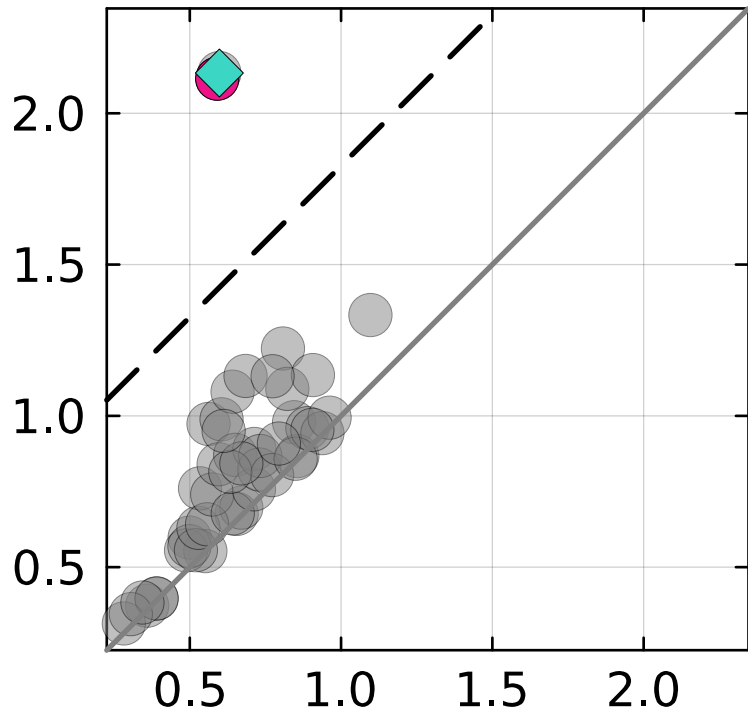


PD(P)



PD(Q)

