## Vector Calculus

## 10.7 Vector Functions and Space Curves

Def: A <u>parametric vector-valued function</u> is a function of the form

$$F: [a,b] \rightarrow \mathbb{R}^2$$
 or  $F: [a,b] \rightarrow \mathbb{R}^3$   
 $F(t) = \langle \chi(t), \chi(t) \rangle$   
parametric plane curve parametric space curve

We say t is the <u>parameter</u>, and we say the real-valued functions x,y,z:[a,b]->R are the <u>components</u> of r. We say the set

is the image of r.

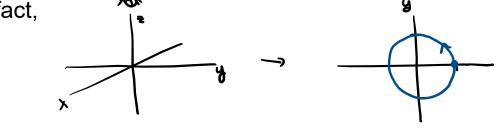
Ex: Sketch the image of the following parametric space curves.

1.  $\vec{r}(t) = \cos(t), \sin(t), t > \text{ for } 0 \le t \le 2pi \text{ the helix}$ 

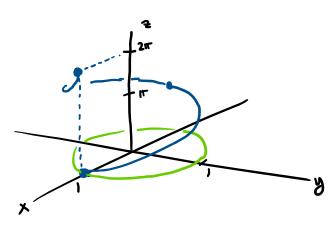
Sol: We compute  $\vec{r}(0) = <1,0,0>$  and  $\vec{r}(t) = <1,0,2pi>$ . Also

$$\vec{r}(t) = \langle cost, sint, t \rangle \implies \chi^2 + \gamma^2 = 1$$

This means that the image of  $\vec{r}$  lies in the unit cylinder  $\vec{x}^2 + \vec{y} = 1$ . In fact,



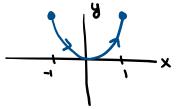
The image of  $\vec{r}$  is

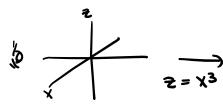


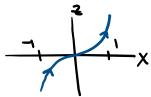
Use CalcPlot3D (libretexts.org)

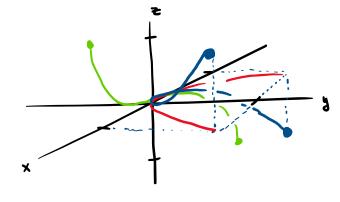
2.  $r(t) = <t, t^2, t^3 > for -1 \le t \le 1$  the twisted cubic

Sol: We compute  $\vec{r}(-1) = <-1,1,-1>$  and  $\vec{r}(1) = <1,1,1>$ . Note that









Ex: Find a parametric space curve  $\vec{r}$  over an interval [a,b] so that the image of  $\vec{r}$  is the intersection between the unit

cylinder  $x^2 + y^2 = 1$  and the plane y+z=2.

Sol: We want the image of r to be

Consider

$$\chi^2 + \eta^2 = 1 \Rightarrow \chi = cost$$
 $y = sint$ 

Then

We conclude that the image of  $r(t) = \cos(t), \sin(t), 2-\sin(t) > 0 \le t \le 2pi$  is the intersection.

Def: Consider a parametric vector-valued function r defined for t near a.

We say  $\hat{r}$  is differentiable at t=a if and only if the components functions of  $\hat{r}$  are differentiable at t=a.

This occurs if and only if the following limit exists:

$$\frac{\partial \vec{r}}{\partial t}\Big|_{t=a} = \vec{r}'(a) = \underbrace{\underbrace{\underbrace{r}(t) - \vec{r}(a)}_{t-a}}_{t-a} = \underbrace{(x'a)y'a)_{z'(a)}}_{=}$$

ellipse?

We say  $\hat{r}'(a)$  is the <u>tangent vector</u> of  $\hat{r}$  at t=a.

We say  $|\hat{r}'(a)|$  is the speed of  $\hat{r}$  at t=a.

