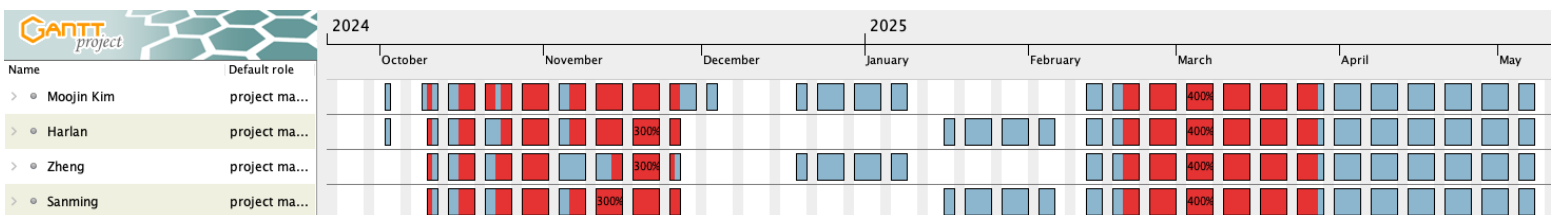


Resource Management



| Component | Vender | Vender No. | Cost per (£) | Qty. | Total Cost (£) |
|---|-------------|---------------|--------------|------|----------------|
| STM32 Nucleo-64 Development Board | Avnet | NUCLEO-F401RE | 15.00 | 1 | <u>15.00</u> |
| Mbed Application Shield | Farnell | 2468119 | 42.54 | 1 | <u>42.54</u> |
| STM32 Break out Board | Proprietary | - | 10.00 | 1 | <u>10.00</u> |
| Motor Drive Board | Proprietary | - | 30.00 | 1 | <u>30.00</u> |
| 6-15V 8W DC Brushed | RS | 238-9737 | 3.92 | 2 | <u>7.84</u> |
| Quadrature Encoder | Farnell | 2467469 | 21.40 | 2 | <u>42.80</u> |
| Gearbox Box (case, gears, terminals, etc.) | UoM | - | 7.00 | 2 | <u>14.00</u> |
| Battery Holder | Farnell | 3829583 | 2.28 | 1 | <u>2.28</u> |
| 1.2 V Rechargeable Battery | Farnell | - | 2.00 | 8 | <u>16.00</u> |
| TCRT5000L | RS | 818-7524 | 0.77 | 6 | <u>4.62</u> |
| Misc. Small Electronics (resistors, wires, switches, etc.) | - | - | - | - | <u>15.00</u> |
| Bluetooth Module | RobotShop | RB-Suf-03 | 13.53 | 1 | <u>13.53</u> |
| Acetal Sheet 600x900x3mm | UoM | - | 42.00 | 0.1 | <u>4.20</u> |
| Ball Castor | Pololu | #955 | 2.47 | 1 | <u>2.47</u> |
| Rubber Tire | Rapid | 06-0654 | 3.92 | 2 | <u>7.84</u> |

The Total Estimated Final Buggy Cost:

£228.12

| Task | Hours/Week | Weeks | Moojin | Harlan | Zheng | Sanming | Notes |
|-----------|------------|-------|--------|--------|-------|---------|--------------------|
| Research | 4 | 24 | 96 | 96 | 96 | 96 | Study |
| Meetings | 2 | 24 | 48 | 48 | 48 | 48 | Weekly |
| Plans | 10 | 1 | 10 | 10 | 10 | 10 | |
| Lab1 | 6 | 1 | 6 | 6 | 6 | 6 | |
| DR1 | 5 | 3 | 15 | 15 | 15 | 15 | |
| Lab2-1 | 3 | 1 | 3 | 3 | 3 | 3 | |
| Lab2-2 | 3 | 1 | 3 | 3 | 3 | 3 | |
| DR2 | 20 | 4 | 80 | 80 | 80 | 80 | |
| Peer1 | 3 | 1 | 3 | 3 | 3 | 3 | |
| Proposal | 10 | 3 | 30 | 30 | 30 | 30 | |
| Sdev | 10 | 10 | 100 | 100 | 100 | 100 | |
| TD1 | 6 | 1 | 6 | 6 | 6 | 6 | Motor Control |
| TD2 | 6 | 1 | 6 | 6 | 6 | 6 | Sensors |
| TD3 | 6 | 1 | 6 | 6 | 6 | 6 | Control & Steering |
| TD4 | 6 | 1 | 6 | 6 | 6 | 6 | Heats & Race |
| Total | 1672(h) | | | | | | |
| Payment/h | 15*2(£) | | | | | | 50160(£) |

