

Combining **loop unrolling** strategies and **code predication** to reduce the **worst-case execution time of real-time software**

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Loop Unrolling-
Code Predication



Motivational Example



Authors' Optimization Approach



Evaluation & Results



Worst-Case Execution Time (WCET)

Combining loop unrolling strategies and code predication to reduce the worst-case execution time of real-time software

- Worst-Case Execution Time (WCET) is an important parameter for a Real-Time System
- Time Analyzers are used in order to evaluate the WCET
- Goal of this paper is to reduce the WCET of a real-time system
- There are **two** ways to reduce the WCET



Loop Unrolling

Combining loop unrolling strategies and code predication to reduce the worst-case execution time of real-time software

- Loops are frequently good targets for compiler optimizations

```
for(int i = 10; i != 0; i = i - 1){  
    a[i] = a[i] + b;  
}
```



```
LOOP:  LW    r2, 0(r1)  
       ADD   r2, r2, r3  
       SW    r2, 0(r1)  
       ADDI  r1, r1, -4  
       BNE   r1, r5, LOOP
```

5 Instr. x 10 Iter. = 50 Instructions

Loop Unrolling



Unrolling Factor = 1

```
for(int i = 10; i != 0; i = i - 2){  
    a[i] = a[i] + b;  
    a[i - 1] = a[i - 1] + b;  
}
```



```
LOOP:  LW    r2, 0(r1)  
       ADD   r2, r2, r3  
       SW    r2, 0(r1)  
       LW    r2, -4(r1)  
       ADD   r2, r2, r3  
       SW    r2, -4(r1)  
       ADDI  r1, r1, -8  
       BNE   r1, r5, LOOP
```

8 Instr. x 5 Iter. = 40 Instructions

Loop Unrolling – keil µVision ARM Example

Combining loop unrolling strategies and code predication to reduce the worst-case execution time of real-time software

Demo Code for Loop Unrolling

```
main.c
1 void loop(int* A, int b){
2
3   for(int i = 10; i != 0; i = i - 1){
4     A[i] = A[i] + b;
5   }
6
7 }
8
9 void unrolledLoop(int* A, int b){
10
11   for(int i = 10; i != 0; i = i - 5){
12     A[i] = A[i] + b;
13     A[i - 1] = A[i - 1] + b;
14     A[i - 2] = A[i - 2] + b;
15     A[i - 3] = A[i - 3] + b;
16     A[i - 4] = A[i - 4] + b;
17   }
18
19 }
20
21 int main(void ){
22
23   int A[10] = {1, 2, 3, 4, 5, 6, 7, 8, 9, 10};
24   int b = 1;
25
26   loop(A, b);
27   //unrolledLoop(A, b);
28
29   return 0;
30 }
31
```

| | |
|-----------|------------|
| System | |
| Internal | |
| Mode | Thread |
| Privilege | Privileged |
| Stack | MSP |
| States | 1366 |
| Sec | 0.00011383 |
| FPU | |

Rolled Loop Time

Unrolled Loop Time

| | |
|-----------|------------|
| System | |
| Internal | |
| Mode | Thread |
| Privilege | Privileged |
| Stack | MSP |
| States | 1347 |
| Sec | 0.00011225 |
| FPU | |

Branch Prediction vs Code Predication

Combining loop unrolling strategies and code predication to reduce the worst-case execution time of real-time software

Branch Prediction

- Predict whether a branch is taken or not
- Synchronous Architectures have about 90% Accuracy
- No penalty if correct prediction
- Huge penalty if wrong prediction

Code Predication

- Do work of both directions
- Throw away instructions from the wrong path
- Waste up to 50%

- Big if-else → Branch Prediction
- Small if-else → Code Predication

```
BEQ    r1, 0, else
ADDI   r2,r2,1
else:
ADDI   r2,r2,-1
```

```
if (f){
    a++;
}else{
    a--;
}
```

```
(f)    ADDI   r2,r2,1
(not f) ADDI   r2,r2,-1
```

Loop Unrolling-
Code Predication



Motivational Example



Motivational Example Loop

```
1 void loop(int a){  
2     int i, j = 0, k = 0;  
3  
4     for(i = 0; i < a ; i++){  
5         j++;  
6         k++;  
7     }  
8 }  
9  
10 int main(int a){  
11     loop(90);  
12 }
```

Listing 1. Simple data-dependent loop.

