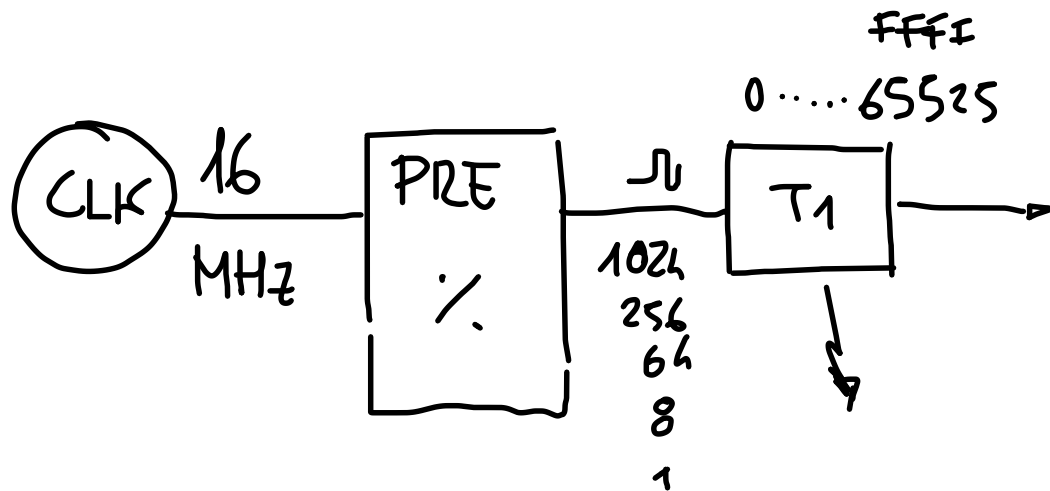
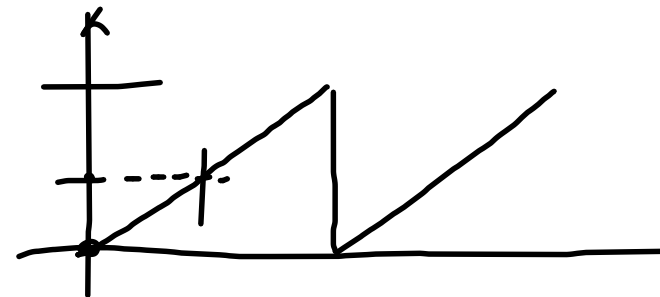


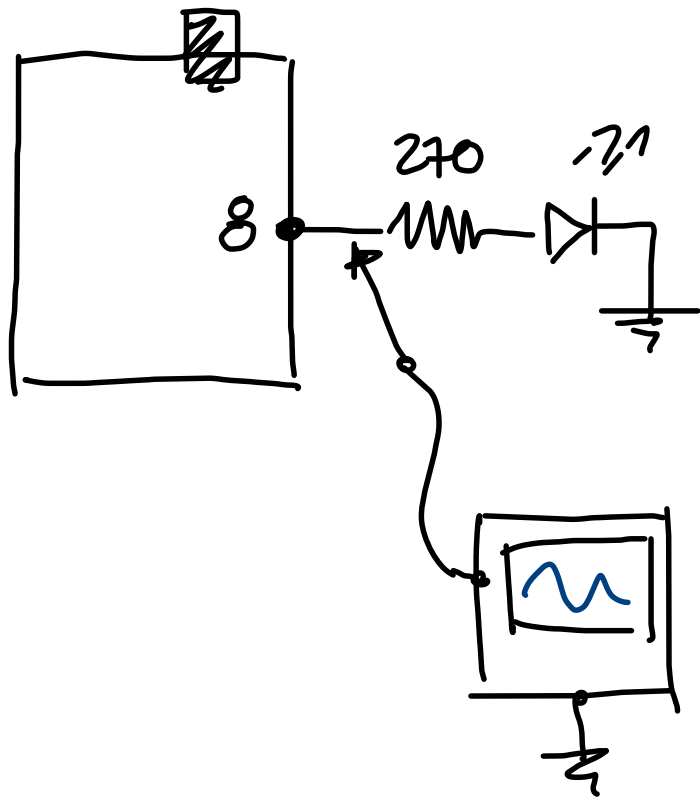
T0	8bit	delay millis
T1	16bit	servo
T2	16bit	tone



