

Project Report On

**Title: Development of a Car Black Box
Using LPC1768 Microcontroller**

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Abstract

The Car Black Box is an advanced embedded system designed using the LPC1768 microcontroller, aimed at enhancing vehicle safety through real-time data monitoring and recording. This system integrates a 4x4 keypad for user interaction, an LCD for data display, an RTC for timekeeping, and a temperature sensor. The Car Black Box records crucial data, such as temperature, timestamps, and user actions, providing valuable insights during vehicle operation. This report details the system's design, implementation, testing, and potential applications, emphasizing its significance in automotive safety and data logging. The Car Black Box system is a comprehensive automotive safety device designed to capture, monitor, and record critical vehicle data using the LPC1768 microcontroller. In an era where vehicle safety and data-driven diagnostics are paramount, this system serves as an indispensable tool for both real-time monitoring and post-incident analysis. Inspired by the concept of flight data recorders in the aviation industry, the Car Black Box system is tailored for automotive applications, offering a robust solution for data logging and retrieval. Built around the LPC1768 microcontroller, the system integrates various peripherals, including an RTC for timekeeping, an ADC-connected temperature sensor, and a UART interface for data communication. This integration ensures that the system not only records data accurately but also displays it in a user-friendly manner while providing secure access through password protection. In addition to its core functionalities, the Car Black Box is designed with flexibility and scalability in mind, making it adaptable to various automotive environments and customizable for different vehicle types. It can log and transmit data continuously, providing a reliable record of vehicle performance and environmental conditions. This report delves into the detailed design, implementation, testing, and potential applications of the Car Black Box system, highlighting its significance in modern automotive safety and diagnostics.

1. Introduction

In the automotive industry, safety and data management have become increasingly important as vehicles evolve with advanced technologies. The concept of a "black box" or flight data recorder, which is integral to aviation safety, has inspired similar innovations in automotive safety systems. These systems are designed to record and analyze critical data during a vehicle's operation, providing valuable insights in the event of an accident or for routine performance monitoring. The Car Black Box, developed using the LPC1768 microcontroller, is a sophisticated embedded system aimed at fulfilling these needs.

The primary function of the Car Black Box is to capture and store essential data such as environmental conditions (e.g., temperature), operational parameters (e.g., time and date), and user interactions. This data is crucial for understanding the circumstances leading to an incident, thereby aiding in accident investigations, legal inquiries, and insurance claims. Furthermore, the Car Black Box can be used for preventive maintenance by monitoring the vehicle's operational environment and alerting users to potential issues before they escalate.

The LPC1768 microcontroller, a powerful and versatile component, serves as the brain of this system. It is chosen for its processing capability, flexibility, and ability to interface with a wide range of peripherals. The system is designed to be user-friendly, featuring a 4x4 keypad for secure access and control, an LCD for real-time data display, and various sensors for data collection. The Car Black Box not only logs data but also provides immediate feedback to the driver, enhancing situational awareness and promoting safer driving behaviors.

In addition to its core functionalities, the Car Black Box is designed with scalability and adaptability in mind. It can be easily integrated into different types of vehicles, from personal cars to commercial fleets, and can be customized to record additional data points as required. The system is also capable of transmitting data via UART to external devices, enabling remote monitoring and analysis, which is particularly useful for fleet management and logistics companies.

The development of the Car Black Box is driven by the need to improve road safety and vehicle reliability. By recording and analyzing data, this system provides a deeper understanding of vehicle behavior under various conditions, which can lead to better-designed safety features, more efficient vehicle maintenance schedules, and enhanced driver training programs. The Car Black

Box represents a significant step forward in the integration of technology and safety in the automotive sector.

