

Paper Review

**Deep Residual Learning for Image
Recognition (2016 CVPR)**

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Contents

- Abstract
- Introduction
- Related Work
- Deep Residual Learning
- Experiments
- Conclusions

Abstract

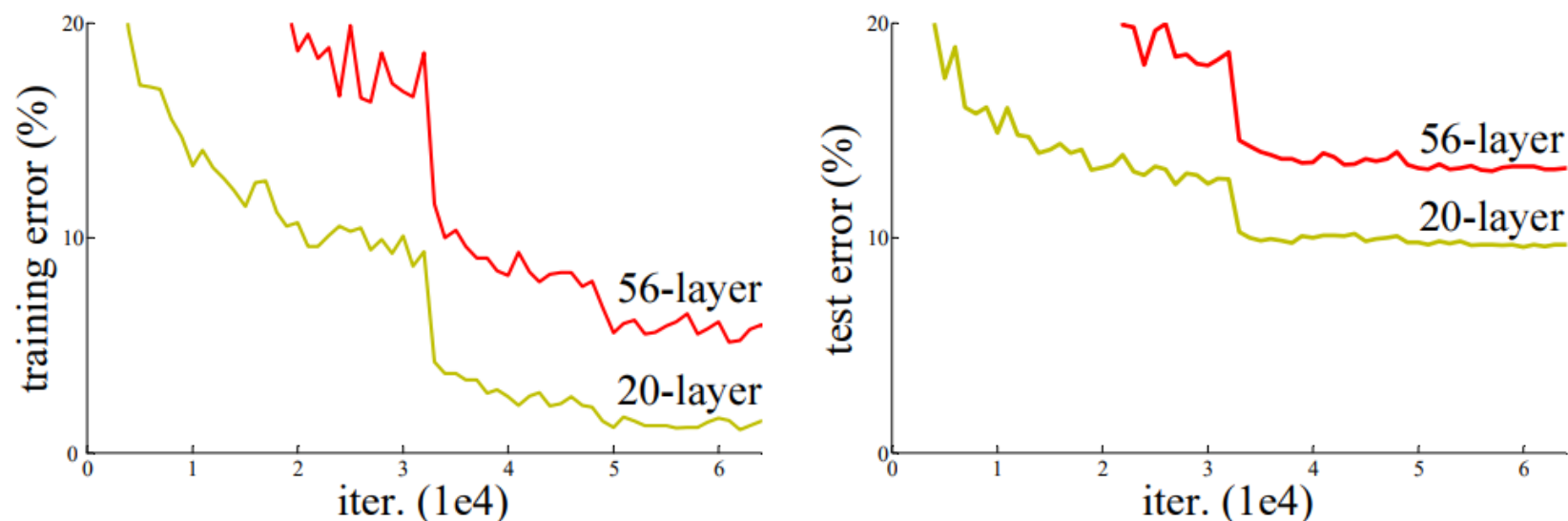


Figure 1. Training error (left) and test error (right) on CIFAR-10 with 20-layer and 56-layer “plain” networks. The deeper network has higher training error, and thus test error. Similar phenomena on ImageNet is presented in Fig. 4.

ResNet @ ILSVRC & COCO 2015 Competitions

1st places in all five main tracks

- ImageNet Classification : “Ultra-deep” 152-layer nets
- ImageNet Detection : 16% better than 2nd
- ImageNet Localization : 27% better than 2nd
- COCO Detection : 11% better than 2nd
- COCO Segmentation : 12% better than 2nd

