```
Kasitphoom Thowongs
 """Increasing Subsequence"""
 memorization = {}
                                                                                                        """Two Item finding"""
                                                                                                        """Function of finding sum of two numbers"""
 """Increasing recursive function to find increasing sequences"""
 def increasina(k):
                                                                                                       def opt():
                                                                                                            target = int(input())
     if k in memorization:
                                                                                                           arr = list(map(int, input().split()))
        return memorization[k]
                                                                                                            arr = sorted(arr)
     if k == 0:
                                             """Double, Triple, and Increment"""
                                                                                                            low = 0
        return 1
                                             memo = \{\}
                                                                                                           high = len(arr) - 1
                                             def increment(x):
     max_length = 0
                                                 if x in memo:
     for i in range(k):
                                                                                                            while low \neq high:
                                                    return memo[x]
         if sample[i] \le sample[k]:
                                                                                                                calc = arr[low] + arr[high]
                                                 if x == 1:
            val = increasing(i)
                                                                                                                if calc == target:
            if max_length < val:
                                                    memo[1] = 0
                                                                                                                    return "Yes"
                max_length = val
                                                    return memo[1]
     memorization[k] = 1 + max_length
                                                                                                                elif calc < target:</pre>
     return memorization[k]
                                                 if x % 3 == 0:
                                                                                                                    low += 1
                                                    memo[x] = min(increment(x / 3), increment(x - 1)) + 1
                                                                                                                else:
 def lis():
                                                    return memo[x]
                                                                                                                    high -= 1
     max_length = 0
                                                 if x % 2 == 0:
     for i in range(len(sample)):
                                                    memo[x] = min(increment(x / 2), increment(x - 1)) + 1
                                                                                                            return "No"
        val = increasing(i)
                                                    return memo[x]
        if val > max_length:
                                                 if x - 1 > 0:
           max length = val
                                                                                                       print(opt())
                                                    memo[x] = increment(x - 1) + 1
     return max_length
                                                     return memo[x]
                                                                                                         def merge_sort(arr):
 sample = list(map(int, input().split()))
                                             print(increment(int(input())))
                                                                                                             if len(arr) > 1:
 print(lis())
                                                                                                                  mid = len(arr) // 2
 """Finding subset sum problem"""
                                                                                                                  L = arr[:mid]
 mem = \{\}
                                                                                                                  R = arr[mid:]
 """Finding that is there a target in the set"""
 def check(index, target):
                                                                                                                  merge_sort(L)
     if (index, target) in mem:
                                                                                                                  merge_sort(R)
         return mem[(index, target)]
                                                                                                                  i = j = k = 0
     if index == 0:
        mem[(index, target)] = (target == 0)
                                                                                                                  while i < len(L) and j < len(R):
         return (target == 0)
                                                                                                                      if L[i] < R[j]:
     if target < inputSet[index - 1]:</pre>
                                                                                                                          arr[k] = L[i]
         mem[(index, target)] = check(index - 1, target)
                                                                                                                          i += 1
         return mem[(index, target)]
                                                                                                                          arr[k] = R[j]
         mem[(index, target)] = check(index - 1, target) or check(index - 1, target - inputSet[index - 1])
                                                                                                                          j += 1
         return mem[(index, target)]
                                                                                                                      k += 1
 inputSet = list(map(int, input().split()))
 target = int(input())
                                                                                                                  while i < len(L):
 print(check(len(inputSet), target))
                                                                                                                      arr[k] = L[i]
 def quick_sort(arr):
                                                                                                                      i += 1
      if len(arr) \leq 1:
                                                                                                                      k += 1
           return arr
                                                                                                                  while j < len(R):
      else:
                                                                                                                      arr[k] = R[j]
           pivot = arr[0]
                                                                                                                      j += 1
           less = [x for x in arr[1:] if x \le pivot]
                                                                                                                      k += 1
           greater = [x for x in arr[1:] if x > pivot]
           return quick_sort(less) + [pivot] + quick_sort(greater)
                                                                                                             return arr
                                   list_numbers = list(map(int, input().split()))
def largest_x(y):
    left = 0
                                    def picking_number(list_num):
    right = y
                                        if len(list_num) == 0:
                                            return True
    while left ≤ right:
                                        else:
        mid = (left + right) // 2
                                            return picking_numbers(list_num[1:], list_num[0]) or picking_numbers(list_num[:-1], list_num[-1])
        if mid * mid + mid \leq y:
            left = mid + 1
                                    def picking_numbers(list_num, picked_num):
                                        if len(list_num) == 0:
           right = mid - 1
                                            return True
                                        else:
    return right
                                            f h = False
                                            s_h = False
                                             if abs(list_num[0] - picked_num) \leq 9:
                                                 f_h = picking_numbers(list_num[1:], list_num[0])
                                             if abs(list_num[-1] - picked_num) \leq 9:
```

