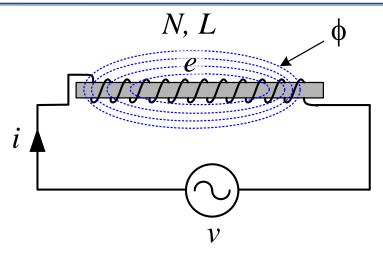
## Electromagnetism

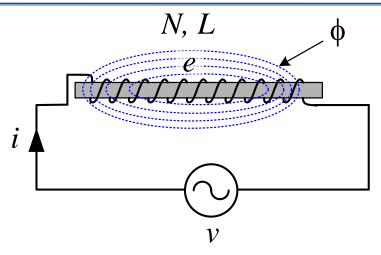
Day 22

## ILOs – Day 22

- Derive expression for energy stored in an electromagnet
- Derive expression for lifting force (pulling force) of a magnet
- Describe magnetization characteristics of a magnetic material with AC supply
- Explain energy losses during magnetization:
  - Hystereis loss
  - Eddy current loss

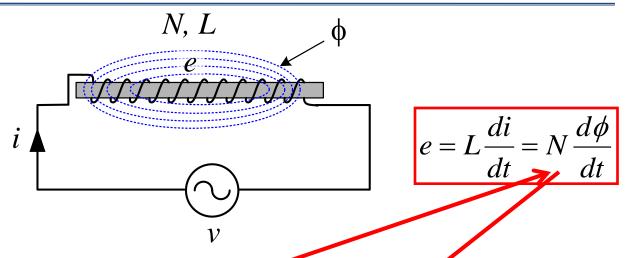


- An electromagnet is produced by passing current through a solenoid
- The electrical energy supplied from the voltage source is partly stored in the electromagnet as magnetic energy
- The remaining part of the input energy is wasted as power loss (heat) during the magnetization process



- Let the electromagnet is produced by passing current i through a coil of N number of turns
- Let, self-inductance of the coil is L
- The flux  $\phi$  linking with the coil itself produces a self-induced EMF of e in it

$$e = L\frac{di}{dt} = N\frac{d\phi}{dt}$$



Electric energy supplied from the source in small time dt is:

$$dE = P \times dt = (e \times i) \times dt$$

- If the losses are neglected, then this amount of electrical energy supplied will entirely be stored as magnetic energy
- Thus, during that small time interval dt, energy consumed by the electromagnet coil can bence be given as:

$$dE = N \frac{d\phi}{dt} \times i \times dt = Nid\phi$$

$$dE = Nid\phi$$

• Total energy stored in the magnetic field can be found out by integration:  $E = \int dE = Ni \int_{0}^{\phi} d\phi$ 

$$dE = e \times i \times dt$$

$$dE = L \frac{di}{dt} \times i \times dt$$

$$dE = Lidi$$

$$E = \int dE = L \int_{0}^{I} i di = \frac{1}{2} Li^{2} \Big|_{0}^{I} = \frac{1}{2} LI^{2}$$
 Joules

$$E = \frac{1}{2}LI^2$$

Expression for self-inductance of a coil :  $L = \frac{N^2 \mu_0 \mu_r a}{I}$ 

$$E = \frac{1}{2}LI^{2} = \frac{1}{2}\frac{N^{2}\mu_{0}\mu_{r}a}{l}I^{2} = \frac{1}{2}\mu_{0}\mu_{r}(al)\frac{N^{2}I^{2}}{l^{2}} = \frac{1}{2}\mu_{0}\mu_{r}(al)H^{2}$$

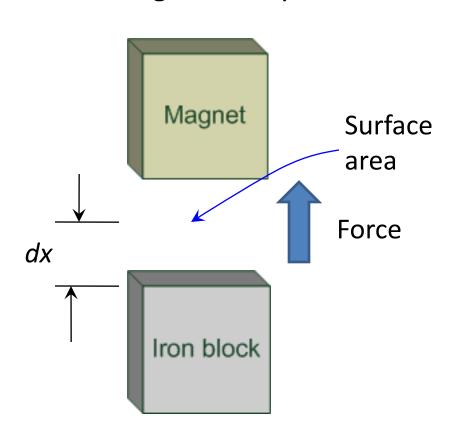
$$E = \frac{1}{2} \mu_0 \mu_r (V) H^2$$

 $E = \frac{1}{2} \mu_0 \mu_r(V) H^2$  where V = aI = Volume of the core material

Energy density:

$$E_V = \frac{E}{V} = \frac{1}{2} \mu_0 \mu_r H^2 = \frac{1}{2} (\mu_0 \mu_r H) H = \frac{1}{2} BH$$
 Joules/m<sup>3</sup>