**Is learning better networks
as simple as stacking more layers?**

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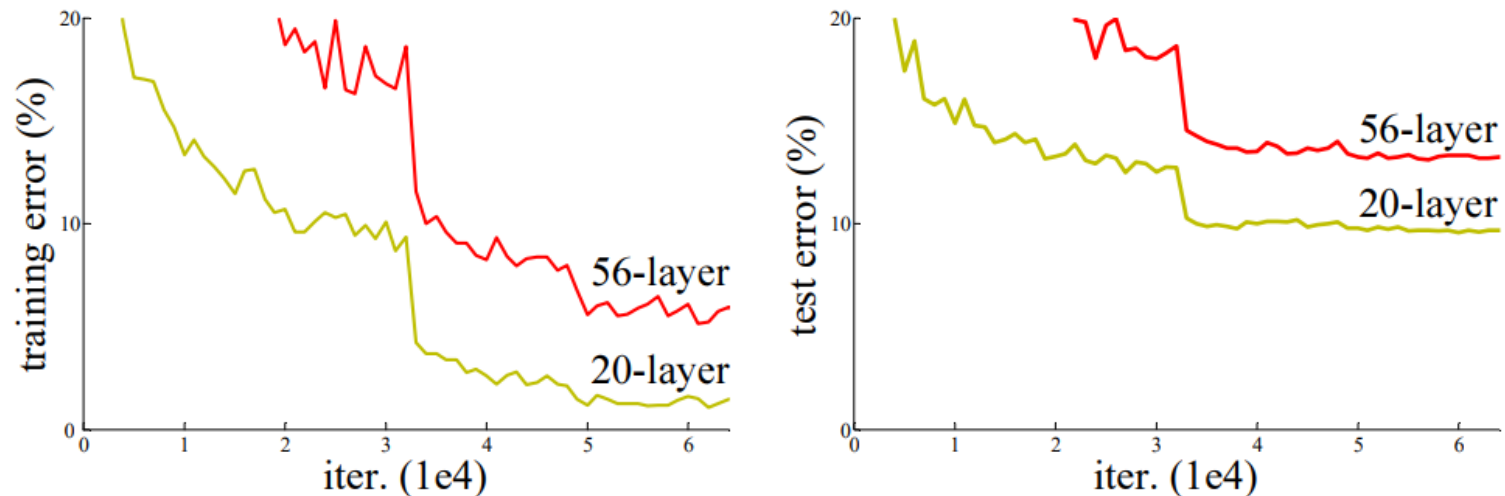
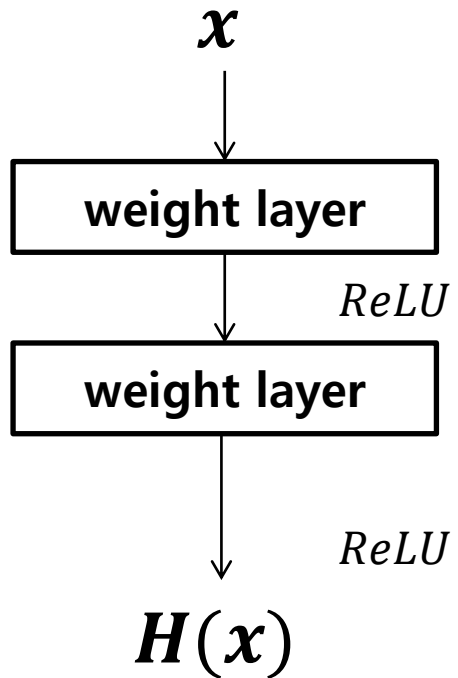


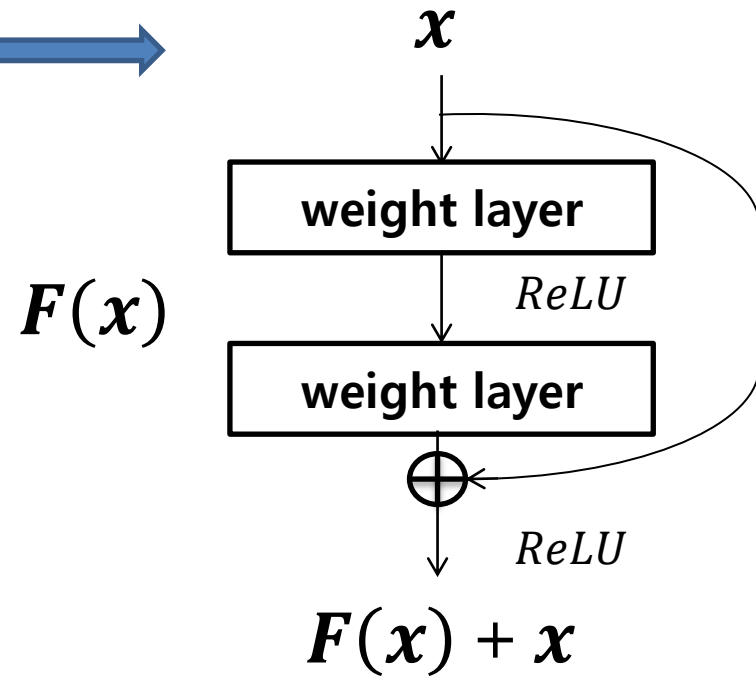
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Introduction

$$F(x) := H(x) - x$$



Plain Net



Residual block

Related Work

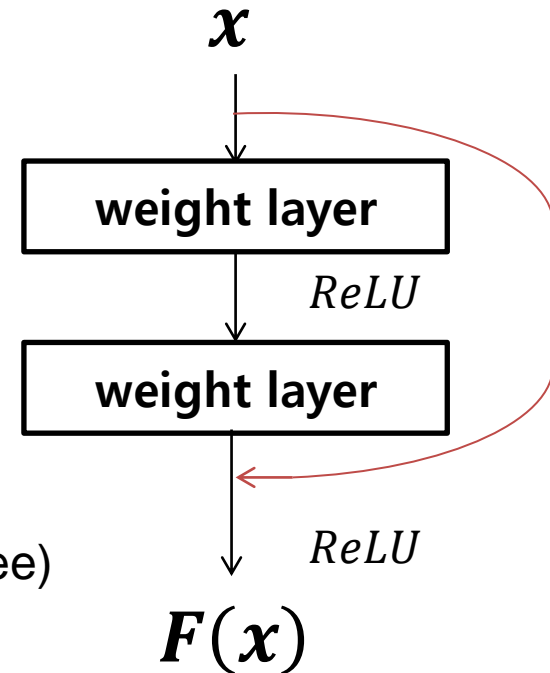
Shortcut Connection (Skip Connection)

GoogleNet vs ResNet

- Low parameter
- Not required Auxillary Classifier separately.

