

Assignment 3

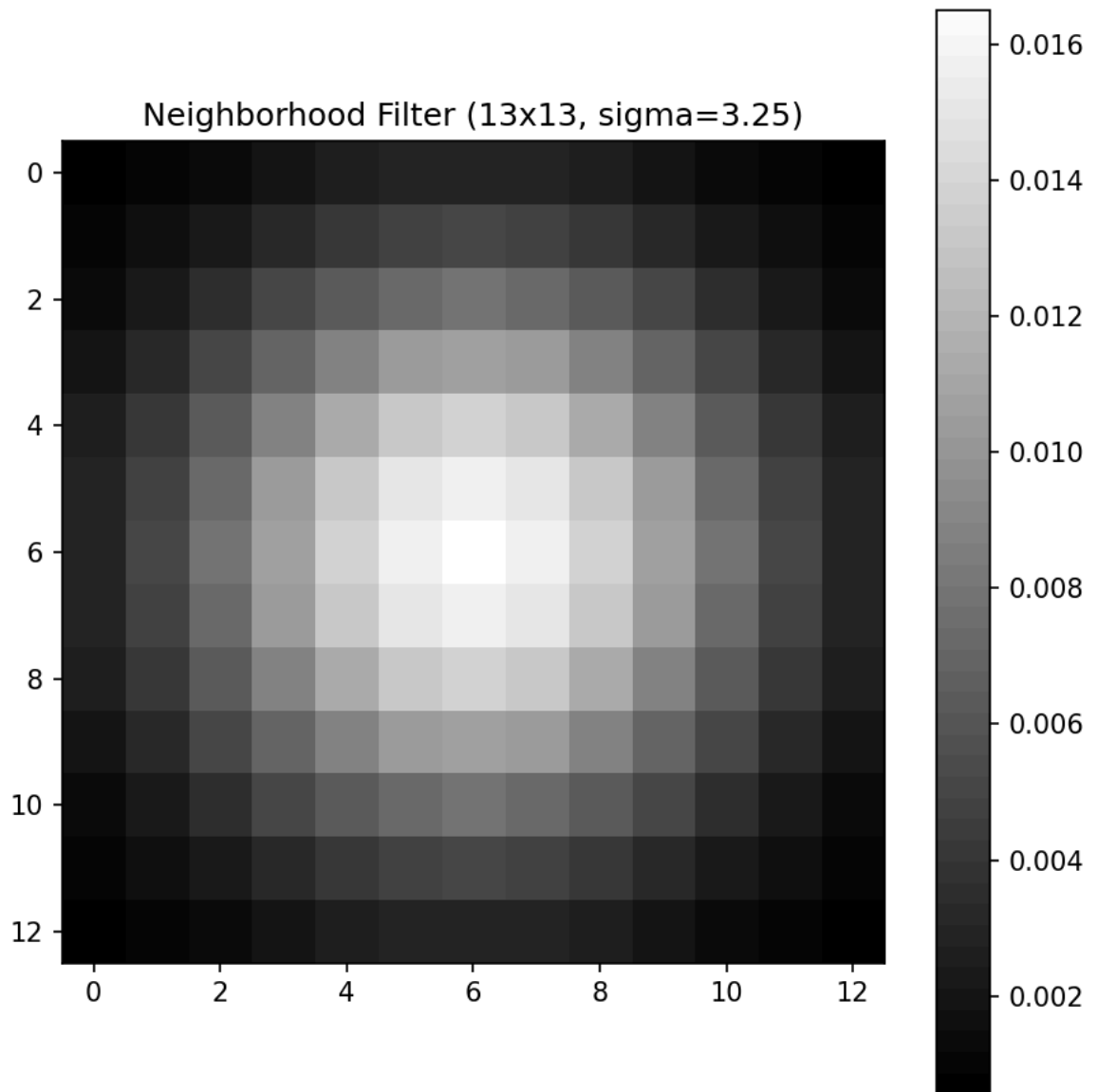
Image Segmentation

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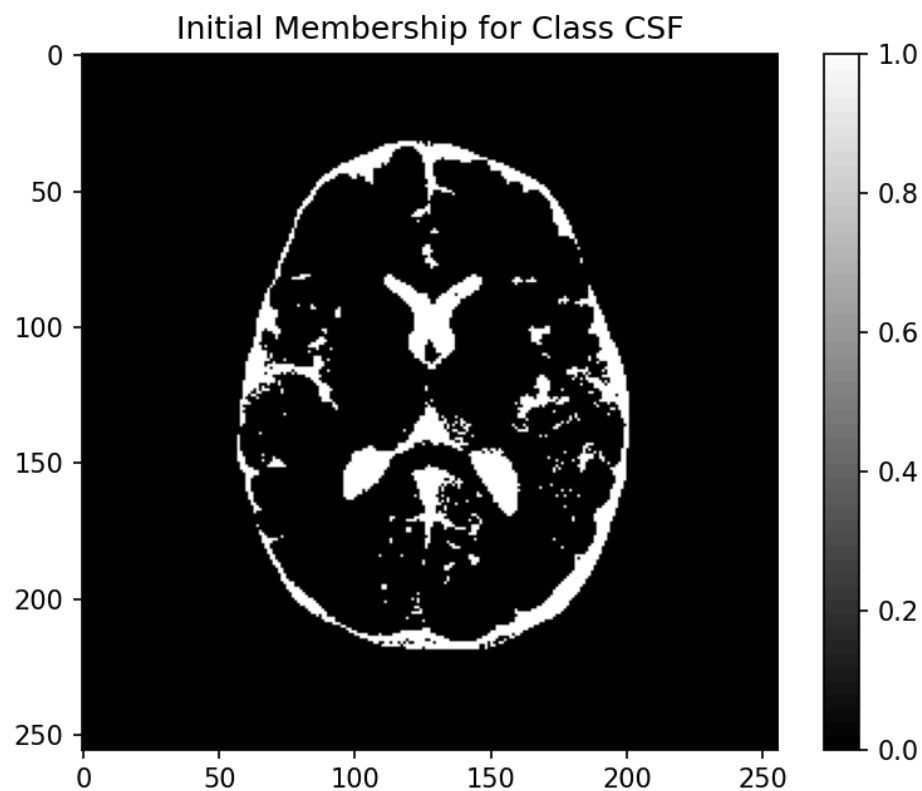
Suraj Prasad
22b0607

