

**VISVESVARAYA TECHNOLOGICAL
UNIVERSITY**

“JnanaSangama”, Belgaum -590014, Karnataka.



LAB REPORT

on

Artificial Intelligence (23CS5PCAIN)

Submitted by

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in partial fulfillment for the award of the degree of

BACHELOR OF ENGINEERING

in

COMPUTER SCIENCE AND ENGINEERING



B.M.S. COLLEGE OF ENGINEERING

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**B.M.S. College of Engineering,
Bull Temple Road, Bangalore 560019**
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Department of Computer Science and Engineering



CERTIFICATE

This is to certify that the Lab work entitled “Artificial Intelligence (23CS5PCAIN)” carried out by **Sohan R (1BM23CS336)**, who is bonafide student of **B.M.S. College of Engineering**. It is in partial fulfillment for the award of **Bachelor of Engineering in Computer Science and Engineering** of the Visvesvaraya Technological University, Belgaum. The Lab report has been approved as it satisfies the academic requirements in respect of an Artificial Intelligence (23CS5PCAIN) work prescribed for the said degree.

Dr. Seema Patil Associate Professor Department of CSE, BMSCE	Dr. Kavitha Sooda Professor & HOD Department of CSE, BMSCE
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Program 1

Implement Tic – Tac – Toe Game
Implement vacuum cleaner agent

Algorithm:

Implement Tic – Tac – Toe Game

Implement vacuum cleaner agent

Code:

Implement Tic – Tac – Toe Game

```
def print_board(board):
    print(f" {board[0]} | {board[1]} | {board[2]} ")
    print("-----")
    print(f" {board[3]} | {board[4]} | {board[5]} ")
    print("-----")
    print(f" {board[6]} | {board[7]} | {board[8]} ")

def check_win(board, player):
    win_conditions = [
        [0, 1, 2], [3, 4, 5], [6, 7, 8],
        [0, 3, 6], [1, 4, 7], [2, 5, 8],
        [0, 4, 8], [2, 4, 6]
    ]
    for condition in win_conditions:
        if board[condition[0]] == board[condition[1]] == board[condition[2]] == player:
            return True
    return False

def is_draw(board):
    return ' ' not in board

def tic_tac_toe():
    board = [' '] * 9
    current_player = 'X'
    game_on = True

    print("Welcome to Tic-Tac-Toe!")
    print("Player 1 is 'X', Player 2 is 'O'.")
```

```

print("Enter a number from 1-9 to place your move.")

while game_on:
    print_board(board)
    try:
        position = int(input(f"Player {current_player}, choose your
position (1-9): "))
        index = position - 1

        if 0 <= index < 9 and board[index] == ' ':
            board[index] = current_player

            if check_win(board, current_player):
                print_board(board)
                print(f"Player {current_player} wins! Congratulations!")
                game_on = False
            elif is_draw(board):
                print_board(board)
                print("It's a draw!")
                game_on = False
            else:
                current_player = 'O' if current_player == 'X' else 'X'
        else:
            print("This position is already taken or invalid. Please try
again.")
    except ValueError:
        print("Invalid input. Please enter a number.")

if __name__ == "__main__":
    tic_tac_toe()

```

A screenshot of a Google Colab notebook titled "tic_tac_toe.py". The code implements a simple Tic-Tac-Toe game where Player X starts and Player O follows. The game board is represented by a 3x3 grid of underscores. The output shows the progression of the game from start to finish, ending with a win for Player X.

```
if __name__ == "__main__":
    tic_tac_toe()

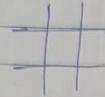
Welcome to Tic-Tac-Toe!
Player 1 is 'X', Player 2 is 'O'.
Enter a number from 1-9 to place your move.
| |
-----
| |
-----
| |
Player X, choose your position (1-9): 5
| |
-----
| |
-----
| x |
Player O, choose your position (1-9): 6
| |
-----
| x | o
-----
| |
Player X, choose your position (1-9): 4
| |
-----
x | x | o
-----
| |
Player O, choose your position (1-9): 9
| |
-----
x | x | o
-----
| o |
Player X, choose your position (1-9): 3
| | x
-----
x | x | o
-----
| o | o
Player X, choose your position (1-9): 7
| | x
-----
x | x | o
-----
x | o | o
Player X wins! Congratulations!
```

Date / /
Page

Date / /
Page

Output:

Welcome to tic tac toe



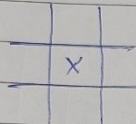
X's turn

filled.

position. ?

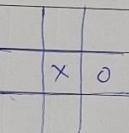
row.

Enter your move: 1, 1



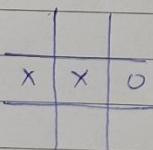
O's turn

Enter your move: 1, 2



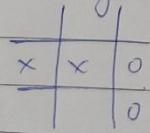
X's turn

Enter your move 1, 0



O's turn

Enter your move 2, 2



X's turn

Enter your move 0, 2

		X
X	X	O
		O

o's turn

Enter your move 2, 1

		X
X	X	O
	O	O

x's turn

Enter your move 2, 0

		X
X	X	O
X	O	O

o's turn

Enter your move 0, 1

	0	X
X	X	O
X	O	O

x's turn

Enter your move 0, 0

X	0	X
X	X	O
X	O	O

X won

Implement vacuum cleaner agent

```
import collections

def get_actions(state):
    actions = []
    room_status = list(state[:4])
    location = state[4] - 1

    if room_status[location] == 1:
        actions.append("Suck")

    if location < 3:
        actions.append("Right")

    if location > 0:
        actions.append("Left")

    return actions

def apply_action(state, action):
    room_status = list(state[:4])
    location = state[4] - 1

    if action == "Suck":
        room_status[location] = 0
    elif action == "Right":
        location += 1
    elif action == "Left":
        location -= 1

    return tuple(room_status + [location + 1])

def solve_vacuum_problem(initial_state):
    queue = collections.deque([(initial_state, [])])
    visited = {initial_state}

    while queue:
        current_state, path = queue.popleft()
```

```

        if all(room == 0 for room in current_state[:4]):
            print("Goal state reached:", current_state)
            print("Path taken:", path)
            return path

    actions = get_actions(current_state)

    for action in actions:
        next_state = apply_action(current_state, action)

        if next_state not in visited:
            visited.add(next_state)
            new_path = path + [action]
            queue.append((next_state, new_path))

    return None

if __name__ == "__main__":
    initial_state_1 = (1, 1, 1, 1, 1)
    print("Solving for initial state:", initial_state_1)
    solve_vacuum_problem(initial_state_1)

    print("\n" + "="*50 + "\n")

    initial_state_2 = (0, 1, 0, 1, 3)
    print("Solving for initial state:", initial_state_2)
    solve_vacuum_problem(initial_state_2)

```

The screenshot shows a Google Colab interface with multiple tabs open. The active tab is 'vacuum.py - Colab'. The code in the notebook is as follows:

```
vacuum.py
File Edit View Insert Runtime Tools Help
Commands + Code + Text > Run all
actions = get_actions(current_state)

for action in actions:
    next_state = apply_action(current_state, action)

    if next_state not in visited:
        visited.add(next_state)
        new_path = path + [action]
        queue.append((next_state, new_path))

return None

if __name__ == "__main__":
    initial_state_1 = (1, 1, 1, 1, 0)
    print("Solving for initial state:", initial_state_1)
    solve_vacuum_problem(initial_state_1)

    print("\n" + "="*50 + "\n")

    initial_state_2 = (0, 1, 0, 1, 2)
    print("Solving for initial state:", initial_state_2)
    solve_vacuum_problem(initial_state_2)
```

The output of the code execution is:

```
Solving for initial state: (1, 1, 1, 1, 0)
Goal state reached: (0, 0, 0, 0, 2)
Path taken: ['Suck', 'Right', 'Suck', 'Down', 'Suck', 'Left', 'Suck']

-----
Solving for initial state: (0, 1, 0, 1, 2)
Goal state reached: (0, 0, 0, 0, 1)
Path taken: ['Right', 'Suck', 'Up', 'Suck']
```

Output:-

Enter status of room A (C for clean, D for dirty): d

Enter status of room B (C for clean, D for dirty): d

Which room to move to ? (A or B): a

Room A is dirty cleaning now.

Which room to move to ? (A or B): b

Room B is dirty cleaning now.

All rooms are clean. Exiting.

Total cost of moves \$0

\$ 0.00

Program 2

Implement 8 puzzle problems using

- a) Depth First Search (DFS)
- b) Iterative deepening search

- a) Depth First Search (DFS):

Code:

```
def print_state(state):
    for i in range(0, 9, 3):
        print(state[i:i+3])
    print()

def is_goal(state):
    return state == "123804765"

def get_neighbors(state):
    neighbors = []
    moves = {'Up': -3, 'Down': 3, 'Left': -1, 'Right': 1}
    zero_index = state.index('0')

    for move, pos_change in moves.items():
        new_index = zero_index + pos_change
        if move == 'Left' and zero_index % 3 == 0:
            continue
        if move == 'Right' and zero_index % 3 == 2:
            continue
        if move == 'Up' and zero_index < 3:
            continue
        if move == 'Down' and zero_index > 5:
            continue
        state_list = list(state)
        state_list[zero_index], state_list[new_index] = state_list[new_index],
        state_list[zero_index]
        neighbors.append("".join(state_list), move))
    return neighbors

def dfs(start_state, max_depth=20):
    visited = set()
    stack = [(start_state, [], [], 0)] # (state, path, moves, depth)
```

```

while stack:
    current_state, path, moves, depth = stack.pop()

    if current_state in visited:
        continue
    visited.add(current_state)

    if is_goal(current_state):
        steps = path + [current_state]
        print("\n Goal reached (DFS)!\n")
        for i, step in enumerate(steps):
            print(f"Step {i}:")
            print_state(step)
        print("Moves:", " -> ".join(moves))
        print("Total steps to goal:", len(steps) - 1)
        print("Total unique states visited:", len(visited))
        return

    if depth < max_depth:
        for neighbor, move in reversed(get_neighbors(current_state)):
            if neighbor not in visited:
                stack.append((neighbor, path + [current_state], moves + [move], depth + 1))

print(f"No solution found within depth limit {max_depth}!")

```

start = "283164705"
dfs(start, max_depth=10)

The screenshot shows a Google Colab notebook titled "Untitled2.ipynb". The code cell contains a search algorithm, likely Depth-First Search (DFS), which has reached its goal. The output is as follows:

```
Goal reached (DFS)!

Step 0:
283
164
765

Step 1:
283
184
765

Step 2:
283
184
765

Step 3:
023
184
765

Step 4:
123
084
765

Step 5:
123
084
765

Moves: Up -> Up -> Left -> Down -> Right
Total steps to goal: 5
Total unique states visited: 32
```

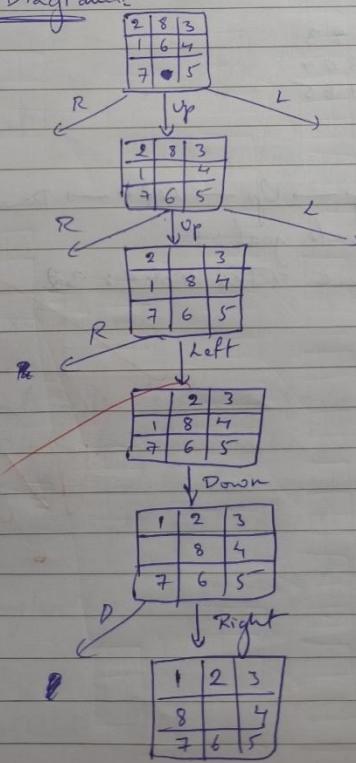
At the bottom of the Colab interface, there is a text input field with the placeholder "What can I help you build?" and a button with a diamond icon and a right-pointing arrow.

4. 8-puzzle problem (non-heuristic using DFS)

Algorithm

- Start from Initial state and compare with the goal matrix.
- In DFS move the space to the up, down, right and left
- Then move the space to available space to the left most & check if it matches the solution or else backtrace to started matrix then compare.
- If found return the matrix or No of iterations.
- We must set the depth limit. (10)

Transition Diagrams



(Depth limit = 10)

Output:

Goal Reached (DFS)!

Step 0: 283

164

765

Step 1: 283

104

765

Step 2: 203

184

765

Step 3: 023

1084

765

Step 4: 123

084

765

Step 5: 123

804

765

Moves: Up → Up → Left → Down → Right

Total steps to goal: 5

Total unique states visited: 32.