If  $\vec{r}$ '(a)=/ $\vec{0}$ , then we say the <u>tangent line of  $\vec{r}$ 'at t=a</u> is the line through  $\vec{r}$ (a) in the direction of  $\vec{r}$ '(a).

If r'(t) exists for all t near a and is differentiable at t=a, then we let  $r''(a) = \frac{\partial}{\partial t} r'(t) \Big|_{t=a}$ 

denote the second derivative of r at t=a.

Ex: Consider the helix  $\vec{r}(t) = \cos(t), \sin(t), t > \text{ for } t \text{ in } R$ .

1. Compute the tangent vector and speed of r at t=pi/2.

Sol: We compute

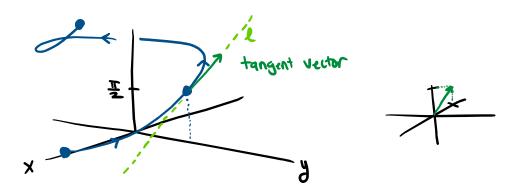
and 
$$|\vec{r}'(\frac{\pi}{2})| = \frac{\partial \vec{r}}{\partial t}|_{t=\frac{\pi}{2}} = \frac{\partial}{\partial t} \left\langle (ast, sint, t) \right\rangle_{t=\frac{\pi}{2}}$$

$$= \left\langle -sint, (ast, 1) \right\rangle_{t=\frac{\pi}{2}}$$

$$= \left\langle -l, 0, 1 \right\rangle_{t=\frac{\pi}{2}}$$

2. Compute the tangent line of r at t=pi/2.

Check:

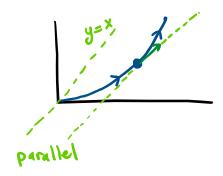


The tangent vector, and so the tangent line, are \*tangent\* to the image of  $\hat{r}$  at  $\hat{r}(a)$ .

Ex: Consider  $\vec{r}(t) = \langle \vec{t}/2, \vec{t}/3 \rangle$  for t in R.

1. Compute the tangent vector and speed of  $\vec{r}$  at t=1.

2. Compute the tangent line of  $\hat{r}$  at t=1.



Fact: Suppose r is a vector-valued function defined over [a,b], and suppose f:[alpha,beta]->[a,b] is continuous.

Suppose f is increasing with

$$f(\alpha) = \alpha$$
 and  $f(\beta) = b$ 

and define the parametric vector-valued function

Then  $\vec{r}, \vec{r}_{\epsilon}$  have the same images.  $\vec{r}_{\epsilon}(a) = \vec{r}(\epsilon(a)) = \vec{r}(a)$ 

$$\vec{r}_F(a) = \vec{r}(F(a)) = \vec{r}(a)$$

$$\vec{r}_F(a) = \vec{r}(F(a)) = \vec{r}(b)$$

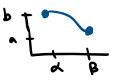
However, re traces the image of r with different speed. In fact,

$$|\vec{r}_{F}(s)| = |F'(s)\vec{r}'(F(s))| = F'(s) |\vec{r}'(F(s))|$$

assuming f is differentiable.

Suppose f is decreasing with

$$f(\alpha) = b$$
 and  $F(\beta) = a$ 



and define the parametric vector-valued function

Then  $\vec{r}, \vec{r}_{\epsilon}$  have the same images. However,  $\vec{r}_{\epsilon}$  traces the image of  $\vec{r}$  in the opposite direction and with different speed. In fact,

$$\frac{(beck)}{r_{\epsilon}(a)} = \frac{1}{r}(\epsilon(a)) = \frac{1}{r}(b)$$

$$\frac{1}{r_{\epsilon}(a)} = \frac{1}{r}(\epsilon(a)) = \frac{1}{r}(a)$$

$$|\vec{r}_{F}(s)| = |F'(s)\vec{r}'(F(s))|$$

$$= -F'(s) |\vec{r}'(F(s))|$$
F is decreasing  $\Rightarrow 0$ 

Def: We say  $r_e$  is a <u>reparameterization of r.</u>

Ex: Consider the helix

Recall that

$$\vec{r}(\underline{T}) = \langle 0_1 |_{\underline{T}} \rangle$$
,  $\vec{r}'(\underline{F}) = \langle -1_1 0_1 \rangle$ , and  $|\vec{r}(t)| = \sqrt{2}$   
tangent vector speed