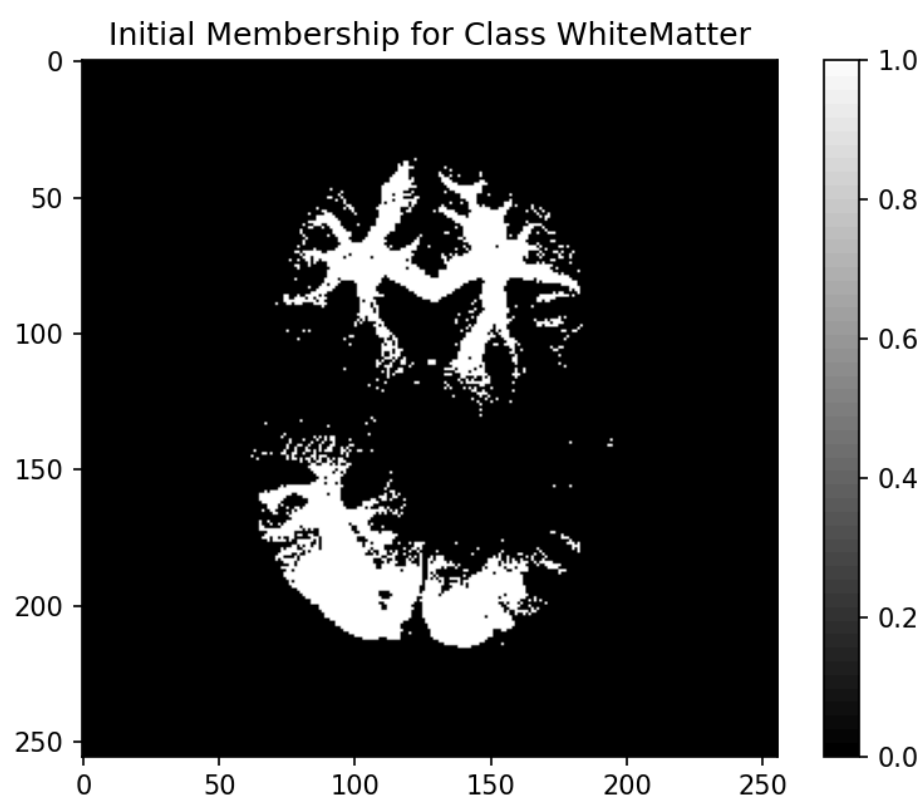
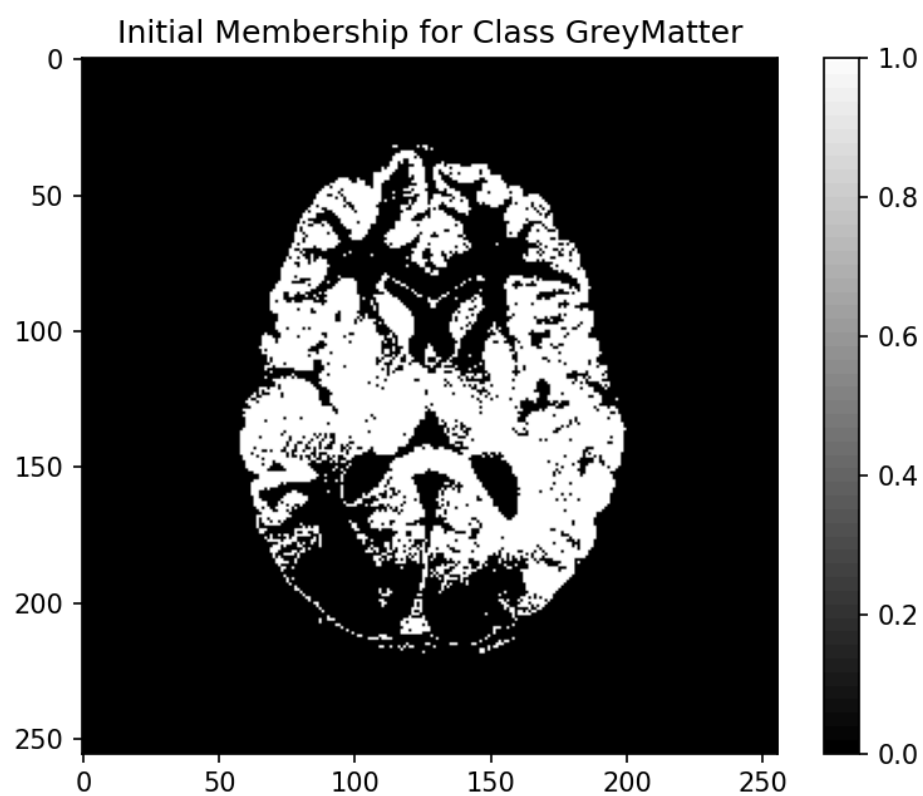
Question 1:

- a) Chosen value of $q = 2$
- b) The mask is 13×13 with standard deviation of 3.25



c) We initialise means with K means algorithm. Then we used these means to make initialise membership of each pixel to be crisp such that it is 1 for closest mean and 0 for others. We thought this was a good starting point instead of initialising them from the random.





d) Initial class means were found using K means algorithm as it is relatively simple and fast algorithm.

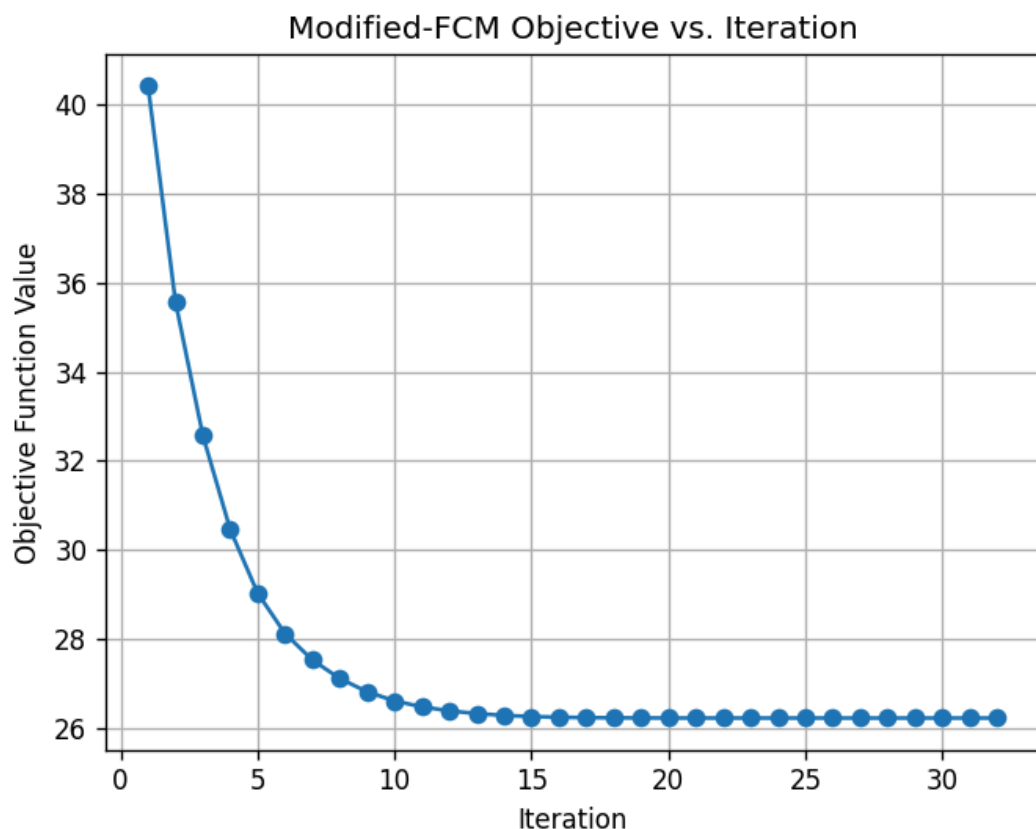
Means :

