

Software Engineering Laboratory

# Theory of Computing

Проф. Мануель Маццара

Guest lecture: CSP

(Bertrand Meyer)

with material from the ETH course

"Concepts of Concurrent Computation"

# CSP purpose

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# Concurrency formalism

- Expresses many concurrent situations elegantly
- Influenced design of several concurrent programming languages, in particular Occam (Transputer)

### Calculus

- Formally specified: laws
- > Makes it possible to prove properties of systems

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# Concurrency calculi

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Also known as process calculi

Aim: provide abstract models of concurrent computation

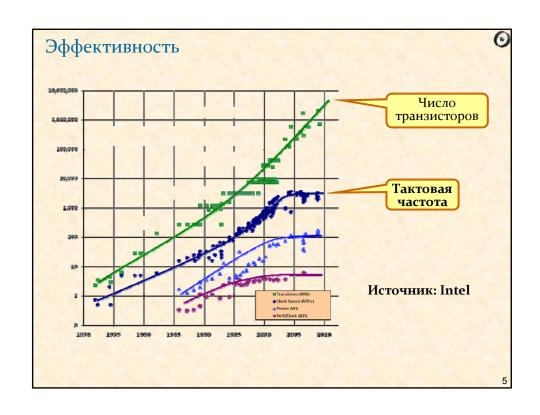
Independent of particular concurrency frameworks, languages, architectures, implementations

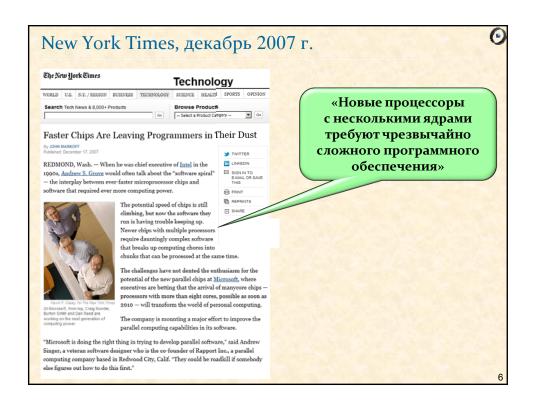
Examples:

- > CSP (this lecture), Tony Hoare
- CCS (Calculus of Communicating Systems), Robin Milner, 1973-1980
- $\rightarrow$   $\pi$ -calculus, Milner: distribution
- > Ambient Calculus, Cardelli/Gordon: mobility

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Concurrent programming is hard!





### Что говорят о параллельном программировании

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### Интел, 2006:

 Многоядерные вычисления быстрым и захватывающим путем переводят индустрию на абсолютно новую территорию

### Рик Рашид, глава Microsoft Research, 2007:

 Многоядерные процессоры представляют собой одну из крупнейших смен технологии, с глубокими следствиями в методах разработки программ

### Билл Гейтс:

Мы никогда не сталкивались с подобными задачами.
 Здесь нужен прорыв.

### Дэвид Паттерсон, Калифорнийский университет в Беркли, 2007:

 Вся индустрия, в принципе, сделала отчаянный выбор. Она делает ставку на параллельные вычисления. Ставка сделана, но большая проблема - добиться выигрыша

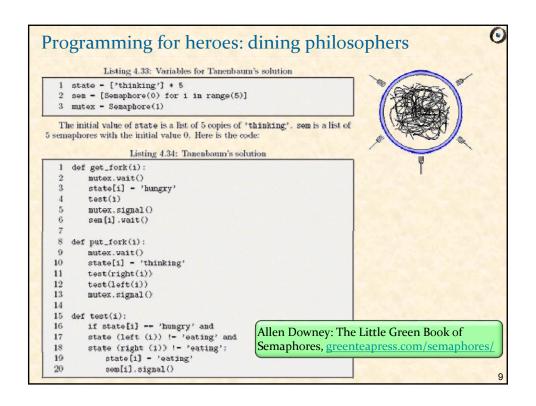
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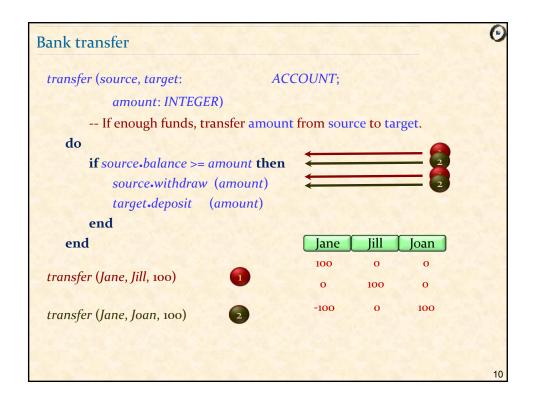
# US National Academy of Science, 2011

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**Heroic programmers** can exploit vast amounts of parallelism...