| Category | Item/Description | Unit Cost(£) | Quantity | Total Cost(£) |
|--------------------------|------------------------|--------------|----------|---------------|
| Materials and Components | Sensors, motors, etc. | 228.12 | 1 | 228.12 |
| Fabrication and Assembly | PCB Fabrication | 30 | 2 | 60 |
| Fabrication and Assembly | 3D Printing | 12+20 | 1 | 32 |
| Tools and Equipment* | Temporary Tool Rental | 5427 | 1 | 5427 |
| Testing and Calibration | Prototyping Parts | 147.05 | 1 | 147.05 |
| Testing and Calibration | Calibration Equipment | 30 | 1 | 30 |
| Labour Costs | Labour Cost | 15*2 | 1672 | 50160 |
| Miscellaneous Costs | Shipping/Handling | 15 | 1 | 15 |
| Miscellaneous Costs | Presentation Materials | 20 | 1 | 20 |
| Miscellaneous Costs | Documentation | 10 | 1 | 10 |
| Contingency Buffer | Contingency | - | - | 55 |

| Tools and Equipment * | my DAQ | DMM | Scope | Toolkit | Soldering iron | SolidWorks | PSU | Function Generator |
|-----------------------|--------|------|-------|---------|----------------|------------|------|--------------------|
| Cost(£) | 253 | 1414 | 1339 | 39 | 199 | 99 | 1264 | 820 |
| Total | 5427 | | | | | | | |

The total estimated final project cost:

£56184.17

RISK REGISTER FOR EMBEDDED SYSTEMS PROJECT

| | | | | | |
|----------------|------------|-------------|------------------|---------------|--|
| Group Number: | 27 | | Submission Date: | 06/11/2024 | |
| Group Members: | Moojin Kim | Harlan Sims | Zheng Xu | Sanming Xiong | |

| Project Risk | Severity | | | Potential | | | Score (Severity x Potential) L=1, M=2, H=3 | Mitigation Measures | Owner |
|--------------------------------|----------|---|---|-----------|---|---|--|--|---------------|
| | L | M | H | L | M | H | | | |
| Sensor malfunction | | | o | | o | | 6 | Calibrate the sensor, ensure correct distance from lines | Moojin Kim |
| Power supply issue | | | o | | o | | 6 | Monitor battery levels and fully charge before testing | Zheng Xu |
| Hardware component failure | | | o | o | | | 3 | Prepare spare parts, simulate stress test in advance | Moojin Kim |
| Communication fail within team | | o | | | o | | 4 | Set weekly meetings, use shared drive for information | Moojin Kim |
| Project timeline delays | | o | | o | | | 2 | Track progress with Gantt chart, set deadlines weekly | Sanming Xiong |
| Motor control inconsistency | | | o | o | | | 3 | Test the motor driver board before implementing by simulating code | Harlan Sims |
| Software failure | | | o | o | | | 3 | Test code regularly and save working codes separately | Zheng Xu |
| Environmental factors (Light) | | o | | o | | | 2 | Test sensors in various lighting, check data sheet | Sanming Xiong |
| Exceeding budget | o | | | o | | | 1 | Track expenses, find alternatives for expensive components | Zheng Xu |
| Misalignment of wheel axis | | o | | o | | | 2 | Ensure proper assembly, use adjustable mounts | Harlan Sims |
| Overheating of components | | o | | | o | | 4 | Monitor temperature levels, consider heatsink | Harlan Sims |
| Code version control issue | | o | | o | | | 2 | Use version controls (Github), Share code | Sanming Xiong |

We confirm that all group members participated in the production of this risk register: Yes