## SKILL ACTIVITY NO: 1 Date: 06/02/2025

( To be filled by the Instructor )

| Title: Interfacing keypad, pushbutton, bu  | uzzer and display (LED, LCD, ELZ, norminalED) |
|--|---|
| with Arduno.   |   |
| Skills / competencies to be acquired ;   |   |
| 1. Ardviro   | 5. Use of UED/UED display.                    |
| 2. Use of teypad.  | 8.  |
| 3. Use of Push Button  | 7   |
| 4. Use of buzzer.  | 8   |
| Duration of activity ( hours ):/   |   |
| ( To be filled by the Student )  1. What is the purpose of this activity? ( Explain in | n 3 - 4 lines )                               |
| - Free attaller to be less to  | A demonstrate has to interface                |
| The purpose of this activity is to leave<br>various components like a keypad,          | oushbutton, buzzer different                  |
| troce of displays (IFP, LCP, 3x2 "   | natrix (FD) with an Arduna.                   |
| By completing this project, you we controlling input and output device                 | jill gain hand-on experience in               |
|  |   |
| 2. Steps performed in this activity (Explain in 5 -                                    | 8 lines )                                     |
| 1) Setting up the Ardvino environ  | NEVE !  |
| 2) Cornecting the Keypood.   |   |
| 3) Corner try the pushbut ton.   |   |
| 5) Interfacing the LED Display.  |   |
|  |   |

| 3. | What resources / materials / equipments / tools | s did | you use for this activity? |
|----|---|-------|----------------------------|
|    | Arduino   |       | Laptop                     |
|    | Keyead  | 6.    | 7-sigment LED display      |
|    | Buzzer  | 7.    | LCD display                |
|    | LED/LCD display.                                | . 8.  | Jumpes wires & Breakourd   |
|    |   |       |                            |
|    |   |       |                            |
| 4. | What skills did you acquire?                    |       |                            |
| 1. | Arduino   | 5.    | Use of LED/UD dispuy       |
| 2  | Use of keypad                                   |       | - 10 mm 10 di              |
| 1  | Use of puch button                              | 7.    |                            |
| 4  | Use of buzzer                                   | 8.    |                            |
|    |   |       |                            |
|    |   |       |                            |
| 5. | Time taken to complete the activity ?           | 3 15  | (hours)                    |

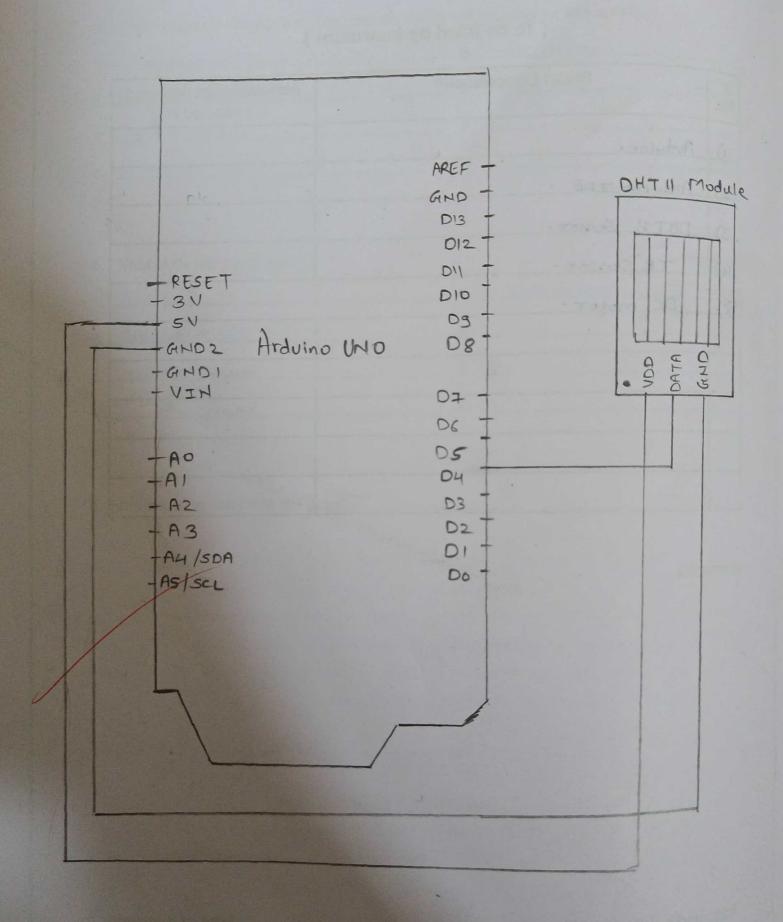
(Signature) Instructor Signature) Student