However, none of those developments comes close to the ubiquitous support for programming parallel hardware that is required to ensure that IT's effect on society over the next two decades will be as stunning as it has been over the last half-century





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Bank transfer (better version)

transfer (source, target: ACCOUNT;

amount: INTEGER)

-- Transfer amount from source to target.

require

source.balance >= amount

do

source.withdraw (amount)

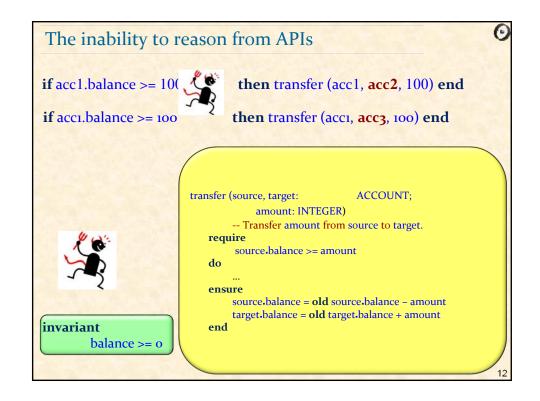
target.deposit (amount)

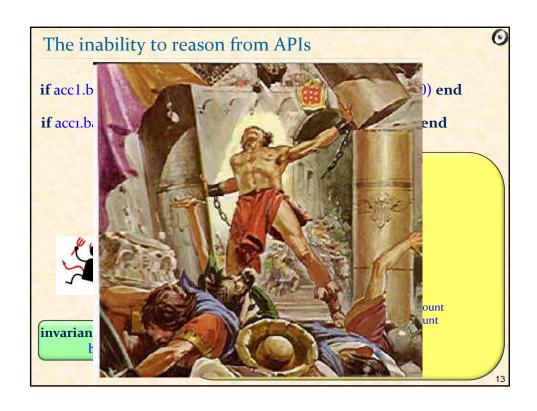
ensure

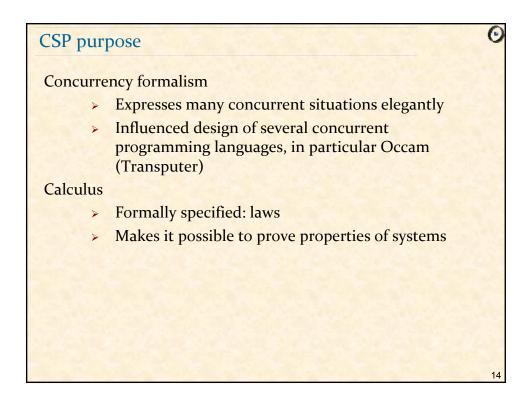
source.balance = old source.balance - amount

target.balance = old target.balance + amount

end
```







### Traces

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A trace is a sequence of events, for example

```
<coin, coffee, coin, coffee>
```

Many traces of interest are infinite, for example

```
<coin, coffee, coin, coffee, ...>
```

(Can be defined formally, e.g by regular expressions, but such traces definition are not part of CSP; they are descriptions of CSP process properties.)

Events come from an *alphabet*. The alphabet of all possible events is written  $\Sigma$  in the following.

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## Processes and their traces



A CSP process is characterized (although not necessarily defined fully) by the set of its traces. For example a process may have the trace set

```
{<>,
  <coin, coffee>,
  <coin, tea>}
```

The special process STOP has a trace set consisting of a single, empty trace:

{<>}

```
Basic CSP syntax

P ::=

STOP | -- Does not engage in any events

a \rightarrow Q | -- Engages in a, then acts like Q

Q \sqcap R | -- Internal choice

Q \sqcap R | -- External choice

Q \sqcap R | -- Concurrency (E: subset of alphabet)