for CSF = 0.22

for Grey Matter = 0.45

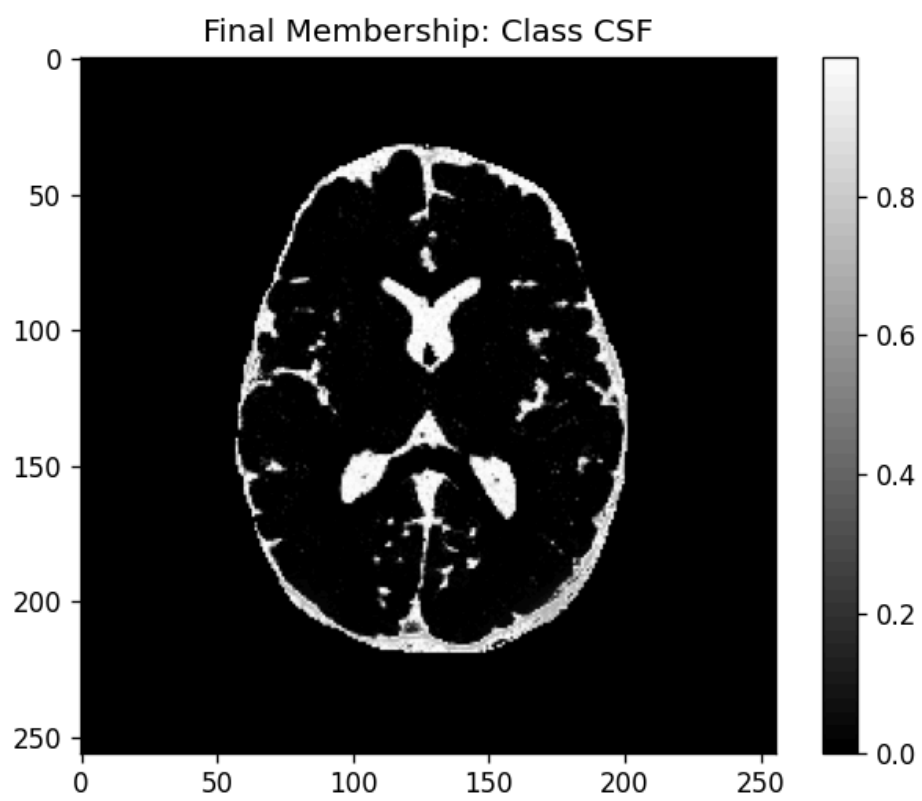
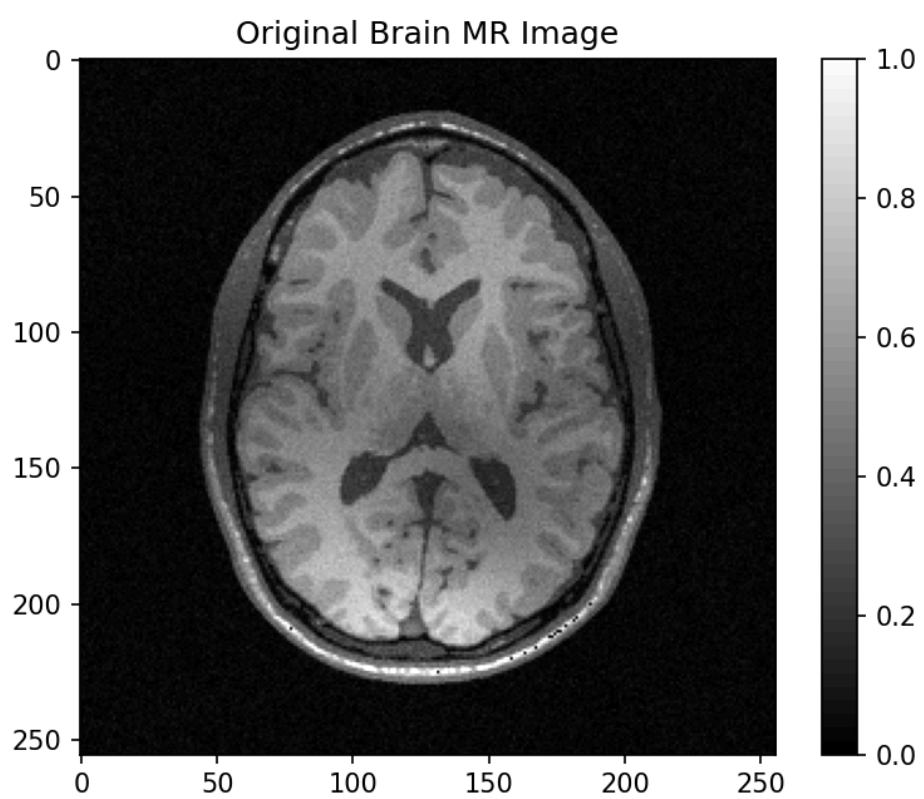
for White Matter = 0.63