Highway Networks vs ResNet

- Low parameter (identity shortcut – parameter free)
- Not demonstrated accuracy gains with extremely increased depth (highway)

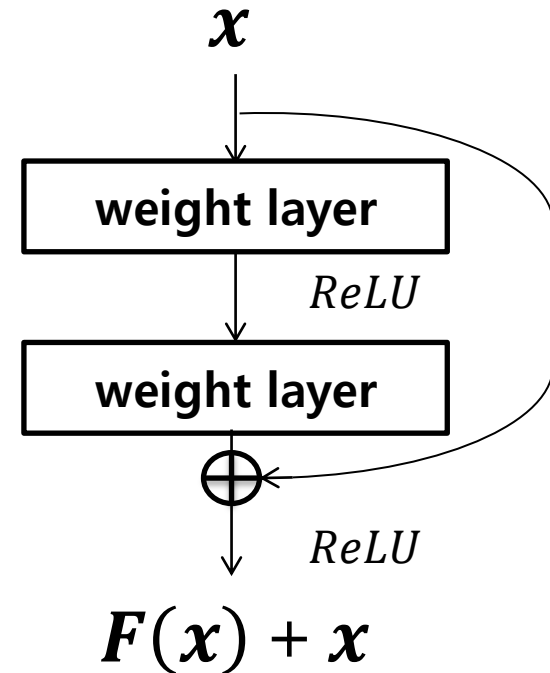


Deep Residual Learning

Residual Learning

- If identity were optimal, easy to set weights as 0
- If optimal mapping is closer to identity, easier to find small functions

$F(x)$



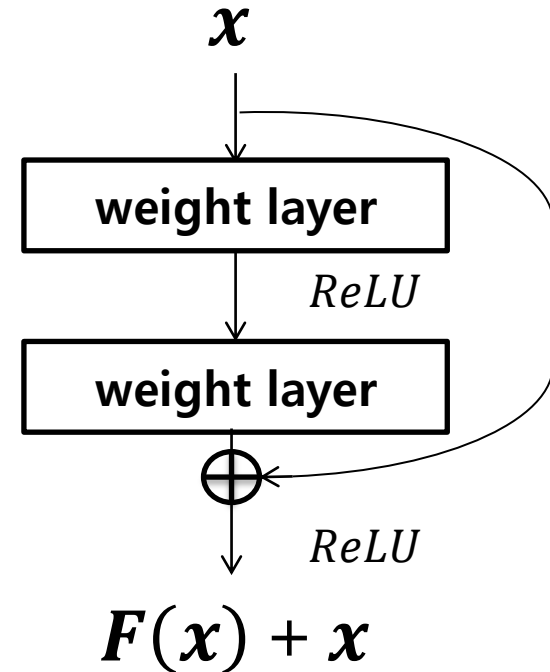
Residual block

Deep Residual Learning

Residual Learning

- If identity were optimal, easy to set weights as 0
- If optimal mapping is closer to identity, easier to find small functions

$$y = F(x, W_i) + W_s x$$



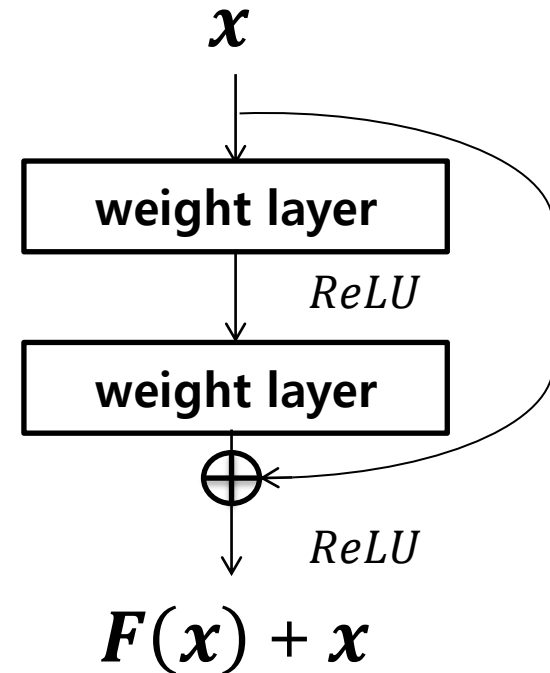
Residual block

Deep Residual Learning

Residual Learning

- If identity were optimal, easy to set weights as 0
- If optimal mapping is closer to identity, $F(x)$ easier to find small functions

$$y = W_1 x + x = (W_1 + 1)x$$



Residual block

Deep Residual Learning

Network Architectures

- Keep it simple
- Basic design (VGG-style)
 - All 3×3 conv (almost)
 - Spatial size / 2 => # filters × 2
 - Simple design; just deep!