- **Data-Dependent** Loop (since loop iterations variable is not static)
- Compiler generated a **Control Flow Graph (CFG)**
- A problem with Data-Dependent loops is the difficulty to choose an **effective unrolling factor**
- We need to add **exit conditions** for each body replication

for(i = 0; i < a; i++)

(Header)

*j++;
k++;*

(Body)

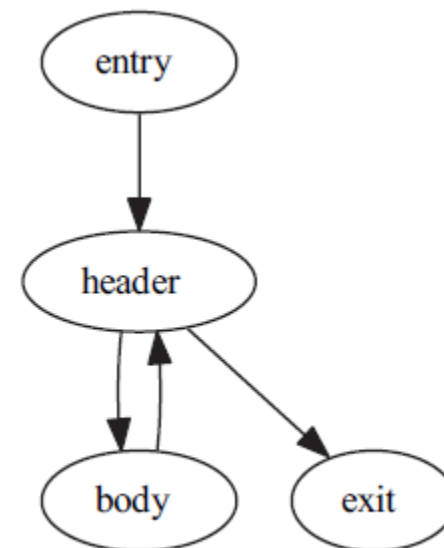


Fig. 1. Control flow graph of Listing 1.

Loop Unrolling – keil µVision ARM Example

Combining loop unrolling strategies and code predication to reduce the worst-case execution time of real-time software

Demo Code for Loop Unrolling with exit conditions

```
main.c startup_stm32f401xe.s
21 void falseUnroll(int* A, int b){
22
23     for(int i = 10; i != 0; i = i - 3){
24         A[i] = A[i] + b;
25         A[i - 1] = A[i - 1] + b;
26         A[i - 2] = A[i - 2] + b;
27     }
28
29 }
30
31 void correctUnroll(int* A, int b){
32
33     for(int i = 10; i != 0;){
34         A[i] = A[i] + b;
35         i--;
36         if(i != 0){
37             A[i - 1] = A[i - 1] + b;
38             i--;
39         }
40         if(i != 0){
41             A[i - 2] = A[i - 2] + b;
42             i--;
43         }
44     }
45
46 }
47
48 int main(void ){
49
50     int A[10] = {1, 2, 3, 4, 5, 6, 7, 8, 9, 10};
51     int b = 1;
52
53     //loop(A, b);
54     //unrolledLoop(A, b);
55     falseUnroll(A, b);
56     correctUnroll(A, b);
57
58     return 0;
59 }
```

Motivational Example Loop

```
1 void loop(int a){
2     int i, j = 0, k = 0, l = 0;
3
4     for(i = 0; i < a; i+=1){
5         l = 0;
6         j++;
7         k++;
8         l++;
9         if(i+1 >= a) break;
10        j++;
11        k++;
12        l++;
13        if(i+1 >= a) break;
14        j++;
15        k++;
16        l++;
17    }
18 }
```

Listing 2. Unrolled loop.

- Note that, **instructions increased**
- If the target architecture **supports code predication**, we can consider the following code, in which we are able to do *if-conversion*