- It is a common experience that when we put a piece of iron close to a magnet, the iron piece is pulled in towards the magnet
- Here, we will try to find out an expression for that force exerted by the magnet on a piece of iron



- Due to pull of the magnet, let the iron piece moves up by a small distance dx through air
- The work done in moving up the iron is equal to the change in stored energy

Work done in moving up the iron is equal to the change in stored energy

 $E = \frac{1}{2} \mu_0 \mu_r (V) H^2$ 

$$W = \frac{1}{2}$$
Magnet

Force

Iron block

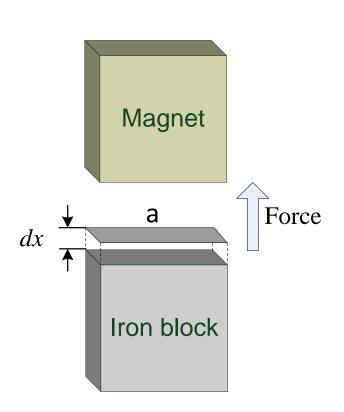
$$W = dE = \frac{1}{2} \mu_0 \mu_r (dV) H^2 = \frac{1}{2} \mu_0 \mu_r (adx) H^2$$

- Since the iron piece moves through air,  $\mu_r = 1$
- If the lifting force is *F*, then we have:

$$W = F.dx$$
$$F.dx = \frac{1}{2}\mu_0(adx)H^2$$

$$F.dx = \frac{1}{2}\mu_0(adx)H^2$$

Thus, lifting force:



$$F = \frac{1}{2} \mu_0(a) H^2$$

$$=\frac{B^2a}{2\mu_0}$$

 Lifting force per unit area, i.e. lifting pressure:

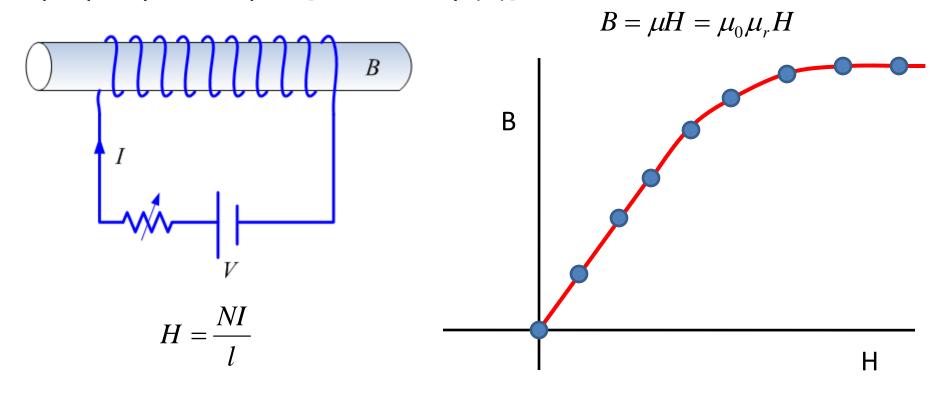
$$P = \frac{F}{a} = \frac{1}{2} \mu_0 H^2$$

$$= \frac{1}{2} (\mu_0 H) H$$
$$= \frac{1}{2} BH$$

## Magnetization characteristics of a magnetic material

#### Magnetization characteristics of a magnetic material

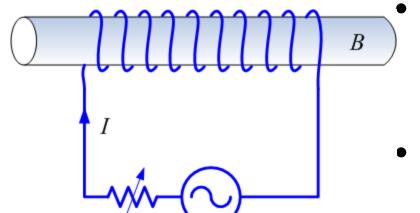
 Relation between the magnetizing force (H) and the magnetic property developed [flux density (B)]



- Initially linear increase in B, but saturated afterwards
- When all the magnetic domains get fully oriented then saturated
- B-H characteristics is thus non-linear