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e
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b) Iterative deepening search

Code:

```
GOAL = "123804765"
MOVE_OFFSETS = {'U': -3, 'L': -1, 'R': 1, 'D': 3}
```

```
def is_valid_move(z, m):
    if m == 'L' and z % 3 == 0: return False
    if m == 'R' and z % 3 == 2: return False
    if m == 'U' and z < 3: return False
    if m == 'D' and z > 5: return False
    return True

def apply_move(state, m):
    z = state.index('0')
    s = z + MOVE_OFFSETS[m]
    a = list(state)
    a[z], a[s] = a[s], a[z]
    return ''.join(a)

def depth_limited_search(state, limit, visited, path):
    if state == GOAL: return path
    if limit == 0: return None
    visited.add(state)
    z = state.index('0')
    for m in ['U','L','R','D']:
        if is_valid_move(z, m):
            ns = apply_move(state, m)
            if ns not in visited:
                r = depth_limited_search(ns, limit - 1, visited, path + m)
                if r is not None: return r
    return None

def iterative_deepening_search(start_state):
    d = 0
    total_visited = set()
    while True:
        visited = set()
        r = depth_limited_search(start_state, d, visited, "")
        total_visited |= visited
        if r is not None:
            return r, len(r), len(total_visited)
        d += 1

def print_board(state):
    for i in range(0, 9, 3):
        print(state[i], state[i+1], state[i+2])
```

```

def replay_and_print(start_state, path):
    print("Steps:")
    print("Step 0:")
    print_board(start_state)
    cur = start_state
    for i, m in enumerate(path, 1):
        cur = apply_move(cur, m)
        print(f"Step {i} ({m}):")
        print_board(cur)

if __name__ == "__main__":
    start_state = "283164705"
    path, steps, unique_states = iterative_deepening_search(start_state)
    print("Moves to Goal:", path)
    print("Total Steps:", steps)
    print("Unique States Visited:", unique_states)
    replay_and_print(start_state, path)

```

```

Moves to Goal: UUDLR
Total Steps: 5
Unique States Visited: 20
Steps:
Step 0:
2 8 3
1 6 4
7 0 5
Step 1 (U):
2 8 3
1 0 4
7 6 5
Step 2 (U):
2 0 3
3 8 4
7 6 5
Step 3 (L):
0 2 3
1 8 4
7 6 5
Step 4 (D):
1 2 3
0 8 4
7 6 5
Step 5 (R):
1 2 3
8 0 4
7 6 5

```

5. 8-puzzle problem (non-heuristic) using iterative deepening search (IDS)

Ax
Algorithm Used for IDS:-

IterativeDeepeningSearch(start, goal):

for depth = 0 to ∞ :

 result = DepthLimitedSearch(start, goal, depth)

 if result == goal:

 return result.

DepthLimitedSearch(node, goal, limit):

 if node == goal:

 return goal

 else if limit == 0:

 return "cutoff"

 else:

 for each child in Expand(node):

 result = DepthLimitedSearch(child, goal, limit)

 if result == goal:

 return result

 return "not found"

→ IDS starts with depth = 0 (only the root)

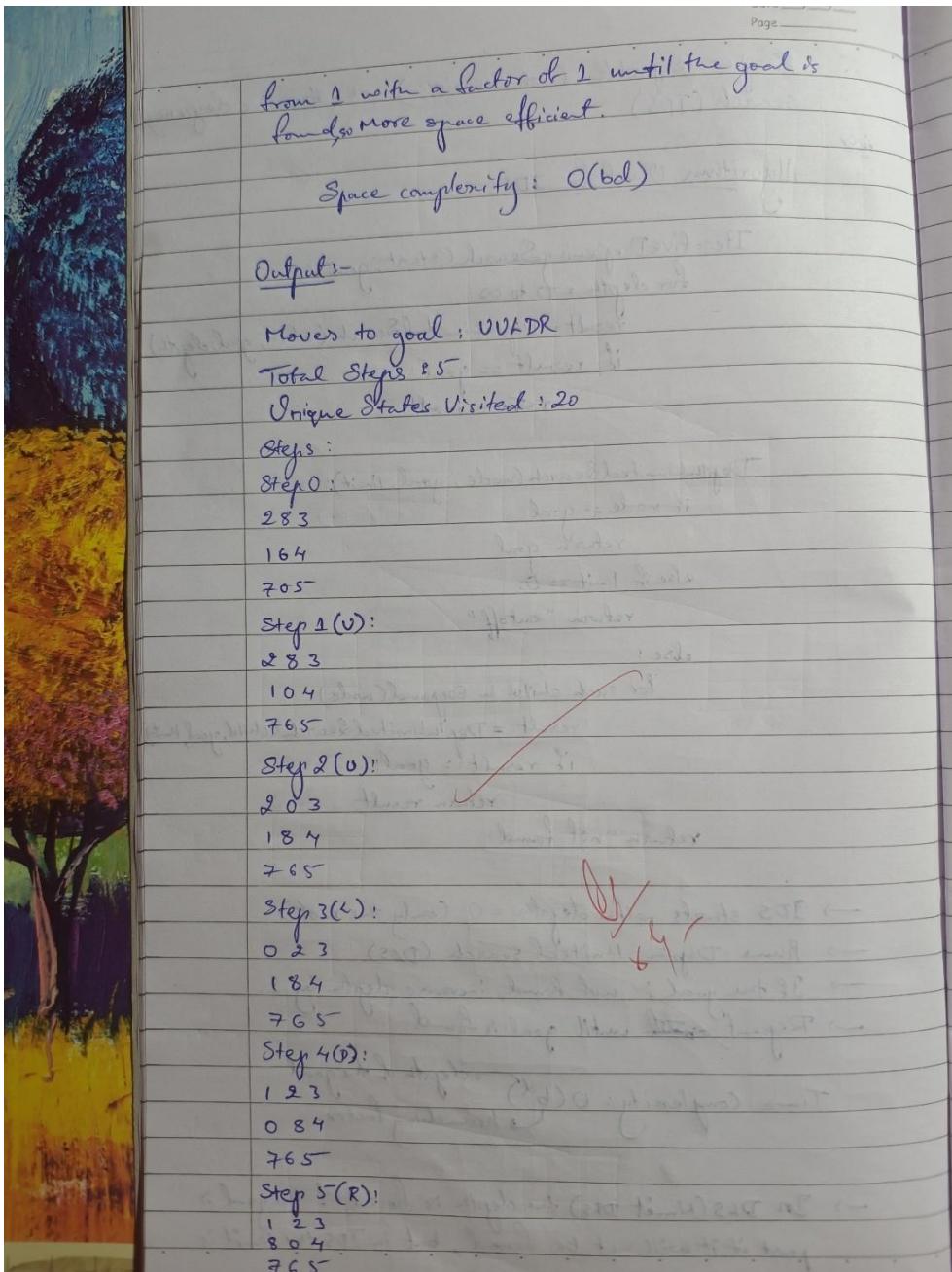
→ Runs Depth-Limited Search (DLS).

→ If the goal is not found, increase depth by 1.

→ Repeat until goal is found.

Time Complexity: $O(b^d)$ depth of the goal
branching factor.

→ In DLS (which is IDS) the depth is fixed, if the goal is not found then it will not be found but in IDS the limit is



Program 3

Implement A* search algorithm

- a) Misplaced Tiles
- b) Manhattan Distance

Misplaced Tiles

Code:

```
GOAL = "123804765"
MOVE_OFFSETS = {'U': -3, 'L': -1, 'R': 1, 'D': 3}

def is_valid_move(z, m):
    if m == 'L' and z % 3 == 0: return False
    if m == 'R' and z % 3 == 2: return False
    if m == 'U' and z < 3: return False
    if m == 'D' and z > 5: return False
    return True

def apply_move(state, m):
    z = state.index('0')
    s = z + MOVE_OFFSETS[m]
    a = list(state)
    a[z], a[s] = a[s], a[z]
    return ''.join(a)

def misplaced_tiles(state):
    return sum(1 for i in range(9) if state[i] != '0' and state[i] != GOAL[i])

def ida_star(start):
    bound = misplaced_tiles(start)
    path = [(start, '')]
    visited = set([start])
    total_visited = set()

    def search(path, g, bound):
        state, moves = path[-1]
        f = g + misplaced_tiles(state)
        if f > bound:
            return f, None
        if state == GOAL:
            return True, moves
        min_bound = float("inf")
        z = state.index('0')
        for m in ['U', 'L', 'R', 'D']:
            if is_valid_move(z, m):
                new_state = apply_move(state, m)
                if new_state not in visited:
                    path.append((new_state, moves + [m]))
                    if search(path, g + 1, bound):
                        return f, moves
                    path.pop()
                    visited.add(new_state)
                    if f < min_bound:
                        min_bound = f
        return min_bound, None

    f, moves = search(path, 0, bound)
    return f, moves
```

```

        if new_state not in {s for s, _ in path}:
            path.append((new_state, moves + m))
            total_visited.add(new_state)
            t, sol = search(path, g+1, bound)
            if t == True: return True, sol
            if isinstance(t, int) and t < min_bound:
                min_bound = t
            path.pop()
        return min_bound, None

while True:
    t, sol = search(path, 0, bound)
    if t == True:
        return sol, len(sol), len(total_visited)
    if t == float("inf"):
        return None, 0, len(total_visited)
    bound = t

def print_board(state):
    for i in range(0, 9, 3):
        print(state[i], state[i+1], state[i+2])

def replay_and_print(start_state, path):
    print("Steps:")
    print("Step 0:")
    print_board(start_state)
    cur = start_state
    for i, m in enumerate(path, 1):
        cur = apply_move(cur, m)
        print(f"Step {i} ({m}):")
        print_board(cur)

def is_solvable(state):
    s = [int(c) for c in state if c != '0']
    inv = 0
    for i in range(len(s)):
        for j in range(i+1, len(s)):
            if s[i] > s[j]: inv += 1
    return inv % 2 == 0

if __name__ == "__main__":
    start_state = "283164705"
    path, steps, unique_states = ida_star(start_state)
    print("Moves to Goal:", path)
    print("Total Steps:", steps)
    print("Unique States Visited:", unique_states)
    replay_and_print(start_state, path)

```

The screenshot shows a Google Colab interface with a notebook titled "Untitled3.ipynb". The code in the notebook is as follows:

```
if __name__ == "__main__":
    start_state = "283164795"
    path, steps, unique_states = ida_star(start_state)
    print("Moves to Goal:", path)
    print("Total Steps:", steps)
    print("Unique States Visited:", unique_states)
    replay_and_print(start_state, path)
```

The output of the code is:

```
Moves to Goal: UMLDR
Total Steps: 5
Unique States Visited: 9
Steps:
Step 0:
2 8 3
1 6 4
7 0 5
Step 1 (U):
2 8 3
1 0 4
7 6 5
Step 2 (U):
2 0 3
1 8 4
7 6 5
Step 3 (L):
0 2 3
1 8 4
7 6 5
Step 4 (D):
1 2 3
0 8 4
7 6 5
Step 5 (R):
1 2 3
8 0 4
7 6 5
```

Below the notebook, a terminal window shows the execution environment. The status bar indicates "Variables" and "Terminal" are open, along with system information like "3:14 PM" and "Python 3".

Date ___/___/___
Page ___

6. 8 puzzle (heuristic approach) ~~A*~~ Misplaced tiles

Algorithm:

Step 1: Initialize start node with $g=0$,

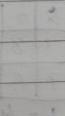
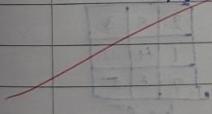
calculate $h = \text{no. of tile out of place}$,

$f(n) = g(n) + h(n)$, put it in open list

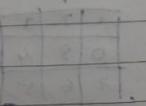
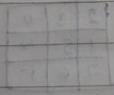
Step 2: Take node with lowest from open list. If goal, stop.