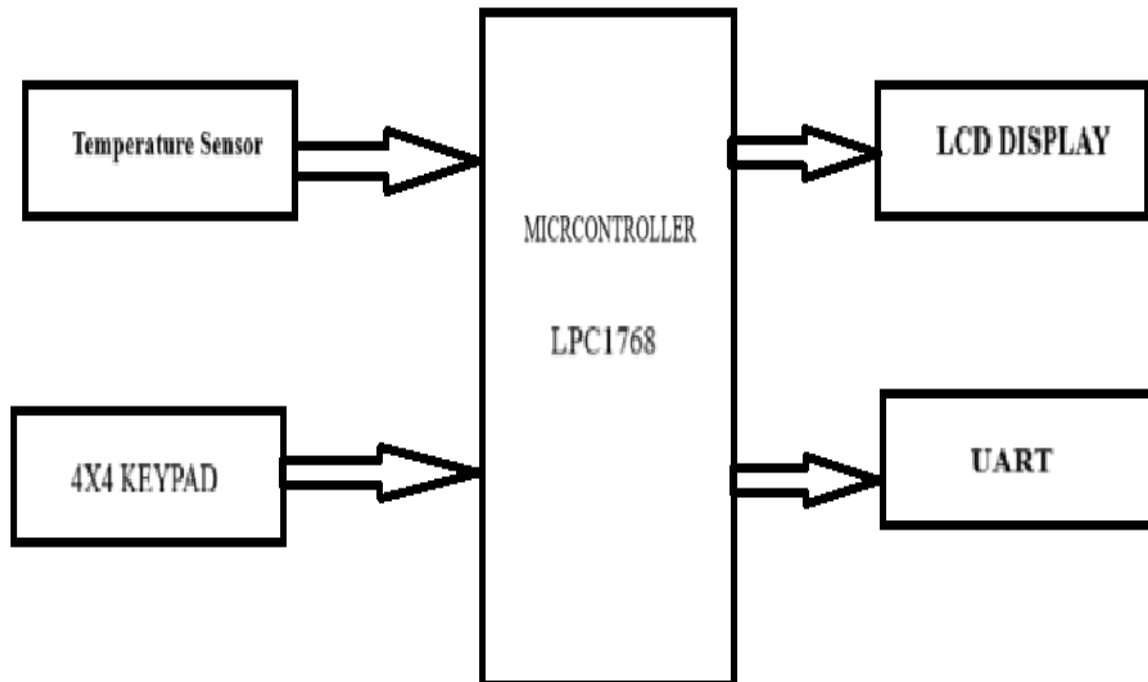
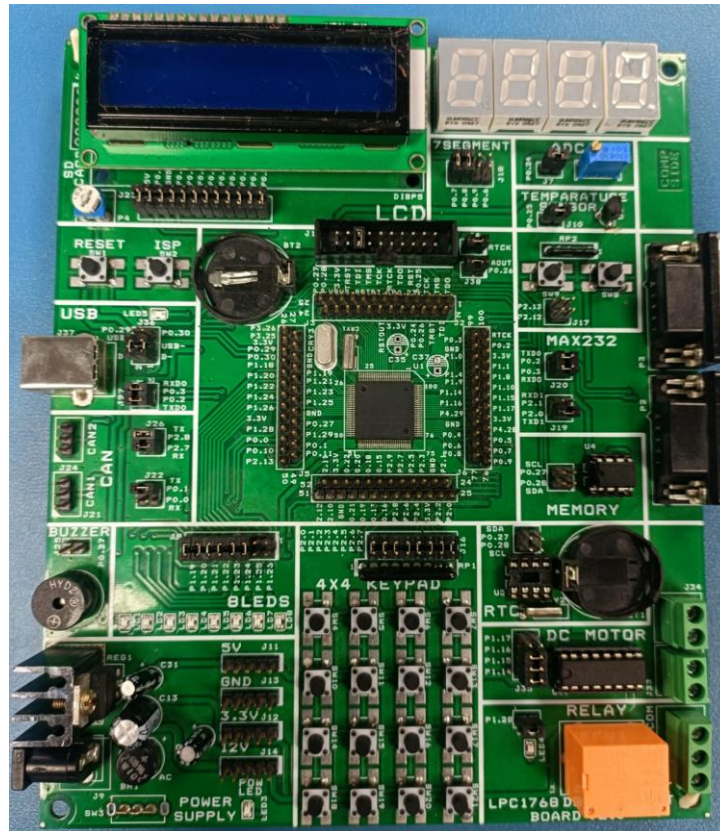
This report provides a comprehensive overview of the Car Black Box project, including its design, development, testing, and potential applications. It explores the technical challenges faced during the project, the solutions implemented, and the results achieved. The report also discusses the future potential of the Car Black Box, considering the rapid advancements in automotive technology and the growing importance of data-driven safety solutions.

The introduction of the Car Black Box into the automotive industry is expected to have a profound impact, not only in improving safety standards but also in shaping the future of vehicle data management. As vehicles become more connected and autonomous, systems like the Car Black Box will play a critical role in ensuring that data is used effectively to enhance safety, optimize performance, and reduce risks on the road.

2. Objectives

- To design and implement a Car Black Box system using the LPC1768 microcontroller.
- To develop a secure keypad-based interface for user interaction.
- To monitor and record environmental data, such as temperature, and provide real-time feedback to the user.
- To accurately log time and date using an RTC, ensuring precise data recording.
- To display all collected data on an LCD and transmit it via UART for further analysis.

3. Block Diagram



The block diagram outlines the primary components of the Car Black Box system and their interactions. The LPC1768 microcontroller serves as the central processing unit, interfacing with the following components:

- **4x4 Keypad:** User input interface for entering passwords and selecting options.
- **LCD Display:** Visual output for displaying system prompts, real-time data, and user feedback.
- **Temperature Sensor (ADC Input):** Captures real-time temperature data from the vehicle environment.
- **RTC (Real-Time Clock):** Provides accurate time and date information for logging purposes.
- **UART (Universal Asynchronous Receiver-Transmitter):** Facilitates data transmission to an external monitor or recording device.

4. Methodology

4.1 System Initialization

- The system begins by initializing the LCD, keypad, temperature sensor, and RTC.
- The microcontroller sets up the GPIO pins for the keypad and LCD, configures the ADC for temperature sensing, and initializes the RTC for accurate timekeeping.

4.2 Keypad Interaction and Password Verification

- The user interacts with the system via the 4x4 keypad.
- Upon startup, the system prompts the user to enter a password. The password is compared with a predefined correct password stored in the microcontroller's memory.
- If the password is correct, the system grants access to various functionalities such as viewing the date/time, selecting audio options, and monitoring temperature.
- If the password is incorrect, the system displays an error message and returns to the password prompt.

4.3 Function Selection and Data Display

- After successful password entry, the user can select from the following options:
 - **View Date/Time:** The system retrieves the current date and time from the RTC and displays it on the LCD.
 - **Select Audio Language:** The user can select a language option (e.g., Kannada, English, Hindi) for audio playback. This feature is represented as a choice between different keys on the keypad.
 - **Monitor Temperature:** The system reads the temperature from the sensor, converts the analog value to digital, and displays the temperature on the LCD. If the temperature exceeds a specified threshold, the system can trigger an alert (e.g., turning on a fan or blinking an LED).

4.4 Data Logging and UART Transmission

- The system logs all user interactions and sensor data, transmitting this information via UART to an external monitor or recording device.
- This ensures that all critical data is preserved for future analysis, particularly useful in post-accident investigations or vehicle performance reviews.

5. Hardware and Software Requirements

5.1 Hardware Requirements

- **LPC1768 Microcontroller:** Central processing unit for the Car Black Box.
- **4x4 Keypad:** User interface for inputting commands and data.
- **16x2 LCD Display:** Output interface for displaying system information and data.
- **Temperature Sensor (Analog Input):** Measures environmental temperature within the vehicle.
- **RTC (Real-Time Clock) Module:** Provides accurate date and time for logging purposes.
- **Power Supply:** Provides the necessary power to all components within the system.