1. Suppose f(s)=2s, and consider  $r_{\epsilon} = r_{\epsilon}(s)$ . Compute  $r_{\epsilon}(pi/4)$ , and compute the tangent vector and speed of  $r_{\epsilon}$  at s=pi/4.

Sol: We compute

$$\vec{r}_{F}(\vec{q}) = \vec{r}_{F}(s) = \vec{r}_{F}(f(s)) \Big|_{\vec{q}}$$

$$= \langle \cos(2s), \sin(2s), 2s \rangle \Big|_{s=\vec{q}}$$

$$\vec{r}_{F}(f(s))$$

$$= \langle (2)^{1}/(\frac{\pi}{2}) \rangle = \langle$$

We also compute

$$\vec{r}_{F}(\vec{t}) = \frac{\delta}{\delta s} \vec{r}_{F}(s) \Big|_{s = \frac{\pi}{4}} = \frac{\delta}{\delta s} \langle \cos(2s), \sin(2s), 2s \rangle \Big|_{s = \frac{\pi}{4}}$$

$$= \langle -2\sin 2s, 2\cos 2s, 2 \rangle \Big|_{s = \frac{\pi}{4}}$$

$$= \langle -2\sin \frac{\pi}{2}, 2\cos \frac{\pi}{2}, 2 \rangle$$

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$$= \langle -2\sin \frac{\pi}{2}, 2\cos \frac{\pi}{2}, 2 \rangle$$
Speed =  $|\vec{r}_{F}(\vec{t}, t)| = |\vec{t}_{F}(t, t)|$ 

check: Note that  $r_c(pi/4) = r(pi/2) = <0,1,pi/2>$ . It takes half the time for  $r_c$  to get to <0,1,pi/2>. This means the speed of  $r_c$  should be double...2 $\sqrt{2}$ .

2. Suppose f(s)=pi-s, and consider  $\vec{r_s} = \vec{r_s}$ (s). Compute  $\vec{r_s}$ (pi/2), and compute the tangent vector and speed of  $\vec{r_s}$  at s=pi/2.

Sol: We compute

$$\vec{r}_{F}(\underline{\underline{T}}) = \vec{r}(F(s))|_{s=\underline{T}} = \langle \cos(\pi - s), \sin(\pi - s), \pi - s \rangle$$

$$= \langle \cos(\underline{\underline{T}}), \sin(\underline{\underline{T}}), \underline{\underline{T}} \rangle$$

$$= \langle \cos(\underline{\underline{T}}), \sin(\underline{\underline{T}}), \underline{\underline{T}} \rangle$$

$$= \langle \cos(\underline{\underline{T}}), \sin(\underline{\underline{T}}), \underline{\underline{T}} \rangle$$

We also compute

$$\vec{r}_{\xi'}(\bar{z}) = \frac{1}{15} \left\langle \cos(\pi - 5), \sin(\pi - 5), \pi - 5 \right\rangle \Big|_{S = \bar{z}}$$

$$= \left\langle + \sin(\pi - 5), - \cos(\pi - 6), -1 \right\rangle \Big|_{S = \bar{z}}$$

$$= \left\langle \sin \bar{z}, - \cos \bar{z}, -1 \right\rangle$$

$$= \left\langle \left\langle 1, 0, -1 \right\rangle \right\rangle = -\vec{r}'(\bar{z})$$

$$|\vec{r}_{\xi'}(\bar{z})| = \sqrt{1 + 1} = \sqrt{2} \quad \text{Same Speed}$$