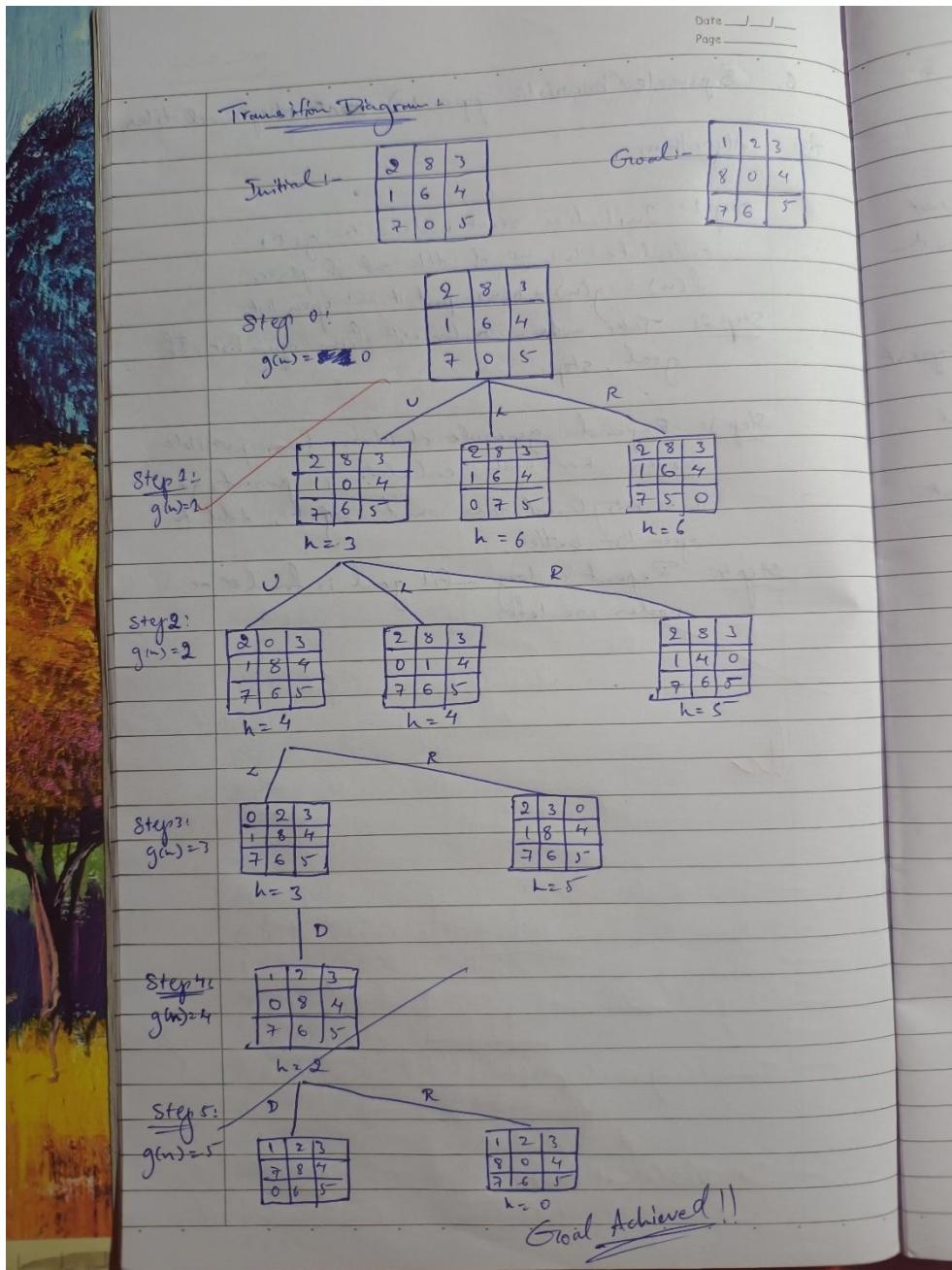
Step 3: Expand: generate children from possible moves. For each, calculate $g = \text{parent } g + 1$, $h = \text{misplaced tiles count, } f = g + h$, add to open list better.

Step 4: Repeat, loop until goal is found or no nodes are left.



Or





Output:

Moves to Goal: UULDR

Total Steps : 5

Unique States Visited: 9

Steps :

Step 0:

2 8 3

1 6 4

7 0 5

Step 1 (U):

2 8 3

1 0 4

7 6 5

Step 2 (U):

2 0 3

1 8 4

7 6 5

Step 3 (L):

0 2 3

1 8 4

7 6 5

Step 4 (D):

1 2 3

0 8 4

7 6 5

Step 5 (R):

1 2 3

9 0 4

7 6 5

Manhattan Distance:

Code:

GOAL = "123804765"

MOVE_OFFSETS = {'U': -3, 'L': -1, 'R': 1, 'D': 3}

```
def is_valid_move(z, m):
    if m == 'L' and z % 3 == 0: return False
    if m == 'R' and z % 3 == 2: return False
    if m == 'U' and z < 3: return False
    if m == 'D' and z > 5: return False
    return True
```

```
def apply_move(state, m):
    z = state.index('0')
    s = z + MOVE_OFFSETS[m]
    a = list(state)
    a[z], a[s] = a[s], a[z]
    return ''.join(a)
```

```
def manhattan_distance(state):
    dist = 0
    for i, val in enumerate(state):
        if val != '0':
            goal_pos = GOAL.index(val)
            x1, y1 = divmod(i, 3)
            x2, y2 = divmod(goal_pos, 3)
            dist += abs(x1 - x2) + abs(y1 - y2)
    return dist
```

```
def ida_star(start):
    bound = manhattan_distance(start)
    path = [(start, '')]
    total_visited = set([start])
```

```
def search(path, g, bound):
    state, moves = path[-1]
    f = g + manhattan_distance(state)
    if f > bound:
        return f, None
    if state == GOAL:
        return True, moves
    min_bound = float("inf")
    z = state.index('0')
    for m in ['U', 'L', 'R', 'D']:
        if is_valid_move(z, m):
            new_state = apply_move(state, m)
            if new_state not in {s for s, _ in path}:
```

```

        path.append((new_state, moves + m))
        total_visited.add(new_state)
        t, sol = search(path, g+1, bound)
        if t == True:
            return True, sol
        if isinstance(t, int) and t < min_bound:
            min_bound = t
            path.pop()
        return min_bound, None

while True:
    t, sol = search(path, 0, bound)
    if t == True:
        return sol, len(sol), len(total_visited)
    if t == float("inf"):
        return None, 0, len(total_visited)
    bound = t

def print_board(state):
    for i in range(0, 9, 3):
        print(state[i], state[i+1], state[i+2])

def replay_and_print(start_state, path):
    print("Steps:")
    print("Step 0:")
    print_board(start_state)
    cur = start_state
    for i, m in enumerate(path, 1):
        cur = apply_move(cur, m)
        print(f"Step {i} ({m}):")
        print_board(cur)

def is_solvable(state):
    s = [int(c) for c in state if c != '0']
    inv = 0
    for i in range(len(s)):
        for j in range(i+1, len(s)):
            if s[i] > s[j]: inv += 1
    return inv % 2 == 0

if __name__ == "__main__":
    start_state = "283164705"
    path, steps, unique_states = ida_star(start_state)
    print("Moves to Goal:", path)
    print("Total Steps:", steps)
    print("Unique States Visited:", unique_states)
    replay_and_print(start_state, path)

```

```
File Edit View Insert Runtime Tools Help
Commands + Code + Text Run all
if __name__ == "__main__":
    start_state = "283164705"
    path, steps, unique_states = ida_star(start_state)
    print("Moves to Goal:", path)
    print("Total Steps:", steps)
    print("Unique States Visited:", unique_states)
    replay_and_print(start_state, path)

Moves to Goal: UUDR
Total Steps: 5
Unique States Visited: 6
Steps:
Step 0:
2 8 3
1 6 4
7 0 5
Step 1 (U):
2 8 3
1 0 4
7 6 5
Step 2 (U):
2 0 3
1 8 4
7 6 5
Step 3 (L):
0 2 3
1 8 4
7 6 5
Step 4 (D):
1 2 3
0 8 4
7 6 5
Step 5 (R):
1 2 3
8 0 4
7 6 5
```

Variables Terminal

Date _____
Page _____

7. Manhattan A* (heuristic 8-puzzle problem).

A*

A* algorithm:

- A* search evaluates nodes by combining $g(n)$, the cost to reach the node and $h(n)$, the cost to get from the node to the goal.
- $f(n) = g(n) + h(n)$
- $f(n)$ is the evaluation function which gives the cheapest solution cost
- $g(n)$ is exact cost to reach node n from the initial state.
- $h(n)$ is an estimation of the assumed cost from current state(n) to reach the goal.

Step 1:-

Step 2:-

Step 3:-

$$f(n)=12$$

Step 4:-

blank).

Transition Diagrams

1	5	8
3	2	0
4	6	7

Initial State

1	2	3
4	5	6
7	8	

Goal State.

a), the cost
get from the

the cheapest

be initial

for current

Step 1:-

1	5	8
3	2	0
4	6	7

U

1	5	8
3	2	0
4	6	7

Goal State.

CUT 14-18

$$f(u) = 1 + 14 = 15 \quad = 1 + 13 = 14 \quad = 1 + 15 = 16$$

Step 2:-

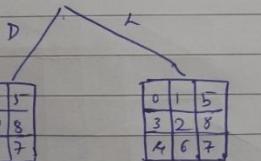
1	0	5
3	2	8
4	6	7

$$f(u) = 15 + 2 = 17$$

Step 3:-

1	2	5
3	0	8
4	6	7

$$f(u) = 12 + 3 = 15$$



Step 4:-

1	2	5
3	8	
4	6	7

$$f(u) = 10 + 4 = 14$$

1	2	5
3	8	
4	6	7

$$f(u) = 10 + 4 = 14$$

1	2	5
3	6	8
4	7	

$$f(u) = 10 + 4 = 14$$

Page _____

Output:

Moves to Goal: UULDR

Total steps: 5

Unique States Visited: 6

Steps:

Step 0:

2	8	3
1	6	4
7	0	5

Step 1 (U):

2	8	3
0	4	1
7	6	5

Step 2 (U):

2	0	3
1	8	4
7	6	5

Step 3 (L):

0	2	3
1	8	4
7	6	5

Step 4 (D):

1	2	3
0	8	4
7	6	5

Step 5 (R):

1	2	3
8	0	4
7	6	5

An 8

Program 4

Implement Hill Climbing search algorithm to solve N-Queens problem

Code:

```
import itertools
```

```
def calculate_attacks(state):
```

```
    attacks = 0
```

```
    n = len(state)
```

```
    for i in range(n):
```

```
        for j in range(i + 1, n):
```

```
            if state[i] == state[j]:
```

```
                attacks += 1
```

```
            if abs(state[i] - state[j]) == abs(i - j):
```

```
                attacks += 1
```

```
    return attacks
```

```
def get_neighbors(state):
```

```
    neighbors = []
```

```
    n = len(state)
```

```
    for col in range(n):
```

```
        for row in range(n):
```

```
            if state[col] != row:
```

```
                new_state = list(state)
```

```
                new_state[col] = row
```

```
                neighbors.append(tuple(new_state))
```

```
    return neighbors
```

```
def hill_climb(initial_state):
```

```
    current = initial_state
```

```
    current_attacks = calculate_attacks(current)
```

```
    print(f"\nStarting Hill Climb from: {current}, Attacks: {current_attacks}")
```

```
    while True:
```

```
        neighbors = get_neighbors(current)
```

```
        if not neighbors:
```

```
            break
```

```
        neighbor = min(neighbors, key=lambda x: calculate_attacks(x))
```

```
        neighbor_attacks = calculate_attacks(neighbor)
```

```
        if neighbor_attacks >= current_attacks:
```

```
            break
```

```
        current, current_attacks = neighbor, neighbor_attacks
```

```
        print(f"Move to: {current}, Attacks: {current_attacks}")
```

```
    return current, current_attacks
```

```
if __name__ == "__main__":
```

```

print("Name: Sohan R")
print("USN: 1BM23CS336")
print(f"\nTotal possible states: {4**4} ")

all_states = itertools.product(range(4), repeat=4)
for state in all_states:
    print(f"State: {state}, Attacks: {calculate_attacks(state)}")

state_input = input("\nEnter initial state as 4 numbers separated by space (e.g. 0 1 2 3): ")
initial_state = tuple(map(int, state_input.strip().split()))

final_state, final_attacks = hill_climb(initial_state)

print("\n==== Final Result ====")
print(f"Final State: {final_state}, Attacks: {final_attacks}")

```

The screenshot shows a Google Colab notebook titled "Untitled2.ipynb". The code cell contains the provided Python script. The output pane shows the execution results:

```

Name: Sohan R
USN: 1BM23CS336

Total possible states: 256
State: (0, 0, 0, 0), Attacks: 6
State: (0, 0, 0, 1), Attacks: 4
State: (0, 0, 0, 2), Attacks: 4
State: (0, 0, 0, 3), Attacks: 4
State: (0, 0, 1, 0), Attacks: 5
State: (0, 0, 1, 1), Attacks: 3
State: (0, 0, 1, 2), Attacks: 4
State: (0, 0, 1, 3), Attacks: 3
State: (0, 0, 2, 0), Attacks: 4
State: (0, 0, 2, 1), Attacks: 3
State: (0, 0, 2, 2), Attacks: 4
State: (0, 0, 2, 3), Attacks: 4
State: (0, 0, 3, 0), Attacks: 3
State: (0, 0, 3, 1), Attacks: 1
State: (0, 0, 3, 2), Attacks: 3
State: (0, 0, 3, 3), Attacks: 3
State: (0, 1, 0, 0), Attacks: 5
State: (0, 1, 0, 1), Attacks: 5
State: (0, 1, 0, 2), Attacks: 3
State: (0, 1, 0, 3), Attacks: 5
State: (0, 1, 1, 0), Attacks: 4
State: (0, 1, 1, 1), Attacks: 4
State: (0, 1, 1, 2), Attacks: 3
State: (0, 1, 1, 3), Attacks: 4
State: (0, 1, 2, 0), Attacks: 4
State: (0, 1, 2, 1), Attacks: 5
State: (0, 1, 2, 2), Attacks: 4

