

Symmetric: $\langle u | A v \rangle = \langle A u | v \rangle \quad \forall v, u \in D_A$; $\mathcal{H} = L^2([0, 2\pi])$
 $u(0) \neq u(2\pi)$

$$P = -i \frac{d}{dx} \quad ; \quad P^* = -i \frac{d}{dx} \quad D_{P^*} \subset D_P$$

$P^* \rightarrow$ symmetric

$P \rightarrow$ not symmetric

expanding the domain: Sym \rightarrow self-adjoint

$$A_\alpha = -i \frac{d}{dx} \quad D_\alpha : \underline{v(2\pi) = e^{2\pi i \alpha} v(0)} \quad ; \quad 0 \leq \alpha < 1 \quad \mathcal{H} = L^2([0, 2\pi])$$

$$\underline{A_\alpha^* = A_\alpha} : \quad u(2\pi)^* v(2\pi) - u(0)^* v(0) = 0$$

$A_\alpha^* \rightarrow$ self-adjoint

$$\text{Spectra:} \quad -i \frac{d}{dx} v = \lambda v \rightarrow \underline{v(x) = e^{i(m+\alpha)x}} \quad ; \quad m \in \mathbb{Z}$$

$$\underline{\lambda = m + \alpha}$$

Aharonov - Bohm:

$$\vec{B} = \nabla \times \vec{A} \Rightarrow \Phi = \int \vec{B} \cdot d\vec{s} = \int \nabla \times \vec{A} \cdot d\vec{s} = \oint \vec{A} \cdot d\vec{l}$$



$$\vec{A} = \frac{\Phi}{2\pi r} \hat{\theta}$$

$$H = \frac{1}{2m} \left(\vec{p} - \frac{q}{c} \vec{A} \right)^2 = \frac{1}{2m} \left(p_r^2 + \frac{1}{r^2} \left(p_\theta - \frac{q}{c} \frac{\Phi}{2\pi} \right)^2 + p_z^2 \right)$$

Classical Mech. : $P_0 \rightarrow P_0 + \frac{q}{c} \frac{\Phi}{2\pi} \Rightarrow H = \frac{P^2}{2m}$

QT : $P_0 = -i\hbar \frac{\partial}{\partial \theta}$. $\psi = e^{i \frac{q\Phi}{2\pi c} \theta} \chi$

$$\left(-i\hbar \frac{\partial}{\partial \theta} - \frac{q}{c} \frac{\Phi}{2\pi} \right) \psi = e^{i \frac{q\Phi}{2\pi c} \theta} \left(-i\hbar \frac{\partial}{\partial \theta} \right) \chi$$

$H\psi = E\psi \Rightarrow \frac{P^2}{2m} \chi = E \chi$, $\chi(\theta=2\pi) = e^{-i \frac{q\Phi}{c}} \chi(0)$
 $\psi(\theta=2\pi) = \psi(\theta=0)$

Radial Momentum: $P_r = -i \frac{d}{dr}$; $\mathcal{H} = L^2([0, \infty])$

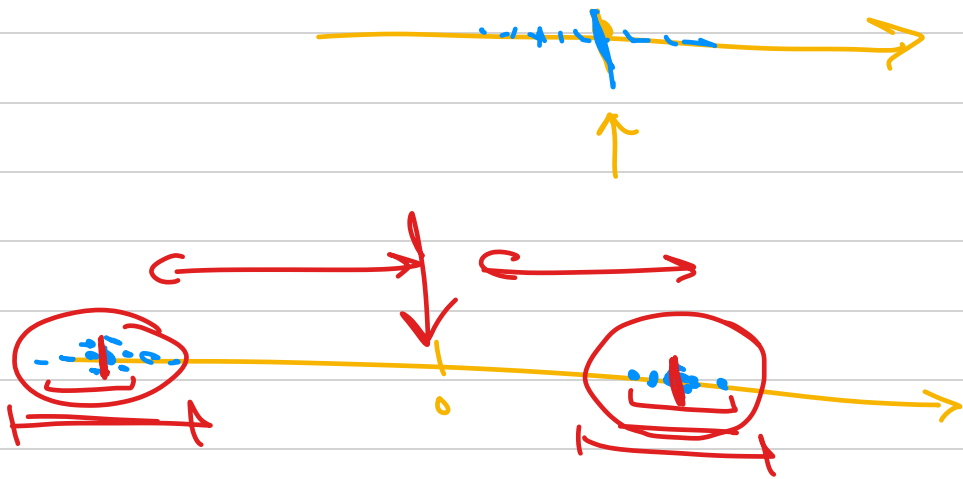
$D_{P_r} =$ all differentiable function in $0 \leq r < \infty$; $\langle u|v \rangle = \int_0^\infty u^* v \, dr$
 $u(\infty) = 0$

$u(0) = 0$ \rightarrow to be symmetric

$\hat{P}_r = -i \frac{d}{dr}$, $D_{P_r} : v(0) = 0 \Rightarrow \hat{P}_r^*$ need not to satisfy $v(0) = 0$!