- **UART Interface:** Allows for serial communication and data logging to an external device.

5.2 Software Requirements

- **Keil uVision IDE:** Development environment for programming the LPC1768 microcontroller in Embedded C.
- **Flash Magic:** Tool for programming the LPC1768 with the developed code.
- **Embedded C Programming Language:** For coding the microcontroller to interact with the hardware components.

6. Design and Implementation

6.1 Circuit Design

The circuit design integrates the LPC1768 microcontroller with peripheral devices including the 4x4 keypad, LCD, temperature sensor, and RTC module. The microcontroller interfaces with each component via its GPIO, ADC, and UART ports.

- **Keypad Interface:** The 4x4 keypad is connected to the microcontroller's GPIO pins. The rows are set as outputs, and the columns are set as inputs. Key presses are detected by scanning the rows and columns.
- **LCD Display:** The LCD is connected to the microcontroller's data and control pins, allowing for the display of system prompts, user inputs, and sensor data.
- **Temperature Sensor:** The sensor is connected to one of the ADC channels on the microcontroller. It provides analog voltage corresponding to the temperature, which is then digitized by the ADC for processing.
- **RTC Module:** The RTC module is connected to the microcontroller via I2C or SPI (depending on the specific RTC module used), providing the current time and date.
- **UART Communication:** The UART interface is set up for serial communication, enabling the transmission of logged data to an external device.

6.2 Implementation Details

The implementation is divided into the following key areas:

- **Keypad Handling:** The microcontroller continuously scans the keypad to detect key presses. When a key is pressed, the corresponding function (e.g., password entry, option selection) is executed.
- **LCD Management:** The LCD is managed using standard commands for initialization, command writing, and data writing. The microcontroller sends appropriate commands to display text, numbers, and sensor data.
- **Temperature Monitoring:** The ADC is configured to read the voltage from the temperature sensor, converting it into a digital value. This value is then converted into a temperature reading in Celsius and displayed on the LCD.
- **Timekeeping:** The RTC is initialized with the current date and time. The microcontroller periodically reads the time from the RTC and displays it upon user request.
- **Data Logging:** All user inputs and sensor data are logged and transmitted via UART to an external monitor for storage and analysis.

7. Testing

Testing was conducted to ensure the system operates as intended, covering the following aspects:

7.1 Keypad Testing

- Verified that each key press is correctly detected and processed.
- Ensured that the password entry and validation process works correctly, allowing access only when the correct password is entered.

7.2 LCD Display Testing

- Tested the display of system prompts, real-time data, and user feedback on the LCD.
- Ensured that the display is clear and readable under various conditions.

7.3 Temperature Monitoring

- Calibrated the temperature sensor to ensure accurate readings.
- Tested the system's response to different temperature ranges, including triggering alerts when the temperature exceeds a specified threshold.

7.4 RTC Functionality

- Verified that the RTC accurately maintains the current date and time.
- Ensured that the correct time and date are displayed when requested by the user.

7.5 UART Communication

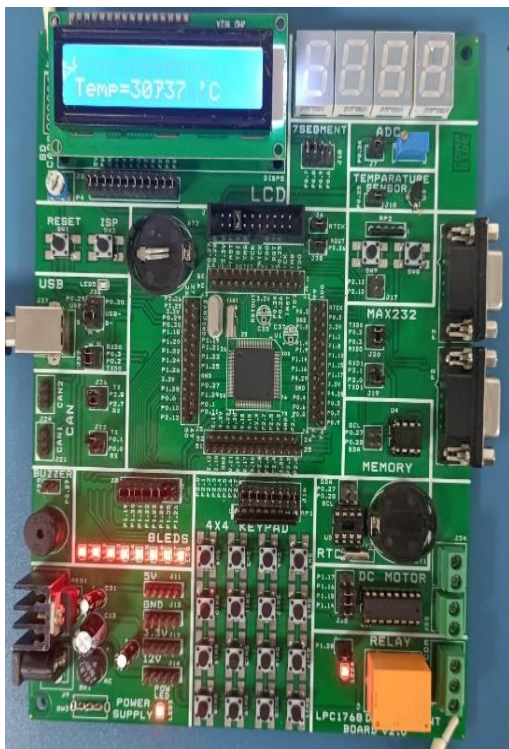
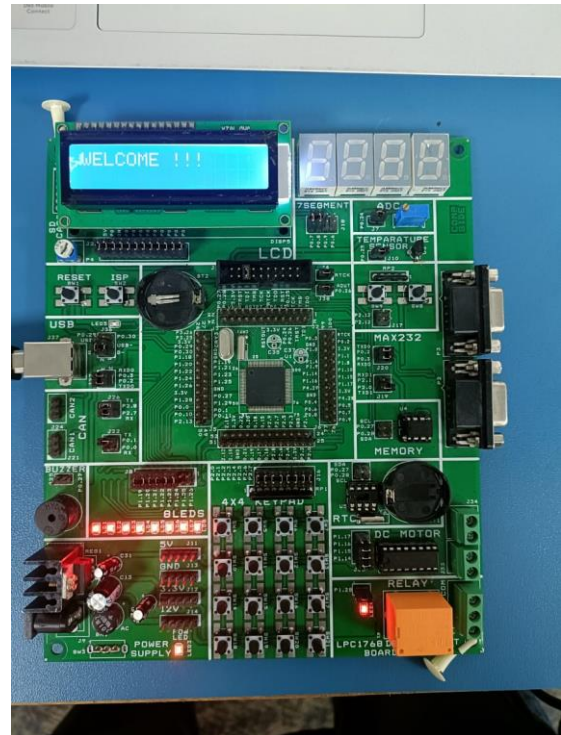
- Tested the transmission of logged data via UART to an external monitor.
- Verified that all data, including user inputs and sensor readings, are correctly logged and transmitted.