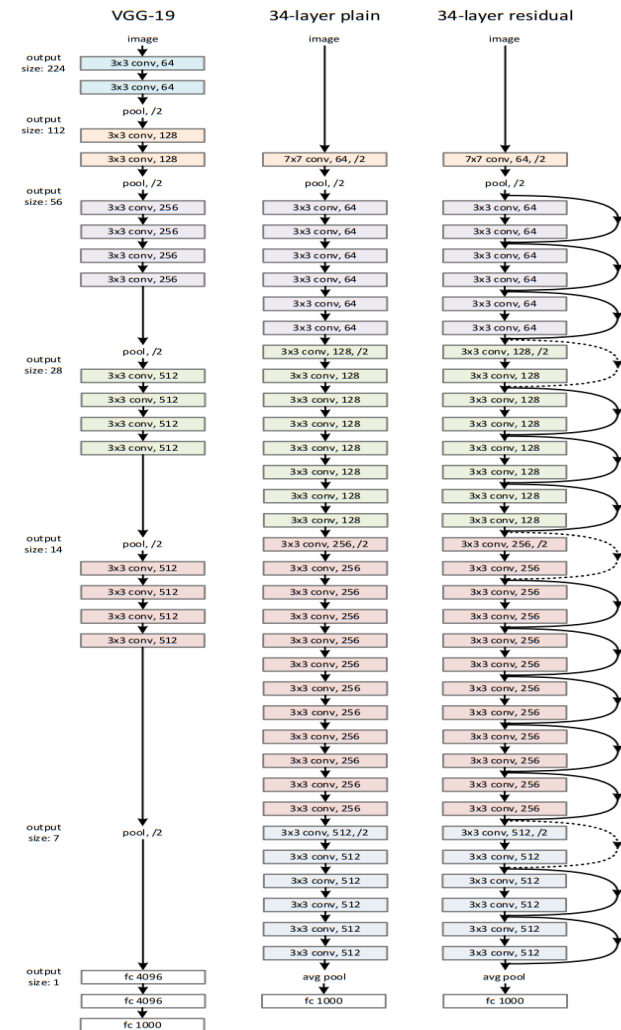


Figure 3. Example network architectures for ImageNet. **Left:** the VGG-19 model [41] (19.6 billion FLOPs) as a reference. **Middle:** a plain network with 34 parameter layers (3.6 billion FLOPs). **Right:** a residual network with 34 parameter layers (3.6 billion FLOPs). The dotted shortcuts increase dimensions. **Table 1** shows more details and other variants.