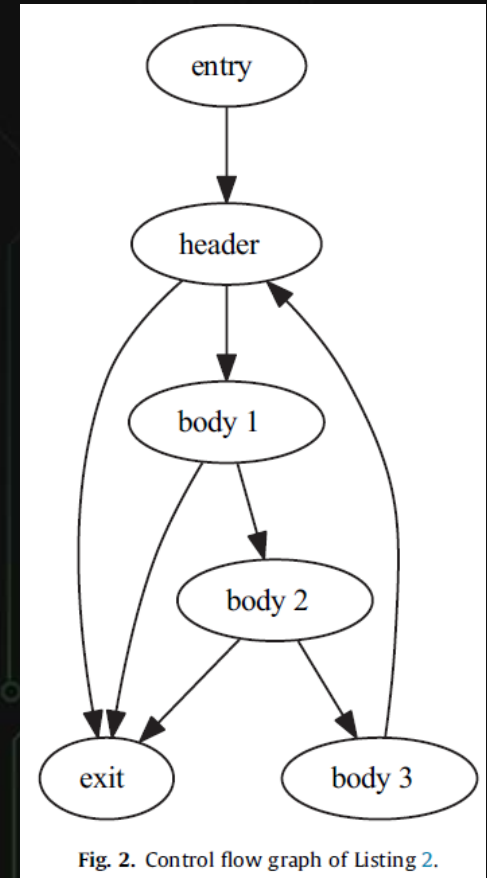


Fig. 2. Control flow graph of Listing 2.

Motivational Example Loop

```
1 void loop(int a){
2     int i, j = 0, k = 0;
3
4     for(i = 0; i < a;){
5         j++;
6         k++;
7         i++;
8
9         if(i < a){
10            j++;
11            k++;
12            i++;
13        }
14        if(i < a){
15            j++;
16            k++;
17            i++;
18        }
19    }
20 }
```

- The prefix (p) means that the execution of blocks *body2* and *body3* are conditioned to some **predication guard p**

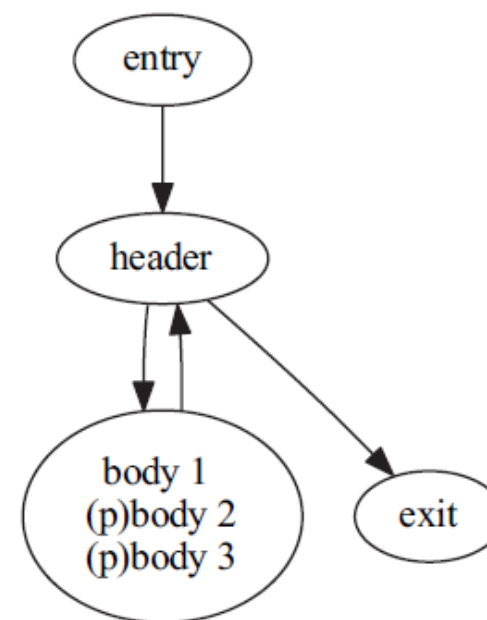


Fig. 4. Control flow graph representing an If-Conversion of the code from Listing 3.

Loop Unrolling-
Code Predication



Motivational Example



Authors' Optimization Approach



Predicated Loop Unrolling Algorithm

Combining loop unrolling strategies and code predication to reduce the worst-case execution time of real-time software

```
1: procedure PREDICATEDLOOPUNROLLING(Loop, U, P)  
  ▷Unroll loop u times  
2:   Header ← loopHeader(Loop)  
3:   Body ← loopBody(Loop)  
4:   removeUncondBranch(Body)  
5:   BodyCopy ← createCopy(Body)  
6:   for i ← 1 to U − 1 do  
7:     NewHeader ← createCopy(Header)  
8:     removeConditionalBranch(NewHeader)  
9:     changeCompareOutput(NewHeader, P)  
10:    Body ← unify(Body, NewHeader)  
11:    NewBody ← createPredCopy(BodyCopy, P)  
12:    Body ← unify(Body, NewBody)  
13:  end for  
14:  insertUncondBranch(Body, Header)  
15: end procedure
```

- Identify **Header & Body** of the loop
- Remove **unconditional branch** and place it in the end
- Create a **body copy** which will be always executed
- Create **predicated body copies** inside the for loop, with *U* iterations, where *U* is the *unrolling factor*

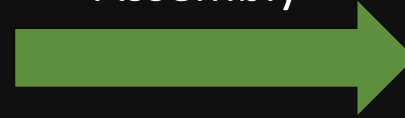
Example of our Approach

Combining loop unrolling strategies and code predication to reduce the worst-case execution time of real-time software

```
1 void loop(int a){
2     int i, j = 0, k = 0;
3
4     for(i = 0; i < a ; i++){
5         j++;
6         k++;
7     }
8 }
9
10 int main(int a){
11     loop(90);
12 }
```

Listing 1. Simple data-dependent loop.