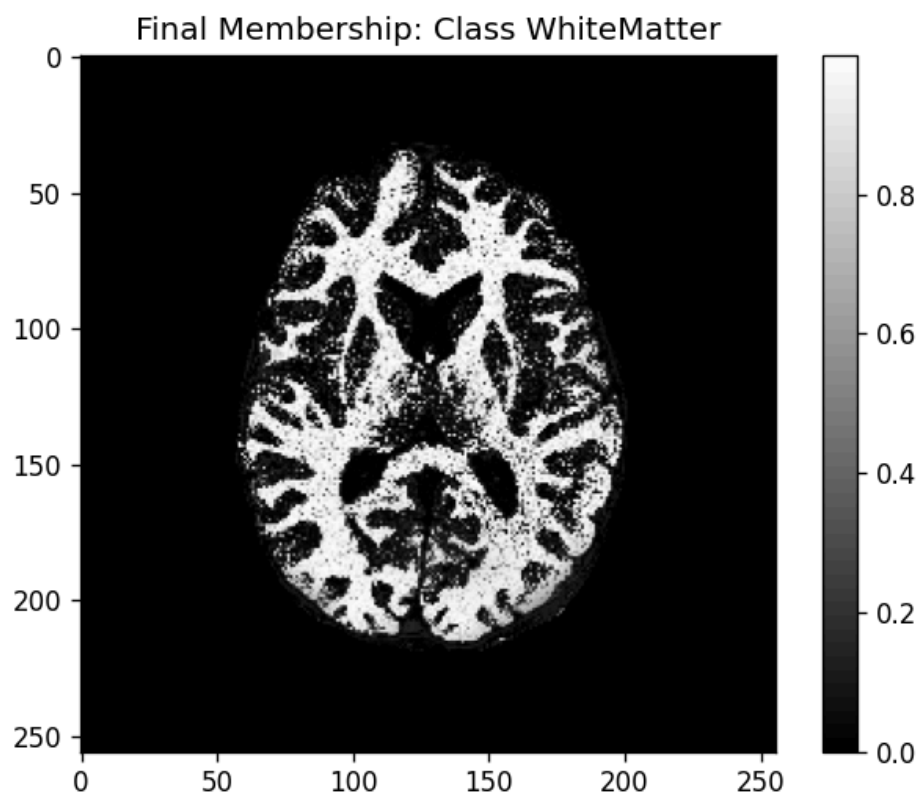
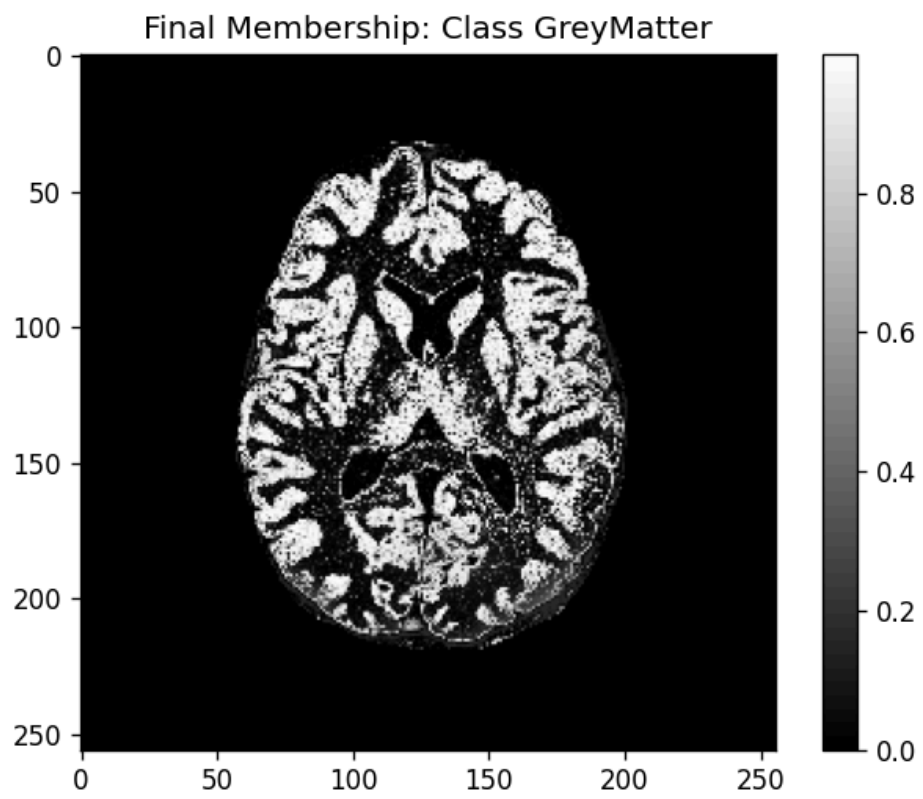
e) The value of objective function:

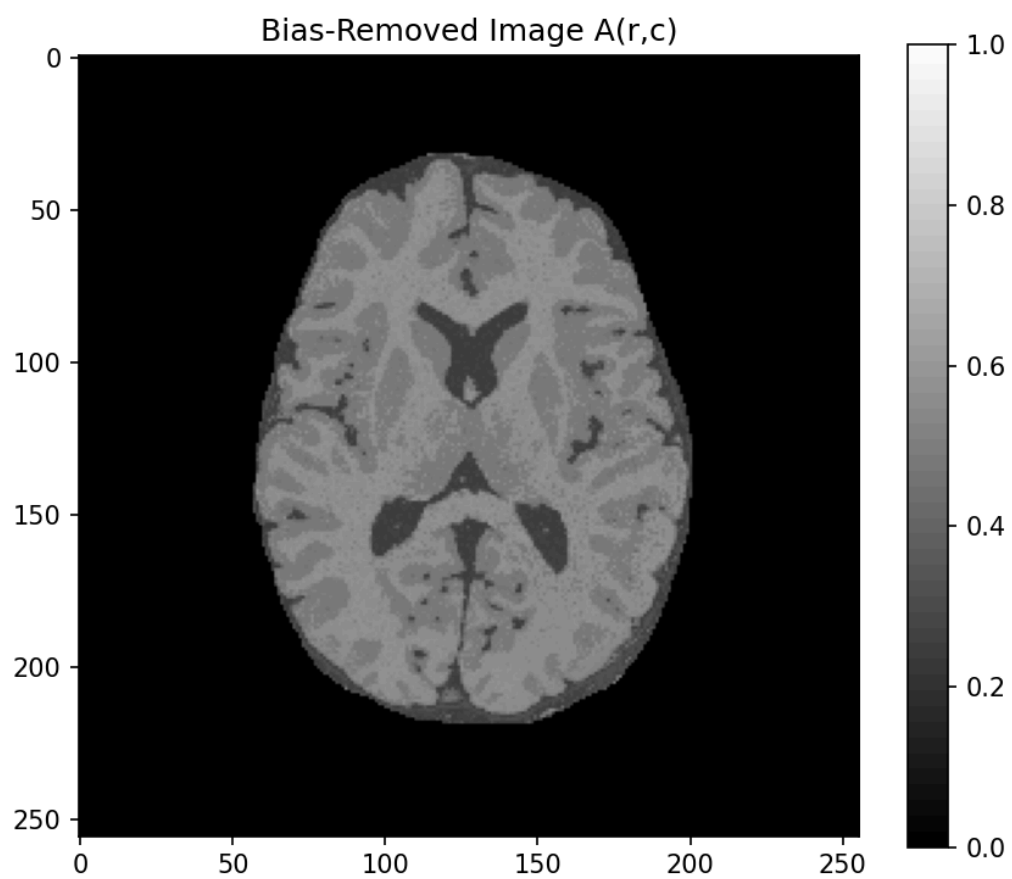
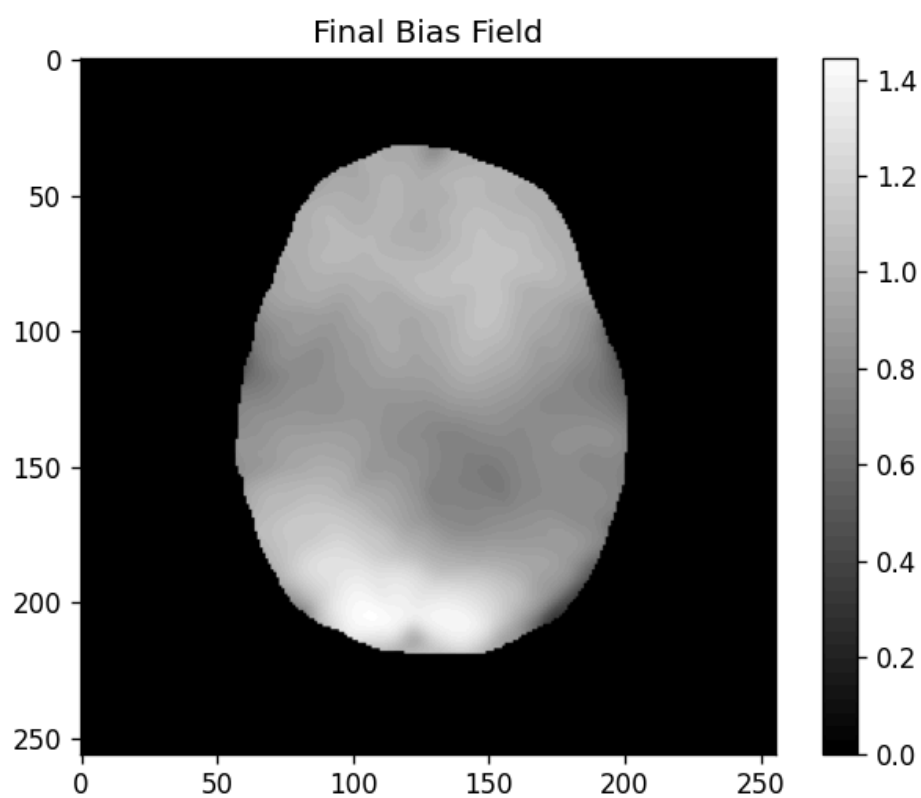