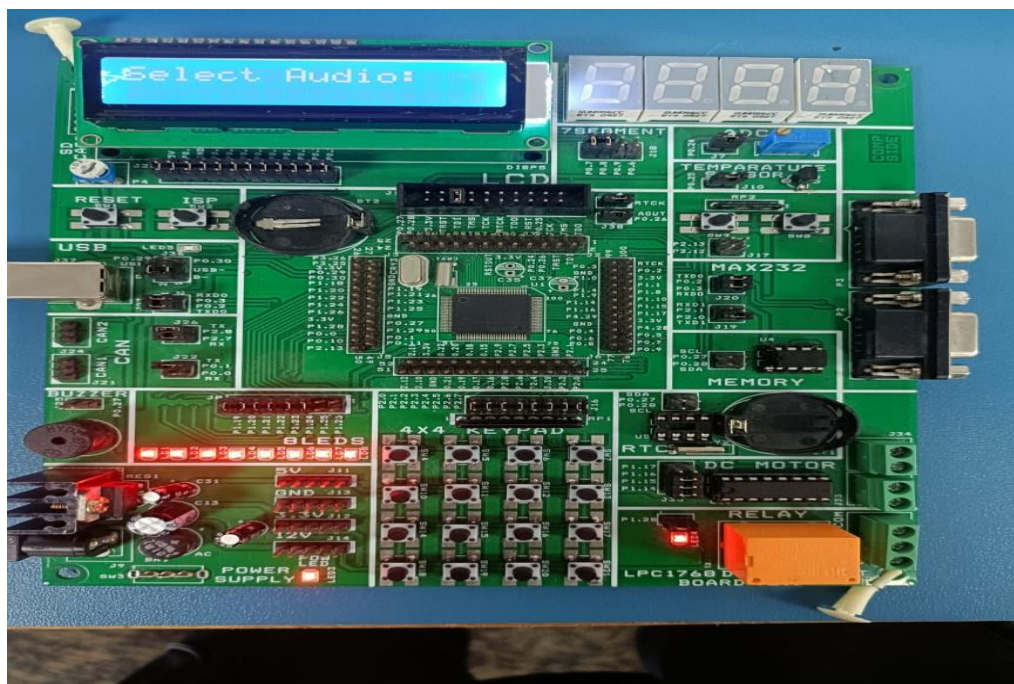
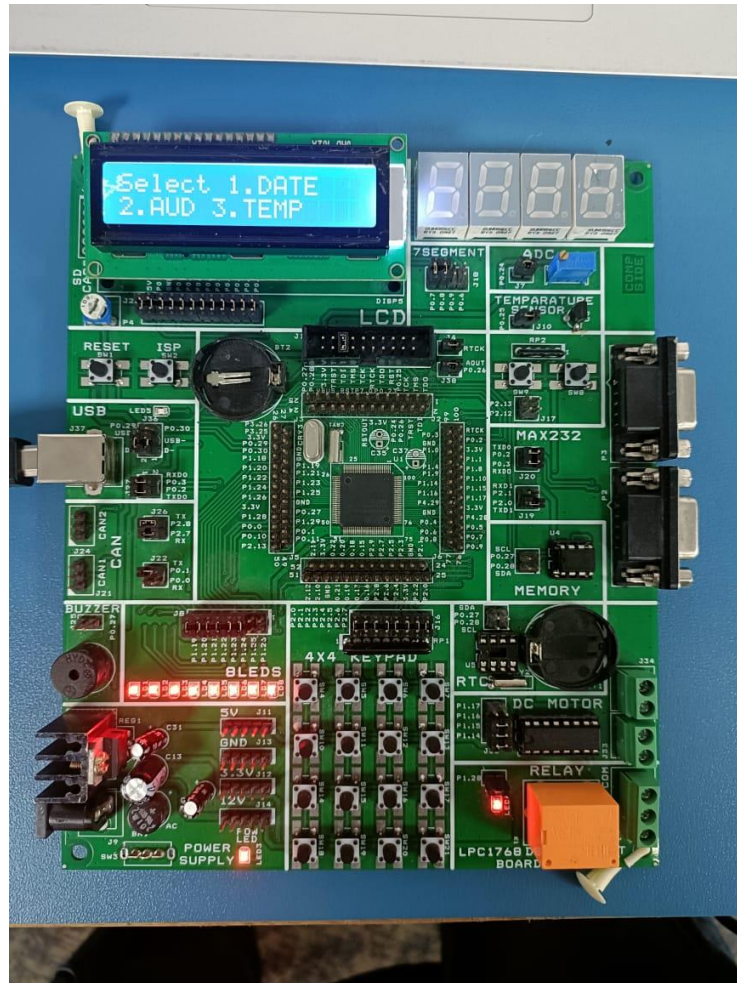
8. Results