```

```

initial_state = tuple(map(int, state_input.strip().split()))
final_state, final_attacks = hill_climb(initial_state)

print("\n==== Final Result ===")
print(f"Final State: {final_state}, Attacks: {final_attacks}")

----- [3] -----
State: (0, 1, 0, 3), Attacks: 5
State: (0, 1, 1, 0), Attacks: 4
State: (0, 1, 1, 1), Attacks: 4
State: (0, 1, 1, 2), Attacks: 3
State: (0, 1, 1, 3), Attacks: 4
State: (0, 1, 2, 0), Attacks: 4
State: (0, 1, 2, 1), Attacks: 5
State: (0, 1, 2, 2), Attacks: 4
State: (0, 1, 2, 3), Attacks: 6
State: (0, 1, 3, 0), Attacks: 2
State: (0, 1, 3, 1), Attacks: 2
State: (0, 1, 3, 2), Attacks: 2
State: (0, 1, 3, 3), Attacks: 4
State: (0, 2, 0, 0), Attacks: 4
State: (0, 2, 0, 1), Attacks: 2
State: (0, 2, 0, 2), Attacks: 2
State: (0, 2, 0, 3), Attacks: 2
State: (0, 2, 1, 0), Attacks: 4
State: (0, 2, 1, 1), Attacks: 2
State: (0, 2, 1, 2), Attacks: 3
State: (0, 2, 1, 3), Attacks: 2
State: (0, 2, 2, 0), Attacks: 4
State: (0, 2, 2, 1), Attacks: 3
State: (0, 2, 2, 2), Attacks: 4
State: (0, 2, 2, 3), Attacks: 4
----- [3] -----
print("Final State: {final_state}, Attacks: {final_attacks}")

----- [3] -----
State: (0, 2, 2, 2), Attacks: 4
State: (0, 2, 2, 3), Attacks: 4
State: (0, 2, 3, 0), Attacks: 3
State: (0, 2, 3, 1), Attacks: 1
State: (0, 2, 3, 2), Attacks: 3
State: (0, 2, 3, 3), Attacks: 3
State: (0, 3, 0, 0), Attacks: 3
State: (0, 3, 0, 1), Attacks: 3
State: (0, 3, 0, 2), Attacks: 1
State: (0, 3, 0, 3), Attacks: 3
State: (0, 3, 1, 0), Attacks: 2
State: (0, 3, 1, 1), Attacks: 2
State: (0, 3, 1, 2), Attacks: 1
State: (0, 3, 1, 3), Attacks: 2
State: (0, 3, 2, 0), Attacks: 3
State: (0, 3, 2, 1), Attacks: 4
State: (0, 3, 2, 2), Attacks: 3
State: (0, 3, 2, 3), Attacks: 5
State: (0, 3, 3, 0), Attacks: 2
State: (0, 3, 3, 1), Attacks: 2
State: (0, 3, 3, 2), Attacks: 2
State: (0, 3, 3, 3), Attacks: 4
State: (1, 0, 0, 0), Attacks: 4
State: (1, 0, 0, 1), Attacks: 4
State: (1, 0, 0, 2), Attacks: 3
State: (1, 0, 0, 3), Attacks: 2
State: (1, 0, 1, 0), Attacks: 5
State: (1, 0, 1, 1), Attacks: 5
State: (1, 0, 1, 2), Attacks: 5
State: (1, 0, 1, 3), Attacks: 3
State: (1, 0, 2, 0), Attacks: 2
----- [3] -----

```


The image shows two side-by-side screenshots of the Google Colab interface, both displaying the same Python code and its execution results.

Code:

```
print(f"Final State: {final_state}, Attacks: {final_attacks}")
```

Execution Results (Visible States):

- State: (2, 0, 1, 2), Attacks: 4
- State: (2, 0, 1, 3), Attacks: 1
- State: (2, 0, 2, 0), Attacks: 2
- State: (2, 0, 2, 1), Attacks: 2
- State: (2, 0, 2, 2), Attacks: 4
- State: (2, 0, 2, 3), Attacks: 2
- State: (2, 0, 3, 0), Attacks: 1
- State: (2, 0, 3, 1), Attacks: 0
- State: (2, 0, 3, 2), Attacks: 3
- State: (2, 0, 3, 3), Attacks: 1
- State: (2, 1, 0, 0), Attacks: 4
- State: (2, 1, 0, 1), Attacks: 5
- State: (2, 1, 0, 2), Attacks: 4
- State: (2, 1, 0, 3), Attacks: 4
- State: (2, 1, 1, 0), Attacks: 3
- State: (2, 1, 1, 1), Attacks: 4
- State: (2, 1, 1, 2), Attacks: 4
- State: (2, 1, 1, 3), Attacks: 3
- State: (2, 1, 2, 0), Attacks: 3
- State: (2, 1, 2, 1), Attacks: 5
- State: (2, 1, 2, 2), Attacks: 5
- State: (2, 1, 2, 3), Attacks: 5
- State: (2, 1, 3, 0), Attacks: 1
- State: (2, 1, 3, 1), Attacks: 2
- State: (2, 1, 3, 2), Attacks: 3
- State: (2, 1, 3, 3), Attacks: 3
- State: (2, 2, 0, 0), Attacks: 4
- State: (2, 2, 0, 1), Attacks: 3
- State: (2, 2, 0, 2), Attacks: 4
- State: (2, 2, 0, 3), Attacks: 2
- State: (2, 2, 1, 0), Attacks: 4
- State: (2, 2, 1, 1), Attacks: 5
- State: (2, 2, 1, 2), Attacks: 5
- State: (2, 2, 1, 3), Attacks: 5
- State: (2, 2, 2, 0), Attacks: 6
- State: (2, 2, 2, 1), Attacks: 4
- State: (2, 2, 2, 2), Attacks: 6
- State: (2, 2, 2, 3), Attacks: 4
- State: (2, 2, 3, 0), Attacks: 3
- State: (2, 2, 3, 1), Attacks: 2
- State: (2, 2, 3, 2), Attacks: 5
- State: (2, 2, 3, 3), Attacks: 3
- State: (2, 3, 0, 0), Attacks: 3
- State: (2, 3, 0, 1), Attacks: 4
- State: (2, 3, 0, 2), Attacks: 3
- State: (2, 3, 0, 3), Attacks: 3
- State: (2, 3, 1, 0), Attacks: 2
- State: (2, 3, 1, 1), Attacks: 3
- State: (2, 3, 1, 2), Attacks: 3
- State: (2, 3, 1, 3), Attacks: 2
- State: (2, 3, 2, 0), Attacks: 3
- State: (2, 3, 2, 1), Attacks: 5
- State: (2, 3, 2, 2), Attacks: 5
- State: (2, 3, 2, 3), Attacks: 5
- State: (2, 3, 3, 0), Attacks: 2
- State: (2, 3, 3, 1), Attacks: 3
- State: (2, 3, 3, 2), Attacks: 4
- State: (2, 3, 3, 3), Attacks: 4
- State: (3, 0, 0, 0), Attacks: 4
- State: (3, 0, 0, 1), Attacks: 2

System Status:

- RAM: 1236 AM
- Disk: 12:58 AM
- 23-09-2025
- ENG IN
- 22°C Mostly cloudy

colab.research.google.com/drive/1BFoKGMeMAXdSQLdgxTqsTLAroQjkSVxv3#scrollTo=7s4uMfypxeR3

Untitled2.ipynb

File Edit View Insert Runtime Tools Help

Commands + Code + Text Run all

```
print("Final State: {final_state}, Attacks: {final_attacks}")
for state in states:
    print(f"State: {state}, Attacks: {attacks}")
```

RAM Disk

Variables Terminal

22°C Mostly cloudy

Search

12:36 AM Python 3

colab.research.google.com/drive/1BFoKGMeMAXdSQLdgxTqsTLAroQjkSVxv3#scrollTo=7s4uMfypxeR3

Untitled2.ipynb

File Edit View Insert Runtime Tools Help

Commands + Code + Text Run all

```
print("Final State: {final_state}, Attacks: {final_attacks}")
for state in states:
    print(f"State: {state}, Attacks: {attacks}")
```

RAM Disk

Variables Terminal

22°C Mostly cloudy

Search

12:36 AM Python 3

Q. Implement Hill climbing algorithm to solve N-Queens problem.

Ans:

Algorithms:-

```
function HILL-CLIMBING(problem) returns a state that  
is a local maximum current ← MAKE-NODE(problem, INITIAL-  
STATE)
```

loop do

```
neighbor ← a highest-valued successor of current  
if neighbor. VALUE < current. VALUE then return  
current. STATE  
current ← neighbor.
```

- State: 4 queens on the board. No pair of queens are attacking each other.

Neighbor

— Variables: n_0, n_1, n_2, n_3 where n_i is the row position of the queen in column i . Assume that there is one queen per column

— Domain for each variable: $n_i \in \{0, 1, 2, 3\} \forall i$.

- Initial state: a random state
- Goal state: 4 queens on the board. No pair of queens are attacking each other.
- Neighbor relation: Swap the row positions of two queens.
- Cost function: The number of pairs of queens attacking each other, directly or indirectly.

Transition diagram



$$\text{Initial} = [3, 1, 2, 0]$$

		Q	
	Q		
		Q	
Q			

	Q			
Q				
	Q			
		Q		

$h=0$ $h=3$ $h=4$

	Q			
		Q		
Q				
	Q			

$h=0$ $h=2$ $h=2$

Q. Outputs:-

Total possible states : 256

State : (0, 0, 0, 0), Attacks : 6

State : (0, 0, 0, 1), Attacks : 4

State : (0, 0, 0, 2), Attacks : 4

State : (0, 0, 0, 3), Attacks : 4

State : (0, 0, 1, 0), Attacks : 5

State : (0, 0, 2, 0), Attacks : 3

⋮

⋮

⋮

⋮



4



2

88
10/2/21

Program 5

Simulated Annealing to Solve 8-Queens problem

Code:

```
import random
import math

def calculate_attacks(state):
    attacks = 0
    n = len(state)
    for i in range(n):
        for j in range(i + 1, n):
            if state[i] == state[j]:
                attacks += 1
            if abs(state[i] - state[j]) == abs(i - j):
                attacks += 1
    return attacks

def get_random_neighbor(state):
    n = len(state)
    col = random.randint(0, n - 1)
    row = random.randint(0, n - 1)
    while row == state[col]:
        row = random.randint(0, n - 1)
    new_state = list(state)
    new_state[col] = row
    return tuple(new_state)

def simulated_annealing(n=8, max_iterations=10000, temperature=100.0, cooling_rate=0.99):
    current = tuple(random.randint(0, n - 1) for _ in range(n))
    current_attacks = calculate_attacks(current)
    best = current
    best_attacks = current_attacks

    for _ in range(max_iterations):
        if current_attacks == 0:
            break
        neighbor = get_random_neighbor(current)
        neighbor_attacks = calculate_attacks(neighbor)
        delta = current_attacks - neighbor_attacks
        if delta > 0 or random.random() < math.exp(delta / temperature):
            current, current_attacks = neighbor, neighbor_attacks
        if current_attacks < best_attacks:
            best, best_attacks = current, current_attacks
        temperature *= cooling_rate
```

```

return best, best_attacks

if __name__ == "__main__":
    print("Name: Sohan R")
    print("USN: 1BM23CS336")

    best_state, attacks = simulated_annealing()
    non_attacking = 8 - attacks

    print("Best State:", best_state)
    print("Number of Attacking Pairs:", attacks)
    print("Number of Non-Attacking Queens:", non_attacking)
    if attacks == 0:
        print("Status: Found an optimal solution!")
    else:
        print("Status: Local optimum reached.")

```

The screenshot shows a Google Colab notebook titled "Untitled2.ipynb". The code cell contains the provided Python script. The output pane shows the execution results:

```

Name: Sohan R
USN: 1BM23CS336
Best State: (2, 4, 7, 3, 0, 6, 1, 5)
Number of Attacking Pairs: 0
Number of Non-Attacking Queens: 8
Status: Found an optimal solution!

```

The notebook interface includes tabs for "Variables" and "Terminal", and a status bar at the bottom showing the date and time.

9. Simulated Annealing: 8-Queens.

Ans

Algorithm:

```
current ← initial state  
T ← a large positive value  
while T > 0 do  
    next ← a random neighbor of current  
    ΔE ← current.cost - next.cost  
    if ΔE > 0 then  
        current ← next  
    else  
        current ← next with probability  $p = e^{\Delta E/T}$   
    end if  
    decrease T  
end while  
return current.
```

Output

The best position found is : [0 4 7 5 2 6 1 3]

The number of queens that are not attacking each other : 8

88
15/9/20

Program 6

Create a knowledge base using propositional logic and show that the given query entails the knowledge base or not.