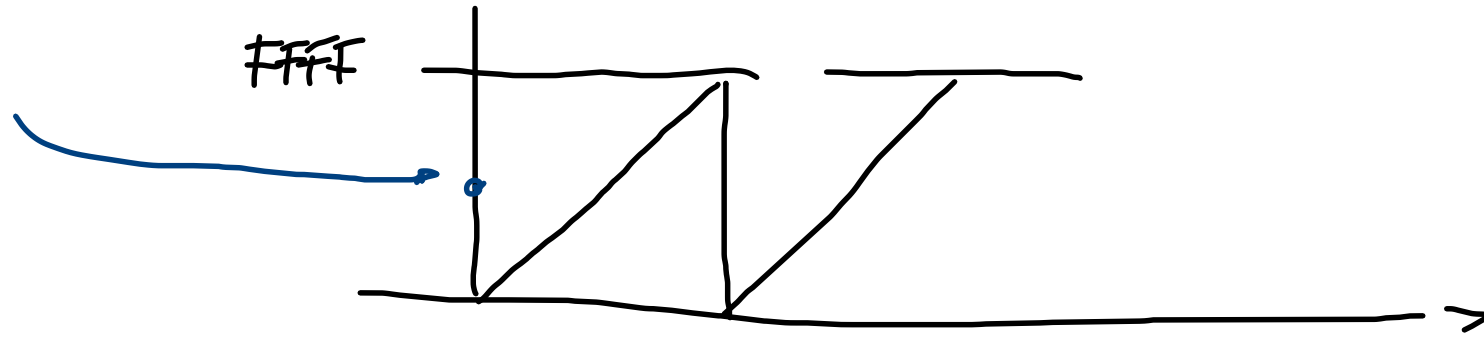
TCCR1B  
TCCR1A

TCNT1





TCNT1

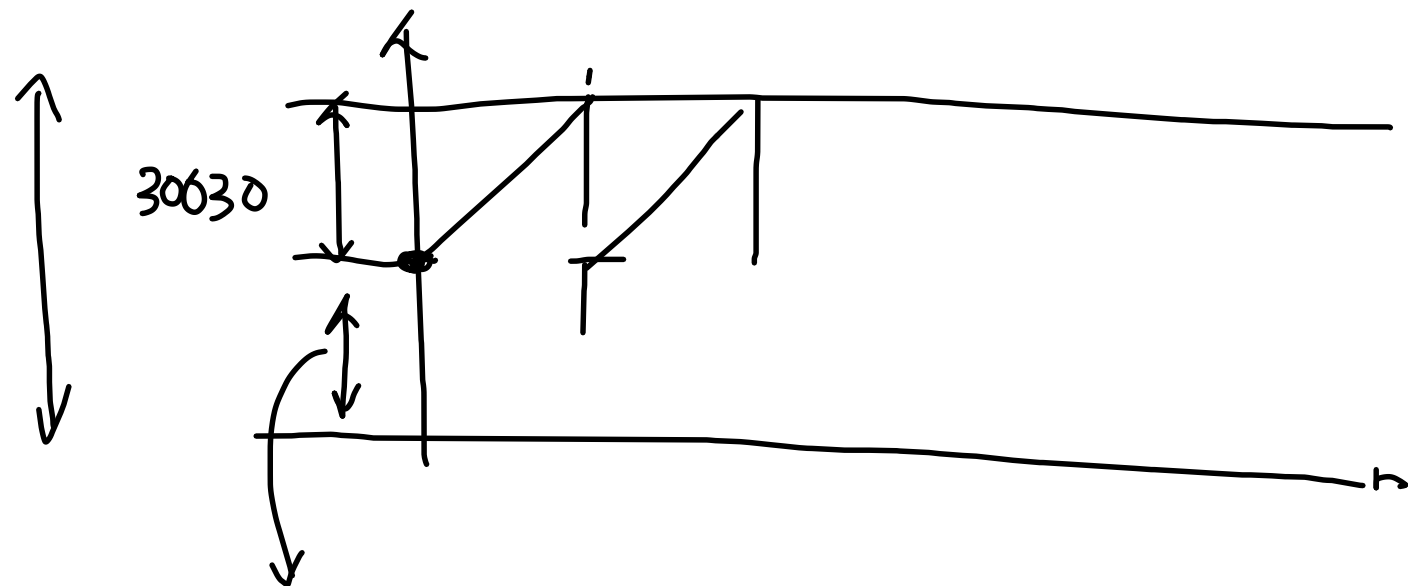


$$\phi \rightarrow F_{\text{FFFF}} = 15 \text{ kHz}$$

$$f = \frac{1}{T} \quad T = \frac{1}{15 \text{ kHz}} = 66,6 \mu\text{s}$$

$$65535 \times 66,6 \mu\text{s} = 4,36 \text{ s}$$

$$2.000.000 \mu\text{s} / 66,6 = 30030 \text{ step}$$



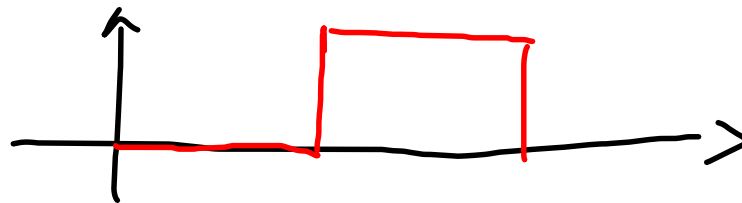
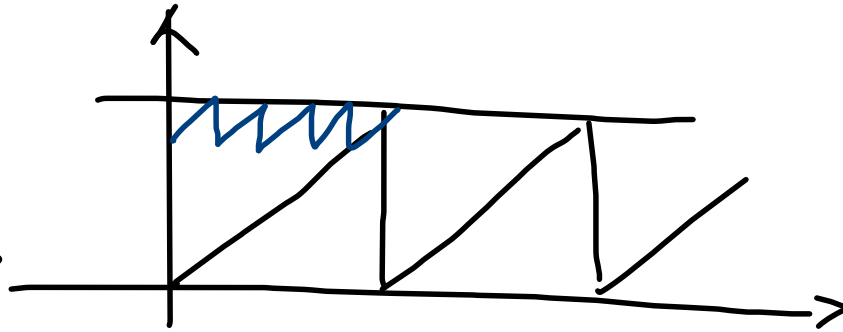
$$65535 - 30030 = 35504$$

↓  
8ABØ

1024  $\rightarrow$  15kHz  $T_1$  16b