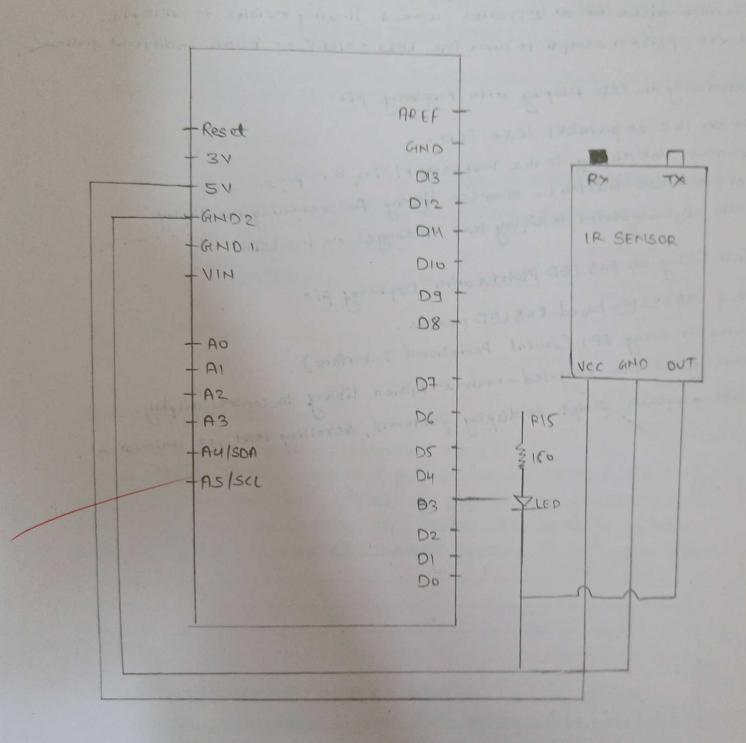
## SKILL ACTIVITY NO: 2 Date: 13 02 25 (To be filled by the Instructor)

Title: Interfacing Various oxnows and achieves with Anduino. Skills / competencies to be acquired ; 1. Anduino 5. DC motor. 2. Avduing IDE 3. DHT II Sensor. 4. IR Genson Duration of activity ( hours ): (To be filled by the Student) What is the purpose of this activity? (Explain in 3 - 4 lines) The purpose of this skill is to integrate and control sensors (such as DHT 11, IR) and actuators (such as DC motor) using an Anduino . This will enable real-time sensing, processing & control of physical systems. Understanding this skill involves working with micro-controllers to read sensor data, process it, and then interact with physical devices like other actuators. 2. Steps performed in this activity (Explain in 5 - 6 lines) 1) Setting up Ardumo and Ardumo IDE: - Install Andrino IDE from Chttps://www.ordvino.co/en/softwore). - Connect your Andrew hoard (like andrew Uno) to your computer using use cable. - Open the Arduino IDE Prelect the correct board I part under the tooks menu 2) Interfacing the DHT 11 Sensor: - The OHTH Densor is digital sensor that outputs temperatures & humidity data. - Connect the sensor to Arduino.

