Theory of Computation

Nondeterminism

Lecture 8a - Manuel Mazzara

Nondeterministic models (1)

- Usually one thinks of an algorithm as a determined sequence of operations
 - In a certain state with a certain input there is no doubt on the next step
- Example: let us compare

```
if x>y then max:=x else max:=y
with

if
     x>=y then max:=x
     x<=y then max:=y
fi</pre>
```

Nondeterministic models (1)

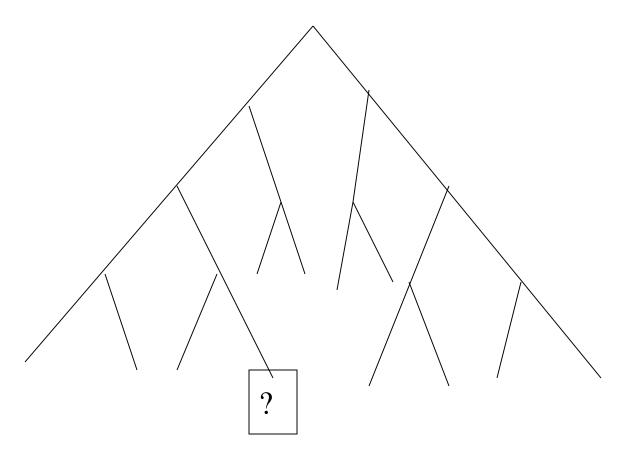
- Is it only a matter of elegance?
- Let us consider the case construct of Pascal: why not having something like the following?

case

```
x=y then S1
z>y+3 then S2
... then
```

endcase

Blind search



Another form of nondeterminsm that is usually "hidden"

Search algorithms

- Search algorithms are a "simulation" of basically nondeterministic algorithms
 - Is the element searched for in the root?

If yes, ok

Otherwise

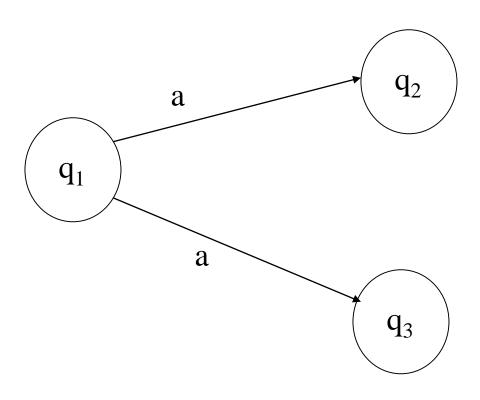
Search the left subtree Search the right subtree

 Choice of priority among paths is often arbitrary

In conclusion

- Nondeterminism (ND) is a model of computation or at least a model of parallel computing
 - Ada and other concurrent languages exploit it
- It is a useful abstraction to describe search problems and algorithms
- It can be applied to various computational models
- Important: ND models must not be confused with stochastic models

Adding nondeterminsm



$$\delta(q_1,a) = \{q_2, q_3\}$$

Nondeterministic FSA

- A nondeterministic FSA (NDFSA) is a tuple
- <Q, I, δ , q₀, F>, where
 - -Q, I, q_0 , F are defined as in (D)FSAs
 - $-\delta: Q \times I \rightarrow \mathcal{P}(Q)$
- What happens to δ^* ?

Move sequence

• δ^* is inductively defined from δ

$$\delta^*(q, \epsilon) = \{q\}$$

$$\delta^*(q, y.i) = \bigcup_{q' \in \delta^*(q, y)} \delta(q', i)$$

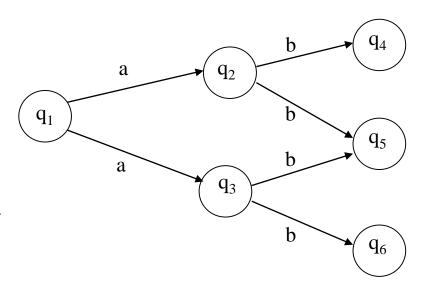
Example:

$$\delta(q_1,a) = \{q_2, q_3\},\$$

$$\delta(q_2,b) = \{q_4, q_5\},\$$

$$\delta(q_3,b) = \{q_6, q_5\}\$$

$$\rightarrow \delta^*(q_1,ab) = \{q_4, q_5, q_6\}\$$



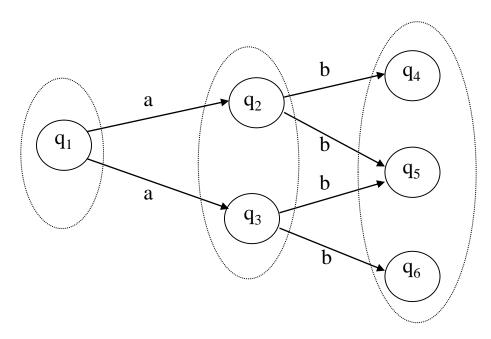
Acceptance condition

$$x \in L \Leftrightarrow \delta^*(q_0,x) \cap F \neq \emptyset$$

Among the various possible runs (with the same input) of the NDFSA, it is sufficient that **one of them succeeds** to accept the input string

- → Existential nondeterminism
 - There exists also a universal interpretation: $\delta^*(q_0,x)\subseteq F$

DFSA vs NDFSA



- Starting from q_1 and reading ab the automaton reaches a state that belongs to the set $\{q_4, q_5, q_6\}$
- Let us call again "state" the set of possible states in which the NDFSA can be during the run

Formally

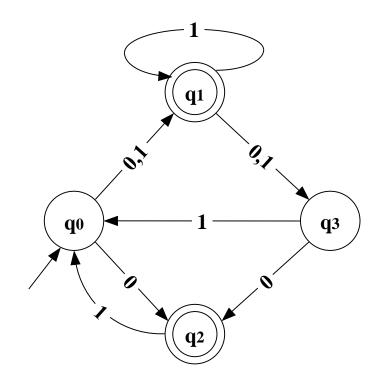
- NDFSA have the same power as DFSA
- Given a NDFSA, an equivalent DFSA can be automatically computed as follows:

If
$$A_{ND} = \langle Q, I, \delta, q_0, F \rangle$$
 then $A_D = \langle Q_D, I, \delta_D, q_{0D}, F_D \rangle$, where $-Q_D = \mathcal{P}(Q)$ $-\delta_D(q_D,i) = \bigcup_{q \in q_D} \delta(q,i)$ $-q_{0D} = \{q_0\}$ $-F_D = \{q_D \mid q_D \in Q_D \land q_D \cap F \neq \emptyset\}$

Example (1)

Transform the following NDFSA into the equivalent DFSA

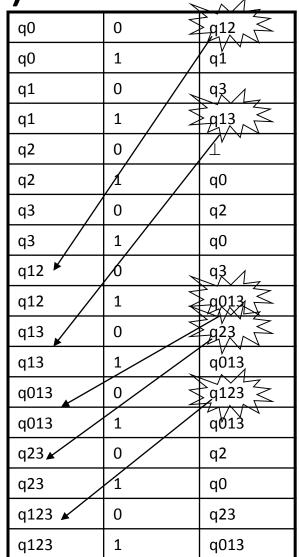
q0	0	q1 \
q0	0	q2 /
q0	1	q1
q1	0	q3
q1	1 /	q3 \
q1	1	q1 /
q2	0	
q2	1	q0
q3	0	q2
q3	1	q0



Example (2)

