computed Tomography: Radon Transform

ds <= 1, nyquist criterion

Step size = 0.5



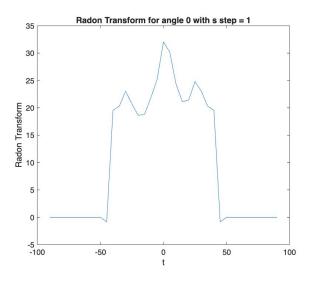


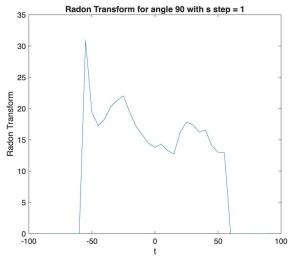


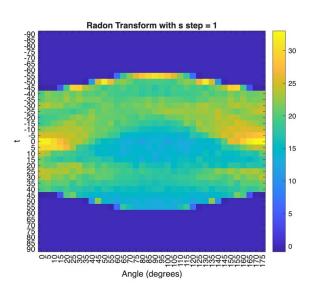
bicubic interpolation. uses large neighbourhood – so deals better with rough images

Q1 - X-Ray Computed Tomography: Radon Transform

Step size = 1

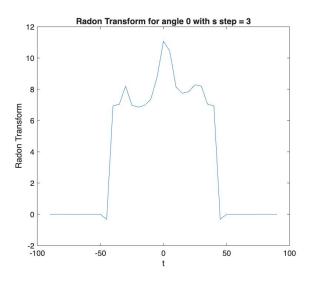


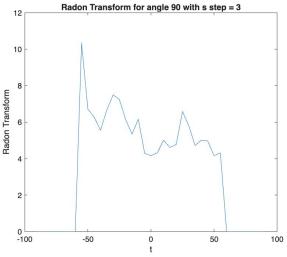


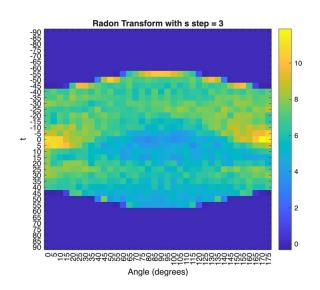


Q1 - X-Ray Computed Tomography: Radon Transform

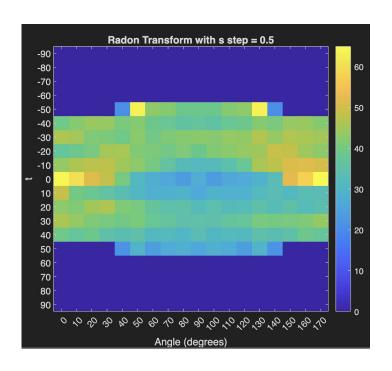
Step size = 3







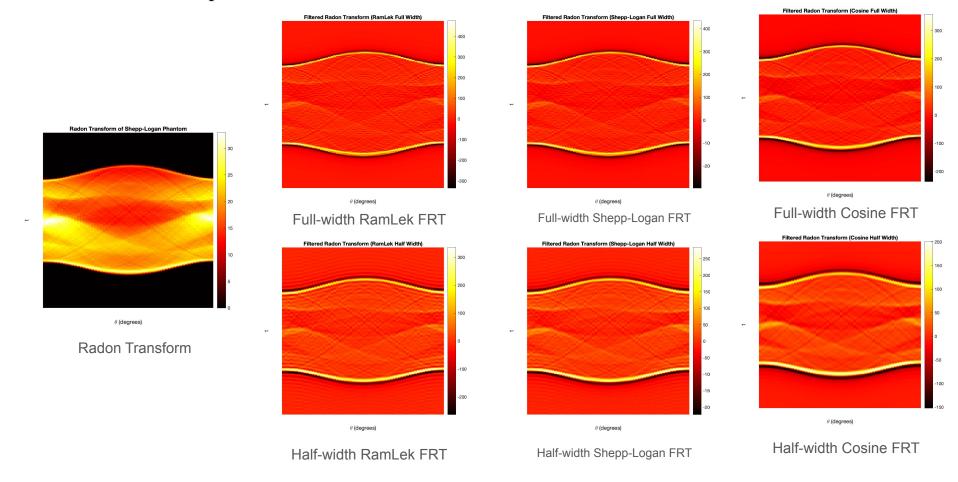
with half the number of angles and ts – lesser radiations, but information loss



Q2 - X-Ray Computed Tomography: Reconstruction by Filtered Backprojection (FBP)



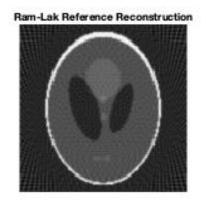
Radon Transform of phantom vs Filtered Radon Transforms for Full-width and Half-width Filters