Assembly



```
1     add $r8 = $zero , 0
2     add $r9 = $zero , 0
3     add $r10 = $zero , 0
4 HEADER:
5     cmplt $br0 , $r9 , $r16
6     brf $br0 , $EXIT
7 BODY:
8     add $r10 = $r10 , 1
9     add $r8 = $r8 , 1
10    add $r9 = $r9 , 1
11    goto $HEADER
12 EXIT:
13
14
15
16
17
18
```

Listing 4. Example of loop in assembly code.

Example of our Approach

Combining loop unrolling strategies and code predication to reduce the worst-case execution time of real-time software

Standard Approach with branch for exit conditions

```
1  add $r8 = $zero, 0
2  add $r9 = $zero, 0
3  add $r10 = $zero, 0
4  HEADER:
5      cmplt $br0, $r9, $r16
6      brf $br0, $EXIT
7  BODY0:
8      add $r10 = $r10, 1
9      add $r8 = $r8, 1
10     add $r9 = $r9, 1
11     cmplt $br0, $r9, $r16
12     brf $br0, $EXIT
13  BODY1:
14     add $r10 = $r10, 1
15     add $r8 = $r8, 1
16     add $r9 = $r9, 1
17     goto $HEADER
18  EXIT:
```

Listing 6. Example of unrolled loop using the standard approach.

Predicated Approach

```
1  add $r8 = $zero, 0
2  add $r9 = $zero, 0
3  add $r10 = $zero, 0
4  HEADER:
5      cmplt $br0, $r9, $r16
6      brf $br0, $EXIT
7  BODY:
8      add $r10 = $r10, 1
9      add $r8 = $r8, 1
10     add $r9 = $r9, 1
11     cmplt $p, $r9, $r16
12     (p)add $r10 = $r10, 1
13     (p)add $r8 = $r8, 1
14     (p)add $r9 = $r9, 1
15     goto $HEADER
16  EXIT:
17
18
```

Listing 5. Example of unrolled loop using code predication.

- We can see that the predicated version has **fewer instructions**

Optimizations Algorithm that is executed by the compiler

```
1: procedure OPTIMIZELOOPS(Program)
2:   LoopList  $\leftarrow$  getLoops(Program)
3:   for each loop  $\in$  LoopList do
4:     if not loop.isDataDep then
5:       simpleLoopUnrolling(loop, loop.uf)
6:     else if loop.hasCall then
7:       branchedLoopUnrolling(loop, loop.uf)
8:     else
9:       predicatedLoopUnrolling(loop, loop.uf, P)
10:    end if
11:  end foreach
12: end procedure
```

- Compiler runs this code **for each loop** that is in the **WCEP**

- ❖ **Standard (without branches)**
Used for **non-data dependent** loops (with fixed executions counts)
- ❖ **Standard (with branches)**
Used for **data dependent** loops that have **call instructions** in the body
- ❖ **Predicated**
Used for **data dependent** loops that have simple bodies and **do not use call instructions**


```
1: procedure CALCULATEUNROLLINGFACTORS(Program)  
   Algorithm executed by the optimization planning tool  
2:   LoopList ← getLoops(Program)  
3:   wcetData ← calculateWCET(Program)  
4:   for each loop ∈ LoopList do  
5:     if isInWCEP(loop, wcetData) then  
6:       lastUF ← 0  
7:       for i ← 2 to 17 do  
8:         if not loop.isDataDep then  
9:           if not divides(loop.bound, i) then  
10:            continue  
11:          end if  
12:        end if  
13:        if parity(loop.bound) = parity(i) then  
14:          loop.uf ← i  
15:          recompile(Program)  
16:          newWcet ← calculateWCET(Program)  
17:          if newWcetData.value ≥ wcetData.value then  
18:            loop.uf ← lastUF  
19:          else  
20:            wcetData ← newWcetData  
21:            lastUF ← i  
22:          end if  
23:        end if  
24:      end for  
25:    end if  
26:  end for each  
27: end procedure
```