Code:

```
import re
def pl_true(expr, model):
    if isinstance(expr, str):
        return model[expr]
    elif isinstance(expr, tuple):
        op = expr[0]
        if op == "not":
            return not pl_true(expr[1], model)
        elif op == "and":
            return pl_true(expr[1], model) and pl_true(expr[2], model)
        elif op == "or":
            return pl_true(expr[1], model) or pl_true(expr[2], model)
        elif op == "implies":
            return (not pl_true(expr[1], model)) or pl_true(expr[2], model)
    return False

def tt_entails(KB, query):
    symbols = list(get_symbols(KB) | get_symbols(query))
    return check_all(KB, query, symbols, {})

def get_symbols(expr):
    if isinstance(expr, str):
        return {expr}
    elif isinstance(expr, tuple):
        return get_symbols(expr[1]) | (get_symbols(expr[2]) if len(expr) > 2 else set())
    return set()

def check_all(KB, query, symbols, model):
    if not symbols:
        if pl_true(KB, model):
            return pl_true(query, model)
        else:
            return True
    else:
        rest = symbols[1:]
        p = symbols[0]
        m1 = model.copy(); m1[p] = True
        m2 = model.copy(); m2[p] = False
        return check_all(KB, query, rest, m1) and check_all(KB, query, rest, m2)

precedence = {
```

```

'not': 3,
'and': 2,
'or': 1,
'implies': 0
}

def infix_to_expr(infix_str):
    # Replace common symbols with standard keywords
    infix_str = infix_str.replace("¬", "not").replace("¬", "not")
    infix_str = infix_str.replace("∧", "and").replace("∧", "and")
    infix_str = infix_str.replace("∨", "or").replace("∨", "or")
    infix_str = infix_str.replace("→", "implies").replace("→", "implies")

    tokens = re.findall(r'[A-Za-z]+|not|and|or|implies|\(|)', infix_str)

    output = []
    ops = []

    def pop_op():
        op = ops.pop()
        if op == "not":
            right = output.pop()
            output.append((op, right))
        else:
            right = output.pop()
            left = output.pop()
            output.append((op, left, right))

    for token in tokens:
        if re.fullmatch(r'[A-Za-z]+', token): # symbol
            output.append(token)
        elif token == '(':
            ops.append(token)
        elif token == ')':
            while ops and ops[-1] != '(':
                pop_op()
            ops.pop() # remove '('
        elif token in precedence:
            while (ops and ops[-1] in precedence and
                   precedence[ops[-1]] >= precedence[token]):
                pop_op()
            ops.append(token)

    while ops:
        pop_op()

    return output[0]

```

```

print("Name: Sohan R")
print("USN : 1BM23CS336")

print("\nEnter logical expressions using standard infix notation.")
print("Supported operators: ~ or ∼ (not), ∧ or & (and), ∨ or | (or), → or -> (implies)")
print("Example KB : (A ∨ C) ∧ (B ∨ ∼C)")
print("Example Query: A ∨ B")

KB_infix = input("Enter Knowledge Base (KB): ")
query_infix = input("Enter Query: ")

try:
    KB = infix_to_expr(KB_infix)
    query = infix_to_expr(query_infix)

    result = tt_entails(KB, query)

    print("\nParsed KB : ", KB)
    print("Parsed Query: ", query)
    print("Does KB entail Query? :", "YES" if result else "NO")

except Exception as e:
    print("Error in parsing expression:", str(e))

```

The screenshot shows a Google Colab notebook titled 'Untitled2.ipynb'. The code cell contains the logic for parsing infix expressions and determining entailment. The output cell displays the user's name and USN, followed by the logic rules, supported operators, and examples. It then shows the parsed KB and query, and finally, it prints 'YES' as the entailment result.

```

Name: Sohan R
USN : 1BM23CS336

Enter logical expressions using standard infix notation.
Supported operators: ~ or ∼ (not), ∧ or & (and), ∨ or | (or), → or -> (implies)
Example KB : (A ∨ C) ∧ (B ∨ ∼C)
Example Query: A ∨ B
Enter Knowledge Base (KB): (A ∨ C) ∧ (B ∨ ∼C)
Enter Query: A ∨ B

Parsed KB : A
Parsed Query: A
Does KB entail Query? : YES

```

10. Propositional Logic :-

Ay Implementation of truth-table enumeration algorithm for deciding propositional entailment.
i.e., create a knowledge base using propositional logic and show that the given query entails the knowledge base or not.

Propositional Logic: Semantics :-

- Truth tables for connectives.

P	Q	$\neg P$	$P \wedge Q$	$P \vee Q$	$P \Leftrightarrow Q$
false	false	true	false	false	true
false	true	true	false	true	false
true	false	false	false	true	false
true	true	false	true	true	true

- Implication operator

P	Q	$P \Rightarrow Q$
false	false	true
false	true	true
true	false	false
true	true	true

$\text{KB} \models \alpha$

$\hookrightarrow \text{KB entails } \alpha \rightarrow$ means if KB is true ' α ' must be true.

<u>Q.</u>	<u>A</u>	<u>B</u>	<u>C</u>	<u>AVC</u>	<u>BV-C</u>	<u>KB</u>	<u>α</u>
	0	0	0	0	1	0	0
	0	0	1	1	0	0	0
	0	1	0	0	1	0	1
	0	1	1	1	1	1	1
	1	0	0	1	1	1	1
	1	0	1	1	0	0	1
	1	1	0	1	1	1	1
	1	1	1	1	1	1	1

Algorithms

1. Input:-

- A Knowledge Base (KB): a set of propositional sentences.
- A Query (α): the statement we want to check if it is entailed by KB

2. List all symbols:-

- Collect all propositional variables appearing in KB and the query

3. Generate models:-

- A model is a truth assignment (True/False) to every symbol.
- Create all possible combinations of truth values. (truth table).

4. Check entailment:-

- For each model:
 - If the KB is true in that model, check if α is also true.
 - If you ever find a model where KB is true but α is false, then KB does not entail α .

5. Final decision:-

- If \models every model where KB is true, α is also true
 \rightarrow return entailed.
- otherwise \rightarrow return not entailed.

Output:-

Name: Suman R

Enter logical expressions using standard infix notation.

Supported operators: \neg or \sim (not), \wedge or $\&$ (and), \vee or $|$ (\oplus)
 \rightarrow or \Rightarrow (implies)Example KB : $(A \vee C) \wedge (B \vee \neg C)$ Example Query: $A \vee B$ Enter Knowledge Base (KB): $(A \vee C) \wedge (B \vee \neg C)$ Enter Query: $A \vee B$

Parsed KB : A

Parsed Query: A

Does KB entail Query?: YES.

Consider $S \in T$ as variables & following relation.

$$a : r(S \vee T)$$

$$b : (S \wedge T)$$

$$c : T \vee r(T)$$

While truth table & show.

whether.

(i) a entails b

(ii) a entails c

TT

S	T	$a = S \vee T$	$b = S \wedge T$	$c = T \vee r(T)$
T	T	T	T	T
T	F	T	F	T
F	T	T	F	T
F	F	F	F	T

(i) Row 2: $a = T, b = F \times$

Row 3: $a = T, b = F \times$

\therefore No, a does not entail b

(ii) $a \vdash c$?

c is tautology

\therefore Yes.

8/8
2/9/28

Program 7

Implement unification in first order logic

Code:

```
import re
from collections import deque
VARIABLES = {"X", "Y", "Z", "z"}

TOKEN_REGEX = r"\s*([A-Za-z0-9_]+|[,()])\s*"

def tokenize(s):
    return [t for t in re.findall(TOKEN_REGEX, s) if t.strip()]

class Term:
    def __init__(self, name, args=None):
        self.name = name
        self.args = args or []
    def is_variable(self):
        return (not self.args) and (self.name in VARIABLES)
    def is_constant(self):
        return (not self.args) and (self.name not in VARIABLES)
    def __repr__(self):
        if self.args:
            return f'{self.name}({", ".join(map(repr, self.args))})'
        return self.name

def parse_term(tokens):
    name = tokens.popleft()
    if tokens and tokens[0] == '(':
        tokens.popleft()
        args = []
        if tokens[0] != ')':
            while True:
                args.append(parse_term(tokens))
                if tokens[0] == ',':
                    tokens.popleft()
                    continue
                elif tokens[0] == ')':
                    break
            tokens.popleft()
    return Term(name, args)
    return Term(name, [])

def parse(s):
    tks = deque(tokenize(s))
    term = parse_term(tks)
```

```

if tks:
    raise ValueError("Extra tokens after parse: " + ".join(tks))
return term

def apply_subst(t, subst):
    if t.is_variable():
        if t.name in subst:
            return apply_subst(subst[t.name], subst)
        return t
    if t.args:
        return Term(t.name, [apply_subst(a, subst) for a in t.args])
    return t

def occurs_check(var, term, subst):
    t = apply_subst(term, subst)
    if t.is_variable():
        return t.name == var
    if t.args:
        return any(occurs_check(var, a, subst) for a in t.args)
    return False

def unify(a, b):
    subst = {}
    eqs = deque([(a, b)])
    trace = []
    step = 0
    while eqs:
        step += 1
        s, t = eqs.popleft()
        s = apply_subst(s, subst)
        t = apply_subst(t, subst)
        trace.append((step, s, t, dict(subst)))
        if repr(s) == repr(t):
            continue
        if s.is_variable():
            if occurs_check(s.name, t, subst):
                return None, trace
            subst[s.name] = t
            continue
        if t.is_variable():
            if occurs_check(t.name, s, subst):
                return None, trace
            subst[t.name] = s
            continue

    if s.args and t.args:
        if s.name != t.name or len(s.args) != len(t.args):

```

```

        return None, trace
    for sa, ta in reversed(list(zip(s.args, t.args))):
        eqs.appendleft((sa, ta))
    continue

    return None, trace
    return subst, trace

def print_result(subst, trace):
    for item in trace:
        step, s, t, st = item
        print(f"Step {step}: unify {s} with {t} S = {st}")
    if subst is None:
        print("\nResult: UNIFICATION FAILED")
    else:
        final = {k: apply_subst(v, subst) for k, v in subst.items()}
        print("\nFinal MGU:")
        for k, v in final.items():
            print(f" {k} -> {v}")

if __name__ == "__main__":
    s1 = "p(b,X,f(g(Z)))"
    s2 = "p(z,f(Y),f(Y))"
    t1 = parse(s1)
    t2 = parse(s2)
    subst, trace = unify(t1, t2)
    print("Name: Sohan R")
    print("USN: 1BM23CS336\n")
    print("Input:")
    print(" ", s1)
    print(" ", s2)
    print("\nTrace:")
    print_result(subst, trace)

```

The screenshot shows a Google Colab notebook titled "Untitled10.ipynb". The code in cell [2] is as follows:

```

x = TermVar("x", "www.BIG.LT")
s1 = "p(b,X,f(g(Z)))"
s2 = "p(z,f(Y),f(Y))"
t1 = parse(s1)
t2 = parse(s2)
subst, trace = unify(t1, t2)
print("Name: Sohan R")
print("USN: 1B023CS36")
print("Input:")
print(s1)
print(" ")
print(s2)
print("Untrace:")
print_result(subst, trace)

```

The output of the code is:

```

Name: Sohan R
USN: 1B023CS36
Input:
p(b,X,f(g(Z)))
p(z,f(Y),f(Y))

Trace:
Step 1: unify p(b, X, f(g(Z))) with p(z, f(Y), f(Y))  S = {}
Step 2: unify b with z  S = {}
Step 3: unify X with f(Y)  S = {z: b}
Step 4: unify f(g(Z)) with f(Y)  S = {z: b, X: f(Y)}
Step 5: unify g(Z) with Y  S = {z: b, X: f(Y)}

Final RES:
z -> b
x -> f(g(z))
y -> g(z)

```

The Colab interface includes tabs for "Variables" and "Terminal" at the bottom, and a status bar showing "3:59PM" and "Python 3".

Solve the following:

1. Find Most General Unifier (MGU) of $\{p(b, x, f(g(z))), p(z, f(y), f(y))\}$

Ans:

$$\{p(b, x, f(g(z))), p(z, f(y), f(y))\}$$

$$s = \{\}$$

$$z \rightarrow b \rightarrow s = \{z \rightarrow b\}$$

$$x \rightarrow f(y) \rightarrow s = \{z \rightarrow b, x \rightarrow f(y)\}$$

$y \rightarrow g(z) \rightarrow$ substitute into $x \rightarrow x \rightarrow f(g(z))$

$$\text{Final MGU: } \{z \rightarrow b, x \rightarrow f(g(z)), y \rightarrow g(z)\}$$

2. Find Most General Unifier (MGU) of $\{Q(a, g(x, a), f(y))$ and $Q(a, g(f(b), a), x)\}$

Ans:

$$\{Q(a, g(x, a), f(y)), Q(a, g(f(b), a), x)\}$$

$$s = \{\}$$

$$x \rightarrow f(b) \rightarrow s \{x \rightarrow f(b)\}$$

$$y \rightarrow b \rightarrow s \{x \rightarrow f(b), y \rightarrow b\}$$

$$\text{Final MGU: } \{x \rightarrow f(b), y \rightarrow b\}$$

Date _____
Page _____

3. Find MGU of $\{f(a), g(y)), p(x, x)\}$

Ans: $S = \{\}$
 From arg₃: $x \rightarrow f(a) \rightarrow S = \{x \rightarrow f(a)\}$
 From arg₂: x must = $g(y)$ → requires $f(a) = g(y)$
 → impossible ($f \neq g$)

Result: UNIFICATION FAILS.