s\_h = picking\_numbers(list\_num[:-1], list\_num[-1])

return f\_h or s\_h

```
def binary_search_approximation(arr, l, r, x):
    if r \ge 1:
        mid = l + (r - l) // 2
        if arr[mid] == x:
            return mid
        elif arr[mid] > x:
            return binary_search_approximation(arr, l, mid - 1, x)
            return binary_search_approximation(arr, mid + 1, r, x)
    el se:
        return r
def cutting(length, cuts):
    memo = \{\}
    def opt(l, r):
        if r - l == 1:
            return 0
        if (l, r) in memo:
            return memo[(l, r)]
        res = float("inf")
        for c in cuts:
            if l < c < r:
                res = min(res, r - l + opt(l, c) + opt(c, r))
        if res == float("inf"):
            res = 0
        memo[(l, r)] = res
        return res
    return opt(0, length)
```

## Closest Pair of Points (Improved)

#### CLOSEST-PAIR(Px: list of points sorted in x, Py: list of points sorted in y)

RFTURN δ.

```
Find vertical line L such that half the points are on each side of the line.
                                                                                                         \Theta(1)
PxLeft= Px with all the points to the right of L removed
                                                                                                         \Theta(n)
PxRight = Px with all the points to the left of L removed
                                                                                                         \Theta(n)
PyLeft = Py with all the points to the right of L removed
                                                                                                         \Theta(n)
PyRight = Py with all the points to the left of L removed
                                                                                                         \Theta(n)
\delta 1 \leftarrow CLOSEST-PAIR(PxLeft, PyLeft).
                                                                                                         C'(n/2)
\delta 2 \leftarrow CLOSEST-PAIR(PxRight, PyRight).
                                                                                                         C'(n/2)
\delta \leftarrow \min \{ \delta 1, \delta 2 \}.
                                                                                                         \Theta(1)
Delete all points further than \delta from line L.
                                                                                                         \Theta(n)
Sort remaining points by y-coordinate.
Scan points in y-order and compare distance between each point and next 7 neighbors. If any of these distances is less than \delta, update \delta.
                                                                                                         \Theta(n)
                                                                                                         \Theta(1)
```

```
jobs.sort(key=lambda x: x[1])
        latest_non_conflicting = -1
            if jobs[j][1] <= jobs[i][0]:
                latest_non_conflicting = j
        dp[i] = \max(dp[i-1], \ jobs[i][2] + (dp[latest\_non\_conflicting] \ if \ latest\_non\_conflicting \ l= -1 \ else \ \emptyset))
jobs = [list(map(int, input().split())) for _ in range(n)]
orint(max_earning(n, jobs))
```

#### **Cutting Stick**

```
opt_profit[1...N] = Array of length n
opt_cuts[1...N] = Array of length n
opt_profit[1] = P[1]
opt_cuts[1] = []
for n = 2 to N:
 max_profit = P[n]
  max cuts = []
  for k from 1 to n-1
    if max\_profit < P[k]+opt\_profit[n-k]-C
        max\_profit = P[k]+opt\_profit[n-k]-C
        \max \text{ cuts} = \lceil k \rceil + \text{ opt } \text{ cuts} \lceil n - k \rceil
  opt profit[n] = max profit
  opt_cuts[n] = max_cuts
print(opt_profit[N], opt_cuts[N])
```