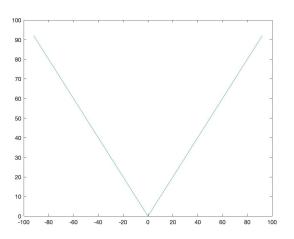


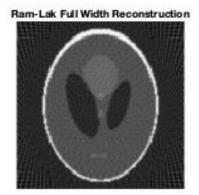
FBP Analysis

- The RamLak filter -
 - \circ A(w) = |w|*rect(L); which amplifies higher frequencies, ie., noise and thus creates a noisy reconstruction than the other two filters. For half-width L, the image omits higher frequencies which results in image smoothing but some unavoidable loss of information
- The Shepp-logan filter -
 - O $A(w) = |w|^* rect(L)^* sinc(w/2L)$ which lessens the amplification of noise and is thus better than the RamLak filter. Similar to RamLak half-width, the image gets smoothened.
- Cosine Filter
 - A(w) = $|w|^* \text{rect}(L)^* \cos(\pi w/2L)$ which further lessens amplification of noise and better than both other filters.

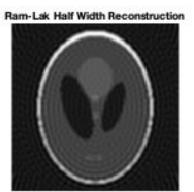
Filtered Backprojection(FBP) for Full-width and Half-width Filters vs FBP using Matlab In-built library





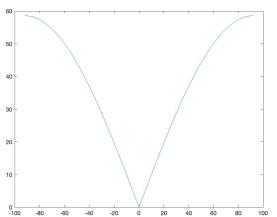






Filtered Backprojection(FBP) for Full-width and Half-width Filters vs FBP using Matlab In-built library

Shepp-Logan Reference Reconstruction

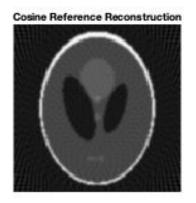


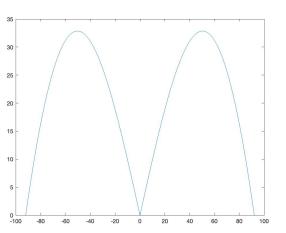
Shepp-Logan Full Width Reconstruction

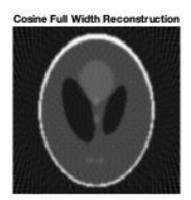




Filtered Backprojection(FBP) for Full-width and Half-width Filters vs FBP using Matlab In-built library





