

AI Deep Learning: Convolutional Neural Networks (III)

Deep Learning with Big Data

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AI Deep Learning: Convolutional Neural Networks (CNN)

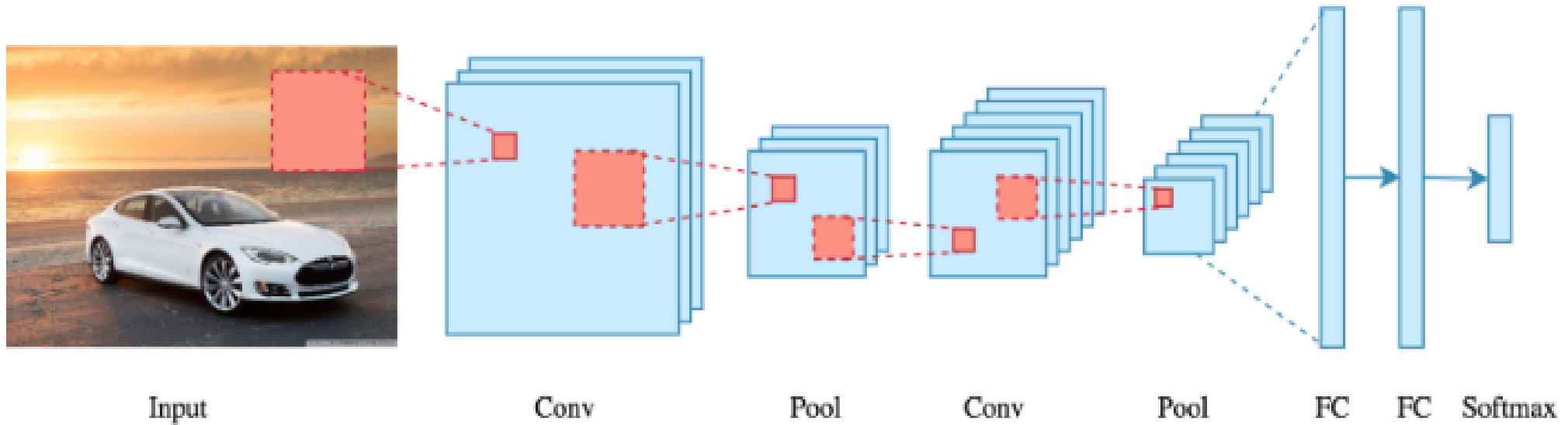
1. AI Deep Learning: Convolutional Neural Networks Overview
2. AI Deep Learning: Properties of Images
3. AI Deep Learning: Convolution Layers in Convolutional Neural Networks
4. AI Deep Learning: Pooling Layers in Convolutional Neural Networks
5. AI Deep Learning: Convolutional Neural Networks: Architectures: Overview
6. AI Deep Learning: Convolutional Neural Networks: Architectures: Layers
7. AI Deep Learning: Build and Train Convolutional Neural Networks

AI Deep Learning: Convolutional Neural Networks (CNN)



AI Deep Learning: Convolutional Neural Networks (CNN)