4. Unify $\{ \text{prime}(11) \text{ and prime}(y) \}$

Ans: $S = \{\}$
 $y \rightarrow 11$
 Final MGU: $\{y \rightarrow 11\}$

5. Unify $\{ \text{knows}(\text{John}, x), \text{knows}(y, \text{mother}(y)) \}$

Ans:
 $S = \{\}$
 $y \rightarrow \text{John} \rightarrow S = \{y \rightarrow \text{John}\}$
 $x \rightarrow \text{mother}(\text{John}) \rightarrow S = \{y \rightarrow \text{John}, x \rightarrow \text{mother}(\text{John})\}$
 Final MGU: $\{y \rightarrow \text{John}, x \rightarrow \text{mother}(\text{John})\}$

6. Unify $\{ \text{knows}(\text{John}, x), \text{know}(y, \text{Bill}) \}$

Ans:
 $S = \{\}$
 ~~$y \rightarrow \text{John} \rightarrow S = \{y \rightarrow \text{John}\}$~~
 ~~$x \rightarrow \text{Bill} \rightarrow S = \{y \rightarrow \text{John}, x \rightarrow \text{Bill}\}$~~
~~Final MGU: $\{y \rightarrow \text{John}, x \rightarrow \text{Bill}\}$~~

Week - 7

II. Unification Algorithm :- (First Order Logic - The process of finding a substitution that make different FOL (first order logic))

It is the process used to find substitution that make different FOL (first order logic)

Algorithm/Definitions

① Unify ($\text{knows}(\text{John}, n)$, $\text{knows}(\text{John}, \text{Jane})$)

$$\Theta = n / \text{Jane}$$

n / Jane
Unify ($\text{knows}(\text{John}, \text{Jane})$, $\text{knows}(\text{John}, \text{Jane})$)

② Unify ($\text{knows}(\text{John}, n)$, $\text{knows}(y, \text{Bill})$)

$$\Theta = y / \text{John}$$

$\text{knows}(\text{John}, n)$, $\text{knows}(\text{John}, \text{Bill})$

$$\Theta = n / \text{Bill}$$

$\text{knows}(\text{John}, \text{Bill})$, $\text{knows}(\text{John}, \text{Bill})$

Q. Find the NGU of

$$\left\{ P(b, x, f(g(z))) \right\}$$

$$\left\{ P(z, f(y), f(Y)) \right\}$$

Algorithm: Unify(V_1, V_2)

- Step 1: If V_1 or V_2 are variable or constant, then
- If V_1 or V_2 are identical, then return NIL.
 - Else if V_1 is a variable,
 - a. Then if V_2 occurs in V_1 , then return FAILURE.
 - b. Else return $\{ (V_2 / V_1) \}$.
 - Else if V_2 is a variable,
 - a. If V_1 ~~is variable~~ occurs in V_2 , then return FAILURE.
 - b. Else return $\{ (V_1 / V_2) \}$.
 - Else return FAILURE.

Step 2: If the initial Predicate symbols in V_1 and V_2 are not same, then return FAILURE.

Step 3: If V_1 and V_2 have a different number of arguments, then return FAILURE.

Step 4: Set Substitution set (SUBST) to NIL.

Step 5: For i = 1 to the number of elements in V_1 ,

- call Unify function with the ith element of V_1 and ith element of V_2 , and put the result into S.
Ans:
- If $S = \text{Failure}$ then return Failure.
- If $S \neq \text{NIL}$ then do,
 - a. Apply S to the remainder of both V_1 and V_2 .
 - b. SUBST = APPEND (S , SUBST).

Step 6: Return SUBST.

Solve

1. Find

A: 10A

B: 9B

C: 8C

D: 7D

E: 6E

F: 5F

G: 4G

H: 3H

I: 2I

J: 1J

Output for Question :-

Input:

$p(b, x, f(g(z)))$

$p(z, f(y), f(y))$

Traces

Step 1:- unify $p(b, x, f(g(z)))$ with $p(z, f(y), f(y)) \quad S = \{ \}$

Step 2:- unify b with $z \quad S = \{ z : b \}$

Step 3:- unify x with $f(y) \quad S = \{ z : b, x : f(y) \}$

Step 4:- unify $f(g(z))$ with $f(y) \quad S = \{ z : b, x : f(y) \}$

Step 5:- unify $g(z)$ with $y \quad S = \{ z : b, x : f(y) \}$

Final MGV:-

$z \rightarrow b$

$x \rightarrow f(g(z))$

$y \rightarrow g(z)$

Program 8

Create a knowledge base consisting of first order logic statements and prove the given query using forward reasoning.

Code:

```
name = "Sohan R"  
usn = "1BM23CS336"
```

```
KB = [  
    "American(Robert)",  
    "Enemy(A, America)",  
    "Missile(T1)",  
    "Owns(A, T1)"  
]
```

```
rules = [  
    {"name": "R1", "if": ["American(p)", "Weapon(q)", "Sells(p, q, r)", "Hostile(r)"], "then":  
    "Criminal(p)"},  
    {"name": "R2", "if": ["Missile(x)"], "then": "Weapon(x)"},  
    {"name": "R3", "if": ["Missile(x)", "Owns(A, x)"], "then": "Sells(Robert, x, A)"},  
    {"name": "R4", "if": ["Enemy(x, America)"], "then": "Hostile(x)"}  
]
```

```
def match(pattern, fact):  
    return pattern.split("(")[0] == fact.split("(")[0]
```

```
def condition_satisfied(cond, KB):  
    return any(match(cond, fact) for fact in KB)
```

```
def substitute(statement, mapping=None):  
    if not mapping:  
        mapping = {"p": "Robert", "r": "A", "q": "T1", "x": "T1"}  
    for var, val in mapping.items():  
        statement = statement.replace(var, val)  
    return statement
```

```
def forward_chaining(KB, rules):  
    inferred = set()  
    derivations = {}  
    added = True  
    while added:  
        added = False  
        for rule in rules:  
            if all(condition_satisfied(cond, KB) for cond in rule["if"]):  
                conclusion = substitute(rule["then"])  
                if conclusion not in KB:
```

```

        KB.append(conclusion)
        inferred.add(conclusion)
        derivations[conclusion] = {"rule": rule["name"], "premises": [substitute(p) for p in
rule["if"]]}
        added = True
    return KB, derivations

def print_tree(derivations, goal, level=0):
    if goal not in derivations:
        print(" " * level + f" └─ {goal}")
        return
    rule_info = derivations[goal]
    print(" " * level + f" └─ {goal} ← ({rule_info['rule']})")
    for premise in rule_info["premises"]:
        print_tree(derivations, premise, level + 1)

final_KB, derivations = forward_chaining(KB.copy(), rules)

print("\n====")
print(" FORWARD CHAINING RESULT")
print("====")
for fact in final_KB:
    print(f"- {fact}")

print("\n====")
print(" INFERENCE TREE")
print("====")
for conclusion in derivations:
    print_tree(derivations, conclusion)
    print()

print("-----")
print(f"Name : {name}")
print(f"USN : {usn}")
print("-----")

```

The screenshot shows a Google Colab interface with several tabs at the top: AI-LAB/lab8 at main · Sohan R · Week-9-AI-lab-FOL-Resolution · Week-10-AI-lab-Alpha-Beta-P · Untitled14.ipynb - Colab · Python code forward chaining.

The main area displays the following Python code:

```
print("Name : (name)")  
print("USN : (usn)")  
print("-----")
```

Below the code, the output is shown in two sections:

FORWARD CHAINING RESULT

```
-----  
- American(Robert)  
- Enemy(A, America)  
- Missile(T1)  
- Owns(A, T1)  
- WealthAttack(T1)  
- Sells(Robert, T1, A)  
- Hostile(T1)
```

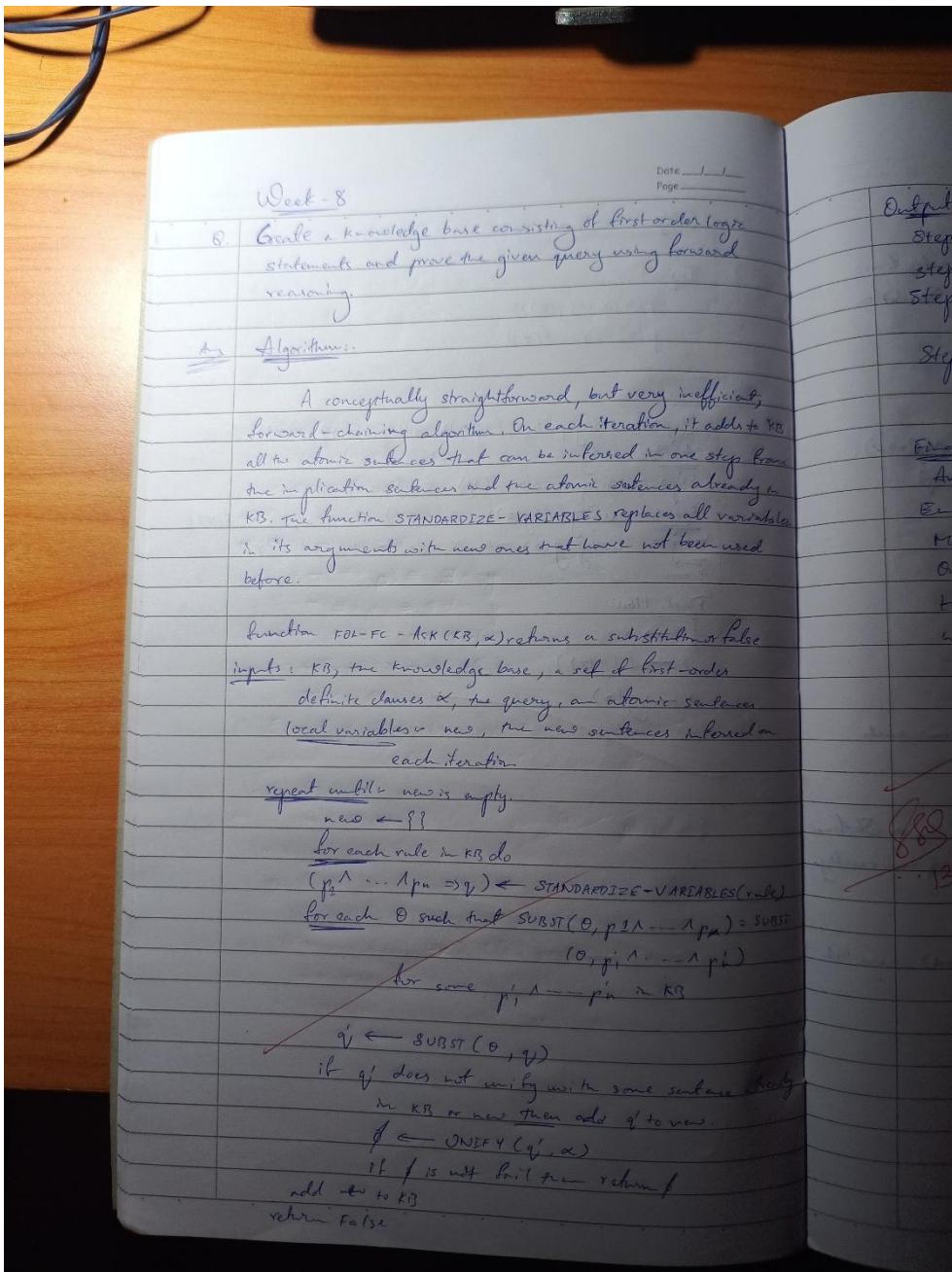
INFERENCE TREE

```
-----  
└── Meets(Robert, T1) ← (R2)  
    └── Missile(T1)  
        └── Sells(Robert, T1, A) ← (R3)  
            └── Missile(T1)  
                └── Owns(A, T1)  
            └── Hostile(T1) ← (R4)  
                └── Enemy(T1, AmerAsia)
```

At the bottom of the code cell, the variables are listed:

```
Name : Sohan R  
USN : 1BM2JCS336
```

The Colab interface includes standard navigation and search tools at the bottom.