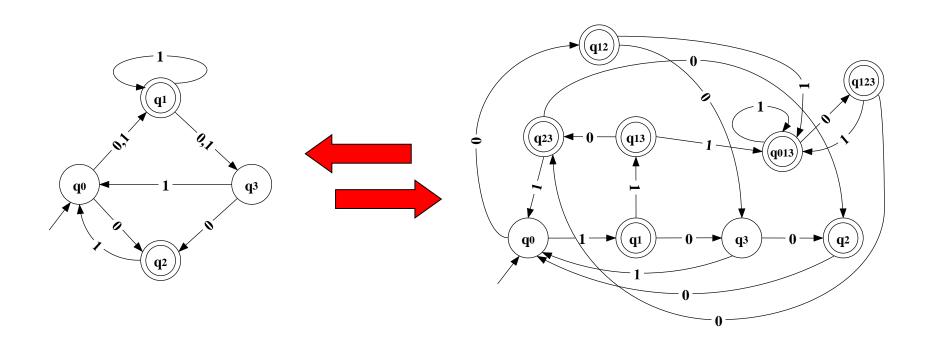
Let us proceed recursively

q0	0	q1
q0	0	q2
q0	1	q1
q1	0	q3
q1	1	q3
q1	1	q1
q2	0	\perp
q2	1	q0
q3	0	q2
q3	1	q0



Example (3)

Graphically



Why ND?

- NDFSAs are no more powerful than FSAs, but they are not useless
 - It can be easier to design a NDFSA
 - They can be exponentially smaller w.r.t. the number of states
- Example: a NDFSA with 5 states becomes in the worst case a FSA with 2⁵ states

Nondeterministic TM

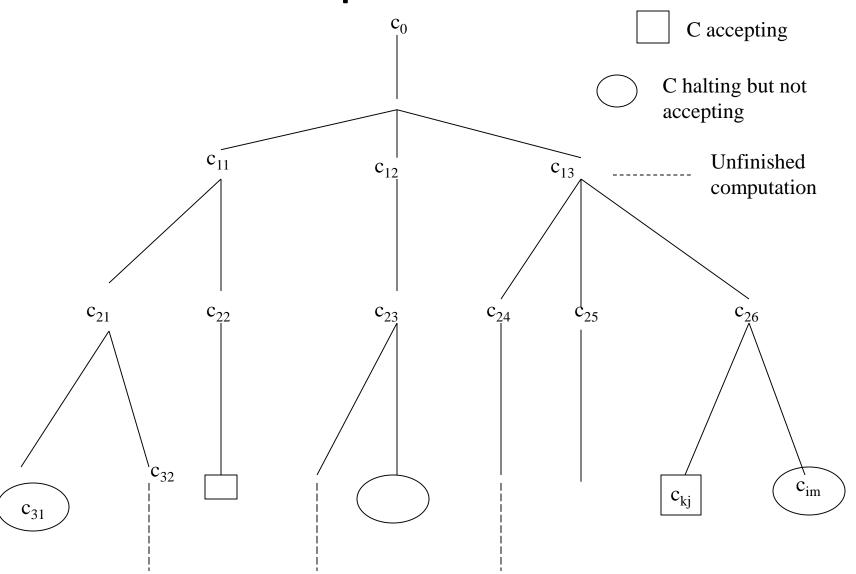
- To define a nondeterministic TM (NDTM), we need to change the transition function and the translation mapping
- All the other elements remain as in a (D)TM
- The transition function is

$$\delta: (Q-F) \times I \times \Gamma^k \rightarrow \mathcal{P}(Q \times \Gamma^k \times \{R,L,S\}^{k+1})$$

and the output mapping

$$\eta: (Q-F) \times I \times \Gamma^k \rightarrow \mathcal{P}(O \times \{R,S\})$$

Computation tree



Acceptance condition

- A string x∈I* is accepted by a NDTM if and only if there exists a computation that terminates in an accepting state
- It would seem that the problem of accepting a string can be reduced to a visit of a computation tree
 - How should we perform the visit?
 - What about the relationship between DTMs and NDTMs?

Visiting the computation tree

- We know different kinds of visits:
 - Depth-first visit
 - Breadth-first visit
- A depth-first visit cannot work in our problem because the computation tree could have infinite paths and the algorithm might "get stuck" in it
- We should adopt a breadth-first visit algorithm

DTM vs NDTM

Can we build a DTM that visits a tree level by level?