CNN: Architectures: Overview

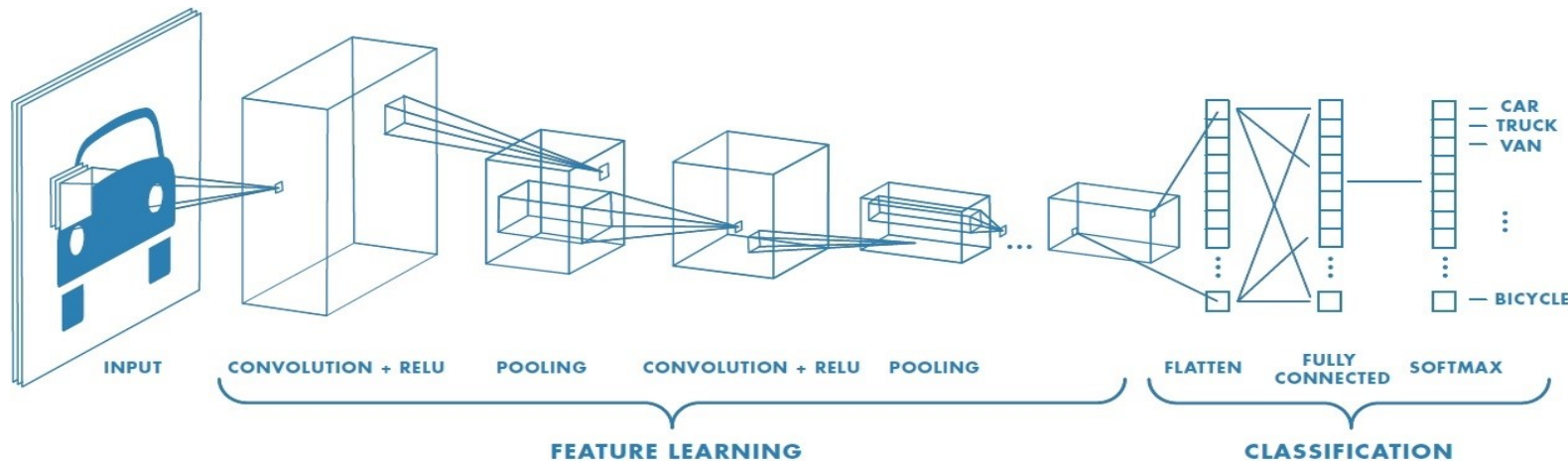


Sources: <http://towardsdatascience.com>

AI Deep Learning: Convolutional Neural Networks (CNN)

CNN: Architectures: Layers

- **CNN** can be viewed as the combination of two sub-networks:
 - First sub-network: **the feature-learning sub-network**:
 - This sub-network comprises layers that aim to **learn or extract the features** from inputs.
 - Second sub-network: **the fully-connected sub-network**:
 - That is very similar to a normal multi-layered neural network, i.e., multi-layer perceptron (MLP)
 - That comprises of **fully-connected layers**
 - That processes the outputs from the feature-learning sub-neural network and **finishes the jobs**



Sources: <http://www.mathworks.com>

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CNN: Architectures: Layers

In general, besides the input and output layer:

- There are **three main types of layers** in a convolutional neural networks,
 - **Convolution layers (CONV)**
 - **Pooling layers (POOL)**
 - **Fully-connected layers (FC)**

There are other layers that work hand-in-hand with the above main layers

For examples:

- **Reshape/Flattening** layers where multi-dimensional data are flattened into 1D data, i.e., a vector.
- **ReLU** layers that are actually where the activation functions process data progressively.
- **Softmax** layer where the last activation function (softmax) processes outputs from the fully-connected layer and produces the final outputs.
- **Dropout** layer where some inputs are randomly dropped before final outputs are produced.

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CNN: Architectures: Layers: Convolution Layer (CONV)

- The **convolution layer** is the **core building block** of a convolutional neural network.
 - That does most of its computational heavy lifting.
- Convolution is the **first layer**, after the input layer, of a convolutional neural network.
 - A convolution layer tries to **extract higher-level features** by **replacing data for each (one) pixel with a value** computed from the pixels covered by **the filter**, e.g., a 5x5 filter, **centered on that pixel** (all the pixels in that region).
 - Convolution **preserves the relationship between pixels** by **learning image features** using small squares of input data, i.e., the filter.