## Magnetization with AC supply

Input voltage is AC, i.e. varies sinusoidally from + to -



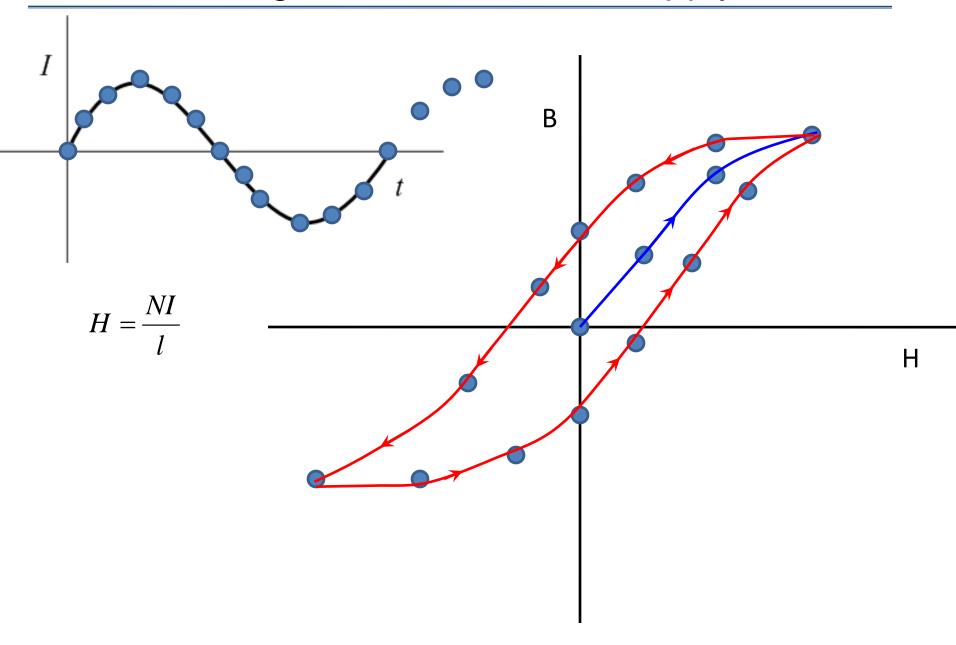
Thus, input current *I* is also AC, *i.e.* varies sinusoidally from + to -

$$H = \frac{NI}{l}$$

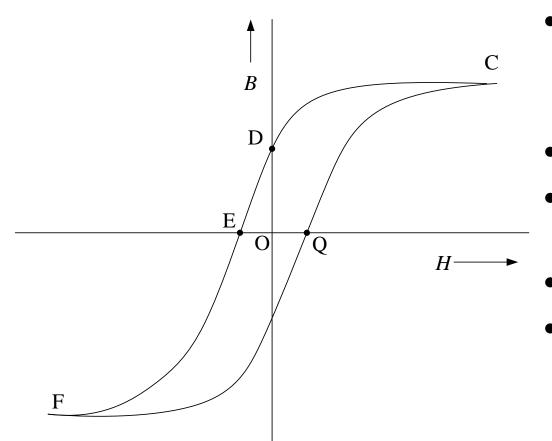
Thus, magnetizing force *H* is also AC, *i.e.* varies sinusoidally from + to -

 Thus, the magnetizing force starts from zero, rises up to a positive maximum value, then comes down back to zero, drops down to a negative minimum value and goes back again to zero. This cycle continues

## Magnetization with AC supply



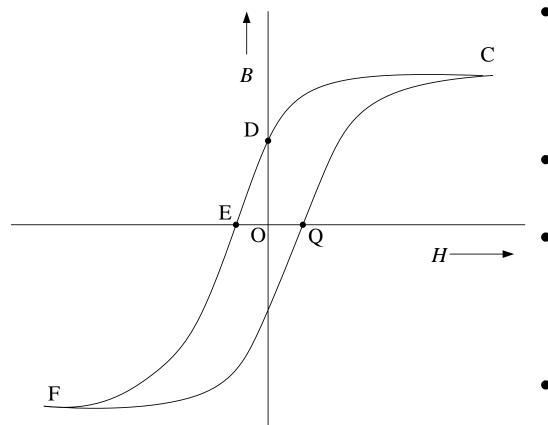
## Magnetization with AC supply



- The loop CDEFQC is called hysteresis loop
- C = Positive saturation
- OD = Retentivity (residual flux density) or remanence
- OE = Coercivity
- F = Negative saturation