Q \mid \mid R | -- Lock-step concurrency (same as Q \mid \mid R)

Q \mid R | -- Hiding

\mu Q \bullet f(Q) -- Recursion
```

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Generalization of → notation

Basic:

a → P

Generalization:

x: E → P (x)

Accepts any event from E, then executes P (x) where x is that event

Also written

? x: E → P (x)

Note that if E is empty then x: E → P (x) is STOP for any P
```

# Some laws of concurrency 1. $P \mid\mid Q = Q \mid\mid P$ 2. $(P \mid\mid (Q \mid\mid R)) = ((P \mid\mid Q) \mid\mid R)$ 3. $P \mid\mid STOP = STOP$ 4. $(c \rightarrow P) \mid\mid (c \rightarrow Q) = (c \rightarrow (P \mid\mid Q))$ 5. $(c \rightarrow P) \mid\mid (d \rightarrow Q) = STOP$ — If $c \neq d$ 6. $(x: A \rightarrow P(x)) \mid\mid (y: B \rightarrow Q(y)) = (z: (A \cap B) \rightarrow (P(z) \mid\mid Q(z))$

```
Basic notions

Processes engage in events
Example of basic notation:

CVM = (coin → coffee → coin → coffee → STOP)

Right associativity: the above is an abbreviation for

CVM = (coin → (coffee → (coin → (coffee → STOP))))

Trace set of CVM: {<coin, coffee, coin, coffee>}

The events of a process are taken from its alphabet:

α(CVM) = {coin, coffee}

STOP can engage in no events
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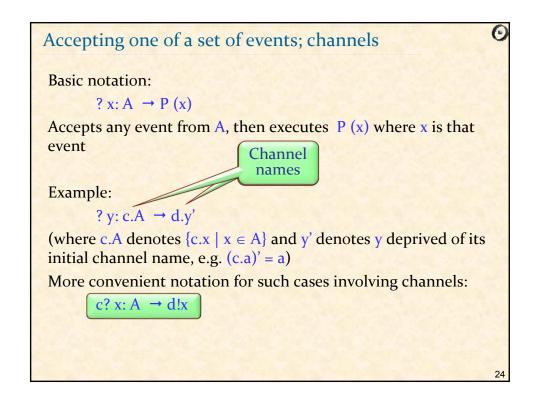
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Traces
traces (e \rightarrow Q) = \{ \langle e \rangle + s \mid s \in traces (Q) \}
```

```
Recursion

CLOCK = (tick → CLOCK)

This is an abbreviation for 
CLOCK = μP • (tick → P)

A recursive definition is a fixpoint equation. The μ notation denotes the fixpoint
```



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A simple buffer

COPY = c?x: A \rightarrow d!x \rightarrow COPY
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External choice

COPYBIT = (in.0 → out.0 → COPYBIT

in.1 → out.1 → COPYBIT)
```

```
External choice

COPY1 = in? x: A \rightarrow out1!x \rightarrow COPY1

COPY2 = in? x: B \rightarrow out2!x \rightarrow COPY2

COPY3 = COPY1 \square COPY2
```

External choice	0
Consider	
CHM1 = $(in1r \rightarrow out50k \rightarrow out20k \rightarrow out20k \rightarrow out10k)$ CHM2 = $(in1r \rightarrow out50k \rightarrow out50k)$	
CHM = CHM1 □ CHM2	
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```
Consider

P = ?x: A \rightarrow P'

Q = ?x: B \rightarrow Q'

Then

P \mid\mid Q = ?x \rightarrow

P \mid\mid Q' \mid\mid Q' \mid\quad \text{if } x \in A \cap B \mid\quad \text{otherwise}

(to be generalized soon)
```

```
More examples

VMC =

(in2f →

((large → VMC) □

(small → out1f → VMC))

□

(in1f →

((small → VMC) □

(in1f → large → VMC))

FOOLCUST = (in2f → large → FOOLCUST □

in1f → large → FOOLCUST)

FV = FOOLCUST || VMC =

\mu P \bullet (in2f \rightarrow large \rightarrow P \square in1f \rightarrow STOP)
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```

Hiding

Consider

$$P = a \rightarrow b \rightarrow Q$$

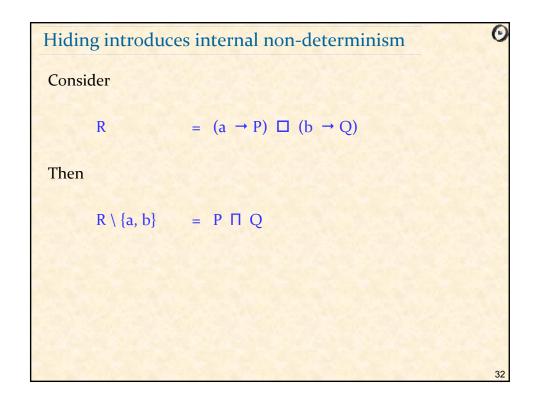
Assuming Q does not involve b, then

$$P \setminus \{b\} = a \rightarrow Q$$

More generally:
$$(a \rightarrow P) \setminus E =$$

$$P \setminus E \qquad \text{if } a \in E$$

$$P \setminus E \qquad \text{if } a \notin E$$