$D_{P_r} \subset D_{P_r^*}$

uncertainty relations :



$$\Delta A \Delta B = \frac{1}{2} | \langle AB - BA \rangle |$$

Proof :

$$\|A_n\|^2 \|B_n\|^2 \geq |(A_n|B_n)|^2$$

$$\langle Au | Bu \rangle = \langle u | A^* B u \rangle = \underbrace{\langle u | \frac{A^* B + B^* A}{2} | u \rangle}_{\text{Real}} + \underbrace{\langle u | \frac{A^* B - B^* A}{2} | u \rangle}_{\text{Imag.}}$$

$$A^*B + B^*A \rightarrow \text{sym} \Rightarrow$$

$$i(A^*B - B^*A) \rightarrow \uparrow$$

$$| \langle A u | B u \rangle |^2 = \frac{1}{4} | \langle A^* B + B^* A \rangle |^2 + \frac{1}{4} | \langle A^* B - B^* A \rangle |^2$$

$$\|Au\|^2 = (Au|Au) = (u|A^*Au) = (A^*A)$$

$$\langle A^* A \rangle^2 \langle B^* B \rangle^2 \geq \frac{1}{4} |\langle A^* B + B^* A \rangle|^2 + \frac{1}{4} |\langle A^* B - B^* A \rangle|^2 \geq \frac{1}{4} |\langle A^* B - B^* A \rangle|^2$$

$$\left. \begin{aligned} A &\rightarrow A - \frac{\langle A \rangle}{a} =: \tilde{A} \\ B &\rightarrow B - \langle A \rangle =: \tilde{B} \end{aligned} \right\} \quad \langle \tilde{A}^* \tilde{A} \rangle = \langle \underbrace{(A - a)^2}_{-2aA} \rangle = \langle A^2 - 2aA + a^2 \rangle$$

$$[\tilde{A}, \tilde{B}] = [A, B]$$

$$= \langle A^2 \rangle - 2a^2 + a^2 = \langle A^2 \rangle - \langle A \rangle^2 = \Delta A$$

$$\langle \tilde{A}^* \tilde{A} \rangle = \Delta A \rightarrow (\Delta A)^2 (\Delta B)^2 \geq \frac{1}{4} |\langle A^* B - B^* A \rangle|^2$$

$$(\Delta A)(\Delta B) \geq \frac{1}{2} |\langle AB - BA \rangle|$$

$$u \in D_A, u \in D_B$$

$$u \in D_{A^*}, u \in D_{B^*}$$

$$(A - \langle A \rangle)u \parallel (B - \langle B \rangle)u$$

$$\langle \tilde{A}^* \tilde{B} + \tilde{B}^* \tilde{A} \rangle = 0 \rightarrow \langle u | \tilde{A}^* \tilde{B} | u \rangle + \langle u | \tilde{B}^* \tilde{A} | u \rangle = 0$$

$$\rightarrow \text{Real} \{ \langle A^* B \rangle \} = 0$$

$$\text{Real} \{ \langle v | w \rangle \} = 0$$

$$\frac{\alpha}{\beta} \underbrace{(A - \langle A \rangle)u}_v + \underbrace{(B - \langle B \rangle)u}_w = 0$$

$$\begin{aligned} \langle A^* B \rangle &= \langle u | A^* B | u \rangle \\ &= \underbrace{\langle Au |}_v \underbrace{| Bu \rangle}_w \end{aligned}$$

$$\frac{\alpha}{\beta} v + w = 0 \rightarrow w = -\frac{\alpha}{\beta} v \rightarrow$$

$$1 = -\frac{\alpha}{\beta} \langle w | v \rangle \rightarrow \frac{\alpha}{\beta} : \text{Pure imaginary} \rightarrow i\lambda$$

$$P \text{ \& } X : \Delta P \Delta X \geq \frac{\hbar}{2}$$

$$\psi(x) = C e^{-ax^2 - bx}$$

minimum uncertainty

$$\hat{a} | \alpha \rangle = \alpha | \alpha \rangle \quad \text{Coherent states}$$