Deep Residual Learning

Network Architectures

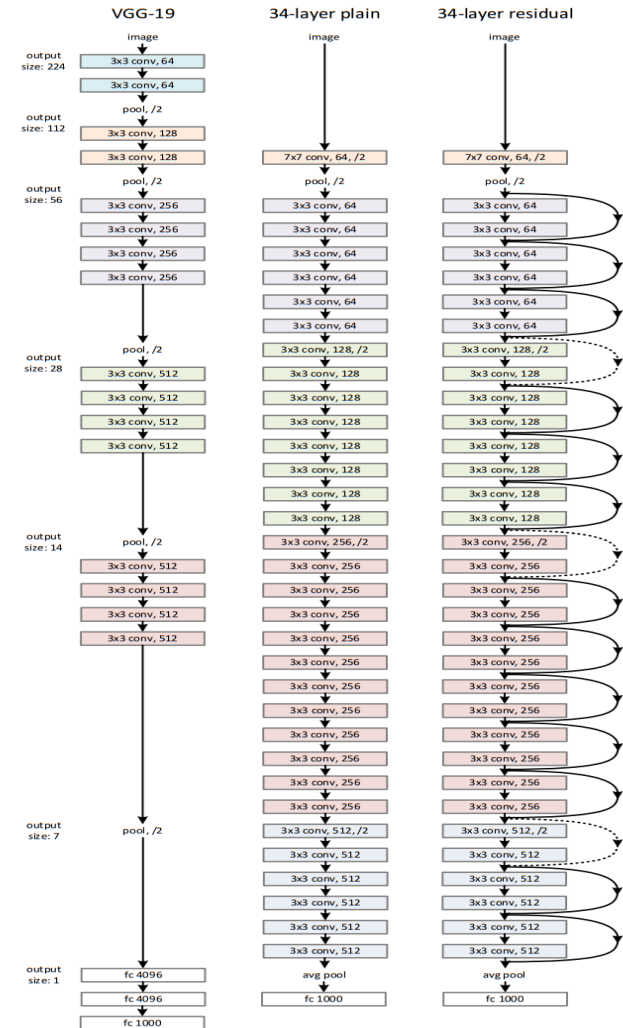
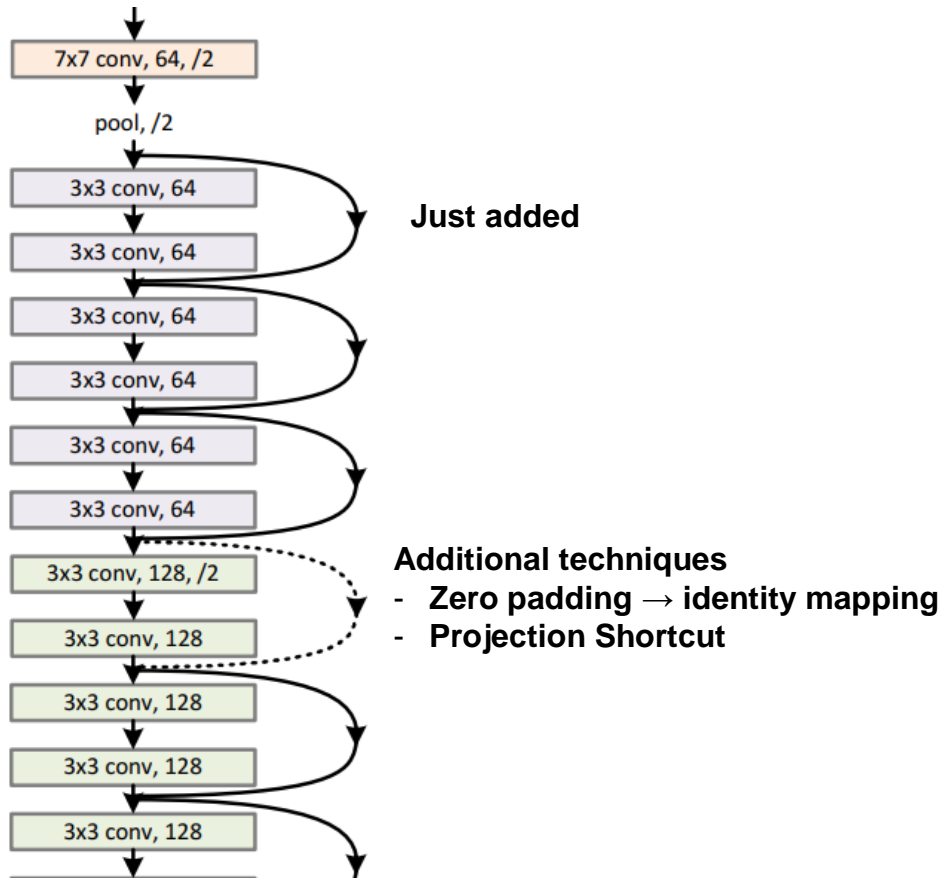
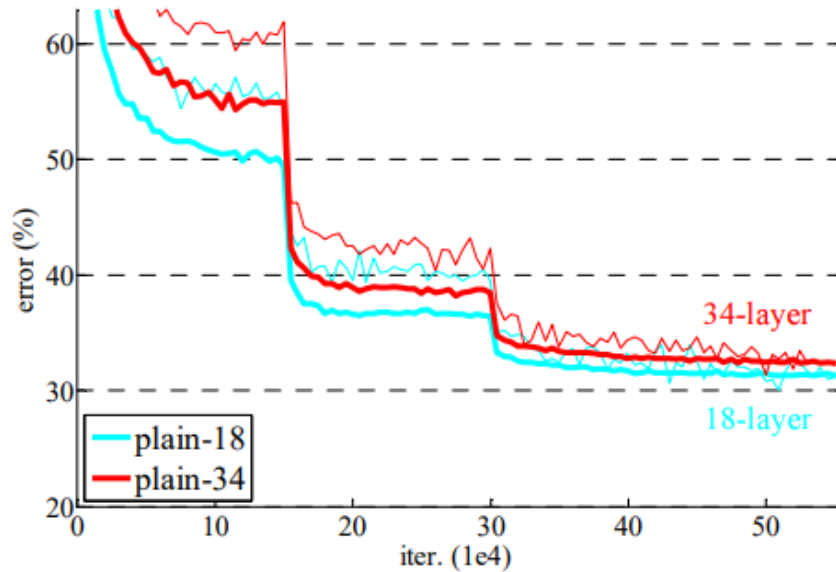