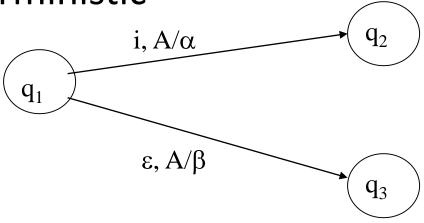
It is a long (and boring) exercise, but YES

- →We can build a DTM that establishes whether a NDTM recognizes a string x
- →Given a NDTM, we can build an equivalent DTM

ND does not add power to TMs

ε Moves and PDAs

- ϵ -moves came with the following constraint: If $\delta(q,\epsilon,A)\neq \perp$, then $\delta(q,i,A)=\perp \ \forall i\in I$
- Without this constraint the presence of ε-moves would make PDAs intrinsically nondeterministic



Adding nondeterminism to PDAs

- Removing the constraint already makes the PDA nondeterministic
- Additionally, we can have nondeterminism by changing the transition function of a PDA and consequently:
 - transitions among configurations
 - acceptance condition

Definition

A nondeterministic PDA (NDPDA) is a tuple

$$<$$
Q, I, Γ , δ , q₀, Z₀, F $>$

- -Q, I, Γ , q_0 , Z_0 , F as in (D)PDA
- $-\delta$ is the transition function defined as

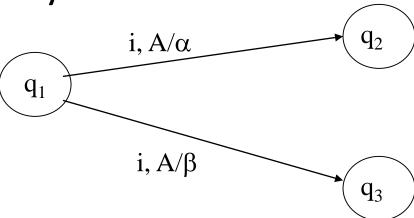
$$δ$$
: Q×(I∪{ε})× $Γ$ → P_F (Q× $Γ$ *)

- What is the \mathcal{F} in $\mathcal{P}_{\mathcal{F}}$?
- Why \mathcal{F} ?

Transition function

$$δ$$
: Q×(I∪{ε})×Γ→ P_F (Q×Γ*)

- P_F indicates the *finite* subsets of $Q \times \Gamma^*$
 - Why did we not specify it for NDTM?
- Graphically:

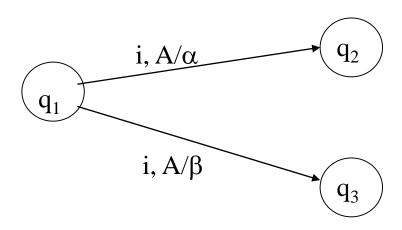


Effects of nondeterminism

- ND does not add expressive power to
 - TMs
 - FSAs
- Does ND add expressive power to DPDAs?

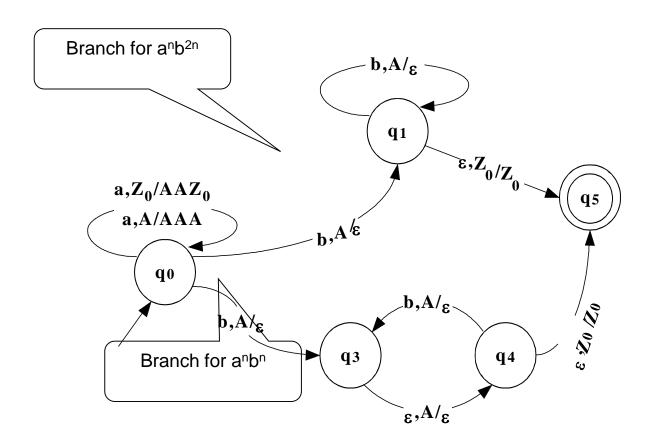
NDPDAs vs DPDAs (1)

- Obviously a NDPDA can recognize all the languages recognizable by DPDAs
- ND allows