Output

Step 2: Enemy (A, America) → Hostile (A)

Step 3: Missile (T₀) → Weapon (T₁)

Step 4: Missile (T₀) ∧ Owns (A, T₁) → Sells (Robert, T₁)

Step 5: American (Robert) ∧ Weapon (T₁) ∧
Sells (Robert, T₁, A) ∧ Hostile (A) → Criminal (Robert)

Final facts

American (Robert)

Enemy (A, America)

Missile (T₀)

Own (A, T₁)

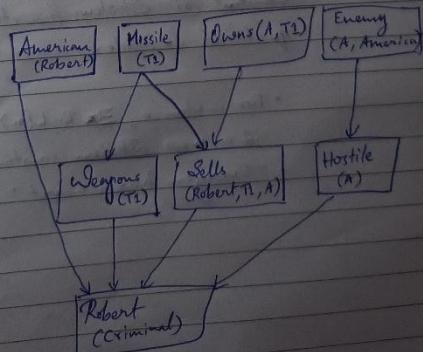
Hostile (A)

Weapon (T₁)

Sells (Robert, T₁, A)

Criminal (Robert)

88
... 13/10/2



Program 9

Create a knowledge base consisting of first order logic statements and prove the given query using Resolution.

Code:

```
def negate_literal(lit):
    return lit[1:] if lit.startswith("~") else "~" + lit

def resolve(ci, cj):
    ci = set(ci)
    cj = set(cj)
    resolvents = []

    for di in ci:
        ndi = negate_literal(di)
        if ndi in cj:
            new_clause = (ci - {di}) | (cj - {ndi})
            if len(new_clause) == 0:
                resolvents.append({"res": set(), "pair": (ci, cj)})
            else:
                resolvents.append({"res": new_clause, "pair": (ci, cj)})
    return resolvents

clauses = [
    {"~Food(x)", "Likes(John,x)"},  

    {"~Eats(x,y)", "~Killed(y)", "Food(y)"},  

    {"Eats(Anil,Peanut)"},  

    {"Alive(Anil)"},  

    {"~Alive(z)", "~Killed(z)"},  

    {"~Likes(John,Peanut)"}
]
steps = []

changed = True
while changed:
    changed = False
    new = []

    for i in range(len(clauses)):
        for j in range(i+1, len(clauses)):
            ci = clauses[i]
            cj = clauses[j]
            resolvents = resolve(ci, cj)
```

```

for r in resolvents:
    res = r["res"]
    if res == set(): # NIL Found
        steps.append((ci, cj, set()))
        print("\n NIL (Contradiction Found)")
        print("=> Query Proven TRUE")
        changed = False
        break

    if res not in clauses and res not in new:
        new.append(res)
        steps.append((ci, cj, res))
        changed = True

if changed is False and resolvents and res == set():
    break

for c in new:
    clauses.append(c)

print("\n=====")
print("    RESOLUTION STEPS")
print("=====")
for (a, b, c) in steps:
    if c == set():
        print(f"\n{a} + {b} => NIL")
    else:
        print(f"\n{a} + {b} => {c}\n")

print("\nRemaining Clauses:")
for c in clauses:
    print(c)

```

The screenshot shows a Google Colab notebook titled "Untitled14.ipynb". The code cell contains the following Python code:

```
print(c)
```

Below the code, a "RESOLUTION STEPS" section displays the following list of clauses:

```
Remaining Clauses:  
{'Likes(John,x)', '~Food(x)'}  
{'~killed(y)', 'Food(y)', '~Eats(x,y)'}  
{'Eats(Anil,Peanut)'}  
{'Alive(Anil)'}  
{'~Alive(z)', '~Killed(z)'}  
{'~Likes(John,Peanut)'}
```

The Colab interface includes a toolbar at the top with File, Edit, View, Insert, Runtime, Tools, Help, and a Share button. Below the toolbar are tabs for Commands, Code, Text, and Run all. The bottom of the screen shows a taskbar with various icons and system status information.

Week-9

First Order Logic

Create a knowledge base consisting of first order logic statements and prove the given query using Resolution.

Algorithm:

1. Eliminate biconditionals and implications:
 - Eliminate \leftrightarrow , replacing $\alpha \leftrightarrow \beta$ with $(\alpha \Rightarrow \beta) \wedge (\beta \Rightarrow \alpha)$.
 - Eliminate \Rightarrow , replacing $\alpha \Rightarrow \beta$ with $\neg \alpha \vee \beta$.

2. Move \neg inward:

- $\neg(\forall x \alpha) \equiv \exists x \neg \alpha$,
- $\neg(\exists x \alpha) \equiv \forall x \neg \alpha$,
- $\neg(\alpha \vee \beta) \equiv \neg \alpha \wedge \neg \beta$,
- $\neg(\alpha \wedge \beta) \equiv \neg \alpha \vee \neg \beta$,
- $\neg \neg \alpha \equiv \alpha$

3. Standardize variables apart by renaming them: each quantifier should use a different variable.

4. Skolemize: each existential variable is replaced by a Skolem constant σ) Skolem function of the enclosing universally quantified variables.

- For instance, $\exists x \text{Rich}(x)$ becomes $\text{Rich}(\sigma)$ where σ is a new Skolem constant.
- "Everyone has a heart" $\forall x \text{Person}$

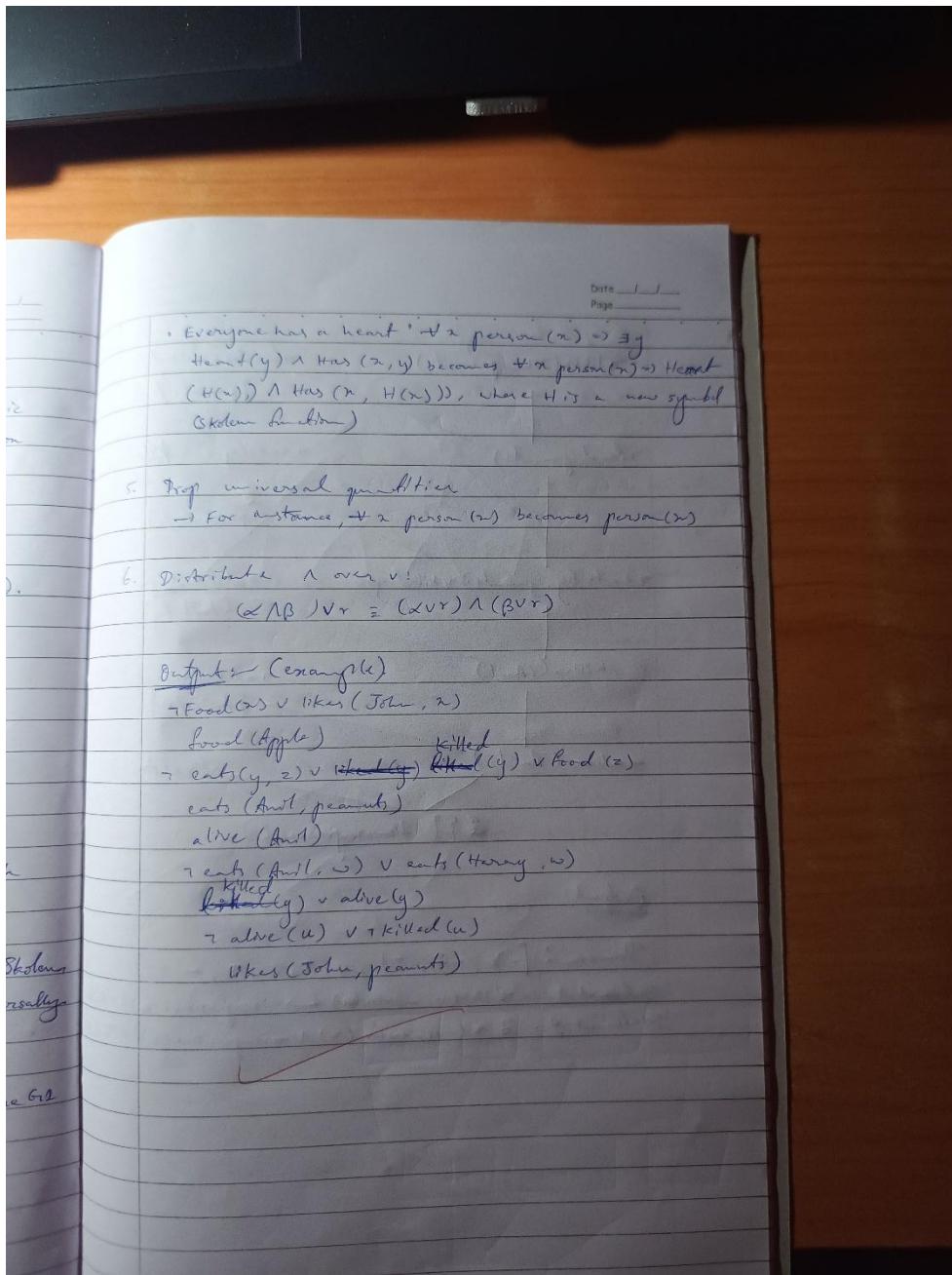
Date _____
Page _____
• Evening
Team
(HC)
(SK)

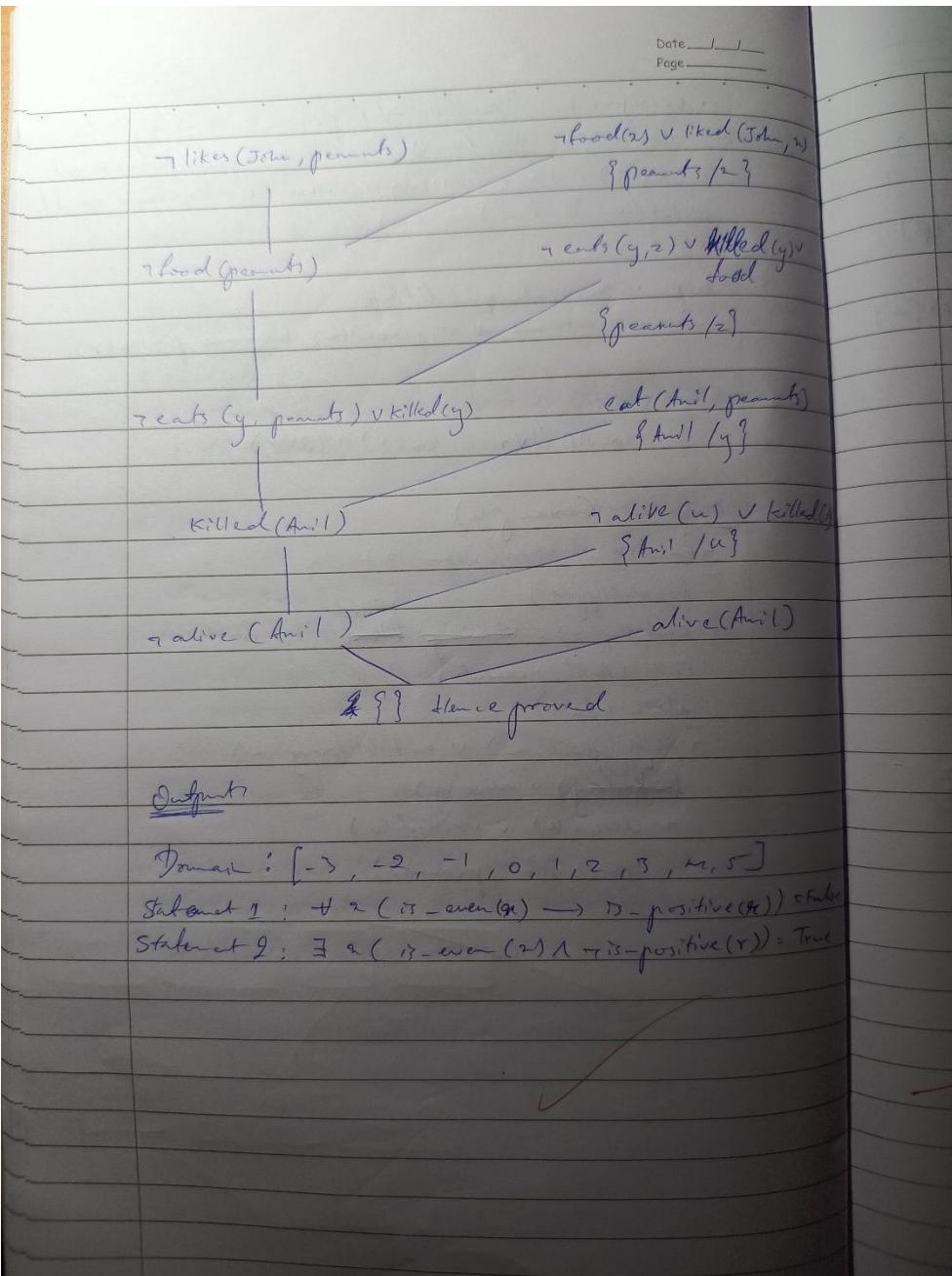
5. Prop

6. Dnf

But

7





Date / /
Page / /

Week - 9:

(Solved example)

Date / /
Page / /

MAX[α]

MIN[β]

MAX[\neg]

Q. Given the KB or Premises:

John likes all kind of food.