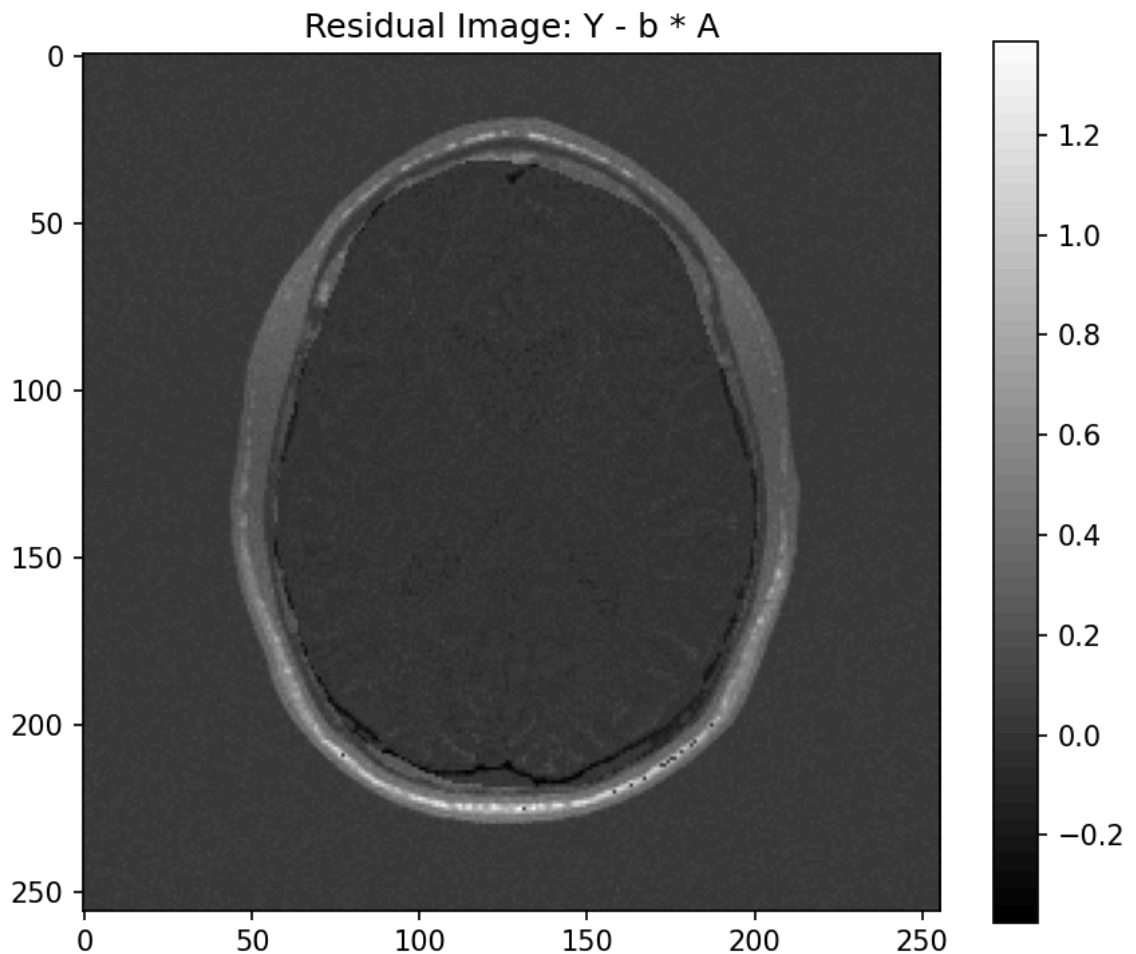
As we can see the objective function decreases significantly upto 15 iteration then it stalls.

f)









g) Class Means:

for CSF = 0.2475255

for Grey Matter = 0.4721438

for White Matter = 0.5716902

Note the initial estimates were pretty close

h) This will not give unique solution:

as $Y_i = B_i \sum_j U_{ij} C_j$, Note our final solution can also be:

$B_i^* \propto C_i$ and $C_j \propto B_j$

Which will give same Y (Bias removed image). Thus infinitely many solutions.

The uniqueness can be ensured by:

A common theoretical remedy is to **normalize the average bias** to 1 after each iteration. Concretely:

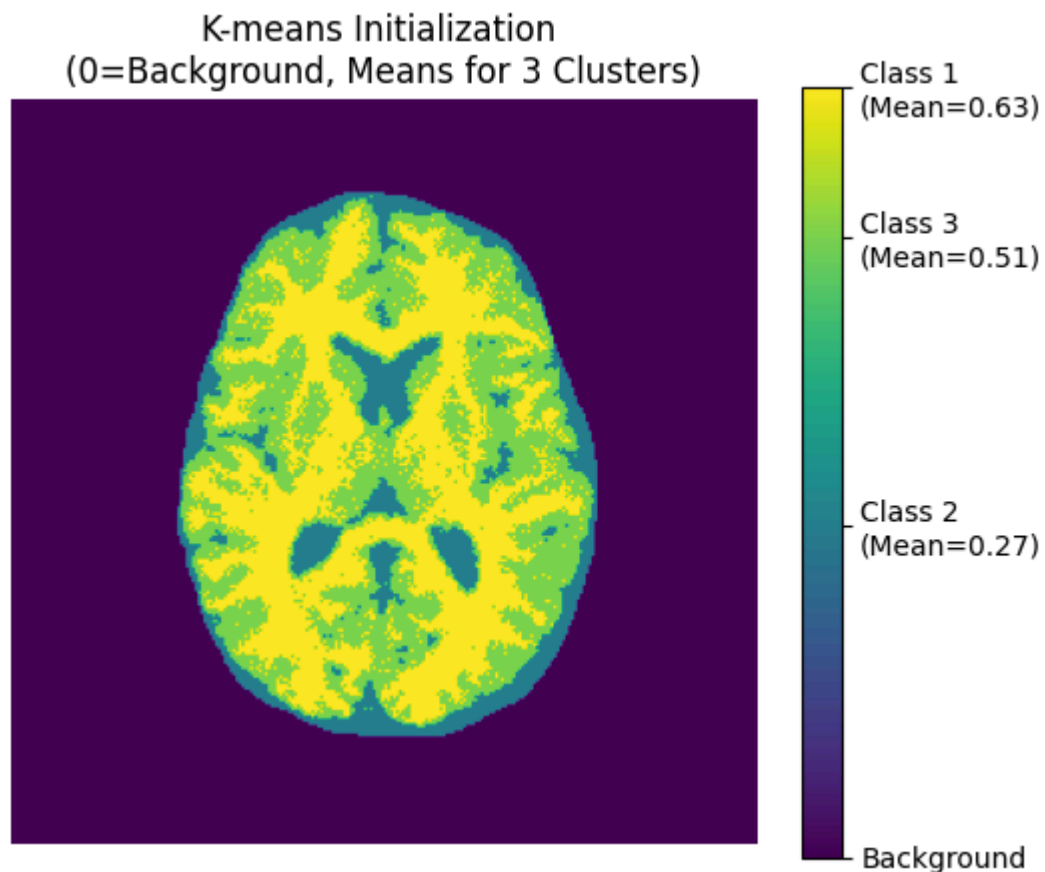
$$\bar{b} = \frac{1}{N} \sum_{n=1}^N b_n \implies b_n \leftarrow \frac{b_n}{\bar{b}}, \quad c_k \leftarrow c_k \times \bar{b}.$$