```
Non-deterministic internal choice: another application \bullet

TRANSMIT (x) = in?x \rightarrow LOSSY (x)

LOSSY (x) = out!x \rightarrow TRANSMIT (x)

\square out!x \rightarrow LOSSY (x)

\square TRANSMIT (x)
```

The general concurrency operator

Consider

$$P = ?x: A \rightarrow P'$$

$$Q = ?x: B \rightarrow Q'$$

Then
$$P \mid\mid Q = ?x \rightarrow P' \mid\mid Q' \qquad \text{if } x \in E \cap A \cap B$$

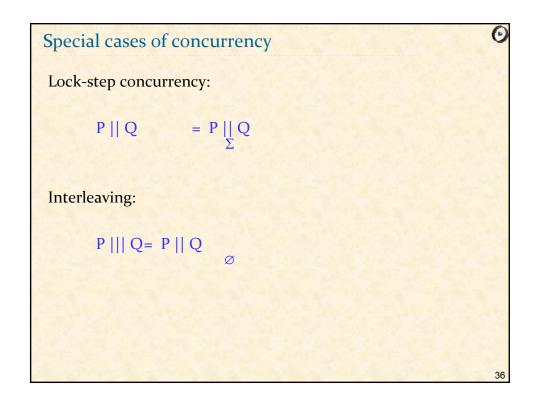
$$P' \mid\mid Q \qquad \text{if } x \in A - B - E$$

$$P' \mid\mid Q' \qquad \text{if } x \in B - A - E$$

$$P' \mid\mid Q \cap P \mid\mid Q' \quad \text{if } x \in A - B - E$$

$$P' \mid\mid Q \cap P \mid\mid Q' \quad \text{if } x \in A - B - E$$

$$P' \mid\mid Q \cap P \mid\mid Q' \quad \text{if } x \in A - B - E$$



```
Lock-step concurrency (reminder)

Consider

P = ?x: A \rightarrow P'
Q = ?x: B \rightarrow Q'

Then

P \mid\mid Q = ?x \rightarrow
\Rightarrow (P' \mid\mid Q') if x \in E \cap A \cap B

\Rightarrow STOP otherwise
```

```
Laws of non-deterministic internal choice

P \sqcap P = P
P \sqcap Q = Q \sqcap P
P \sqcap (Q \sqcap R) = (P \sqcap Q) \sqcap R
x \to (P \sqcap Q) = (x \to P) \sqcap (x \to Q)
P \mid\mid (Q \sqcap R) = (P \mid\mid Q) \sqcap (P \mid\mid R)
(P \sqcap Q) \mid\mid R = (P \mid\mid R) \sqcap (Q \mid\mid R)
The recursion operator is not distributive; consider:
P = \mu X \bullet ((a \to X) \sqcap (b \to X))
Q = (\mu X \bullet (a \to X)) \sqcap (\mu X \bullet (b \to X))
```

# Note on external choice

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From previous slide:

$$x \rightarrow (P \sqcap Q) = (x \rightarrow P) \sqcap (x \rightarrow Q)$$

The question was asked in class of whether a similar property also applies to external choice  $\Box$ 

The conjectured property is

$$x \rightarrow (P \square Q) = (x \rightarrow P) \square (x \rightarrow Q)$$

It does not hold, since

$$(x \rightarrow P) \square (x \rightarrow Q) = x \rightarrow (P \sqcap Q)$$

(As a consequence of rule on next page)

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# General property of external choice

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$$(?x: A \rightarrow P) \square (?x: B \rightarrow Q) =$$

$$?x: A \cup B \rightarrow$$

> P

if  $x \in A-B$ 

> Q

if  $x \in B-A$ 

» PПQ

if  $x \in A \cap B$ 