| 3. What resources / materials / equipments / too | Is did yo | ou use for this activity? |
|--|-----------|---------------------------|
| 3. What resources / materials                    | _ 5       | DC motor.                 |
| 1. Arduino                                       | 6         |                           |
| 2. Ardvino IDE                                   | _ 0       |                           |
| 3. DHT 11 Sensor                                 | _ 7       |                           |
| 4. IR sensor                                     | _ 8       |                           |
|  |           |                           |
|  |           |                           |
| 4. What skills did you acquire?                  |           |                           |
| 1. Arduina                                       | _ 5       | DC Wotar                  |
| 2. Arduino IDE                                   | _ 6       |                           |
| 3. DRT II Sensor                                 |           |                           |
| 4. IR Sensor                                     | _ 8       |                           |
|  |           |                           |
| 5. Time taken to complete the activity?          |           | (hours)                   |

(Signature) Instructor (Signature)





\* Interfacing an LFD with Raspberry PIL

- · Connect pieco or a LED with current limiting resisto 6 to apropin
- · Write python script to turn the LED on/off or blink indifferent pattern
- \* Interfacing an LCD Display with Raspberry Pis
  - · Use an 12 C or parallel 16x2 LCD.
- · Connect the display to the Raspberry Pi in 12c pins.
- · Instant I use Adafruit charles library for controlling the display.
- · Write a python script to display text messages on the LCD.
- \* Interfacing an 8x8 LED Matrix with Rospberry pi"
- · Use a MAX7219 based 8x8 LED mothix.
- · Connect it using SPI (serial Peripheral Interface),
- · Install & use the luma led matrix Python libary to control display.
- · White a python script to display patterns, scrolling text, or animations.

### SKILL ACTIVITY NO: 3 Date: 27/02/25

( To be filled by the Instructor )

| Title: Interfacing Keypad, Rushbutton, Buzzer, and Display (LED, LCD, 8x8 Matrix LED) with Raspberry pi.  |
|---|
| Skills / competencies to be acquired :  |
| 1. Understanding GPIO pins. 5. Displaying text & patterns on LED.   |
| 2. Working with libraries like RPi. GPIB. Writing python scripts in RPI.  |
| 3. Reading Input from a pushbutton. 7.  |
| 4. Controlling output devices. 8.   |
| Duration of activity ( hours ) :  |
| Leaving Supply Committee devices  |
| ( To be filled by the Student )   |
| 1. What is the purpose of this activity? (Explain in 3-4 lines)  To interface various input & output devices with a Rospherry pi, enabling users to build interactive projects. By mastering these interfaces, one can develop applications like security systems interactive displays, embedded control systems & To applications. |
| 2. Steps performed in this activity (Explain in 5 - 6 lines)  |
| Rospherry Bi, pushbutton, keypon, too, buzzer, tico, sex matrix,  |
| to. 1) Interfacing a Rishbutton with Raspberry !!   |
| · Connect a pushbutton to Raspheray Pi GPIO using a pull-up pull-down resistes.   |
| 2) Interfacing a keypad with Raspberry !!   |
| · Use 1x4 0x 3x4 matrix. Connect keypad rows & Columns write from   |
| 3) Interfacing a Buzzer with Raspberry Pi:  |
| · Connect plezo or active buzzer to GPIO pin · Use PMM to control sound patterns. · kin'te Python script ·  |
| 4) Interfacing on LED with Rasphenry Pi'  |
| 5) Interfacing on LCD display with Raspberry Pi. 13   |
| 6) Interfacing an 8x8 LED motorix with Rospherry Pi.  |