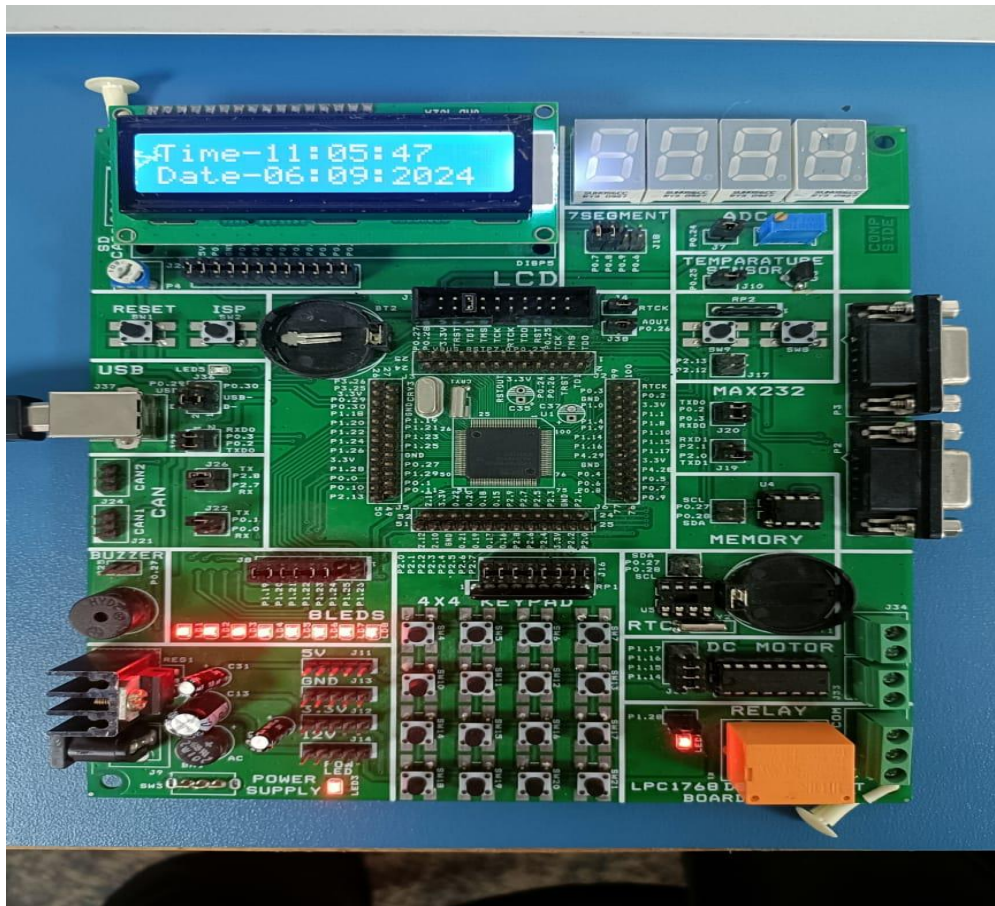
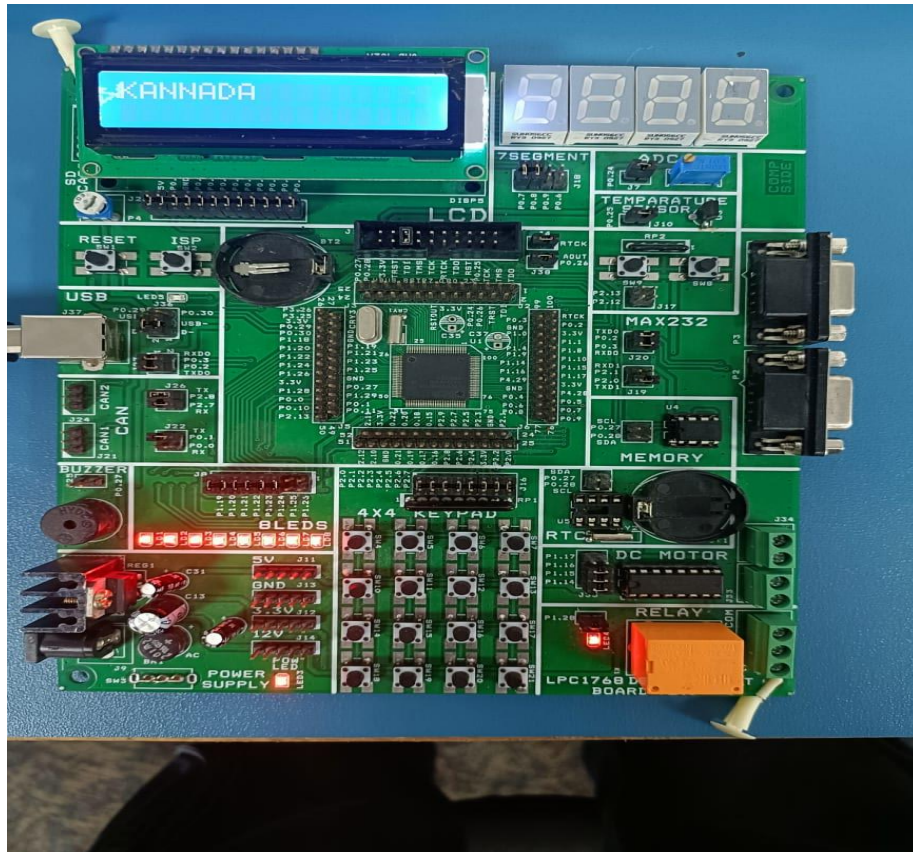
The Car Black Box system successfully met the objectives outlined in the project:

- **Password Protection:** The system accurately prompts for and verifies a user-entered password, ensuring secure access to system functions.
- **Data Display:** The LCD effectively displays real-time temperature readings, date and time, and user-selected options.
- **Accurate Timekeeping:** The RTC module provides precise date and time information, crucial for logging events.
- **Temperature Monitoring:** The temperature sensor accurately measures and displays the ambient temperature, with appropriate alerts triggered for high temperatures.
- **Data Logging:** All interactions and sensor data are successfully logged and transmitted via UART for external analysis.









9. Applications and Future Scope

9.1 Applications

The Car Black Box system, with its robust design and comprehensive data logging capabilities, is poised to serve a wide range of applications in the automotive industry and beyond. Some of the key applications include:

1. Accident Investigation:

- In the event of a collision, the Car Black Box provides crucial data that can be used to reconstruct the events leading up to the incident. This data includes environmental conditions (such as temperature), precise timestamps, and user inputs (e.g., speed, braking patterns). Investigators can analyze this information to determine the causes of the accident, identify responsible parties, and enhance safety protocols to prevent future incidents.

2. Vehicle Performance Monitoring:

- The system continuously monitors key parameters such as temperature, which can indicate the health of the vehicle's engine and other components. By logging and analyzing this data over time, vehicle owners and maintenance teams can identify patterns of wear and tear, diagnose potential issues before they become critical, and optimize maintenance schedules to prolong the vehicle's lifespan.