```
Traces
traces (e \rightarrow P) = \{ \langle e \rangle + s \mid s \in traces (P) \}
```

# Refinement Process Q refines (specifically, trace-refines) process P if traces (Q) ⊆ traces (P) For example: P refines P∏Q

# The trace model is not enough The traces of and are the same: traces (P □ Q) = traces (P) ∪ traces (Q) traces (P □ Q) = traces (P) ∪ traces (Q) But the processes can behave differently if for example: P = a → b → STOP Q = b → a → STOP Traces define what a process may do, not what it may refuse to do

```
For a process P and a trace t of P:

An event set es ∈ P (∑) is a refusal set if P can forever refuse all events in es

Refusals (P) is the set of P's refusal sets

Convention: keep only maximal refusal sets

(if X is a refusal set and Y ⊆ X, then Y is a refusal set)

This also leads to a notion of "failure":

Failures (P, t) is Refusals (P / t)

where P/t is Pafter t:
traces (P / t) = {u | t + u ∈ traces (P))
```

```
Comparing failures

Compare

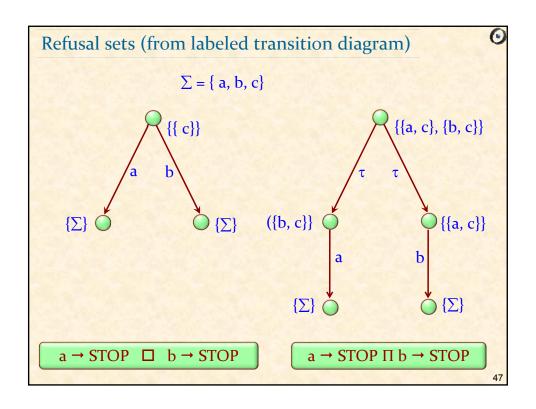
P = a \rightarrow STOP \square b \rightarrow STOP

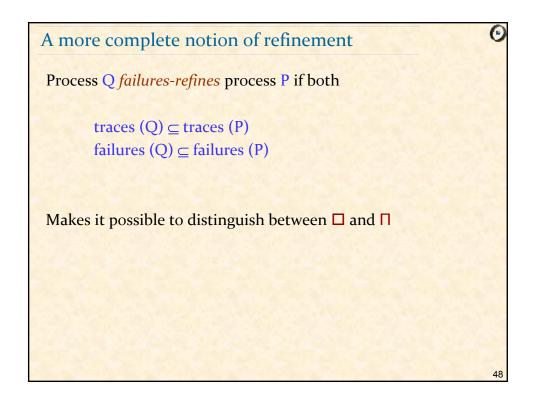
Q = a \rightarrow STOP \square b \rightarrow STOP

Same traces, but:

Refusals (P) = Ø

Refusals (Q) = {{a}, {b}}
```





# Divergence

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A process diverges if it is not refusing all events but not communicating with the environment

This happens if a process can engage in an infinite sequence of  $\tau$  transitions

An example of diverging process:

$$(\mu p.a \rightarrow p) \setminus a$$

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# The divergence model (Brookes, Roscoe)



CSP semantics is often expressed through a failures set A failure is of the form

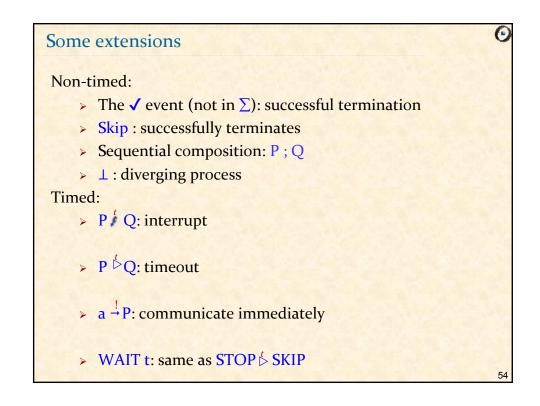
where s is a trace (sequence of events) and X a finite set of events

A failure set must satisfy the following properties:

- $\triangleright$  [ $\langle \rangle$ ,  $\emptyset$ ]  $\in$  F
- $ightharpoonup [s+t,\varnothing] \in F \Rightarrow [s,\varnothing] \in F$
- $ightharpoonup [s, X] \in F \land Y \subseteq X \Rightarrow [s, Y] \in F$
- $\blacktriangleright \ [s,X] \in F \land [s+\langle c\rangle,\varnothing] \not\in F \ \Rightarrow \ [s,X\cup\{c\}] \in F$