- It is necessary to find the **optimal Unrolling Factor** for each loop that resides inside the WCEP
- If it is in the WCEP, we test different *Unrolling Factors*, from **2 to 17**
- For **Data-Independent** loops the *Unrolling Factor* must **exactly divide the execution count** of the loop in order to avoid corner exit conditions
- For **Data-Dependent** loops we consider *Unrolling Factors* whose **parity** is equal to the **loop bounds' parity**
- Then we **recompile** the program and test for WCET changes
- Algorithm complexity is $O(n^2)$
- **Better WCET** with the cost of **higher compilation time**

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Authors' Optimization Approach



Evaluation & Results



Target Architecture

Combining loop unrolling strategies and code predication to reduce the worst-case execution time of real-time software

- Supports a simplified complete **Predication Support**
- 32-bit Microprocessor with **RISC** Instructions
- **Direct-Mapped** Cache Memory(32 blocks of 256 bits, thus 1024kB)
- No Data-Cache
- No out-of-order execution
- Four issue, five stage static scheduled **pipeline**


Table 1
Obtained results

| Benchmark | Initial WCET | Initial code size | Optimized WCET | Optimized code size | WCET reduction (%) | Code increase (%) |
|--------------|--------------|-------------------|----------------|---------------------|--------------------|-------------------|
| adpcm.c | 19,607 | 10,208 | 19,373 | 14,816 | 1.19 | 31.10 |
| bsort100.c | 272,623 | 432 | 271,985 | 560 | 0.23 | 22.86 |
| cnt.c | 9046 | 752 | 8566 | 864 | 5.31 | 12.96 |
| compress.c | 140,139 | 4912 | 137,162 | 5488 | 2.12 | 10.50 |
| crc.c | 113,846 | 2048 | 112,671 | 2624 | 1.03 | 21.95 |
| duff.c | 1859 | 592 | 1397 | 816 | 24.85 | 27.45 |
| edn.c | 96,871 | 2336 | 73,042 | 3296 | 24.60 | 29.13 |
| expint.c | 113,473 | 1540 | 76,661 | 1812 | 32.44 | 15.01 |
| fft1.c | 1,034,634 | 19,984 | 727,844 | 44,272 | 29.65 | 54.86 |
| fir.c | 509,930,221 | 976 | 444,387,758 | 1616 | 12.85 | 39.60 |
| insertsort.c | 2720 | 304 | 2111 | 432 | 22.39 | 29.63 |
| jfdctint.c | 3947 | 1264 | 3568 | 1536 | 9.60 | 17.71 |
| lms.c | 352,360,015 | 14,016 | 303,674,957 | 70,768 | 13.82 | 80.19 |
| ludcmp.c | 43,902 | 3296 | 43,622 | 4320 | 0.64 | 23.70 |
| matmult.c | 268,362 | 1008 | 225,657 | 1968 | 15.91 | 48.78 |
| ndes.c | 146,612 | 5376 | 144,282 | 7248 | 1.59 | 25.83 |
| qsort-exam.c | 503,582 | 2528 | 480,816 | 2784 | 4.52 | 9.20 |
| st.c | 1,480,353 | 5088 | 1,198,582 | 5856 | 19.03 | 13.11 |
| | | | | Average | 6.72 | 15.56 |
| | | | | Maximum | 32.44 | 80.19 |

$$WCET\ Reduction = \frac{Initial\ WCET - Optimized\ WCET}{Initial\ WCET} * 100$$

$$Code\ Increase = \frac{Initial\ Code - Optimized\ Code}{Initial\ Code} * 100$$

- A total of 18 from 33 benchmarks are shown, since there was no gain in the other ones
- We can see that the combination of techniques was able to reduce the WCET of half of the benchmarks

An abstract background pattern of thin, light green lines and small circles, resembling a circuit board or neural network, set against a dark grey background.

Thank you for your time!
Questions?