

Exercise 1 (Algorithms for Qualitative Model Checking)

3 points

Let $D = (S, \mathbf{P}, s_{init}, AP, L)$ be a finite DTMC and $a, b \in AP$. Give algorithms (in pseudocode) to compute the following sets and briefly explain the complexity of your algorithm.

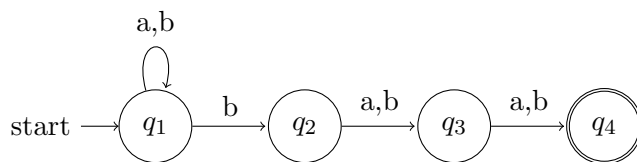
a) $S_{=0} = \{s \in S \mid Pr(s \models a \cup b) = 0\}$

b) $S_{=1} = \{s \in S \mid Pr(s \models a \cup b) = 1\}$

Exercise 2

2.5 points

Using subset construction for automata determinization, determinize the following automaton:



$$L(\mathcal{A}) = \{w \in \Sigma^* \mid b \text{ is in the third position from the end}\}$$

Exercise 3 (Zeroconf protocol in Figure 10.4 in book)

2.5 points

a) $Pr(\Diamond \Box \{s_8\}) = 1$

b) $Pr(\Diamond \Box \{s_6\}) > 0$

c) $Pr(\Diamond \Box \{s_6, s_8\}) = 1$

d) $Pr(\Box \Diamond \{s_6, s_8\}) = 1$

e) $Pr(\Box \Diamond \{s_6\}) > 0$

Exercise 4 (BONUS)

4 points

Write pseudocode for detection of BSCC's in a directed graph with n states and adjacency matrix

$$A \in \{0, 1\}^{n \times n}.$$

(Hint: To get inspired, search Tarjan's connected components algorithm)

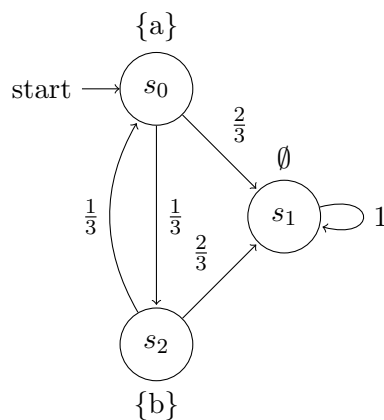
Exercise 5 (ω -regular Properties)

4 points

Non-deterministic Büchi automata are strictly more expressive than deterministic ones. Recall the “powerset construction”, which is used to compute a deterministic finite automaton from a non-deterministic one.

a) Construct a non-deterministic Büchi automaton for the language $(a + b)^*a^\omega$, apply the powerset construction to determinize this automaton and compare the languages of the resulting automaton and the original one by either showing their equivalence or giving a counterexample separating the languages.

b) Consider the following DTMC:



Give a formal definition for the cross-product between a *non-deterministic* Büchi-Automaton and a DTMC.

Apply this definition to the DTMC D and the NBA from a). What problems arise?

(Note on the course: Adapted from Prof. Joost-Pieter Katoen’s course titled “Modelling and Verification of Probabilistic Systems”, available at <http://moves.rwth-aachen.de/teachings/ws-1516/movep15/>.)