By forcing $\frac{1}{N} \sum_n b_n = 1$, we eliminate the free scaling degree of freedom, thereby **ensuring a unique solution** (up to minor numerical tolerance) for $\{b_n\}$, $\{c_k\}$, and the membership $\{u_{n,k}\}$.

The following is implemented in the code

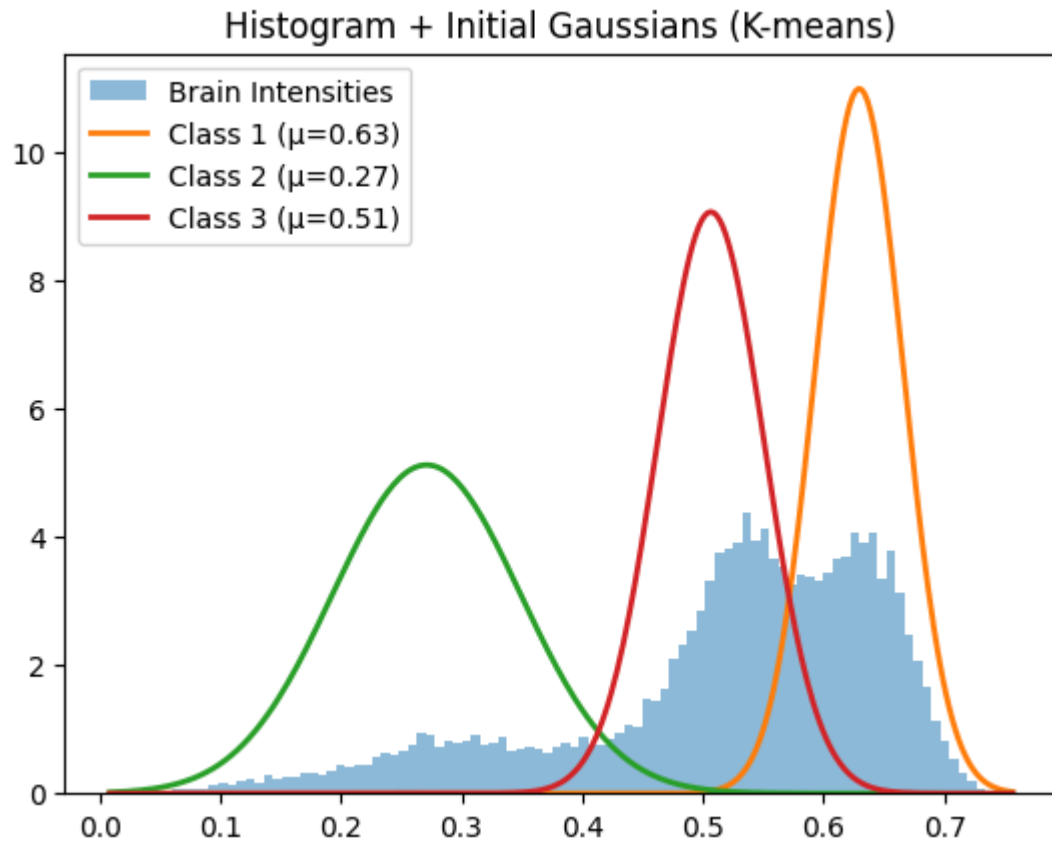
Question 2:

- a) After playing around with multiple values we found that the $\beta = 0.6$ works best.
- b) For initial estimates of labels we used K means algorithm as it is fairly simple and gives close enough initialisation to final desired values.



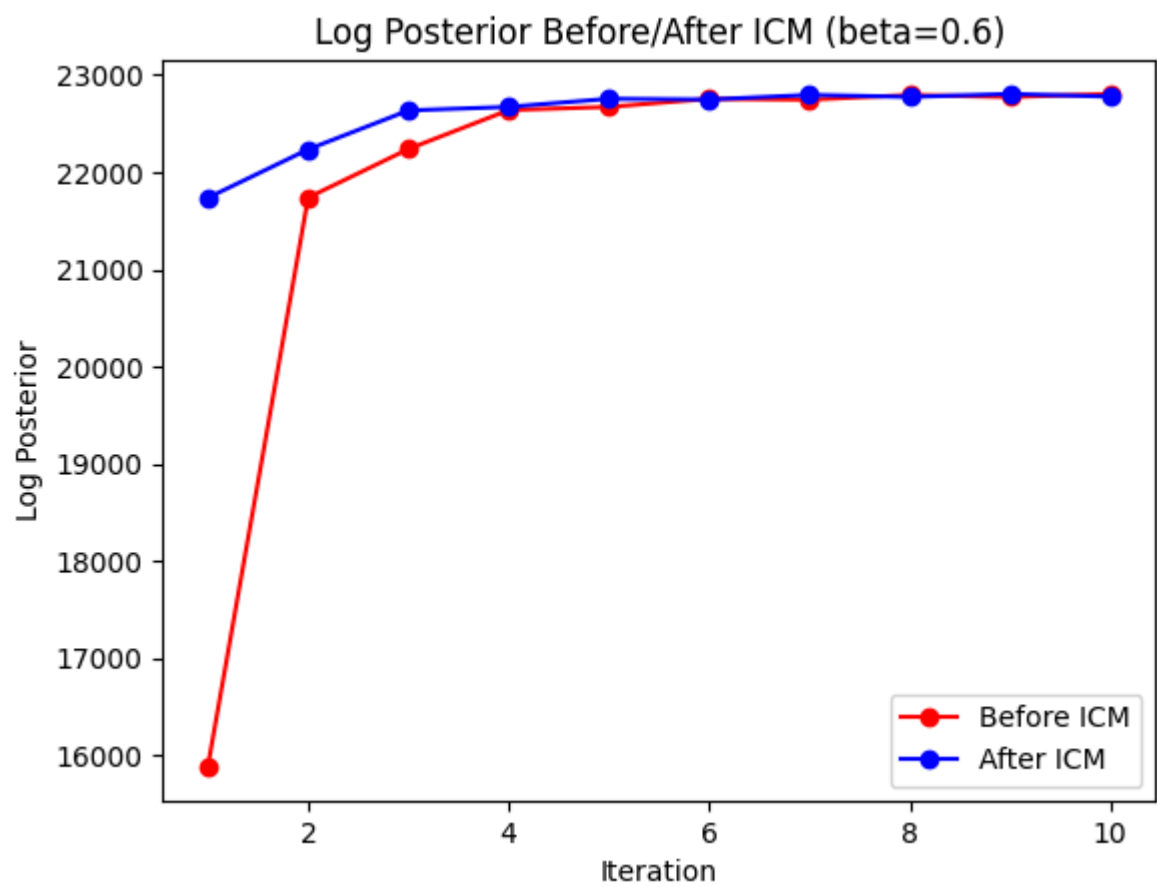
- c) We got means from the K means and then we crisply assigned the pixels to classes. Finally we used the value of

