

4.1.  
(a)  $K_0(x) = K_c(1+x)$

$$K_0(x'_B) = K_c$$

$$\Rightarrow K_c(1+x'_B) = K_c$$

$$x'_B = 0$$

$$u = 100 \text{ km/hr}$$

$$w = 20 \text{ km/hr}$$

$$K_c = 25 \text{ veh/hr}$$

$$Q_{\max} = 2500 \text{ veh/km}$$

$$x = x - 100t$$

$$x_D = x + 20t$$

$$G(x) = \int_x^5 K_0(x) dx = 25 \left[ \left( x + \frac{x^2}{2} \right) + 5 + \frac{5^2}{2} \right]$$

$$= 437.5 - 25x - 12.5x^2$$

$$f(x_u) = G(x_u) = -12500t^2 + 2500tx + 2500t$$

$$-12.5x^2 - 25x + 437.5$$

$$f(x_D) = G(x_D) + K(x_D - x)$$

$$= -5000t^2 - 500tx + 2500t - 12.5x^2 - 25x + 437.5$$

$$f(x'_B) = G(x'_B) + (t-0)Q - (x-0)K_c$$

$$= 2500t - 25x + 437.5 \quad (\text{X}) \text{ not used}$$

However  $\frac{dK_0}{dx} = K_c > 0$ .

So,  $x'_B = 0$  is not an option.

$$N(t, x) = \min \{ f(x_u), f(x_D) \}$$

eq<sup>n</sup> of shock trajectory:

$$f(x_u) = f(x_D)$$

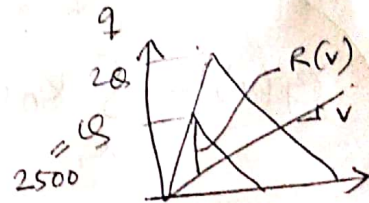
$$\Rightarrow -12500t^2 + 2500tx = -5000t^2 - 500tx$$

$$\Rightarrow 3000tx = 12000t^2$$

$$\boxed{x = 40t}$$



(b)



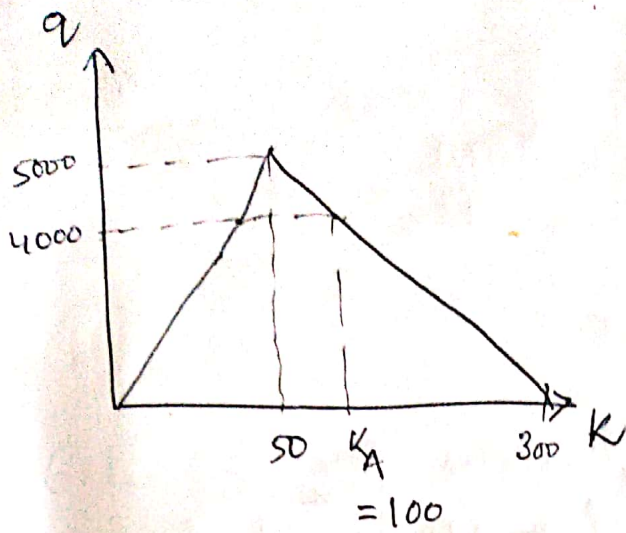
$$c(t_c, x_c)$$

$$x_c = \frac{5}{108} (-\sqrt{1+14.4x+288t} + 432t + 21.6x + 1)$$

$$= \text{cost } P-C + \text{cost } C-O$$

$$= 300 \left( \frac{5}{108} \right) \left( -\sqrt{1 + 14.4x + 288t} + 432t + 1 \right)$$

$$= \frac{-25}{18} \left( \sqrt{5} \sqrt{1440t + 72x + 5} - 3960t + 18x - 5 \right) + \int_0^{t_c} Q \left( 1 - \frac{V_0 + at}{u} \right) dt$$



$$f(x_u) = K_A |x_u|$$

$$= 400 (100t - x) = 100 (100t - x)$$

$$N(t, x) = \min \{ \cos t \, p \rightarrow c \rightarrow 0, f(x_u) \}$$

$$N(t, x) = \min \left\{ \frac{-25}{18} (\sqrt{5} \sqrt{1440t + 72x + 5} - 3960t + 18x - 5), 100(100t - x) \right\}$$

Trajectory of shock is given by :

$$\cos t \, p \rightarrow c \rightarrow 0 = f_u$$

$$\begin{aligned} \frac{-25}{18} (\sqrt{5} \sqrt{1440t + 72x + 5} - 3960t + 18x - 5) \\ = 100 (100t - x) \end{aligned}$$