| · · · · / - minmonts / tool                       | le did      | you use for this activity | ?                    |
|---|-------------|---------------------------|----------------------|
| 3. What resources / materials / equipments / tool | is ala      | a Il and Ros              | ebian ne             |
| 1. Raspherry Pi                                   | _ 5.        | Bread Bo ara, isas        |                      |
| 2 Push button                                     | _ 6.        | 9                         | AFTER LL TELL TO     |
| 3. Keypad, LCD, 8 ×8 LED matrix                   | 7.          | Geory Python              | IOE:                 |
| 4. LED buzzer, jumper wires                       | _ 0.        |                           |                      |
|   |             |                           |                      |
|   |             |                           |                      |
| 4. What skills did you acquire?                   | 5           | Displaying text           | A patterns on LED    |
| 1. Understanding GPIO pins.                       | . 5.        | 201-3                     | Co. J. + C * - O - * |
| 2. Working with libraries like RPi-GPI            | <b>o</b> 6. | Writing python s          | ionprs in ka:        |
| 3. Reading input from a push button.              | 1.          |                           |                      |
| 4. Controlling output devices.                    | 8.          |                           |                      |
|   |             |                           |                      |
|   |             |                           |                      |
| 5. Time taken to complete the activity ?          |             | 1                         | (hours)              |
| 5. Time taken to complete                         |             |                           |                      |
| The transfer pareleggy british                    |             |                           |                      |
| and a standard of the sand                        |             |                           |                      |
|   |             |                           |                      |
|   |             |                           |                      |
|   |             |                           |                      |

#### **SKILL ACTIVITY NO: 4**

( To be filled by the Instructor )

Date: 4/3/25

Title: Interfacing sensors and actuators with Raspherry pi. Skills / competencies to be acquired: 1. Raspberry Pi 2. Reading data from analyg & digital sensors. 3. Understanding appopin configuration for 7. sensors & actuators 4. Using Python libraries for interfacing 8. with sensors & actuators withing python scripts for real time data acquistion & contra Duration of activity (hours): (To be filled by the Student) 1. What is the purpose of this activity? (Explain in 3 - 4 lines) This skill enables users to interface vanious sensors Packators with a Raspherry Pi to develop real-world applications such as automation, robotics and I OT - based systems. By mastering these interfaces users can build projects involving environment monitoring motor control and home automation 2. Steps performed in this activity (Explain in 5 - 6 lines) Interfacing a Temperature & Humidity sensor (DHTIL/DHT 22) with Respherence; Interfacing a PIR Motion sensor with Raspherry Pi. Interfacing a Relay module with Raspherry motor with Raspherry Pi. - skow) with Rospherry Pi. Interfacing an Ultrasonic Sensor

| 3. What resources / materials / equipments / tools   | did you use for this activity? |
|--|--------------------------------|
| 1. Raspberry Pi  | 5. Raspian OS                  |
| 2. DHTII/DHT27   | 6. Python                      |
| 3. PIR   | 7. Thonny Rython IDF           |
| 4. Motion, Relay, servo, altrasonic sensor   | 8. Adafray DHT.                |
|  |                                |
| 4. What skills did you acquire ?   |                                |
| 1. Raspoemy Pi   | 5.                             |
| 2. Reading data from analog Adigital So  | Sebsor,                        |
| 3. Understanding GIPIO pin configuration   | 7. for sensors Pactuators      |
| 4. Using Python libraries for interfacing  | 8. With sensors & actuators    |
| 4. Using Python libraries for interfacing writing python scripts for real time   | e dota acquistion & control.   |
|  |                                |
| 5. Time taken to complete the activity?  | (hours)                        |
| The same of the sa |                                |



(Signature) Student 1) Temperature & Humidity Sensor:

Python Code!

import Adafnit - DHT

Sensor = Adafrul + \_ DHT. DHT1/

Pin-11

humidity temp = Hdufuit - DHT. road-retry (sensorpin)

print (P' Temp: of temp? C, Humidity: of Humidity 3 1/13

2) PIR Motion Sensor! -

Python Code:

import RPI. GP10 as GP10

impost time

PIR-PIN = 17

aprosetmede (aprosem)

GPIO-Setup (AR-PIN; GPIO-IN)

while True!

if apro. Input (PIR-PIN):

print (" Motion Detector")

time · sleep (1)