1x1	1x0	1x1	0	0
0x0	1x1	1x0	1	0
0x1	0x0	1x1	1	1
0	0	1	1	0
0	1	1	0	0

Input x Filter

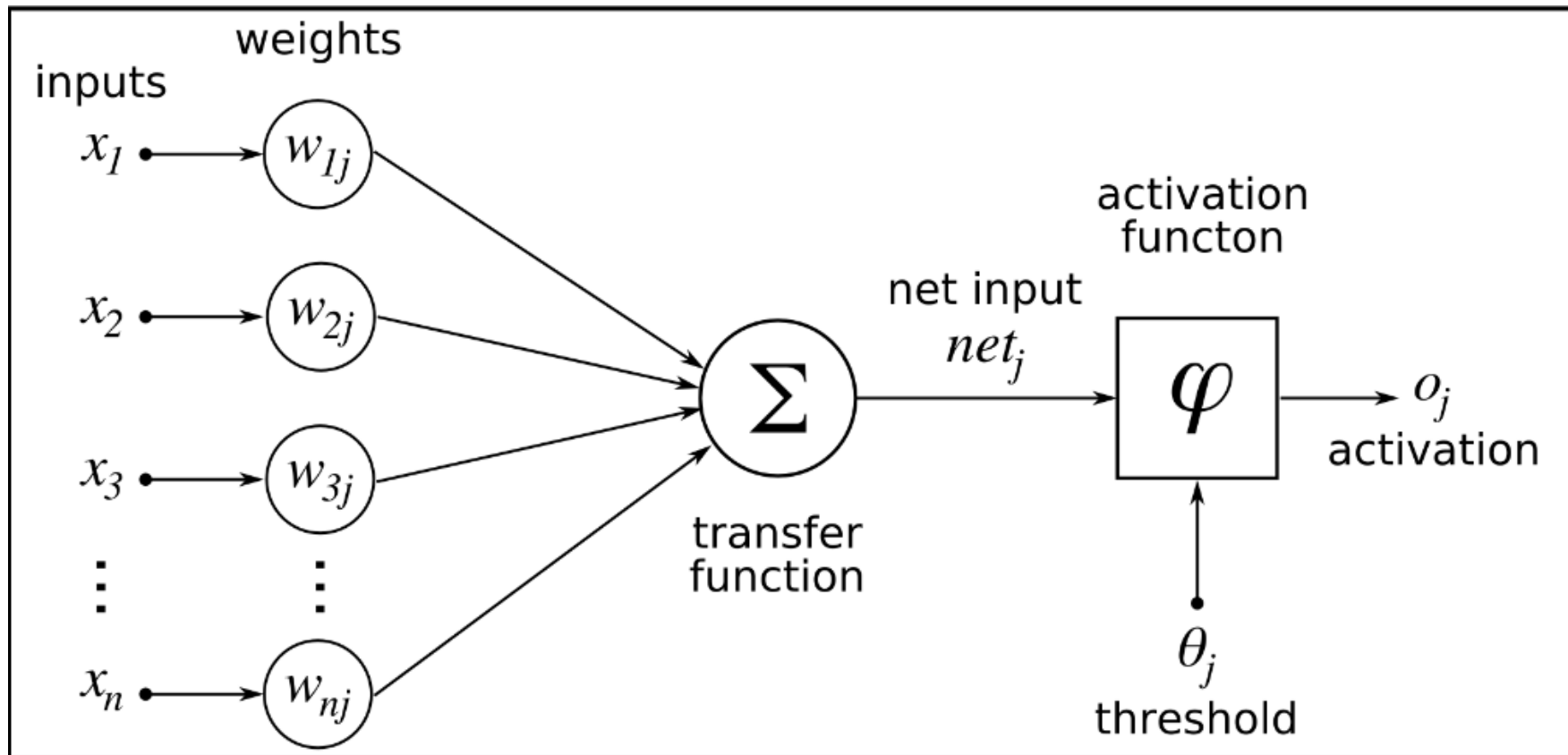
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Feature Map

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CNN: Architectures: Layers: CONV: Activation Function - ReLU

- Let's review the simple McCulloch-Pitts neuron model:

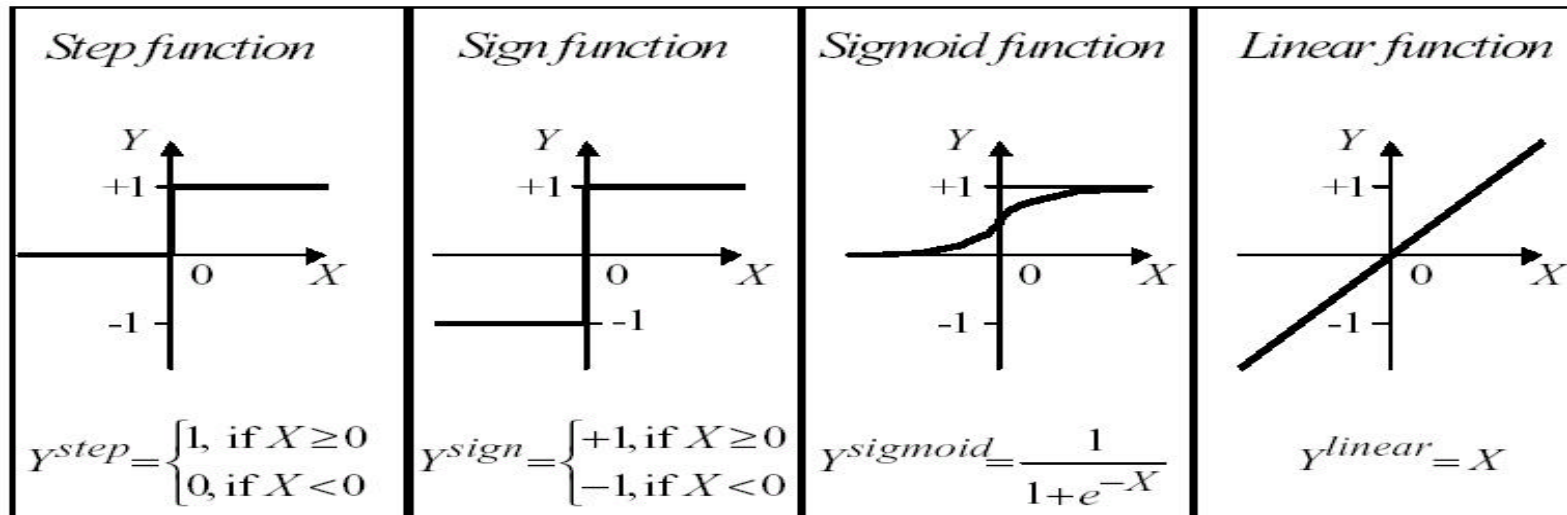


Sources: https://commons.wikimedia.org/wiki/File:ArtificialNeuronModel_english.png

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CNN: Architectures: Layers: CONV: Activation Function - ReLU

- Let's review the simple [McCulloch-Pitts neuron model](#):
 - The inputs multiplied by the weights are summed up by the neuron.
 - The result is delivered as inputs to an activation function that processes the input and produces an output.
- Various functions can be used as activation functions in an artificial neural network. The following functions are commonly used:

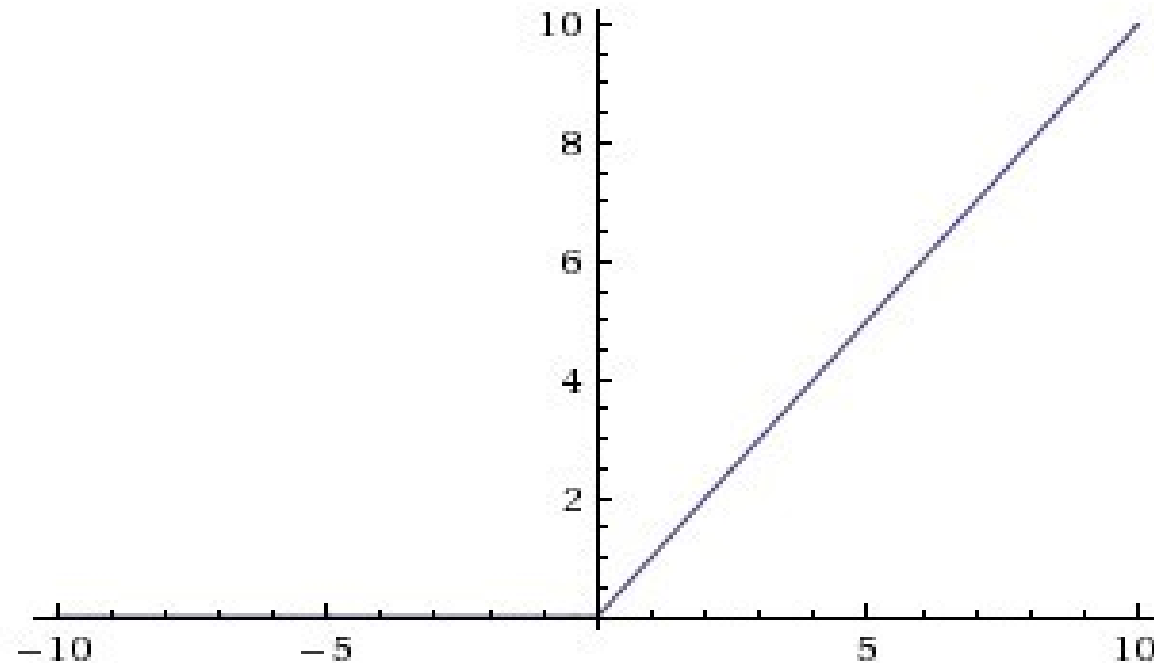


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CNN: Architectures: Layers: CONV: Activation Function - ReLU

For convolutional neural networks:

- **ReLU (Rectified Linear Unit)** is one of the most used activation functions: $y = \max(0, x)$
 - $x \geq 0 \rightarrow y = x$
 - $x < 0 \rightarrow y = 0$



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CNN: Architectures: Layers: CONV: Activation Function - ReLU

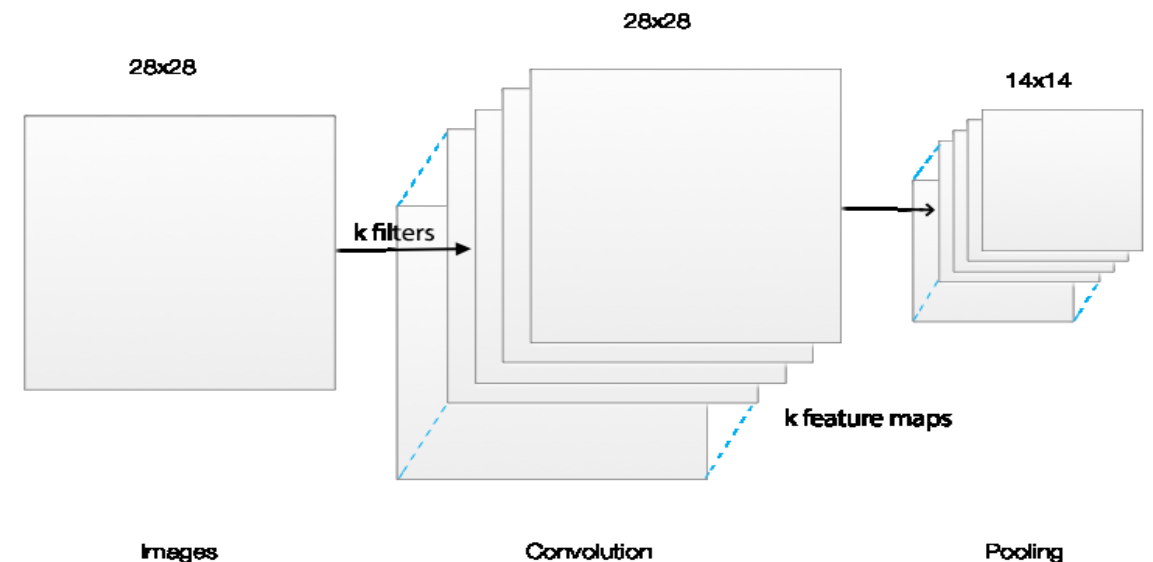
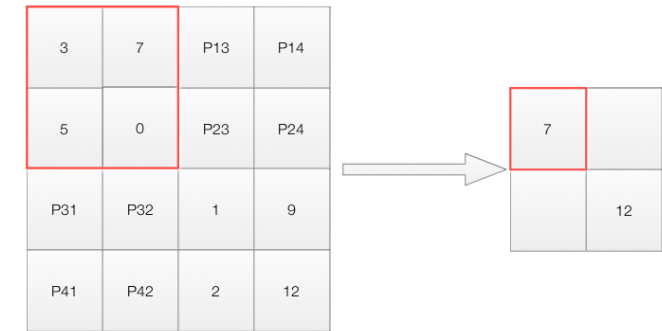
For **convolutional neural networks**:

- **ReLU (Rectified Linear Unit)** is important to convolutional neural networks.
 - Because it can introduce non-linearity into the network.
- **ReLU** can improve neural network performance by speeding up training:
 - The **gradient computation is very simple** (either 0 or 1 depending on the sign of x).
 - Also, the **computational step of a ReLU is easy**: any negative elements are set to 0.0 -- no exponentials, no multiplication or division operations.
- Gradients of logistic and hyperbolic tangent (*two other popular activation functions*) networks are smaller than the positive portion of the ReLU.
 - This means that the **positive portion is updated more rapidly as training progresses**.
 - However, this comes at a cost: The 0 gradient on the left-hand side has its own problem, "dead neurons," in which a gradient update sets the incoming values to a ReLU such that the output is always zero.
 - Modified ReLU units such as ELU (or Leaky ReLU, or PReLU, etc.) can ameliorate this.