#### Max 1D Range Sum - Kadane's Algorithm

• There is an O(n) algorithm to solve the Max 1D Range Sum problem. The algorithm described below is attributed to Jay Kadane.

```
// Kadane's Algorithm
max\_sum = 0
  sum += x[i]
  max_sum = max(max_sum, sum)
if(sum < 0) sum = 0
return max_sum
```

• Try running the above algorithm on the array x =

```
4, -5, 4, -3, 4, 4, -4, 4, -5
```

### Max 2D Range Sum

 Given an n x n table of integers, find a pair (a, b, c, d) of locations in the table which maximizes the partial sum, i.e.

```
sum(a, b, c, d) \ge sum(x, y, x', y')
for all indices w, x, y, z where x \le x' and y \le y'
```

· A straightforward implementation:

```
a = b = c = d = 1

max = x[a,b]
for i1 = 1 ... n

for j1 = 1 ... n

for i2 = i1 ... n

for j2 = j1 ... n

if(sum(i1,j1,i2,j2) > max)

max = sum(i1,j1,i2,j2)

a = i1; b = j1

c = i2; d = j2
  return (a,b,c,d)
```

# Celebrity Problem

• Attempt 4: An improved version of Attempt 2.

```
function celeb da(S)
   if |S| == 1 then return the (only) person in S
        Pick two people P1 and P2 from S.
       if P1 knows P2 then P'=P1 else P'=P2
       S' = S - \{P'\}
       C' = celeb_dq(S')
        if C' ≠ None then
            if P' knows C' and C' does not know P
            then return C' else return None
        else
            return None
```

```
"""Program to find least Articulation points in a graph"""
                                                                                def main():
                                                                                                                                                                                 def
                                                                                     """Main function."""
def art_points(graph, length):
                                                                                     graph_length = int(input())
                                                                                                                                                         print(*graph, sep='\n')
                                                                                                                                                                                 floyd.
        "Articulation points in a graph."""
                                                                                                                                                                             for
                                                                                     graph = [
    visited = [0 for _ in range(length)]
parent = [-1 for _ in range(length)]
                                                                                          [0 for _ in range(graph_length)]
                                                                                                                                                                         for
                                                                                          for _ in range(graph_length)
                                                                                                                                                                             ᆽ
    low = [0 for _ in range(length)]
disc = [0 for _ in range(length)]
                                                                                                                                                                             in
                                                                                                                                                                                _warshall():
                                                                                                                                                                         μ.
    articulation_points = [0 for _ in range(length)]
                                                                                     while True:
    edge = list(map(int, input().split()))
                                                                                                                                                                            range(graph_length):
                                                                                                                                                                         i
    time = 0
                                                                                                                                                                j in range(graph_length):
graph[i][j] = min(graph[i][j], graph[i][k] + graph[k][j])
                                                                                          if edge == [0, 0]:
                                                                                                                                                                         range(graph_length):
    def dfs(node):
                                                                                             break
         """Depth First Search."""
                                                                                          graph[edge[0] - 1][edge[1] - 1] = 1
graph[edge[1] - 1][edge[0] - 1] = 1
         nonlocal time
         children = 0
         visited[node] = 1
                                                                                 print(*art_points(graph, graph_length))
"""BFS Shortest Path Algorithm non weighted graph"""
         low[node] = disc[node] = time
                                                                                 def bfs_shortest():
                                                                                      """Graph Transversal function"""
         for i in range(length):
              if graph[node][i]:
                                                                                      queue = [starting_node - 1]
                   if not visited[i]:
                                                                                      visited = [0 for _ in range(graph_length)]
back = [None for _ in range(graph_length)]
                       children += 1
                       parent[<u>i</u>] = node
                                                                                      found = False
                       dfs(i)
                        low[node] = min(low[node], low[i])
                                                                                      visited[starting_node - 1] = 1
                       if parent[node] == -1 and children > 1:
                                                                                      while queue and not found:
                            articulation points[node] = 1
                                                                                          node = queue.pop(0)
                       if parent[node] ≠ -1 and low[i] ≥ disc[node]:
                                                                                           for i in range(graph_length):
                            articulation_points[node] = 1
                                                                                                if graph[node][i] and i == destination_node - 1