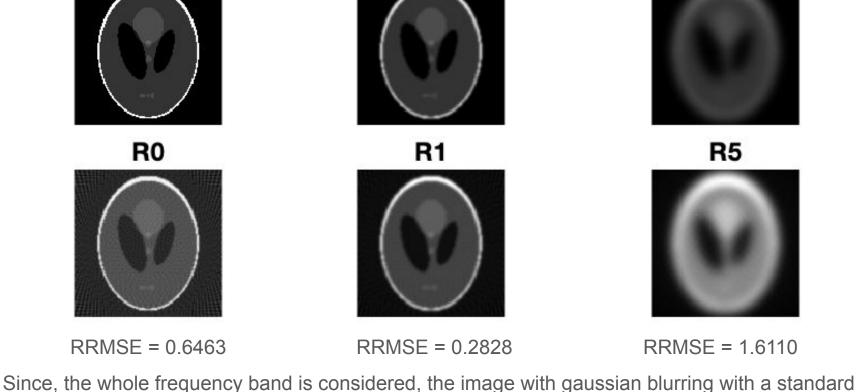






Ram-Lak Filtered Backprojection(FBP) for Blurred Images

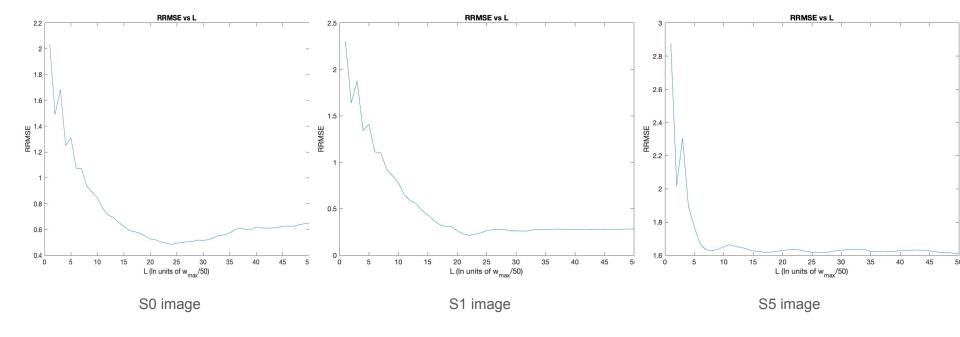
S₀



S5

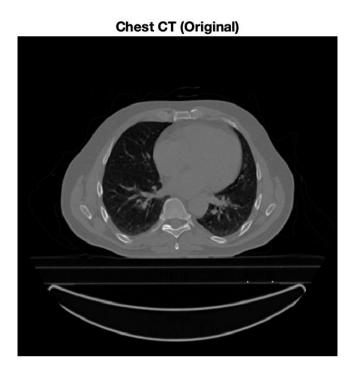
Since, the whole frequency band is considered, the image with gaussian blurring with a standard deviation of 1 already smoothens the input image and thus the reconstruction is closer to it. The image with standard deviation smoothens the image too much causing artifacts in reconstruction.

RRMSE for Ram-Lak Filtered Backprojection(FBP) for different Filter Lengths



The RRMSE reduces as a larger length filter is taken, it reaches a minimum almost around half width of maximum frequencies and almost remains constant later.

Q3 - X-Ray Computed Tomography: Incomplete Data

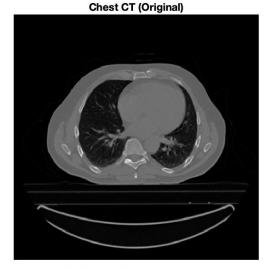




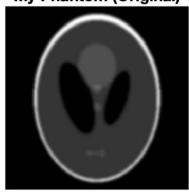


RRMSE vs Starting angle(θ) (all three filters for both datasets)

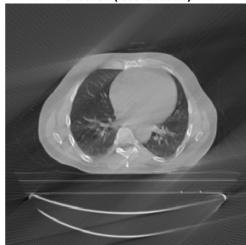
FBP with θ for which RRMSE is least



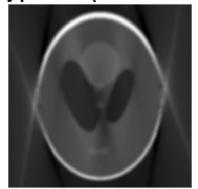
My Phantom (Original)



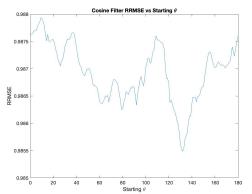
Chest CT (reconstructed)



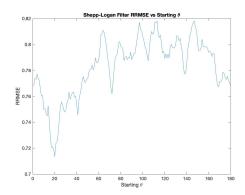
My phantom (reconstructed)



Chosen θ for Chest CT data = 132° (using cosine filter)

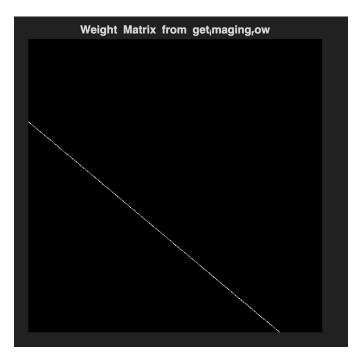


Chosen θ for My phantom data = 20° (using Shepp-Logan filter)



Q4: Algebraic Reconstruction Technique (ART)

```
unction row = get imaging row(n, angle, t, integration params)
weight_matrix = zeros(n, n);
x0 = 1 + (n - 1) / 2;
y0 = 1 + (n - 1) / 2;
s_step = integration_params.s_step;
s_range = -(n-1) * sqrt(2) / 2 : s_step : (n-1) * sqrt(2) / 2;
for s = s_range
    x = x0 + t * cos(angle) - s * sin(angle);
    y = y0 + t * sin(angle) + s * cos(angle);
    x round = round(x);
    y round = round(y);
    if (x_round < 1 || x_round > n || y_round < 1 || y_round > n)
        continue:
    end
    weight_matrix(x_round, y_round) = weight_matrix(x_round, y_round) + 1;
end
row = weight_matrix(:)';
```



```
function x = myART(x0, permutation, b, ts, angles, art_params, integration_params)
  lambda = art_params.lambda;
 max_iter = art_params.max_iter;
 global_tol = art_params.tol;
 x = x0:
 n = sqrt(length(x0));
 for iter = 1:max_iter
     x_old = x;
     for i = permutation
         angle = angles(floor((i-1)/length(ts)) + 1);
         t_{idx} = mod(i-1, length(ts)) + 1;
         t = ts(t_idx);
         a_i = get_imaging_row(n, angle, t, integration_params);
         % ART update
          residual = b(i) - dot(a_i, x);
         x = x + lambda * residual * a_i / norm(a_i)^2;
      end
     % Global convergence check
     if norm(x - x old) < global tol
         disp(['Converged at iteration ', num2str(iter)]);
          break;
      end
     if iter == max_iter
```

disp('Maximum iterations reached');

end end

end