```
CSP laws in the divergence model (1/2)
                                             P \square P \cong_M P
                                             POQ MM QOP
                                     P \square (Q \square R) =_M (P \square Q) \square R
                                     P \square (Q \sqcap R) \equiv_M (P \square Q) \sqcap (P \square R)
                                     P \cap (Q \square R) \equiv_M (P \cap Q) \square (P \cap R)
                                       P STOP MM P
                                  (a \rightarrow (P \sqcap Q)) \cong_M (a \rightarrow P) \sqcap (a \rightarrow Q)
                            (a \to P) \square (a \to Q) \Longrightarrow_M (a \to P) \sqcap (a \to Q)
                                             P \sqcap P = M P
                                             P \sqcap Q \cong_M Q \sqcap P
                                     P \cap (Q \cap R) \equiv_M (P \cap Q) \cap R
                                              P \parallel Q =_M Q \parallel P
                                      P \parallel (Q \parallel R) =_M (P \parallel Q) \parallel R
                                     P \parallel (Q \sqcap R) \equiv_M (P \parallel Q) \sqcap (P \parallel R)
                             (a \rightarrow P) \parallel (b \rightarrow Q) =_M STOP
                                                       =_M (a \rightarrow (P \parallel Q)) if a = b
                                       P | STOP MM STOP
                                                                             (From: Brooks & Roscoe 85)
```

```
CSP laws (2/2)
                                    P || Q \equiv_M Q || P
                           (P ||| Q) ||| R =_M P ||| (Q ||| R)
                           P|||(Q \sqcap R) \equiv_M (P|||Q) \sqcap (P|||R)
                 (a \to P) |||(b \to Q) \equiv_M (a \to (P|||(b \to Q))) \square (b \to ((a \to P)|||Q))
                              P_{i}(Q;R) \rightleftharpoons_{M} (P;Q);R
                             STOP Q SM Q
                                SKIP; Q \equiv_M Q
                              STOP; Q =M STOP
                             P_{i}(Q \cap R) \equiv_{M} (P_{i}Q) \cap (P_{i}R)
                             (P \sqcap Q)_i R \equiv_M (P; R) \sqcap (Q; R)
                            (a \rightarrow P); Q \equiv_M (a \rightarrow P; Q)
                                 (P \setminus a) \setminus b \cong_M (P \setminus b) \setminus a
                                (P \backslash a) \backslash a \equiv_M P \backslash a
                             (a \rightarrow P)\backslash b \equiv_M (a \rightarrow P\backslash b)
                                               EEM P\b
                              (P \sqcap Q) \setminus a \equiv_M (P \setminus a) \sqcap (Q \setminus a)
```



```
Example (Ouaknine)

V1 = coin.in \rightarrow

((coke \rightarrow V1) \square (fanta \rightarrow V1))

(coin.out \stackrel{!}{\rightarrow} V1)
```

```
Some laws no longer hold

P \mid\mid STOP = STOP \text{ if } P \neq \bot
\bot \mid\mid STOP = \bot
(a \rightarrow P) \setminus b = a \rightarrow (P \setminus b) \text{ if } a \neq b
(a \rightarrow P) \setminus a = P \setminus a
```

# **CSP: Summary**

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A calculus based on mathematical laws

Provides a general model of computation based on communication

Serves both as specification of concurrent systems and as a guide to implementation

One of the most influential models for concurrency work