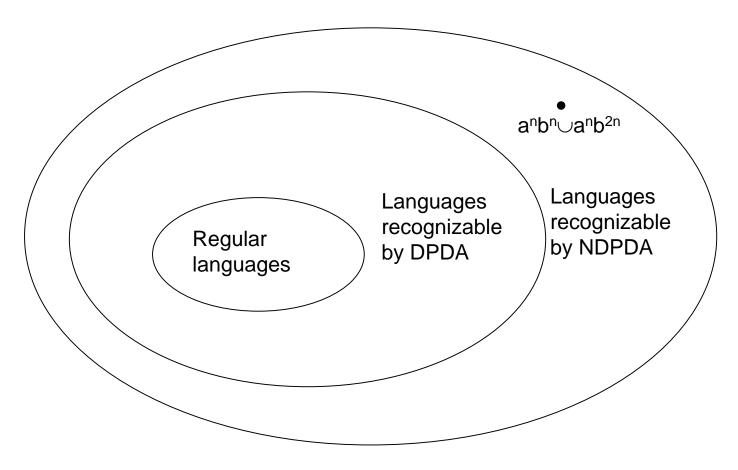


so NPDAs can recognize $\{a^nb^n \mid n \ge 1\}$ U $\{a^nb^{2n} \mid n \ge 1\}$

${a^nb^n \mid n \ge 1} \cup {a^nb^{2n} \mid n \ge 1}$

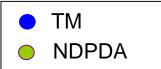


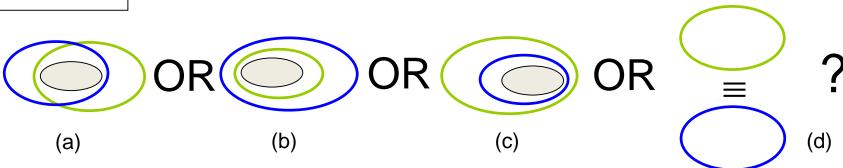
NDPDAs vs DPDAs (2)



Languages recognizable by NDPDAs are called context-free languages

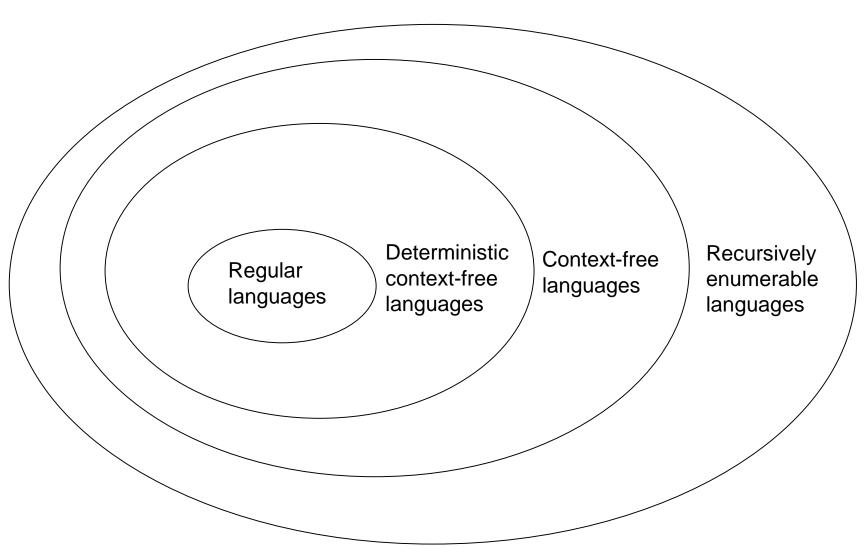
NDPDA vs TM





- (a) and (c): NO!
 - A (N)DTM can simulate a NDPDA by using the tape as a stack
- (d): NO!
 - The stack is still a destructive memory
 - $\{a^nb^n \mid n \ge 1\}$ U $\{a^nb^{2n} \mid n \ge 1\}$ is recognizable by both

The bull's-eye

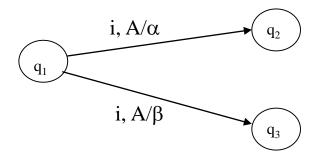


Closure properties in DPDAs

- In DPDAs we have
 - Closure w.r.t. complement
 - Non-closure w.r.t. union, intersection, difference
- Does changing the power of the automata change their behavior w.r.t. operations?
 - It can happen
 - New power, new language