0  $\rightarrow$  65535

$$\text{step} = \frac{1}{f} = 66,6 \mu\text{s}$$



$T = 25 \mu\text{s}$

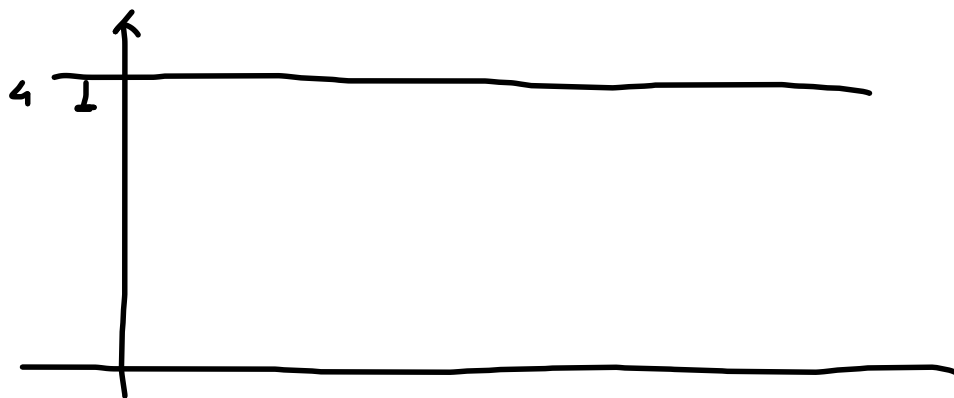
$$f = 2 \text{ kHz} ?$$

$$f = \frac{1}{T} = \frac{1}{n \cdot 2 \cdot 66,6 \mu\text{s}}$$

$$2 \cdot 10^3 = \frac{1}{n \cdot 2 \cdot 66,6 \mu\text{s}}$$

$$n = \frac{1}{2 \cdot 10^3 \cdot 2 \cdot 66,6 \mu\text{s}}$$

$$n = \frac{1}{\cancel{10^3} \cdot 4 \cdot 66,6 \cdot \underbrace{10^{-6}}_{10^{-3}}} = \frac{10^3}{4 \cdot 66,6} = 4$$



FFFF - 4