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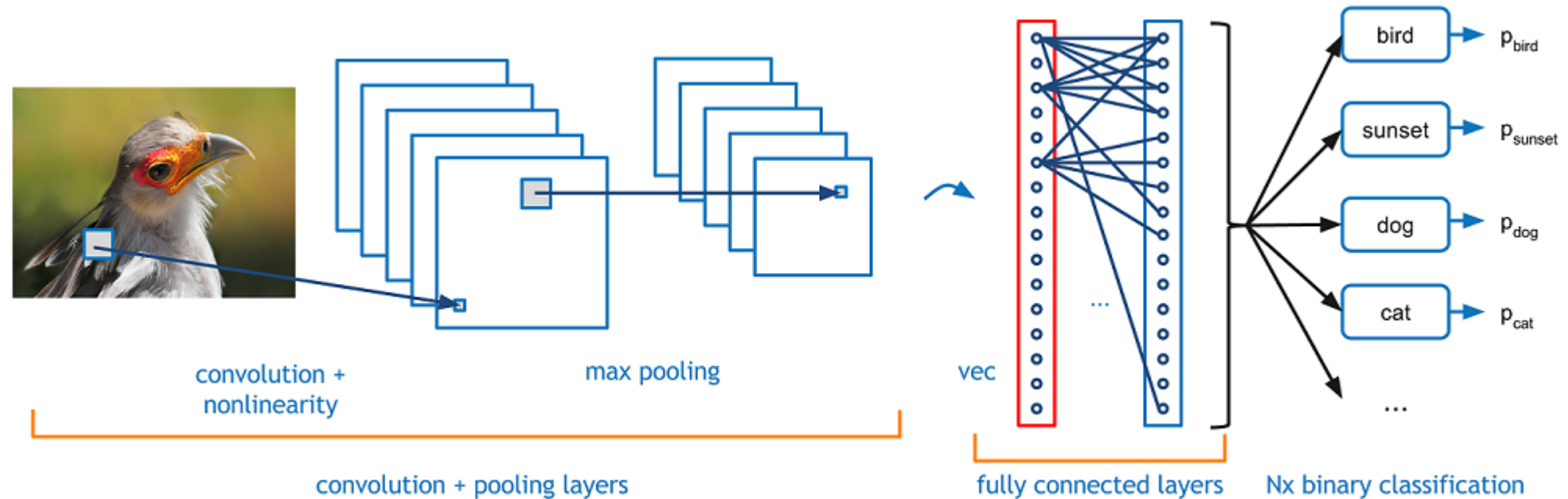
CNN: Architectures: Layers: Pooling Layer (POOL)

- The pooling or down-sampling layer is responsible for reducing the spatial size of the activation maps.
 - Pooling layers accept inputs from convolution layers and non-linearity activation to reduce the computational requirements progressively through the network as well as minimizing the risk of overfitting.
- For example:
 - To reduce the spatial dimension of a feature map, we apply maximum pool (max_pooling).
 - A 2x2 maximum pool replaces a 2x2 area by its maximum.
 - After applying a 2x2 pool, the spatial dimension is reduced from 4x4 to 2x2. (Filter size=2, Stride = 2)