                   elif i \neq parent[node]:
                                                                                                    back[i] = node
                       low[node] = min(low[node], disc[i])
                                                                                                    found = True
     for i in range(length):
                                                                                                    break
                                                                                                if graph[node][i] and not visited[i]:
         if not visited[i]:
             dfs(i)
                                                                                                    queue.append(i)
                                                                                                    visited[i] = \overline{1}
    return [i + 1 for i in range(length) if articulation_points[i]]
                                                                                                    back[i] = node
"""Bipartite graph algorithms."""
def bipartite():
                                                                                          path = [destination_node]
     ""Bipartite graph algorithm."""
                                                                                           while path[-1] ≠ starting_node:
    graph_length = int(input())
                                                                                               path.append(back[path[-1] - 1] + 1)
    graph = [
         [0 for _ in range(graph_length)]
                                                                                          print(*path[::-1])
         for _ in range(graph_length)
                                                                                         print("No path")
                                                                                  """min weight"
         edge = list(map(int, input().split()))
                                                                                      graph_length = int(input())
graph = [[float('inf') for i in range(graph_length)] for j in range(graph_length)]
distance = [float('inf') for i in range(graph_length)]
visited = [0 for i in range(graph_length)]
         if edge == [0, 0]:
             break
         graph[edge[0] - 1][edge[1] - 1] = 1
                                                                                      start = int(input()) - 1
distance[start] = 0
    visited = [0 for _ in range(graph_length)]
    color = [0 for _ in range(graph_length)]
is_bipartite = True
                                                                                      queue = [start]
                                                                                      visited[start] = 1
     while gueue and is_bipartite:
                                                                                       while queue:
         node = queue.pop(0)
                                                                                           node = queue.pop(0)
         for i in range(graph_length):
                                                                                           visited[node] = 1
              if graph[node][i] and not visited[i]:
                                                                                           for i in range(graph_length):
                  queue.append(i)
                                                                                               if graph[node][i]:
                   visited[i] = 1
                                                                                                   distance[i] = min(distance[i], distance[node] + graph[node][i])
                                                                                                    if not visited[i]
                   color[i] = not color[node]
              elif graph[node][i] and color[i] == color[node]:
                                                                                                        queue.append(i)
                                                                                                        visited[i] = 1
                  is_bipartite = False
                  break
                                                                                      print(*distance)
     if is_bipartite:
                                                                                  def bellmanFord():
         \# list every \theta in the color list
                                                                                       graph_length = int(input())
         print(*[i + 1 for i in range(graph_length) if not color[i]])
                                                                                       edges = []
         # list every 1 in the color list
         print(*[i + 1 for i in range(graph_length) if color[i]])
                                                                                       while True:
                                                                                           edge = list(map(int, input().split()))
        print("Not possible")
                                                                                            if edge[0] == 0 and edge[1] ==
                                                                                                break
 def findSCC(G):
                                                                                            edges.append([edge[0] - 1, edge[1] - 1, edge[2]])
  global state, counter, low, num, stack
state = [UNDISCOVERED for i in range(G.numNodes)]
                                                                                       table = [[float("inf") for i in range(graph_length)] for j in range(graph_length)]
  low = [0 for i in range(G.numNodes)]
num = [0 for i in range(G.numNodes)]
                                                                                       table[0][0] = 0
                                                                                       for n in range(1, graph_length):
    for t in range(graph_length):
   counter = 1
  stack = []
                                                                                               table[n][t] = table[n - 1][t]
   for s in range(G.numNodes):
                                                                                           for edge in edges:
     if state[s]==UNDISCOVERED:
                                                                                                v, t, w = edge
if table[n - 1][v] + w < table[n][t]:</pre>
        state[s] = DISCOVERED
        dfsTarjan(G,s)
                                                                                                    table[n][t] = table[n - 1][v] + w
                                                                                           table[n][0] = float("inf")
   sorted_jobs = sorted(jobs, key=lambda x: x[1])
                                                                                       return table[graph_length - 1]
   count =
   last_finish = 0
    for start, finish in sorted_jobs:
        if start >= last_finish:
            count +=
            last finish = finish
   return count
```