Apple and vegetables are food.

Anything anyone eats and not killed is food.

Anil eats peanuts and still alive.

Harry eats everything that Anil eats.

Anyone who is alive implies not killed.

Anyone who is not killed implies alive.

Prove by resolution:-

Step 1. Representation in FOL

- a. $\forall x : \text{food}(x) \rightarrow \text{likes}(\text{John}, x)$
- b. $\text{food}(\text{Apple}) \wedge \text{food}(\text{vegetables})$
- c. $\forall x \forall y : \text{eats}(x, y) \wedge \neg \text{killed}(x) \rightarrow \text{food}(y)$
- d. $\text{eats}(\text{Anil}, \text{Peanuts}) \wedge \text{alive}(\text{Anil})$.
- e. $\forall x : \text{eats}(\text{Anil}, x) \rightarrow \text{eats}(\text{Harry}, x)$
- f. $\forall x : \neg \text{killed}(x) \rightarrow \text{alive}(x)$
- g. $\forall x : \text{alive}(x) \rightarrow \neg \text{killed}(x)$
- h. $\text{likes}(\text{John}, \text{Peanuts})$

Step 2: Eliminate implication ($\alpha \Rightarrow \beta$ with $\neg \alpha \vee \beta$)

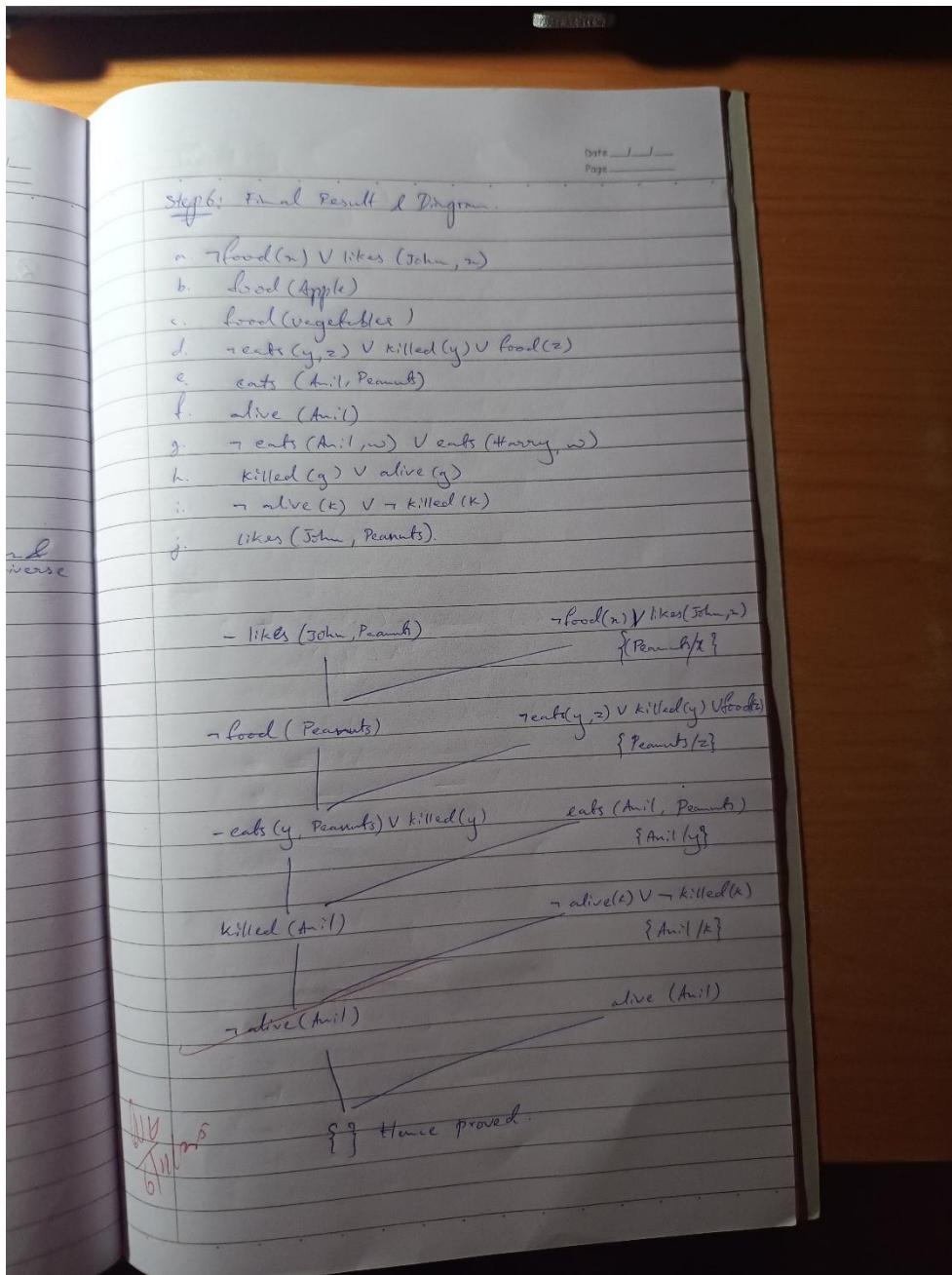
- a. $\forall x \neg \text{food}(x) \vee \text{likes}(\text{John}, x)$
- b. ~~$\text{food}(\text{Apple}) \wedge \text{food}(\text{vegetables})$~~
- c. $\neg \text{Harry} \neg \text{eats}(x, y) \wedge \neg \text{killed}(x) \vee \text{food}(y)$
- d. $\text{eats}(\text{Anil}, \text{Peanuts}) \wedge \text{alive}(\text{Anil})$
- e. $\forall x \neg [\neg \text{killed}(x)] \vee \text{alive}(x)$
- f. $\forall x \neg [\neg \text{killed}(x)] \vee \text{alive}(x)$
- g. $\forall x \neg \text{alive}(x) \vee \neg \text{killed}(x)$
- h. $\text{likes}(\text{John}, \text{Peanuts})$

Step 7: Have negative (\neg) symbols and rewrite.

- a. $\neg x \wedge \text{Poodle} \vee \text{likes}(\text{John}, x)$
- b. $\text{food}(\text{Apple}) \wedge \text{food}(\text{vegetable})$
- c. $\neg \text{Heavy} \neg \text{eats}(x, y) \vee \neg \text{killed}(x) \vee \text{food}(y)$
- d. $\neg \text{eats}(\text{Anil}, \text{Peanuts}) \wedge \neg \text{alive}(\text{Anil})$
- e. $\neg x \neg \text{eats}(\text{Anil}, x) \vee \text{eats}(\text{Haray}, x)$
- f. $\neg x \neg \text{killed}(x) \vee \text{alive}(x)$
- g. $\neg x \neg \text{alive}(x) \vee \neg \text{killed}(x)$
- h. $\text{Likes}(\text{John}, \text{Peanuts})$.

Step 4&5: Rename variables or standardize variables and
Prop Universe

- a. $\neg \text{food}(x) \vee \text{likes}(\text{John}, x)$
- b. $\text{Food}(\text{Apple})$
- c. $\text{Food}(\text{Vegetables})$
- d. $\neg \text{eats}(y, z) \vee \text{killed}(y) \vee \text{Food}(z)$
- e. $\text{eats}(\text{Anil}, \text{Peanuts})$
- f. $\text{alive}(\text{Anil})$
- g. $\neg \text{eats}(\text{Anil}, w) \vee \neg \text{eats}(\text{Haray}, w)$
- h. $\neg \text{killed}(g) \vee \text{alive}(g)$
- i. $\neg \text{alive}(k) \vee \neg \text{killed}(k)$
- j. $\text{Likes}(\text{John}, \text{Peanuts})$.



Program 10

Adversial Search or Alpha- Beta pruning

Code:

```
name = "Sohan R"  
usn = "1BM23CS336"
```

```
import math
```

```
class Node:
```

```
    def __init__(self, name, value=None):  
        self.name = name  
        self.value = value  
        self.children = []  
        self.pruned = False
```

```
def alpha_beta(node, depth, alpha, beta, maximizing_player):
```

```
    if not node.children: # leaf node  
        return node.value
```

```
    if maximizing_player:
```

```
        max_eval = -math.inf
```

```
        for child in node.children:
```

```
            eval = alpha_beta(child, depth + 1, alpha, beta, False)
```

```
            max_eval = max(max_eval, eval)
```

```
            alpha = max(alpha, eval)
```

```
            if beta <= alpha:
```

```
                child.pruned = True
```

```
                break
```

```
        node.value = max_eval
```

```
        return max_eval
```

```
    else:
```

```
        min_eval = math.inf
```

```
        for child in node.children:
```

```
            eval = alpha_beta(child, depth + 1, alpha, beta, True)
```

```
            min_eval = min(min_eval, eval)
```

```
            beta = min(beta, eval)
```

```
            if beta <= alpha:
```

```
                child.pruned = True
```

```
                break
```

```
        node.value = min_eval
```

```
        return min_eval
```

```
def print_tree(node, level=0):
```

```
    prefix = " " * level + "└── "
```

```
    if node.pruned:
```

```

        print(f"{{prefix}} {{node.name}} (PRUNED)")
else:
    if node.children:
        val = node.value if node.value is not None else "-"
        print(f"{{prefix}} {{node.name}} [Value={{val}}]")
        for child in node.children:
            print_tree(child, level + 1)
    else:
        print(f"{{prefix}} {{node.name}} [Leaf={{node.value}}]")

leaf_values = [3, 5, 6, 9, 1, 2, 0, -1]

root = Node("A")
b = Node("B")
c = Node("C")
root.children = [b, c]

b1 = Node("B1")
b2 = Node("B2")
c1 = Node("C1")
c2 = Node("C2")
b.children = [b1, b2]
c.children = [c1, c2]

b1.children = [Node("L1", leaf_values[0]), Node("L2", leaf_values[1])]
b2.children = [Node("L3", leaf_values[2]), Node("L4", leaf_values[3])]
c1.children = [Node("L5", leaf_values[4]), Node("L6", leaf_values[5])]
c2.children = [Node("L7", leaf_values[6]), Node("L8", leaf_values[7])]

print("====")
print("  ALPHA-BETA PRUNING")
print("====")
print(f"\nLeaf Node Values: {leaf_values}\n")

result = alpha_beta(root, 0, -math.inf, math.inf, True)

print("====")
print(f"Value of Root Node (MAX): {result}")
print("====")

print("\nTREE STRUCTURE (with pruning):")
print_tree(root)

print("\n-----")
print(f"Name : {name}")
print(f"USN : {usn}")
print("-----")

```

The screenshot shows a Google Colab interface with multiple tabs open at the top. The active tab is 'Untitled14.ipynb'. The code in the notebook is as follows:

```
ALPHA-BETA PRUNING  
Leaf Node Values: [3, 5, 6, 9, 1, 2, 0, -1]  
Value of Root Node (MAX): 5  
  
TREE STRUCTURE (with pruning):  
└ A [Value=5]  
    └ B [Value=5]  
        └ B1 [Value=5]  
            └ L1 [Leaf=3]  
            └ L2 [Leaf=5]  
        └ B2 [Value=6]  
            └ L3 [PRUNED]  
            └ L4 [Leaf=9]  
        └ C [Value=2]  
            └ C1 (PRUNED)  
            └ C2 [Leaf=0]  
                └ L7 [Leaf=0]  
                └ L8 [Leaf=-1]  
  
Name : Sohan R  
USN : 18923CS336
```

Below the code, there are three buttons: 'How can I install Python libraries?', 'Load data from Google Drive', and 'Show an example of training?'. A search bar and a help button are also present. At the bottom, there are tabs for 'Variables' and 'Terminal', along with system status icons like battery level, signal strength, and date/time.

Week - 10

Adversarial Search (Min-Max Algorithm)

Algorithm 1

function ALPHA-BETA-SEARCH (state) returns an action

$v \leftarrow \text{max-value}(\text{state}, -\infty, +\infty)$

return the action $a \in \text{Actions}(\text{state})$ with value v

function max-value (state, α, β) returns a utility value

if TERMINAL-TEST (state) then return

UTILITY (state)

$v \leftarrow -\infty$

for each $a \in \text{actions}(\text{state})$ do

$v \leftarrow \text{MAX}(v, \text{min-value}(\text{RESULT}(s, a), \alpha, \beta))$

if $v \geq \beta$ then return v

~~$\alpha \leftarrow \max(\alpha, v)$~~

return v

function min-value (state, α, β) returns G

utility value

if TERMINAL-TEST (state) then return

UTILITY (state)

$v \leftarrow +\infty$

for each $a \in \text{actions}(\text{state})$ do

$v \leftarrow \text{min}(v, \text{max-value}(\text{RESULT}(s, a), \alpha, \beta))$

if $v \leq \beta$ then ~~return~~ return v

$\beta \leftarrow \min(\beta, v)$

return v .

