ITS202: Algorithms and Data Structure Shortest Paths

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December 6, 2020

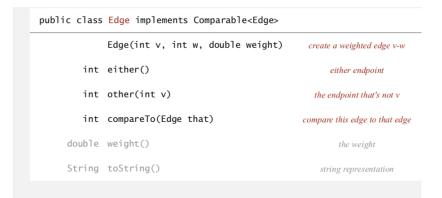
Edge-Weighted Graphs

An edge-weighted graph is a graph model where we associate weights or costs with each edge.

Types of Edge Weighted Graph

- Edge Weighted Graph
- 2 Edge Weighted Digraph

Weighted Undirected Edge API



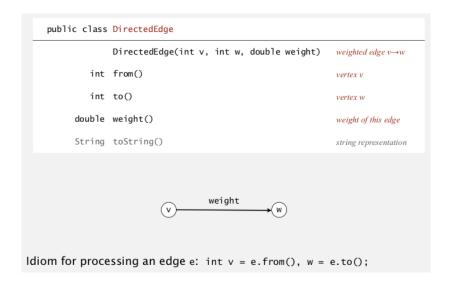


Idiom for processing an edge e: int v = e.either(), w = e.other(v);

Edge-Weighted graph API

public class EdgeWeightedGraph EdgeWeightedGraph(int V) create an empty graph with V vertices EdgeWeightedGraph(In in) create a graph from input stream void addEdge(Edge e) add weighted edge e to this graph Iterable<Edge> adi(int v) edges incident to v Iterable<Edge> edges() all edges in this graph int V() number of vertices int E() number of edges String toString() string representation

Weighted Directed Edge API



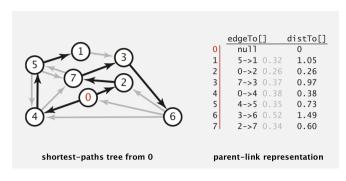
Edge-Weighted Digraph API

public class	EdgeWeightedDigraph	
	EdgeWeightedDigraph(int V)	edge-weighted digraph with V vertices
	EdgeWeightedDigraph(In in)	edge-weighted digraph from input stream
void	addEdge(DirectedEdge e)	add weighted directed edge e
Iterable <directededge></directededge>	adj(int v)	edges pointing from v
int	V()	number of vertices
int	E()	number of edges
Iterable <directededge></directededge>	edges()	all edges
String	toString()	string representation

Data structures for single-source shortest paths

Goal. Find the shortest path from s to every other vertex. Can represent the shortest-paths tree (SPT) with two vertex-indexed arrays:

- distTo[v] is length of shortest path from s to v.
- edgeTo[v] is last edge on shortest path from s to v.



Edge Relaxation

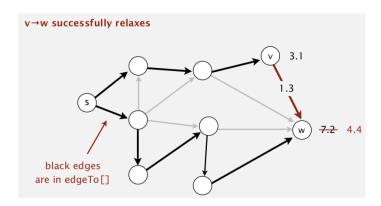
Relax edge $e = v \rightarrow w$.

- distTo[v] is length of shortest known path from s to v.
- distTo[w] is length of shortest known path from s to w.
- edgeTo[w] is last edge on shortest known path from s to w.
- If e = v→w gives shorter path to w through v, update both distTo[w] and edgeTo[w].

Edge Relaxation

Relax(u,v,w)

- if d[v] >= d[u] + w(u,v)
- $\bullet \longrightarrow \mathsf{d}[\mathsf{v}] = \mathsf{d}[\mathsf{u}] + \mathsf{w}(\mathsf{u},\mathsf{v})$



Generic shortest-paths algorithm

Generic algorithm (to compute SPT from s)

Initialize distTo[s] = 0 and distTo[v] = ∞ for all other vertices.

Repeat until optimality conditions are satisfied:

---->Relax any edge.

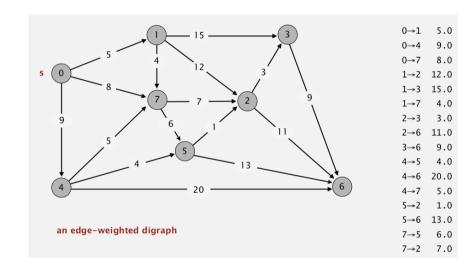
Efficient implementations. How to choose which edge to relax?

- 1. Dijkstra's algorithm (nonnegative weights).
- 2. Bellman-Ford algorithm (nonnegative cycles and nonnegative weights).

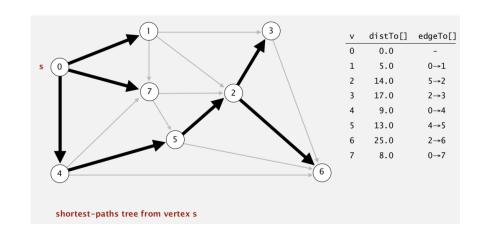
Dijkstra's algorithm

- Consider vertices in increasing order of distance from s (non-tree vertex with the lowest distTo[] value).
- Add vertex to tree and relax all edges pointing from that vertex.

Dijkstra's algorithm



Dijkstra's algorithm



Shortest paths with negative weights: failed attempts

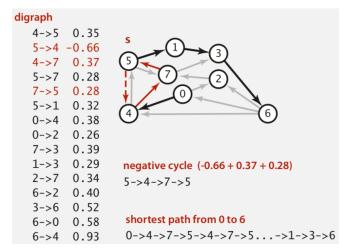
Dijkstra. Doesn't work with negative edge weights.



Conclusion. Need a different algorithm.

Negative cycles

Def. A negative cycle is a directed cycle whose sum of edge weights is negative.



Bellman-Ford algorithm

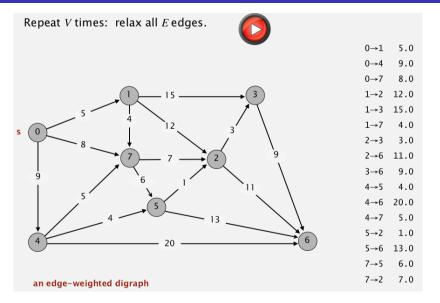
Bellman-Ford algorithm

Initialize distTo[s] = 0 and distTo[v] = ∞ for all other vertices.

Repeat V times:

- Relax each edge.

Bellman-Ford algorithm demo



Bellman-Ford algorithm demo