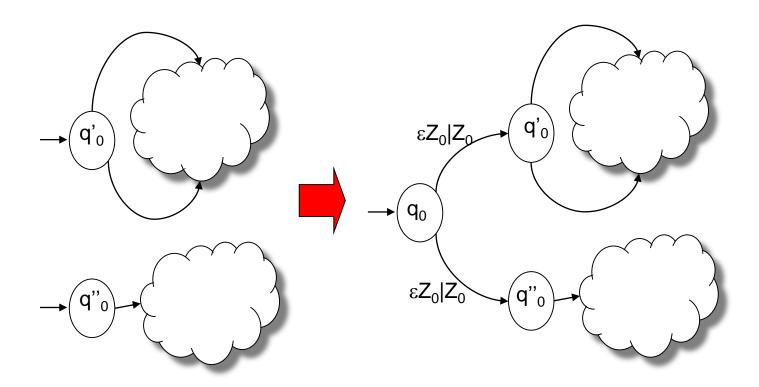
Union (1)

- NDPDAs are closed under union
 - Intuition:



• Given two NDPDAs, P_1 and P_2 , we can always build a NDPDA that represents the union by creating a new initial state that is connected to both initial states of P_1 and P_2 with an ϵ -move

Union (2)



Intersection

- The closure w.r.t. intersection still does <u>not</u> hold
- Consider
 - $\{a^nb^nc^*\}$
 - $\{a^*b^nc^n\}$

both are recognizable by (N)DPDAs, but ${a^nb^nc^*}\cap {a^*b^nc^n}={a^nb^nc^n}$ is not recognizable by any NDPDA

Complement (1)

- If a class of languages is closed w.r.t. union, but not w.r.t. intersection it cannot be closed w.r.t. complement
 - We can write intersection in terms of union and complement
- NDPDAs are not closed w.r.t complement

Remarks

- If a machine is deterministic and its computation terminates, the complement can be obtained by
 - Completing the machine
 - Swapping accepting and non accepting states
- Nondeterminism or infinite computation does not allow the application of this approach

Complement (2)

- For NDPDAs, computations can always be made terminating (as for DPDAs)
- However, ND can cause this problem:

One can have two computations:

$$-c_0 = \langle q_0, x, Z_0 \rangle | -^* - c_1 = \langle q_1, \varepsilon, \gamma \rangle$$

 $-c_0 = \langle q_0, x, Z_0 \rangle | -^* - c_2 = \langle q_2, \varepsilon, \gamma \rangle$
with $q_1 \in F$ and $q_2 \notin F$

→ even if we swap accepting and non accepting state, x is still accepted

Theory of Computation

A bit of History and Context

Lecture 8b - Manuel Mazzara

Gottfried Wilhelm Leibniz

 "It is unworthy of excellent men to lose hours like slaves in the labor of calculation which could safely be regulated to anyone else if machines were used."

1646 - 1716

The "decision problem" (1928)

 The problem asks for an algorithm that takes as input a statement of a first-order logic and answers "Yes" or "No" according to whether the statement is provable from the axioms using the rules of logic."

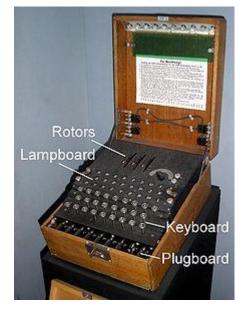
David Hilbert, 1928

Alan Turing (1)

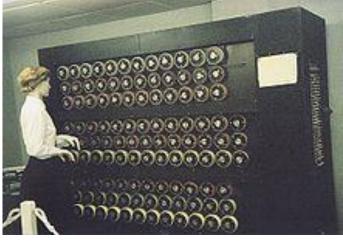
- Independently negatively answered the decision problem
- As we have seen he defined the nowadays
 Turing Machine – a <u>machine</u> foundation for computing

Alan Turing (2)

 Led to Von Neumann computers and family of imperative programming languages



The Enigma
Cryptographic
Device



Turing designed the machine to decrypt Enigma messages.



Alonzo Church (1)

- Church's Theorem (1936)
- Independently negatively answered the decision problem

• 1903-1995



Alonzo Church (2)

- Defined the Lambda (λ) Calculus a <u>language</u> foundation for computing
- Led to family of functional programming languages
- Today the Lambda Calculus serves as a mathematical foundation for the study of functional programming languages.