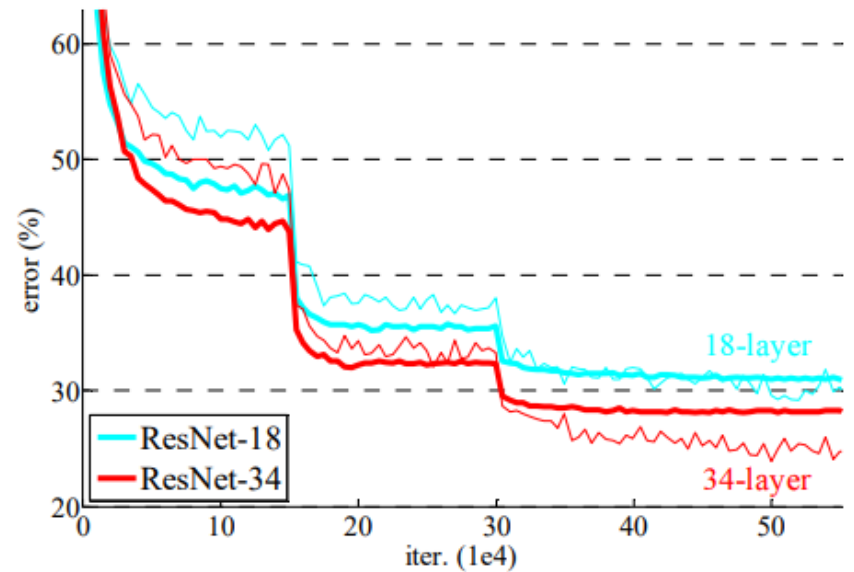
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Experiments

ImageNet experiments



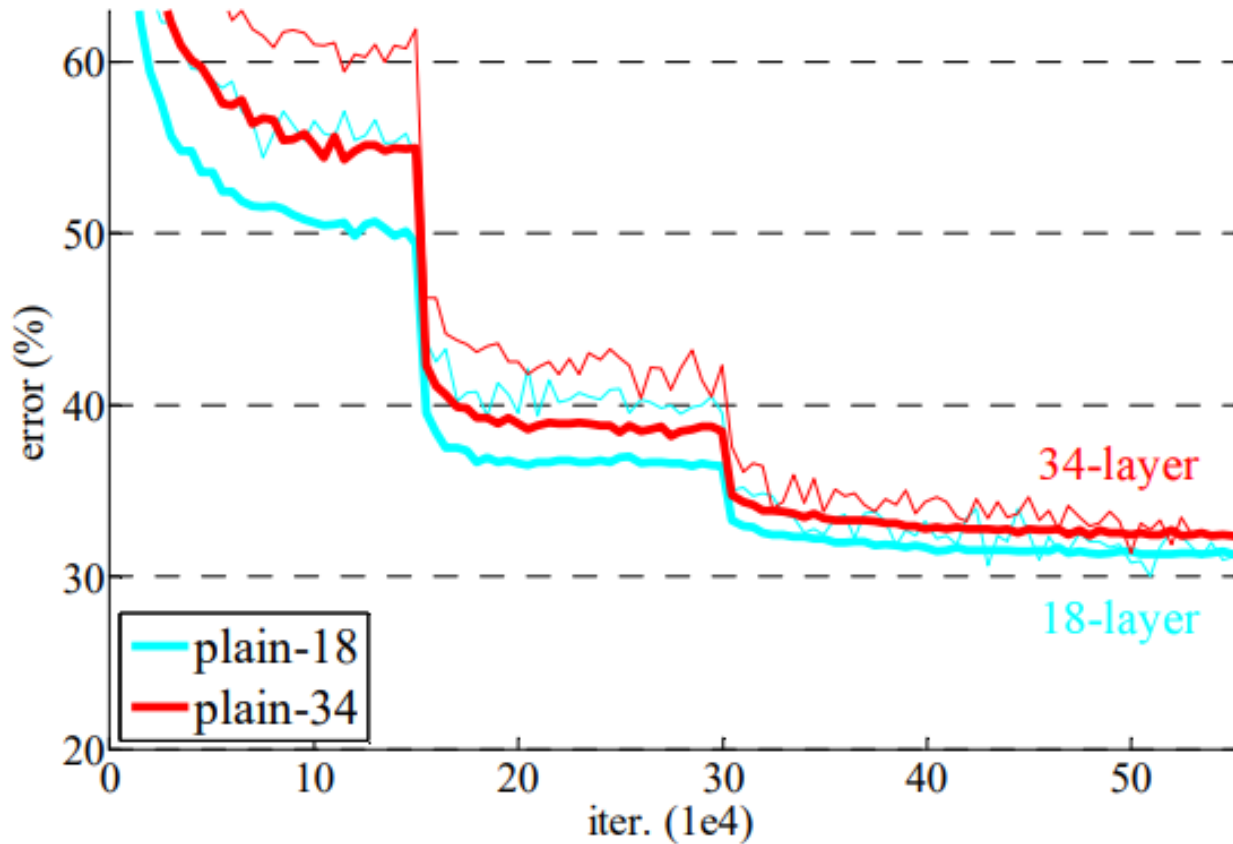
Plain networks of 18 and 34 layers.