3. Fleet Management:

- For commercial fleet operators, the Car Black Box offers a centralized solution to monitor and manage multiple vehicles. Data collected from each vehicle can be transmitted to a central server, where it is analyzed to optimize routes, monitor driver behavior, and ensure vehicles are operating within safe and efficient parameters. This leads to cost savings, improved safety, and better compliance with regulatory standards.

4. Driver Behavior Analysis:

- The system can be used to monitor and evaluate driver behavior, particularly in commercial and professional driving contexts. By analyzing data such as speed, braking patterns, and reaction times,

fleet managers can assess driver performance, provide targeted training, and reduce the risk of accidents caused by human error.

5. Insurance Claims and Disputes:

- Insurance companies can use data from the Car Black Box to assess claims more accurately and fairly. The detailed logs of vehicle operation before and during an incident provide objective evidence that can support or refute claims, thereby reducing fraudulent claims and ensuring that policyholders receive appropriate compensation.

10. References

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3. **B. Kumar, R. Kumar, and N. Gupta** - "Car Black Box with Collision Avoidance and Collision Detection System," *International Journal of Innovative Technology and Exploring Engineering (IJITEE)*, vol. 9, no. 5, pp. 1585-1589, 2020.
4. **T. A. Mikulski and M. A. Krawczuk** - "Development of an Event Data Recorder (EDR) System for Automotive Applications," *Journal of Transportation Safety & Security*, vol. 10, no. 4, pp. 374-391, 2018.
5. **K. Smith, M. Watkins, and A. Brown** - "Automobile Event Data Recorders: Understanding Data Collection and Applications in Accident Analysis," *Accident Analysis & Prevention*, vol. 65, pp. 1-8, 2014.

11. Appendix

A. Source Code:

```

#include <lpc17xx.h>
#include <stdint.h>
#include <string.h> // For strcmp

#define ROW_PINS (0x0F << 4) // Rows connected to P2.4 to P2.7
#define COL_PINS (0x0F << 0) // Columns connected to P2.0 to P2.3
#define LCD_DATA_PINS (0xFF << 15) // LCD Data pins connected to P0.15
to P0.22
#define LCD_RS_PIN(X) (1 << X) // RS pin for LCD connected to P0.X
#define LCD_EN_PIN(X) (1 << X) // Enable pin for LCD connected to P0.X

#define VREF 3.3 //Reference Voltage at VREFP pin, given VREFN =
0V(GND)
#define ADC_CLK_EN (1<<12)
#define SEL_AD0_2 (1<<2) //Select Channel AD0.1
#define CLKDIV (3 << 8) //ADC clock-divider
(ADC_CLOCK=PCLK/CLKDIV+1) = 1Mhz @ 4Mhz PCLK
#define PWRUP (1<<21) //setting it to 0 will power it down
#define START_CNV (1<<24) //001 for starting the conversion immediately
#define ADC_DONE (1U<<31) //define it as unsigned value or compiler will
throw #61-D warning int m
#define LCD_DATA_PINS (0xff<<15)
#define T_COEFF 100.0f

#define LCD_DATA_PINS (0xFF << 15)
#define LCD_RS_PIN(X) (1 << X)
#define LCD_EN_PIN(X) (1 << X)

```



```
const char CORRECT_PASSWORD[] = "123"; // Define the correct password
```

```
void lcd_config(void);
```

```
void lcd_init(void);
```

```
void lcd_cmd_write(char cmd);
```

```
void lcd_data_write(char dat);
```

```
void lcd_str_write(char *str);
```

```
void delay(uint32_t ms);
```

```
void lcd_num(unsigned int num);
```

```
void handle_key_action(char key);
```

```
void handle_audio_selection(void);
```

```
float temperature();
```

```
int date_time();
```

```
int main() {
```

```
    uint8_t i, j;
```

```
    uint8_t val;
```

```
    uint8_t scan[4] = {0x0E, 0x0D, 0x0B, 0x07}; // Row  
activation pattern
```

```
    char key[4][4] = {
```

```
        {'P', '1', '2', '3'},
```

```
        {'V', '5', '6', '7'},
```

```
        {'T', '9', 'A', 'B'},
```

```
        {'C', 'D', 'E', 'F'}
```

```
    };
```

```

// Initialize GPIO and LCD
LPC_GPIO2->FIODIR |= ROW_PINS; // Set row pins as
output
LPC_GPIO2->FIODIR &= ~COL_PINS; // Set column pins
as input
LPC_GPIO0->FIODIR |= LCD_DATA_PINS |
LCD_RS_PIN(10) | LCD_EN_PIN(11); // Set LCD pins as output

lcd_init();
lcd_cmd_write(0x0C); // Display on, cursor off command
lcd_str_write("PLEASE LOGIN: ");

LPC_GPIO2->FIODIR |= ROW_PINS; // Set row pins as
output
LPC_GPIO2->FIODIR &= ~COL_PINS; // Set column pins
as input

while (1) {
char pressed_key = '\0'; // Variable to store the pressed key
char entered_password[5] = {0}; // Array to store the entered
password

int password_index = 0;

// Keypad scanning logic
for (i = 0; i < 4; i++) {
LPC_GPIO2->FIOCLR = ROW_PINS; // Clear all
rows
LPC_GPIO2->FIOSET = scan[i] << 4; // Set one row
high

```

```

        delay(50); // Short delay to allow for stabilization

        val = LPC_GPIO2->FIOPIN & COL_PINS; // Read
columns
        for (j = 0; j < 4; j++) {
            if ((val & (1 << j)) == 0) { // Column active if
bit is low
                pressed_key = key[i][j]; // Get the
pressed key value
                break;
            }
        }

        if (pressed_key != '\0') {
            break; // Exit if a key is pressed
        }
    }

    if (pressed_key != '\0') {
        if (pressed_key == 'P') {
            lcd_cmd_write(0x01); // Clear display
            lcd_str_write("Enter Pin:");

            while (password_index < 3) {
                for (i = 0; i < 4; i++) {
                    LPC_GPIO2->FIOCLR =
ROW_PINS; // Clear all rows