Hysteresis loss

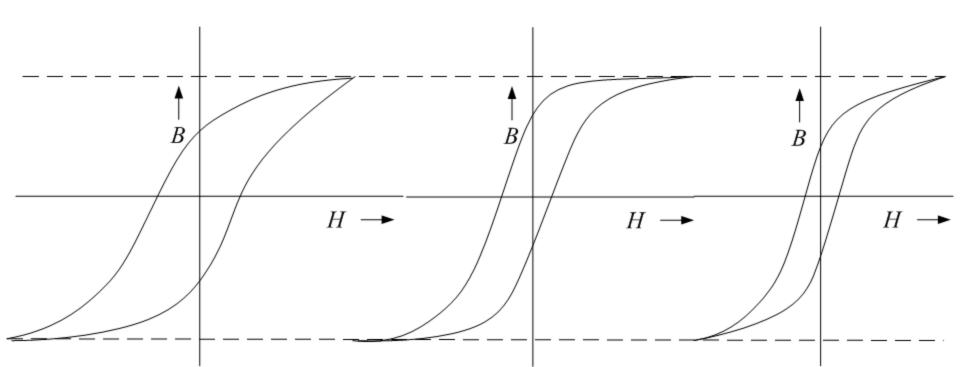
Eddy current loss



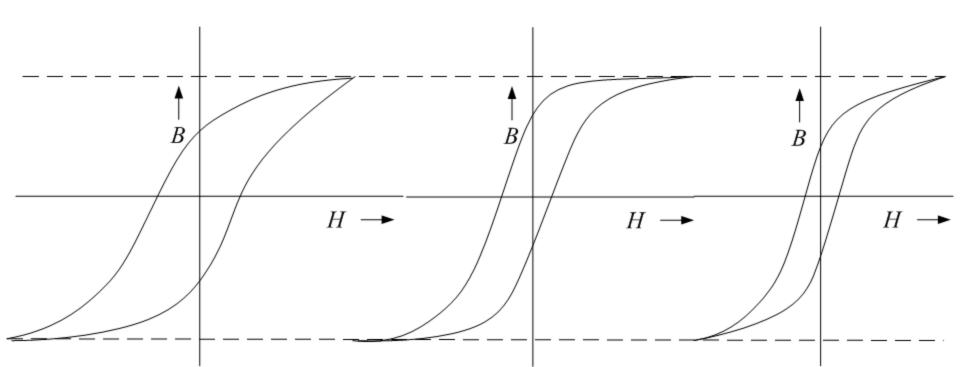
- Energy spent during magnetization is more than the energy released during de-magnetization
- This is evident from the residual magnetism
- The amount of energy thus lost during each cycle of magnetization is called Hysteresis Loss
- This heats up the material during magnetization

Total hysteresis loss in a magnetic material is proportional to the area of its hysteresis loop. The loop area is equal to hysteresis loss (in W) per cycle of the input AC signal.

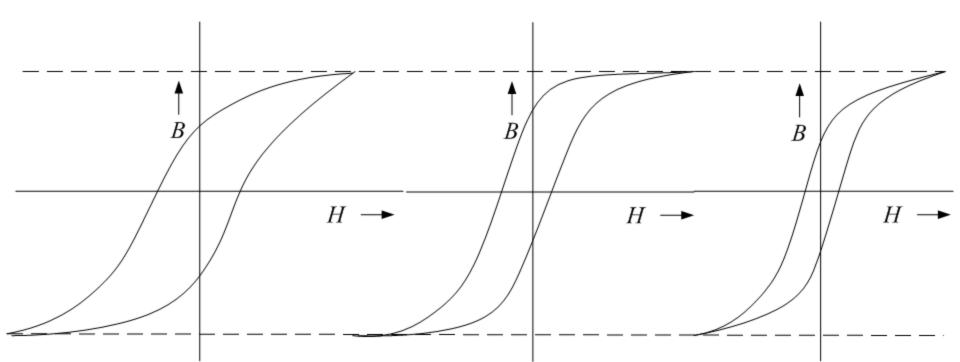
- Hysteresis loop thus measures the energy dissipated due to hysteresis loss
- This loss appears in the form of heat and so raises the temperature of that portion of the magnetic circuit which is subjected to magnetic reversal
- The shape of the hysteresis loop depends on the nature of the magnetic material



