

## Assignment AI 1

الإسم : إسلام محمد محمد إبراهيم      الرقم : 12

الإسم : بهاء الدين أحمد خلف      الرقم : 20

## General Data structure:

Entry Class :

Node class for storing the path and heuristic cost and total cost

## General Functions :

getNeighbor:

to get the adjacent of current state (up,down,left,right)

## For DFS :

Stack for keeping nodes

Hash set to keep visited nodes

Algorithm : DFS

Path to goal: Stack to save depth of nodes and pop it when dfs stack not pushing

Cost of Path : Path Size -1

Node expanded : size of visited nodes

Running time :  $O(4^m)$

## For BFS :

Queue for keeping nodes

Hash set to keep visited nodes

Algorithm : BFS

Path to goal: Store previous path at node class and add new state path to it

Cost of Path : store cost using node

Node expanded : size of visited nodes

Running time :  $O(4^s)$

## For A\* :

Priority queue for keeping nodes

Linked Hash set to keep explored nodes

Entry Class :

Node class for storing the path and heuristic cost and total cost

Algorithm : A\* search

Path to goal: Store previous path at node class called entry

Cost of Path : Stored at node

Node expanded : size of visited nodes

Running time :  $O(4^d)$

Functions :

- A\_StarManhattanDistance:

Input : initial and goal states

Output: boolean to check if got the goal or not

Details :

to use A\* with Manhattan Distance as Heuristic function

- A\_StarEuclideanDistance:

Input : initial and goal states

Output: boolean to check if got the goal or not

Details :

to use A\* with Euclidean Distance as Heuristic function

- a\_star :

Input : explored , initial and goal states, boolean MD to check if it Manhattan or Euclidean Distance

Output: Entry node class

Details:

Use A\* Algorithm

-calcH:

Input: state and goal states, boolean MD to check if it  
Manhattan or Euclidean Distance

Output: Float

Details: Calc Heuristic function