name

print(max\_jobs(jobs))

```
def topSort(G):
                                                                                                                  lass WDGraphAdjLst(WDGraph):
 def dfsTarjan(G,u):
   global state, counter, low, num, stack
                                                         # Computing in-degree of each node
                                                                                                                  def __init__(self, N):
                                                          indegree = [0 for i in range(G.numNodes)]
   low[u] = num[u] = counter
                                                                                                                     self.adjLst = [deque() for j in range(N)]
                                                          for u in range(G.numNodes):
   counter+=1
                                                                                                                     self.numNodes = N
                                                            for v in G.neighbors(u):
                                                                                                                     self.numEdges = 0
   stack.append(u)
                                                             indegree[v]+=1
   for v in G.neighbors(u):
                                                                                                                   def addEdge(self,u,v,d):
                                                         S = [u for u in range(G.numNodes) if indegree[u]==0]
     if state[v]==UNDISCOVERED:
                                                                                                                     if not self.isAdjacent(u,v):
                                                         L = []
       # Tree edge: DISCOVERED \rightarrow UNDISCOVERED
                                                                                                                       self.adjLst[u].append((v,d))
                                                         while len(S)>0:
       state[v] = DISCOVERED
                                                                                                                       self.numEdges+=1
                                                           u = S.pop()
        dfsTarjan(G,v)
                                                           L.append(u)
                                                                                                      [deque([(1, 2), (3, 5)]), deque([(2, 3), (3, 7)]), deque([(5, 4)]),
       low[u] = min(low[u],low[v])
                                                            for v in G.neighbors(u):
     elif state[v]==DISCOVERED:
                                                              indegree[v]-=1
       # Back edge: DISCOVERED \rightarrow DISCOVERED
                                                              if indegree[v]==0:
        low[u] = min(low[u], num[v])
                                                                S.append(v)
     elif state[v]==EXPLORED:
       # Forward/cross edge: DISCOVERED \rightarrow EXPLORED
                                                         return L
       low[u] = min(low[u], num[v])
                                                        def prim():
                                                           graph_length = int(input())
   if low[u]==num[u]:
     scc = []
     while(True):
                                                            while True:
                                                               edge = list(map(int, input().split()))
       v = stack.pop()
                                                               if edge[0] == 0 and edge[1] == 0:
        state[v] = DELETED
        scc.append(v)
                                                               edges.append([edge[0], edge[1], edge[2]])
       if u==v:
         break
                                                           X = [0]
     print(scc)
                                                           T = \overline{1}
   else:
     state[u] = EXPLORED
                                                            while len(X) < graph_length:
                                                               min_edge = [None, None, float("inf")]
 def kruskal():
                                                                for edge in edges:
                                                                   if edge[0] in X and edge[1] not in X and edge[2] < min_edge[2]:
      graph_length = int(input())
                                                                       min_edge = edge
      edges = []
                                                                   elif edge[1] in X and edge[0] not in X and edge[2] < min_edge[2]:
                                                                       min_edge = edge
                                                                                                                     rom collections import deque
      while True:
          edge = list(map(int, input().split()))
                                                               T.append(min_edge)
          if edge[0] == 0 and edge[1] == 0:
                                                               X.append(min_edge[1])
          edges.append([edge[0], edge[1], edge[2]])
                                                           return T
                                                                                                                        self.adjLst = [deque() for j in range(N)]
                                                                                                                        self.numNodes = N
                                                        """Best First Search Algorithm"""
      edges.sort(key=lambda x: x[2])
                                                                                                                        self.numEdges = 0
                                                       import heapq
                                                        # Declaring constants
                                                       UNDISCOVERED = 0
