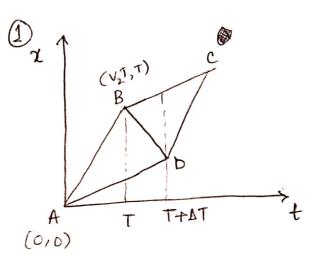
1.1.



Equating displacements to b through AD and A + B + D.

$$V_{0}(T+\Delta T) = V_{2}T - V_{1} \Delta T$$

$$\Delta T = \frac{V_{2}-V_{0}}{V_{0}+V_{1}} T$$

For parallelogram ABCD, AD = BC # So, BC = AD = Vo(T+DT)

Traversing to c through A + B + C,

AB @ v2 for time T + BC @ vo for time (T+AT)

: average speed = 
$$\overline{V} = \frac{V_2T + V_0(T + \Delta T)}{2T + \Delta T}$$

$$= \frac{V_2 + V_0 \left(1 + \frac{V_2 - V_0}{V_0 + V_1}\right)}{7 \left(2 + \frac{V_2 - V_0}{V_0 + V_1}\right)}$$

$$= \frac{2V_2V_0 + V_1V_2 + V_0V_1}{V_0 + 2V_1 + V_2}$$
 [independent of t]

2 
$$\overline{V} = \frac{2.6.3 + 9.6 + 3.9}{3 + 2.9 + 6} = \frac{117}{27} = \frac{13}{3} \text{ mph} = 4.33. \text{mph}$$

3) With more switching, more V-turn penalty is caused. In general otherwise, the average speed will no depend on the value of T. So, the strategy should be to increase T to reduce the V-turn penalty.

1.4. 
$$a = 1 - v - \frac{v}{4}$$
 $\ddot{x} = 1 - \dot{x} - \frac{v}{4}$ 
 $\ddot{x} = 1 - \dot{x} - \frac{v}{4}$ 
 $4\ddot{x} + 4\dot{x} + (x - 4) = 0$ 
 $x - 4 = y(say)$ 
 $\Rightarrow 4xy' + 4xy' + y = 0$ 
 $y = e^{xt}(say)$ 
 $\Rightarrow x = -\frac{1}{2}, -\frac{1}{2} \text{ (repeated roots)}$ 
 $\therefore y = (c_1 t + c_2)e^{-t/2} \text{ (general ferm)}$ 
 $\Rightarrow x = 4 + (c_1 t + c_2)e^{-t/2} \text{ (substituting } x)$ 
 $\Rightarrow x = 4 + (c_1 t - 4)e^{-t/2}$ 
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## 1.7. Eco-Driving

For the assignment, I used Carbon Monoxide (CO) as the parameter to decide on the best strategy. The python script to estimate the emission is attached.

As a continuation of example 1.2.6 of the textbook, we plot Emission vs Distance for different scenarios of  $\beta$  as shown in figure below.

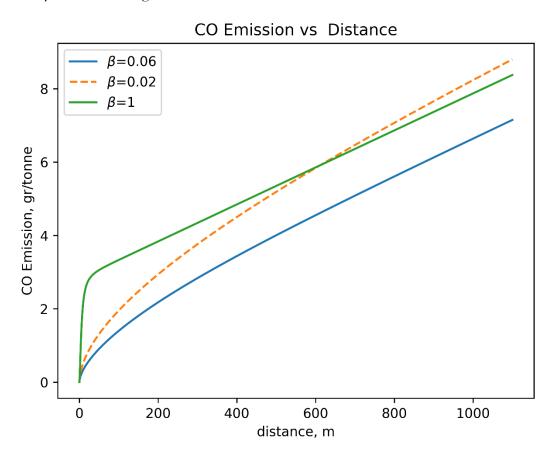
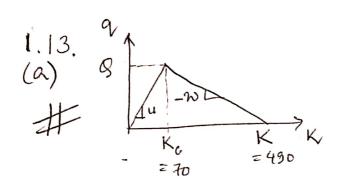
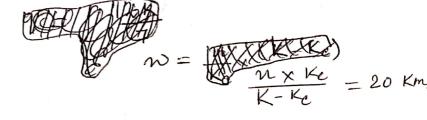


Figure 1: CO-Emission vs Distance based on approximate MOVES formula

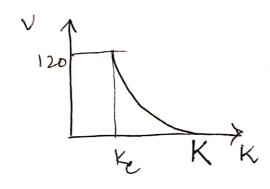
Based on this, being an average driver (i.e. having  $\beta$ =0.06) is consistently the best strategy for minimize CO emissions. Going by the results for the others, within the limit of about 650m, being timid ( $\beta$ =0.02) is the second best strategy. However, beyond that, being an aggressive driver at  $\beta$ =1 is the second best strategy.