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CNN: Architectures



Sources: Adit Deshpande

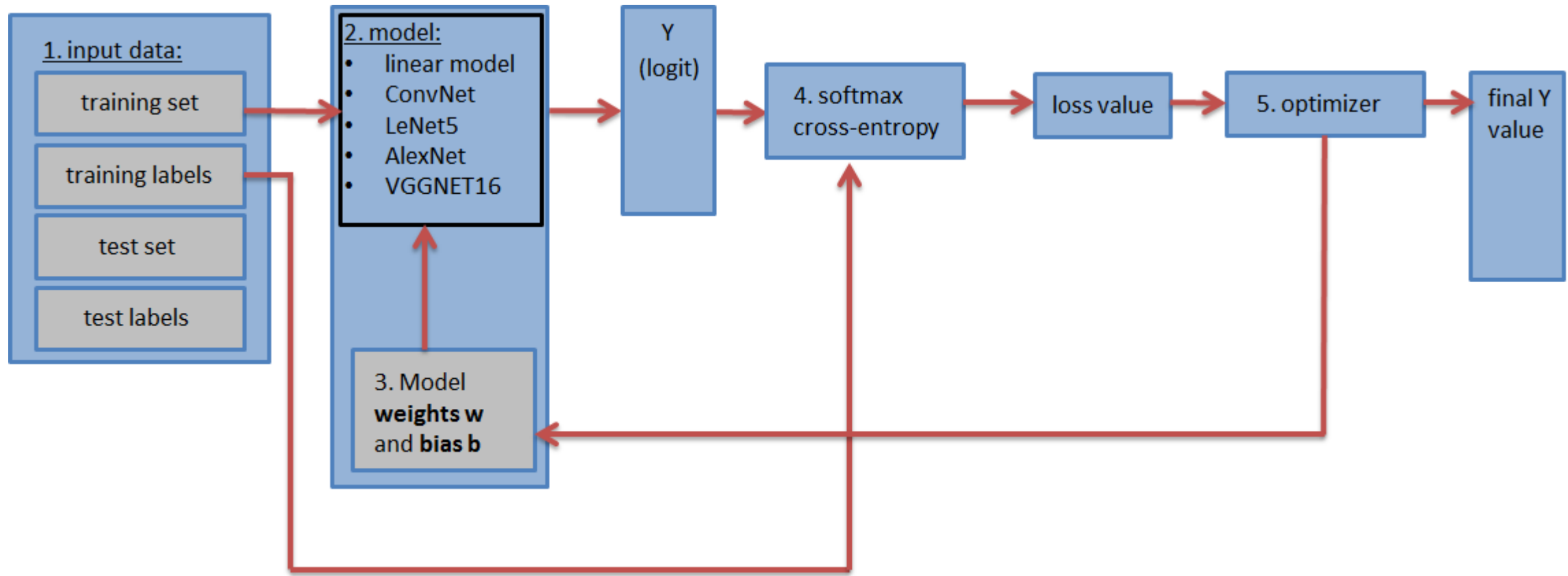
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CNN: Architectures: Layers: Fully-Connected Layer (FC)

- After using a series of convolution layers to extract the spatial features of an image:
 - One or more fully connected layers are used to finish the jobs and produce the final outputs
- First, the outputs of the convolution layers need to be reshaped or flattened into a vector:
 - For example, if the final features maps have a dimension of $4 \times 4 \times 512$, we will flatten it to an array of 8192 elements.
- Then the data (the vector) is fed into the fully-connected layer(s).
 - That produces outputs that will be in turn fed into the final activation functions (Softmax).
- Some of the outputs of the activation functions (Softmax) will be dropped out randomly before the final outputs are produced.

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CNN: Architectures: Overview



Sources: Ahmet Taspinar

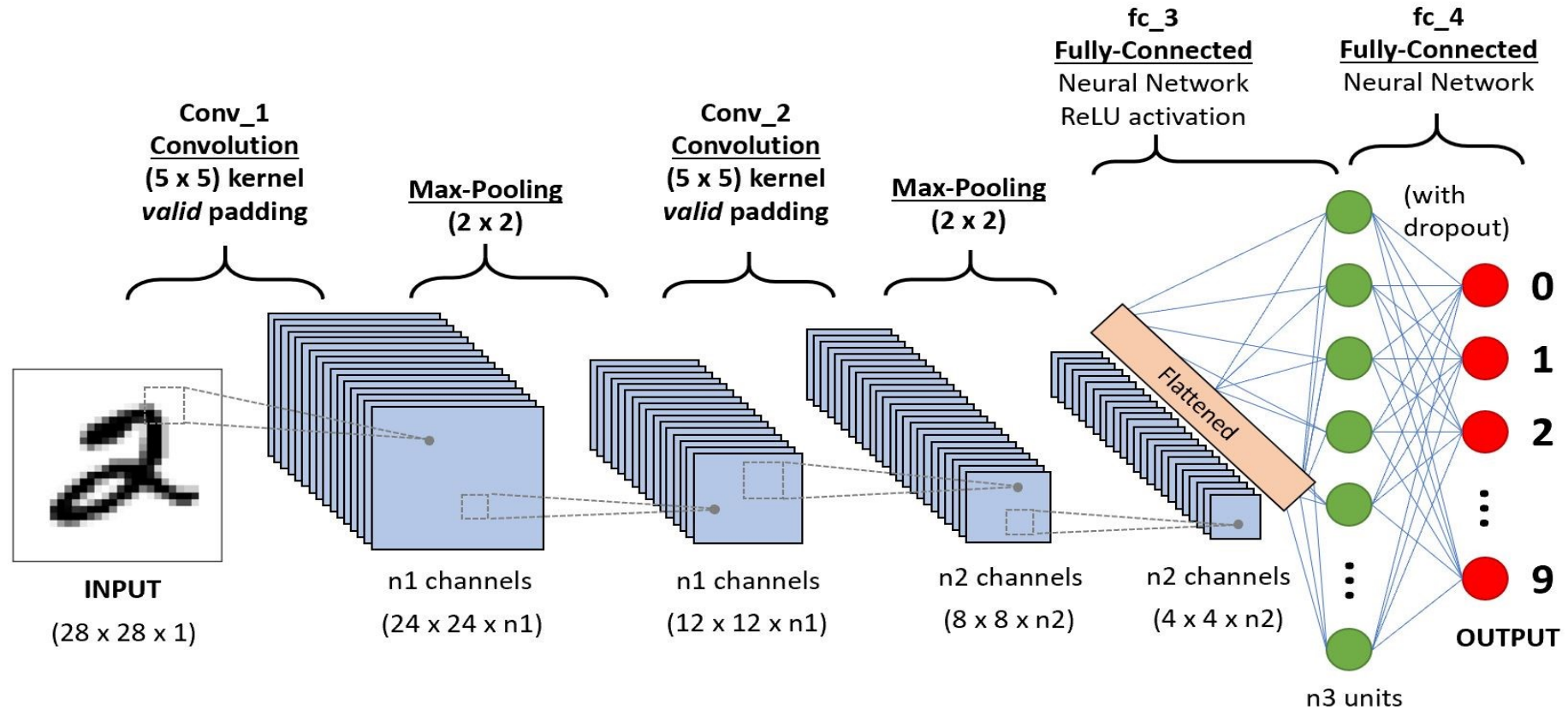
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CNN: Architectures: Overview