ResNets of 18 and 34 layers.

Experiments

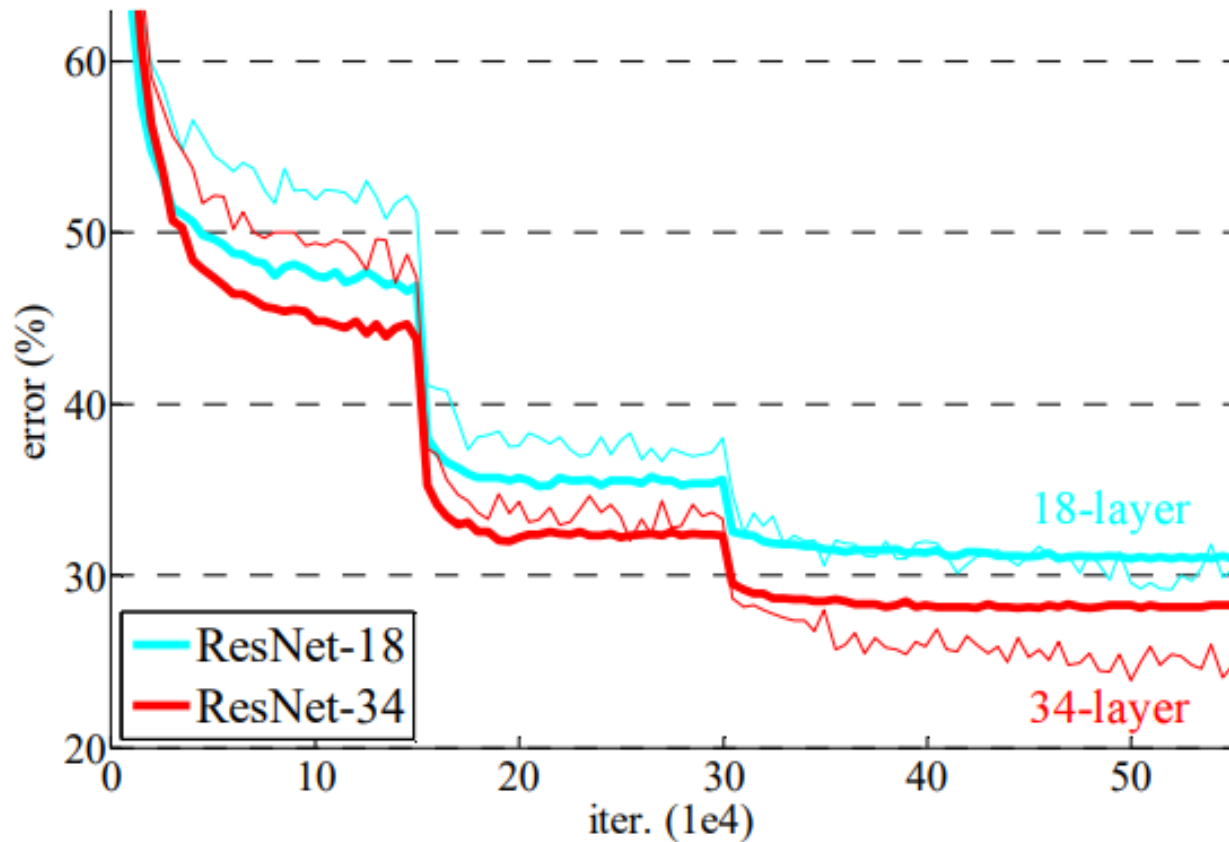
ImageNet experiments



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Experiments

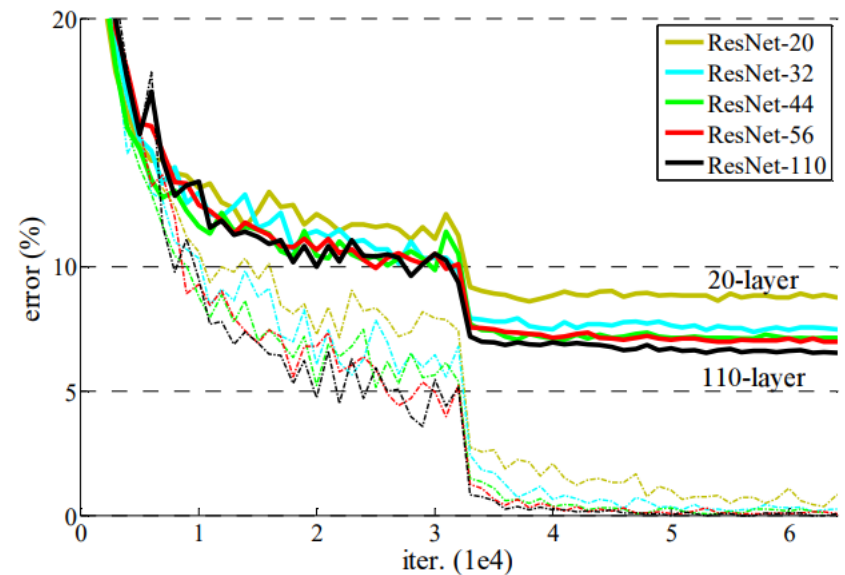
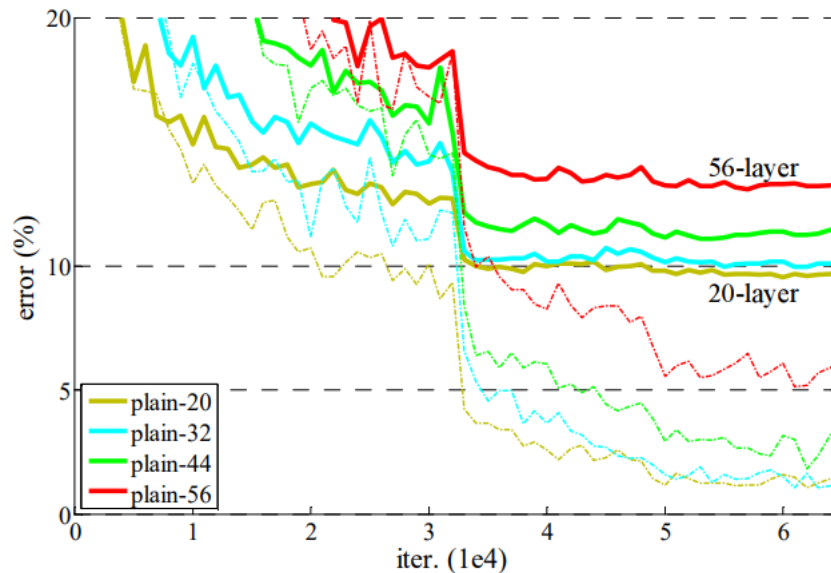
ImageNet experiments



ResNets of 18 and 34 layers.

Experiments

CIFAR-10 experiments



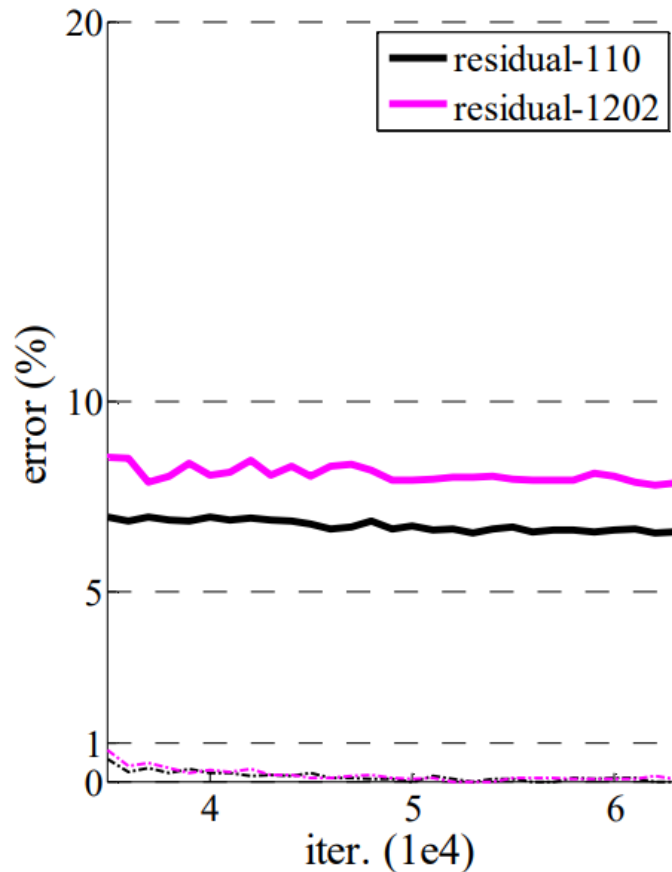
- Deep ResNets can be trained without difficulties
- Deeper ResNets have **lower training error**, and also **lower test error**

Experiments

**Does the performance continue to increase
if you continue to increase the layers of the model?**

Experiments

Does the performance continue to increase if you continue to increase the layers of the model?



No → Because of **overfitting**.

But it could be studied by adding regularization.

Conclusions

- **Deep Residual Networks:**
 - **Easy to train**
 - **Simply gain accuracy from depth**
 - **Well transferable**