intensity of each pixel in given class to find standard deviation for that class.

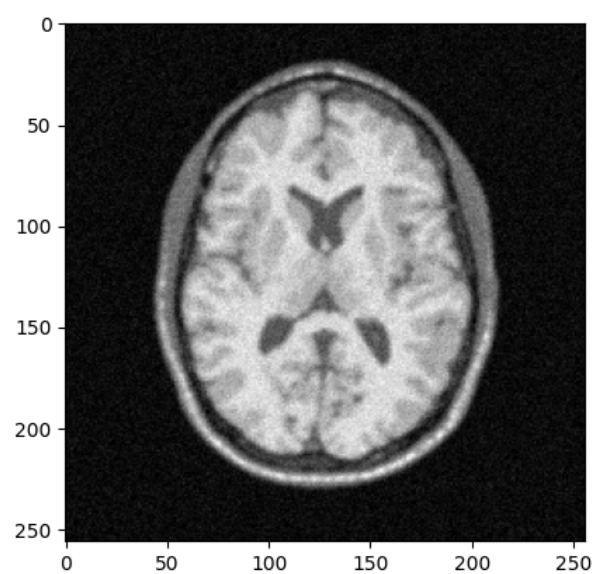


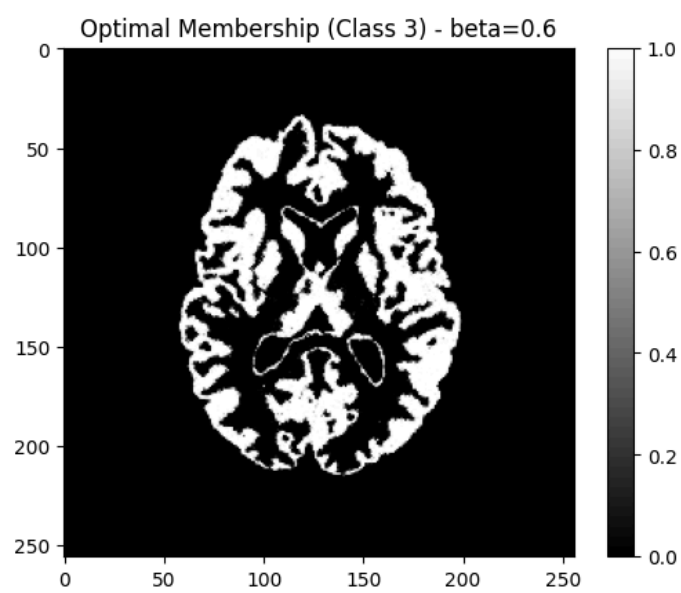
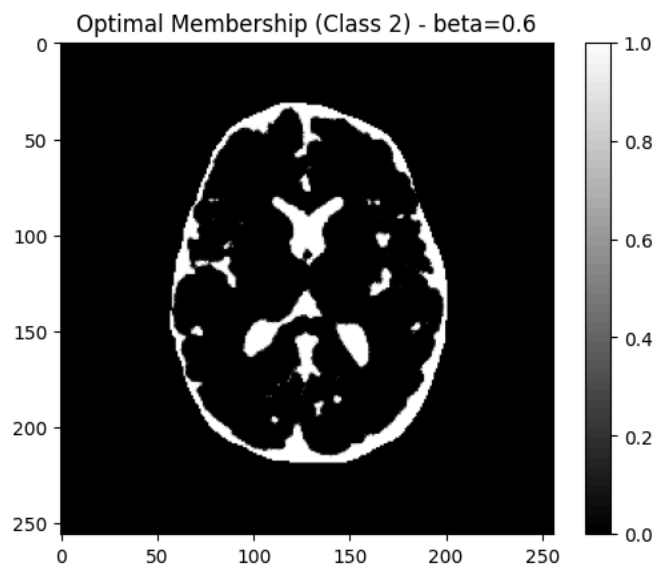
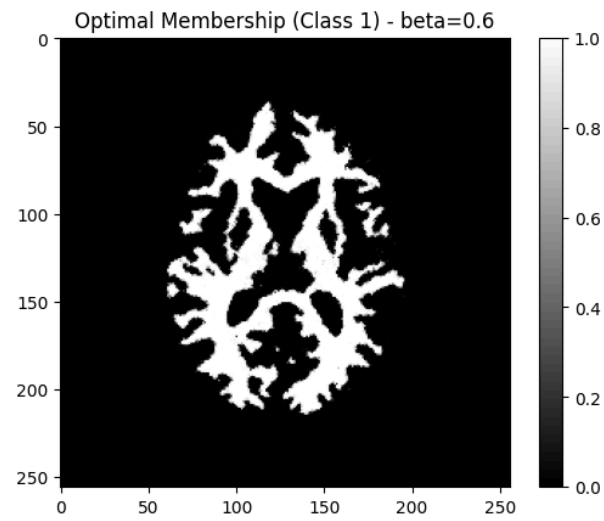
d) For the modified ICM segmentation, the values of the log posterior probability for the labels, before and