```

```

LPC_GPIO2->FIOSET = scan[i]
<< 4; // Set one row high

for stabilization

COL_PINS; // Read columns

LPC_GPIO2->FIOPIN &

for (j = 0; j < 4; j++) {
    if ((val & (1 << j)) == 0) {
        char key_pressed =

key[i][j];

        if (key_pressed == '1'
|| key_pressed == '2' || key_pressed == '3') {

            entered_password[password_index++] = key_pressed; //
Store valid keys

            lcd_data_write('*');

        }
        delay(50); //
Shortened delay for debounce

    }
}

}

}

}

entered_password[3] = '\0'; // Null-terminate the
string

if (strcmp(entered_password,
CORRECT_PASSWORD) == 0) {

```

```

        lcd_cmd_write(0x01); // Clear display
        lcd_str_write("WELCOME !!!!");
        delay(50);
        lcd_cmd_write(0x01);
        lcd_cmd_write(0x80);
        lcd_str_write("Select 1.DATE");
        lcd_cmd_write(0xC0);
        lcd_str_write("2.AUD 3.TEMP");

        while (1) { // Infinite loop to handle key
presses after password is entered correctly

        pressed_key = '\0'; // Reset the
pressed key

        for (i = 0; i < 4; i++) {
            LPC_GPIO2->FIOCLR =
ROW_PINS; // Clear row lines

            LPC_GPIO2->FIOSET =
scan[i] << 4; // Activate single row at a time

            val = LPC_GPIO2->FIOPIN
& COL_PINS; // Read column lines

            for (j = 0; j < 4; j++) {
                if ((val & (1 << j)) ==
0) { // If key is pressed in the scanned row

                    pressed_key =
key[i][j]; // Get the key value from the key map

                    break;
                }
            }
        }
    }

```

```

                                if (pressed_key != '\0') {
                                    break; // If a key is
pressed, exit the loop
                                }
                            }

                                if (pressed_key != '\0') {
                                    if (pressed_key == 'T' || pressed_key == 'V' || pressed_key ==
'C') {
                                        handle_key_action(pressed_key);
                                    } else {
                                        lcd_cmd_write(0x01); // Clear display
                                        lcd_str_write("Invalid Key");
                                        delay(100); // Delay to display invalid key message
                                    }
                                }
                            }
                        } else {
                            lcd_cmd_write(0x01); // Clear display
                                lcd_cmd_write(0x80);
                                lcd_str_write("SORRY !!!");
                                lcd_cmd_write(0xC0);
                            lcd_str_write("Incorrect Pin !");
                            delay(100); // Delay to display incorrect password message
                        }
                    } else {
                        lcd_cmd_write(0x01); // Clear display

```

```

        lcd_str_write("Invalid Key");
        delay(100); // Delay to display invalid key message
    }
}
}
}

```

```

void handle_key_action(char key) {
    if (key == 'T') {
        lcd_cmd_write(0x01); // Clear display
        lcd_str_write("Select Audio:");
        delay(100); // Delay to display selection prompt
        handle_audio_selection();
    } else if (key == 'V') {
        lcd_cmd_write(0x01); // Clear display
        date_time();
        // Add RTC display code here
        delay(100); // Delay to display date and time prompt
    } else if (key == 'C') {
        lcd_cmd_write(0x01); // Clear display
        temperature();
        // Add ADC code to display temperature here
        delay(100); // Delay to display temperature prompt
    } else {
        lcd_cmd_write(0x01); // Clear display
        lcd_str_write("Invalid Key");
    }
}

```

```

        delay(100); // Delay to display invalid key message
    }
}

void handle_audio_selection(void) {
    uint8_t i, j, val;
    uint8_t scan[4] = {0x0E, 0x0D, 0x0B, 0x07}; // Row activation pattern
    char key_map[4][4] = {
        {'P', '1', '2', '3'},
        {'V', '5', '6', '7'},
        {'T', '9', 'A', 'B'},
        {'C', 'D', 'E', 'F'}
    };

    char audio_key = '\0'; // Variable to store selected key
    char *language = NULL; // Pointer to store language message

    while (1) {
        lcd_cmd_write(0x01); // Clear display
        lcd_str_write("Select Audio:"); // Display selection prompt
        delay(10); // Delay to display prompt

        for (i = 0; i < 4; i++) {
            LPC_GPIO2->FIOCLR = ROW_PINS;
            LPC_GPIO2->FIOSET = scan[i] << 4;
            val = LPC_GPIO2->FIOPIN & COL_PINS;

```



```
for (j = 0; j < 4; j++) {  
    if ((val & (1 << j)) == 0) {  
        audio_key = key_map[i][j];  
        break;  
    }  
}  
  
if (audio_key != '\0') {  
    break;  
}  
}  
  
if (audio_key != '\0') {  
    lcd_cmd_write(0x01); // Clear display  
  
    // Determine the language based on the key pressed  
    if (audio_key == '9') {  
        language = "KANNADA";  
    } else if (audio_key == 'A') {  
        language = "ENGLISH";  
    } else if (audio_key == 'B') {  
        language = "HINDI";  
    } else {  
        language = "Unknown";  
    }  
}
```

```

        lcd_str_write(language); // Display selected language
        delay(100); // Delay to display selected language message
        break; // Exit after selection
    }
}
}