3) Relay Module

Python code:

import RPI-GPIO as GPIO

import time

Relay-PIN = 18

apio setmode (apio BCM)

GPIO. setup (Relay-PIN, GPIO. Out)

GPIO. output (Relay - PIN, GIPIO. HIGH)

time · sleep (e)

GPIO output (Relay-Pin, GPIO. LOW)

22 APIO leany.

- . Connect the sensor's Vec to 3:3V, AND to growing and Data to a apro pin.
- · Install the Adatuit DHT library to read temps

- · Connect VCC to. SV; GND to GND and out to applo pin.
- · Use RPI- aplo to detect motion Atrigger an action.

- · Connect Vcc to 5 V, AND to ground, and into GPIO pin.
- . Use python to switch the Relay on A off.

import RPI-GIPIO as GIPIO
import time
SERNO-PIN = 12
GPIO. Setmode (GIPIO.BCM)
PWM = GPIO. PWM (SERVO-PIN, 50)
PWM - Change Duty (ycle (2.5)
time Sleep (1)
pwm-stop()

· Connect the servo's power D ground & contol
pin to applo pin.

. Use pum to control the seno position.

5) Vitrasonic Sensor: -

Python Code!

GP10. Cleany

import RPI-GPIO as GPIO

import time

TRIG = 23

ECHO = 24

4PIO·setmode (GPIO·BCM)

GPIO. Setup (FCHO, GPION)

GPY output (TRIG, TRUE)

time sleep (0.0001)

GP10. output (TRIG, False)

while GPIO. input (Ecno) == 0;

Start\_Hme = time · Hme()

While GPIO-input (ECHO) == 1;

end-time = time . time ()

distance = ((end -time-start\_time) \* 34800/2

GPIO. (leanup()

· Connect VCC to BY, GND to ground, TRIA to a GPIO pin, and ECHO to another GPIO pin.

· Use python to calculate the distance based on the time delay between the signal sort & received

# SKILL ACTIVITY NO: 5 Date: 27 08 25

( To be filled by the Instructor )

| Title: Interface ESP32 with DHT 11 sen  | sor A upload data to a mebpage using Blynk.   |
|---|---|
| Skills / competencies to be acquired :  | Action of the part entered to   |
| 1. Interfacing of DHT11 sensor  | 5. Sending sensors deda to cloud.   |
| 2. klooking with Blynk  | 6   |
| 3. Configuring ESP32 Wi-fi  | 7.  |
| 4. Whiting Ardulno code   | 8.  |
| Duration of activity ( hours ) :  | publisher and restrict to   |
|   | collection M 100 de   |
| (To be filled by the Student)  1. What is the purpose of this activity? (Explain in This skill enables learners to interand pressure sensor with an ESP32 real-time data to the Blynk cloumonitared remotely through a web making it useful for weather mon Tot projects.       | wifi module and transmit  ad post platform. The data can be  dashboard or mobile app,   |
| 2. Steps performed in this activity (Explain in 5-6  1) Hardware Connections: Connect the  Ensure proper power supply (3.3v for  Use putt-up resistors where nece  2) Software Setup: Tostall Arduino  Tostall required libraries (DHT, Ad  Configure Blynk project & get an au | DHT II sensor to the ESP 32 GPIOPINS. ESP 32, 3:3 V/S V for sensors).  SSAMY.  IDE (Or use Micropython on Thomy IDE)  Lafnit BMP/BME, Blynk Simple Esp 32). |

| 3. What resources / materials / equipments / tools | did you use for this activity?                |
|--|---|
| 1. Esp32 (Node MCU)                                | 5. Blynk IOT App (Android/ios)                |
| 2. DHTII (Temp & Humidity Sensor)                  | 6. Serial Monitor                             |
| 3. Jumper wires & Breadboard.                      | 7. Blynk web Dashboard for ordine monitoring. |
| 4. Arduino IDE with ES P32 Board Package           | 8   |
| made or what reasons posterio                      |   |
| 4. What skills did you acquire ?                   |   |
| 1. TOT Integration                                 | 5. Sensor Interfecing.                        |
| 2. Embedded systems Programming                    | 6.  |
| 3. Wireless Communication                          | 7.  |
| 4. Data Visualization                              | 8   |
|  |   |
|  |   |
| 5. Time taken to complete the activity?            | (hours)                                       |

(Signature)

(Signature) Student 3) Writing the Code: · Initialize ESP 82 P connect it to wi-fi.