~~$$2916x^2 - 349920xt + 180x + 10497600t^2 - 39600t = 0$$~~

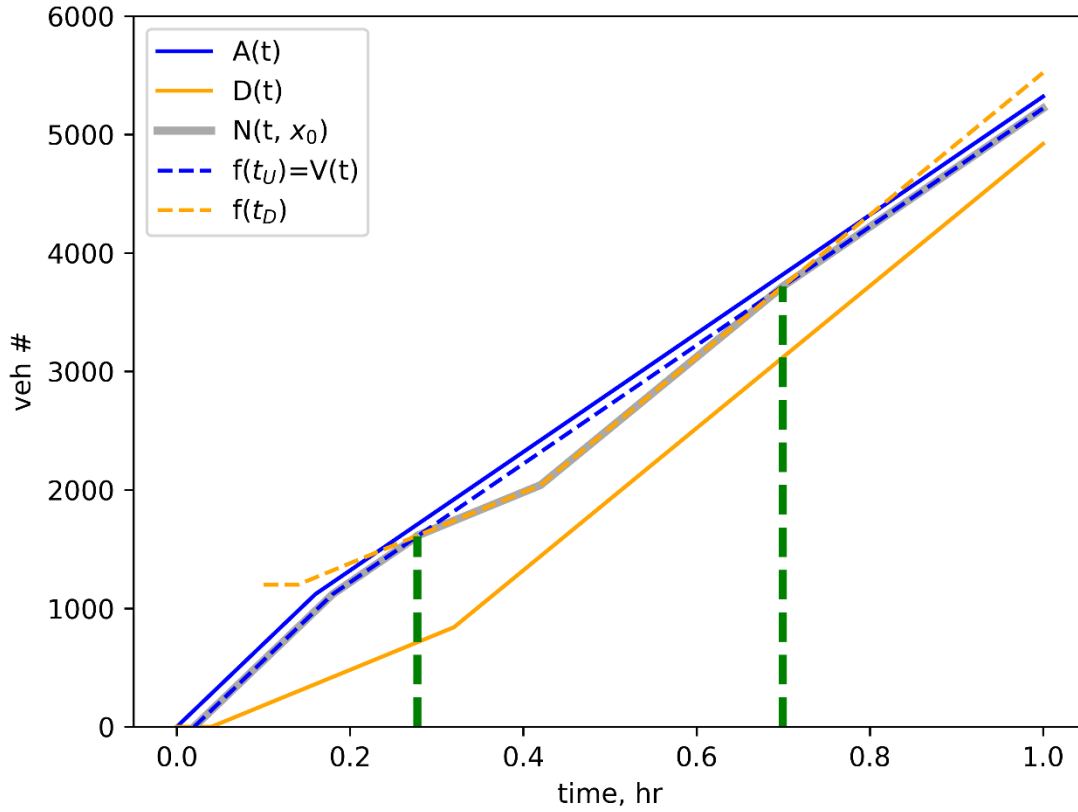
$$2916x^2 - 349920xt + 180x + 10497600t^2 - 39600t = 0$$

parabola trajectory for shock

**4.2.** The N-Curve plots are made using python with the script *Plot\_4.2.py* attached to the submission.

For 4-lanes, the jam density  $K=150*4=600$  veh/km. The “virtual arrival” curve is made by shifting  $A(t)$  by  $(x_0-x_A)/u=(2-0)/100=0.02$  in time-axis.

The “virtual departure” is created by shifting  $D(t)$  by  $(x_D-x_0)/\omega=(4-2)/20=0.1$  along time axis and by  $K(x_D-x_0)=600(4-2)=1200$  along the N-axis.



(a) The shaded area represents N-curve at  $x=2$  km.

(b) The green lines denote two intersections at  $t=0.2776$  hr and  $t=0.6995$  hr. in the first instance the queue starts growing and then in the second instance, the queue starts receding.



6.1.  $\lambda = 500$

$$u = 40 \text{ Km/hr} = \frac{2}{3} \text{ Km/min}$$

$$\tau^* = \frac{l}{u} = 20 \text{ mins} \Rightarrow l = \frac{40}{3} \text{ Km}$$

$$L \times (\text{Jam density}) = n_{\text{jam}}$$

$$\Rightarrow L = \frac{10000}{150} \text{ Km}$$

For (a) and (b),

$$\mu = \frac{100 \times L}{l} = \frac{100 \times 10000 \times 3}{150 \times 40} = 500$$

$$\rho = \frac{\lambda}{\mu} = 1$$

So, we use the graphs for  $\rho = 0.99$ .

(a) Based on graph, the system does not reach equilibrium by  $t = 8\tau^*$  based on the extent of the plot.

It reaches equilibrium at  $n = 0.45 n_{\text{jam}} = 4500$ .

(b) Travel time at  $t = 80 \text{ mins} = 4\tau^*$   
 $= 1.5\tau^* = 30 \text{ mins.}$

(c) After incident removal,

~~Handwritten scribbles~~  $\mu = \frac{200L}{2} = 1000$

$$p = \frac{500}{1000} = 0.5$$

We do not have a curve for  $n(0) = 0.45 n_{jam}$ , but it showed closely follow  $n(0) = 0.5 n_{jam}$ .

It should reach equilibrium  
around  $t = 6\tau^A = 120 \text{ ms}$

and around  $K_1^* = \cancel{0.15} 0.15 \text{ njam}$   
 $\approx 1500$

(d) At  $t = 40 \text{ mins} = 2T$ ,

we have travel time approximately ~~the~~

$$1.2 \tau^* = 24 \text{ mins.}$$