











FONCTION ASSIGN

GP2s

Commande Moteurs

EF R -> PE2 = EventOut EF L -> PE3 = EventOut INR 1 -> PE5 = TIM9 CH1 INR 2 -> PE6 = TIM9 CH2 INL_1 -> PB14 = TIM12_CH1 INL 2 -> PB15 = TIM12 CH2

ADC 1 -> PF3 = ADC $ADC^{2} \rightarrow PF4 = ADC$ ADC 3 -> PF5 = ADC ADC 4 -> PF10 = ADC ADC 5 -> PC4 = ADC ADC 6 -> PC5 = ADC ADC 7 -> PB0 = ADC ADC 8 -> PB1 = ADC

Encodeurs

ENC RI 1 -> PAE9 = TIM1 CH1 ENC RI 2 -> PE11 = TIM1 CH2 ENC RE 1 -> PA0 = TIM2 CH1 ENC_RE_2 -> PA1 = TIM2_CH2 ENC LI 1 -> PD12 = TIM4 CH1 ENC LI 2 -> PD13 = TIM4 CH2 ENC LE 1 -> PC6 = TIM3 CH1 ENC LE 2-> PC7 = TIM3 CH2

GPIOs

GPIO 1 -> PD14 = EventOut GPIO 2 -> PD15 = EventOut GPIO 3 -> PG2 = EventOut GPIO_4 -> PG3 = EventOut GPIO 5 -> PG4 = EventOut GPIO 6 -> PG5 = EventOut GPIO 7 -> PG6 = EventOut GPIO 8 -> PG7 = EventOut

Servomoteurs

PWM SERVO 1 -> PF6 = TIM10 CH1 PWM SERVO 2 -> PF7 =TIM11 CH1 PWM SERVO 3 -> PF8 = TIM13 CH1 PWM_SERVO_4 -> PF9 = TIM14_CH1 PWM SERVO 5 -> PA2 = TIM5 CH3 PWM SERVO 6 -> PA3 = TIM5 CH4 PWM SERVO 7 -> PC8 = TIM8 CH3 PWM SERVO 8 -> PC9 = TIM8 CH4