Read temp, humidity & pressure from the sensor.

· Send the data to Blynk cloud using Blynk. virtual write ().

4) Upload & Run: - . Compile Dupload the code to ESP32.

· Monitor sensor values on Blynk App.

s) Real-Time Monitoring: . . Use Blynk widgets to display live temp, humidity & pressure.

· Enable graph visualization for tracking trends over time.

## SKILL ACTIVITY NO: 6

( To be filled by the Instructor )

Date: 24 04 25

Title: Interfacing ESP8266 with DHTII sensor & Uploading data to Thingspeak Webpage, Skills / competencies to be acquired : 1. Interfacing ESP8266 with DHTII. 5. Real time visualization IoT date. 2. Connecting ESP8266 with wifi. 3. Sending consor data to Thing speak 7. Greating Thing Speak Channels 8 .-Duration of activity ( hours ): (To be filled by the Student) 1. What is the purpose of this activity? (Explain in 3 - 4 lines) This activity aims to demonstrate the process of collecting environmental data (temp, humidity, pressure) using sensors like DHTII or BMPIBME 200 Atransmitting the data to Thing Speak, a cloud-based IDT andly tical platform. It builds hands- on skills in sensor interfacing wi-fi based communication using ESP8266 A cloud dota visualization 2. Steps performed in this activity (Explain in 5 - 6 lines) 1) Hardware setup , Connect DHTHI or BMP / BME sensus to ESP8266 board, 2) Install below librardes in Ardutno IDE ! DHT Sensor, Thing speak ESP8266wifi. 3) Setup Thingspeak: Create account on Thingspeak. Create new channel & add fields (eg. temp, humidity). Hote your write API kay. 4) Write & Upload Arduino Code: Connect FSP8266 to Wifi. Read Sensor data. use Thingspeak. white field() to send data to cloud. Upload code A observe sensor data being updated in real time on Thing-speak dashboard.

5) Monitor D Validate Output! Open sen'd manitor to check for connectivity &

sensor reading- login to Thingspeak Dview live graphs.

| 3. What resources / materials / equipments / tools | did you use for this activity ?       |
|--|---------------------------------------|
| 1. ESP8266 Node MCU                                | 5. USB Cable                          |
| 2. DHTII Sensor                                    | 6. Ardvino IDE                        |
| 3. Jumper wires                                    | 7. Thing Speak Platform.              |
| 4. Breadboard                                      |                                       |
|  |                                       |
| 4. What skills did you acquire ?                   |                                       |
| 1. Interfacting ESP8266 with DHTII.                | 5. Real-time visualization of IoTdata |
| 2. Connecting ESP8266 with wifi.                   |                                       |
| 3. Sending sensor data to Thingspeal               |                                       |
| 4. Greating Thingspeak channels.                   |                                       |
|  |                                       |
| 5. Time taken to complete the activity?            | (hours)                               |
| workers process to sessons out the                 |                                       |
| 19818 to little sail average policy (              |                                       |



(Signature) Student

# (To be filled by Instructor

| Sr. No.  1) Interfacing ESP8266 with DHTII.  2) Connecting ESP8266 to wifi.  3) Sending sensor data to ThingSpeak  4) Sreating ThingSpeak Channels.  5) Real time visualization of IoT data. |
|--|
| 3) Sending sensor data to Thingspeak 4) Breating Thing Speak Channels.   |
| OT LO (doda,   |