- The graph containing the Neural Network should contain the following components
 - The **input datasets**: the training and the test dataset and labels (and the validation dataset and labels).
 - The test and validation datasets can be placed inside a `tf.constant()`.
 - The training dataset is placed in a `tf.placeholder()` so that it can be feeded in batches during the training (stochastic gradient descent).
 - The **artificial neural network model** with all of its layers.
 - The **weight matrices and bias vectors** defined in the proper shape and initialized to their initial values. (One weight matrix and bias vector per layer.)
 - The **softmax cross-entropy and loss value**:
 - The model has as output the logit vector (estimated training labels).
 - By comparing the logit with the actual labels, it is possible to calculate the loss value (with the softmax with cross-entropy function).
 - The loss value is an indication of how close the estimated training labels are to the actual training labels and will be used to update the weight values.
 - An **optimizer**, which will use the calculated loss value to update the weights and biases with backpropagation.

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CNN: Architecture: Layers



Sources: Ryan P. Marchildon

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CNN: Build and Train Deep Learning Convolutional Neural Networks

Two phases: Building the convolutional neural network and train the network

- Phase 1: Build the convolutional neural network
 - Step 1: Create the 1st convolution layer (CONV) that uses ReLU as the activation function
 - Step 2: Create the 1st pooling layer (POOL) that works hand-in-hand with the convolution layer
 - Repeat Step 1 and 2 until finishing all the convolution and pooling layers have been created
 - Step 3: Create a reshape/flattening layer to reshape output data from the last pooling layer
 - Step 4: Create a fully-connected (FC) layer that accepts outputs from the reshape layer as its inputs
 - Repeat Step 4 to create other fully-connected layer if necessary
 - Step 5: Create a dropout layer to drop some of its inputs that it receives.

AI Deep Learning: Convolutional Neural Networks (CNN)

CNN: Build and Train Deep Learning Convolutional Neural Networks

Two phases: Building the convolutional neural network and train the network

- Phase 1: Build the convolutional neural network (Cont.)
 - Step 6: Create the final output layer, an FC layer, that accepts the outputs from the dropout layer as its inputs and produces the final outputs.
 - Step 7: Create the loss function to compute softmax cross entropy between the labels and the predicted outputs
 - *i.e., Measures **the probability error** in discrete classification tasks in which the **classes are mutually exclusive** (each entry is in exactly one class)*
 - Step 8: Create an optimizer to optimize the network
 - Step 9: Create a AI deep learning trainer to train the network
- Phase 2: Train the convolutional neural network
 - Train the network using the AI deep learning trainer created above