```

```

int date_time() {
    char stime[20];
    char sdate[20];
    uint8_t previous_sec, current_sec;
    uint8_t i, j, val;

    LPC_SC->PCONP |= (1 << 9); // Enable power/clock to RTC

    // Select the external 32.768 kHz oscillator as the clock source for the RTC
    LPC_RTC->CCR = (1 << 4);
    LPC_RTC->CCR |= 0x01; // Enable the RTC

    // Initialize the RTC time and date
    LPC_RTC->YEAR = 2024;
    LPC_RTC->MONTH = 9;
    LPC_RTC->DOM = 6;
    LPC_RTC->HOUR = 11;
    LPC_RTC->MIN = 5;
    LPC_RTC->SEC = 45;
}

```

```

previous_sec = LPC_RTC->SEC;

lcd_config();
lcd_cmd_write(0x0C); // Turn on the display

while (1) {
    // Update the current second from the RTC
    current_sec = LPC_RTC->SEC;

    // Update the display only when the second changes
    if (current_sec != previous_sec) {
        previous_sec = current_sec;

        sprintf(stime, "Time-%02d:%02d:%02d", LPC_RTC->HOUR,
LPC_RTC->MIN, current_sec);
        lcd_cmd_write(0x80); // Return to the first line
        lcd_str_write(stime);

        sprintf(sdate, "Date-%02d:%02d:%04d", LPC_RTC->DOM, LPC_RTC-
>MONTH, LPC_RTC->YEAR);
        lcd_cmd_write(0xC0); // Move to the second line
        lcd_str_write(sdate);
    }

    // Key detection to exit
    for (i = 0; i < 4; i++) {
        LPC_GPIO2->FIOCLR = ROW_PINS; // Clear row lines
    }
}

```

```
LPC_GPIO2->FIOSET = (0x0E >> i) << 4; // Activate a single row at a  
time
```

```
val = LPC_GPIO2->FIOPIN & COL_PINS; // Read column lines
```

```
for (j = 0; j < 4; j++) {  
    if ((val & (1 << j)) == 0) { // If a key is pressed in the scanned row  
        return 1; // Exit the date_time function  
    }  
}  
}  
}  
}
```

```
float temperature()  
{
```

```
    int result = 0;
```

```
    float volts = 0;
```

```
    char svolts[20];
```

```
    float temp = 0;
```

```
    char stemp[20];
```

```
    LPC_PINCON->PINSEL1 |= (0x01 << 18); //select AD0.2  
for P0.25
```

```
    LPC_SC->PCONP |= ADC_CLK_EN; //Enable ADC clock
```

```
    LPC_ADC->ADCR = PWRUP | CLKDIV | SEL_AD0_2;
```

```

        lcd_init();

        while(1)
        {
            LPC_ADC->ADCR |= START_CNVR; //Start new
Conversion
            while((LPC_ADC->ADDR2 & ADC_DONE) == 0){}
//Wait untill conversion is finished

            result = (LPC_ADC->ADDR2>>4) & 0xFFF; //12 bit Mask
to extract result

            volts = (result*VREF)/4096.0; //Convert result to Voltage
            lcd_cmd_write(0xC0);

            temp = volts * T_COEFF;
            sprintf(stemp,"Temp=%.2f 'C",temp);
            lcd_str_write(stemp);
            delay(200); //Slowing down Updates to 2 Updates per
second

            lcd_cmd_write(0x01);
            break;
        }

        return 0;//This won't execute
    }

```

```

void lcd_config(void) {
    LPC_GPIO0->FIODIR |= LCD_DATA_PINS;
    LPC_GPIO0->FIODIR |= LCD_RS_PIN(10);
    LPC_GPIO0->FIODIR |= LCD_EN_PIN(11);
    lcd_cmd_write(0x38);
    lcd_cmd_write(0x0E);
    lcd_cmd_write(0x01);
    return;
}

```

```

void lcd_cmd_write(char cmd) {
    LPC_GPIO0->FIOCLR = LCD_DATA_PINS;    // Clear
LCD data pins

    LPC_GPIO0->FIOSET = (cmd << 15);      // Set command
on data pins

    LPC_GPIO0->FIOCLR = LCD_RS_PIN(10);    // RS = 0
for command

    LPC_GPIO0->FIOSET = LCD_EN_PIN(11);    // Enable
high

    delay(50);                            // Increased delay for stability

    LPC_GPIO0->FIOCLR = LCD_EN_PIN(11);    // Enable
low

    delay(50);                            // Delay after command
}

```

```

void lcd_data_write(char dat) {
    LPC_GPIO0->FIOCLR = LCD_DATA_PINS;    // Clear
LCD data pins

```

```

        LPC_GPIO0->FIOSET = (dat << 15);    // Set data on data
pins
        LPC_GPIO0->FIOSET = LCD_RS_PIN(10);  // RS = 1
for data
        LPC_GPIO0->FIOSET = LCD_EN_PIN(11);  // Enable
high
        delay(50);                          // Increased delay for stability
        LPC_GPIO0->FIOCLR = LCD_EN_PIN(11);  // Enable
low
        delay(50);                          // Delay after data
}

```

```

void lcd_str_write(char *str) {
    while (*str) {
        lcd_data_write(*str++);
    }
}

```

```

void lcd_init(void) {
    delay(50); // Ensure power-on delay is long enough
    lcd_cmd_write(0x38); // 8-bit mode, 2-line display, 5x8 font
    lcd_cmd_write(0x0C); // Display ON, Cursor OFF
    lcd_cmd_write(0x01); // Clear display
    delay(50); // Give extra time for initialization
}

```

```

void lcd_num(unsigned int num) { // Recursive function
    if (num) { // 1234

```

```
    lcd_num(num / 10);  
    lcd_data_write(num % 10 + 0x30);  
}  
}
```

```
void delay(uint32_t ms) {  
    uint32_t i, j, k;  
    for (i = 0; i < ms; i++) {  
        for (j = 0; j < 3000; j++) {  
            k++; // _asm volatile ("nop"); // No operation for time-  
wasting  
        }  
    }  
}
```