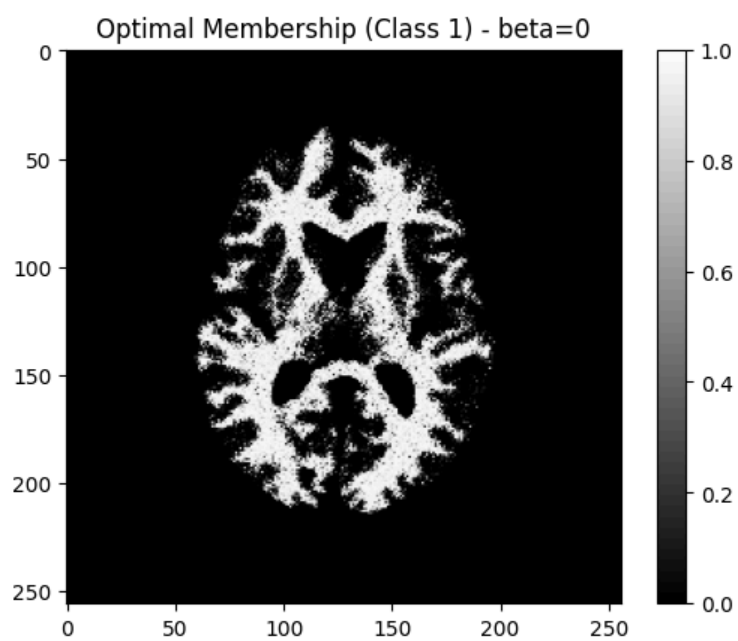
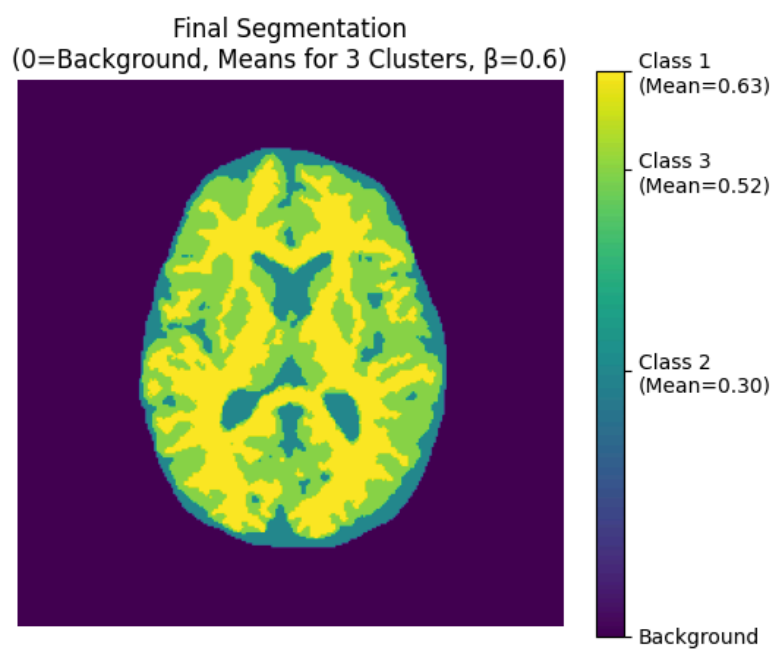
after the ICM update:

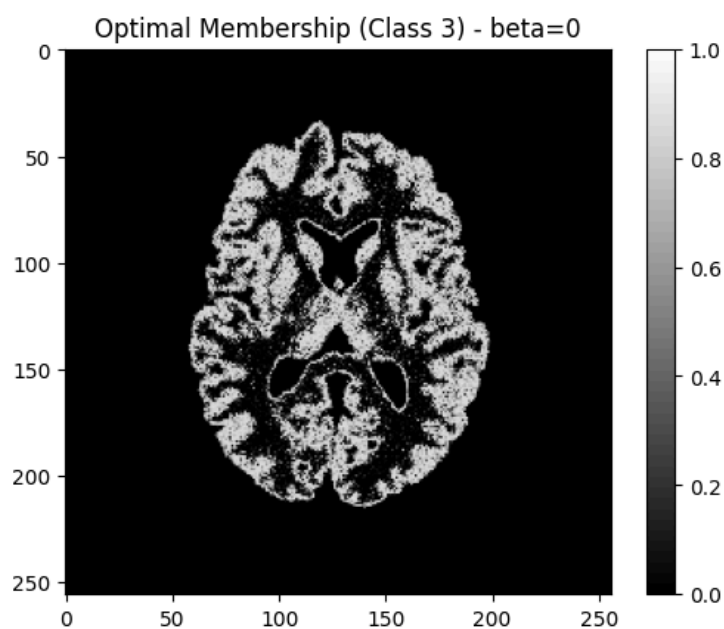
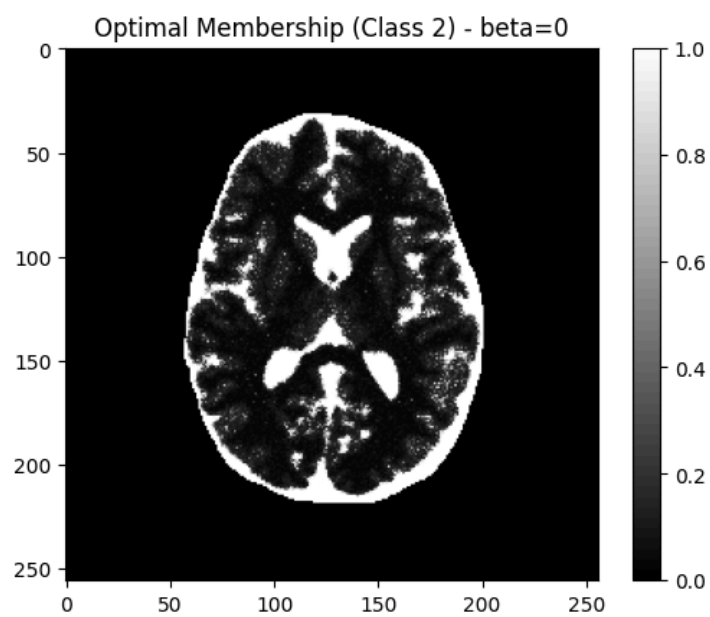


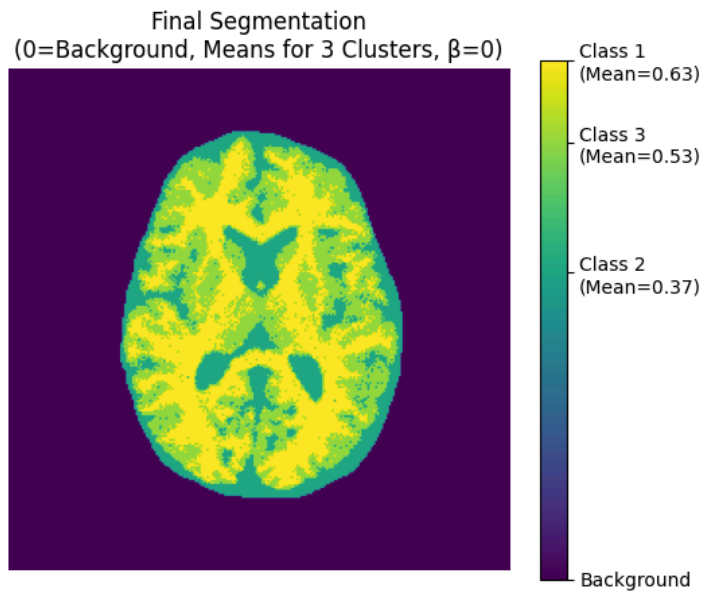
e) Kednvk











f) Class mean = 0.63, 0.52, 0.30