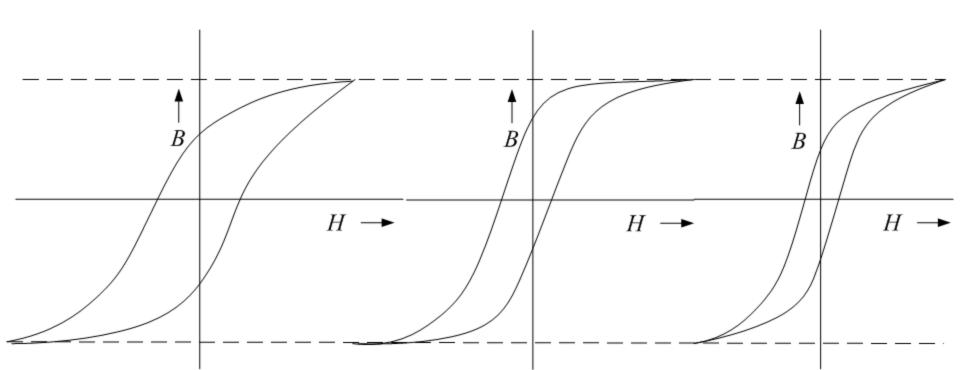
- Loop 1 (left) is for hard magnetic materials
- Due to its high retentivity and coercivity, it is well suited for making permanent magnets
- But due to large hysteresis loss (as shown by large loop area) it is not suitable for rapid reversals of magnetization as in AC machines
- Certain alloys of aluminum, nickel and steel called Alnico alloys are suitable for making permanent magnets



- Loop 2 (middle) is for wrought iron and cast steel
- It shows that these materials have high permeability and fairly good coercivity, hence making them suitable for cores of electromagnets
- The loop area and hence the hysteresis losses are moderate



- Loop 3 is for alloyed sheet steel and it shows high permeability and low hysteresis loss
- Hence, such materials are most suited for making armature and transformer cores in AC machines which are subjected to rapid reversals of magnetization



- An analytical expression for hysteresis loss can be written following the equation established by Charles Steinmetz as:
- Hysteresis loss  $P_h = K_h f B_m^x$  W/m<sup>3</sup>

• Where,

 $B_m$ = Maximum value of flux density in the material

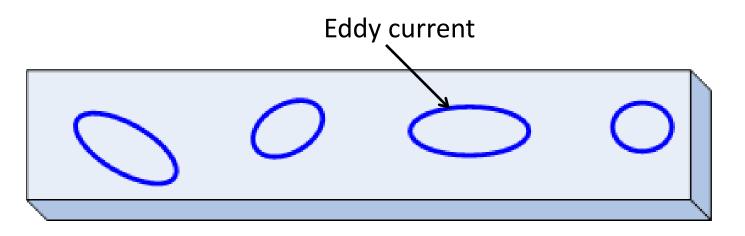
f = frequency of flux reversal, i.e. frequency of the input AC source

 $K_h$  = Steinmetz coefficient, its value depends on property of the material

x = A coefficient in the range 1 < x < 2 depending on value of  $B_m$ ; commonly used value is x = 1.6

- The second type of loss that takes place in a magnetic material during magnetization by an alternating field is called Eddy current loss
- Most magnetic materials are either metallic or are alloys of metallic base
- This makes them conducting to some extent in addition to being magnetic
- The flux that passes through the material is time varying

- The flux that passes through the material is time varying
- This will induce voltage inside the body of the material
- This causes flow of currents in small loops within body of the material



- This causes  $I^2R$  power loss in the material
- This loss is called eddy current loss

An analytical expression for Eddy current loss is available:

$$P_e = K_e f^2 t^2 B_m^2$$
 W/m<sup>3</sup>

Where,
 K<sub>e</sub> is constant depending on the material properties including its resistivity
 f is the supply frequency
 t is the thickness of the material body
 B<sub>m</sub> is maximum value of flux density in the material

Hysteresis loss and eddy current loss are collectively called *iron loss* or *core loss* because they take place invariably in the core material of all electrical machines including transformers, motors, and generators.