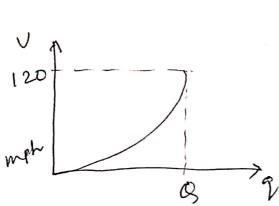


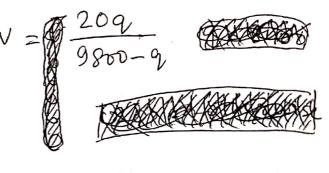
$$Q = \begin{cases} 120k & K \le Ke \\ Q - 20(K - Ke) & K > Ke \end{cases}$$

$$= \begin{cases} 120K & K \le 70 \\ 9800 - 20K & K > 770 \end{cases}$$



$$# V = \frac{9800}{21/\sqrt{-20}} = \frac{3}{2}$$



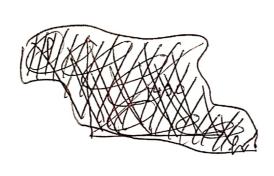


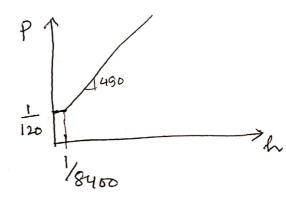
$$h = \frac{1}{2}; \quad p = \frac{1}{2}$$

$$\frac{1}{p} = \frac{20/L}{9800 - 1/L} = \frac{20}{9800L - 1}$$

$$P = \begin{cases} 490h - 0.05 & h > \frac{1}{8400} \end{cases}$$

$$\frac{1}{120} \quad \text{otherwise}$$

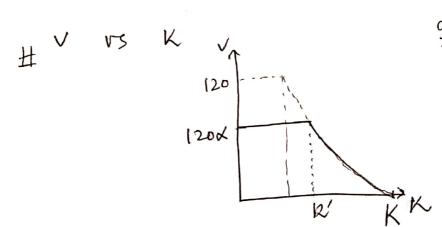




$$V = \int 120 \quad S = 7 + 70$$

$$9800 S - 20 \quad S = 4 + 70$$

1.13.



$$\frac{9800}{k'} - 20 = 120 \times$$

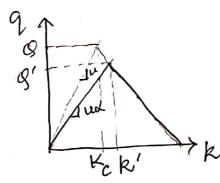
$$k' = \frac{9800}{120 \times + 20}$$

$$V = \begin{cases} 1200 & k \le \frac{9800}{1200 + 20} \\ \frac{9800}{k} - 20 & k > \frac{9800}{1200 + 20} \end{cases}$$

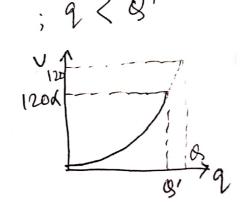
# 9 VS K  

$$9 = VK = \begin{cases} 120 \text{ K} & \text{k} \leq \frac{9800}{120 \text{ K} + 20} = \frac{3800}{120 \text{ K} + 20} = \frac{$$

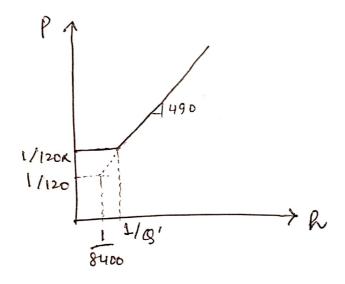
$$k \leq \frac{9800}{1200+20}$$
 $k > \frac{9800}{1200+20}$ 



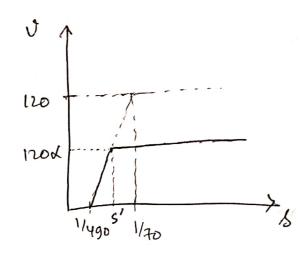
$$8' = \frac{9800 \times 120 \times 12$$



$$P = \begin{cases} 490h - 0.05 & h > \frac{1}{8} \\ \frac{1}{120d} & \text{otherwise} \end{cases}$$



# & U vs 8



$$\frac{1200}{\left(s' - \frac{1}{490}\right)} = 9800$$

$$\Rightarrow s' = \frac{30}{245} + \frac{1}{490} = \frac{600}{490}$$

$$V = \int_{9800S - 20}^{1200} 1200$$
  $S < S'$ 

(e) 
$$V = \frac{209}{9800 - 9} \Rightarrow 9 = \frac{9800 \times 1}{100}$$

Based on a sample of 10 million data points mean = 7297 veh/hr, Sol = 371 veh/hr.