                                                                                                                        if not self.isAdjacent(u,v):
      parent = [i for i in range(graph_length)]
                                                       DISCOVERED = 1
                                                                                                                          self.adjLst[u].append(v)
                                                                                                                          self.numEdges+=1
      def find(x):
                                                        def bestfs(G,s):
          if parent[x] \neq x:
                                                          state = [UNDISCOVERED for i in range(G.numNodes)]
              parent[x] = find(parent[x])
                                                          H = []
                                                                                                                        if self.isAdjacent(u,v):
          return parent[x]
                                                          state[s] = DISCOVERED
                                                                                                                          self.adjLst[u].remove(v)
                                                          heapq.heappush(H,s)
                                                                                                                          self.numEdges-=1
      def union(x, y):
                                                          while len(H)>0:
          parent[find(x)] = find(y)
                                                            u = heapq.heappop(H)
                                                            print("Exploring Node " + str(u))
                                                                                                                        for w in self.adjLst[u]:
      for edge in edges:
                                                            for v in G.neighbors(u):
                                                              if state[v] == UNDISCOVERED:
                                                                                                                          if ω == v:
          u, v, w = edge
          if find(u) \neq find(v):
                                                                state[v] = DISCOVERED
              mst.append(edge)
                                                                heapq.heappush(H,v)
              union(u, v)
                                                                                   findVisitable(G, u
                                                                                   visitable = [False]*G.numNodes
      return mst
                                                                                                                       return list(self.adjLst[u])
                                                                                   queue = deque()
memo = \{\}
                                                                                   queue.append(u)
                                                                                                                      def edges(self):
def test(flee, list num):
    if (flee, tuple(list_num)) in memo:
                                                                                   for v in G.neighbors(u):
                                                                                                                        for u in range(self.numNodes):
        return memo[(flee, tuple(list_num))]
                                                                                       queue.append(v)
                                                                                                                          for v in self.adjLst[u]:
                                                                                       visitable[v] = True
    elif len(list_num) == 0:
                                                                                                                              L.append((u,v))
                                                                                   while queue:
        return 0
                                                                                       u = queue.popleft()
    elif len(list_num) == 1:
                                                                                       for v in G.neighbors(u):
                                                                                           if not visitable[v]:
        memo[(flee, tuple(list_num))] = list_num[0] - flee
                                                                                               queue.append(v)
        return memo[(flee, tuple(list_num))]
                                                                                               visitable[v] = True
        profit_from_f = (list_num[-1] - flee) + test(flee, list_num[:-1])
                                                                                   for i in range(G.numNodes):
                                                                                       if visitable[i]:
        profit\_from\_s = (list\_num[0] - flee) + test(flee, list\_num[1:])
        {\tt memo}[({\tt flee},\,{\tt tuple}({\tt list\_num}))] = {\tt max}({\tt profit\_from\_f},\,{\tt profit\_from\_s})
        return memo[(flee, tuple(list_num))]
                                                                              number = int(input())
    flee = 50
                                                                              G1 = DGraphAdjLst(number)
    list_numbers = [54, 55, 40, 48, 51, 50, 56, 49, 54, 47]
                                                                              start = int(input())
    list_num1 = [45, 50, 49]
    test(flee, list_numbers)
                                                                                  a = input().split()
    # get max value from memo
                                                                                  u = int(a[0])
v = int(a[1])
```

if u == 0 and v == 0:

G1.addEdge(u-1, v-1)

findVisitable(G1, start-1)

result = 0

for key, value in memo.items(): if value > result:

result = value print(result if result > 0 else "No")