# Dynamic Algorithms in Unit Disk Graphs

#### DALGO Lab

Pohang University of Science and Technology

November 10, 2023

#### Abstract

This research focuses on developing dynamic algorithms in unit disk graph for efficiently solving graph-based problems. First, we will present an efficient algorithm for the vertex cover problem. In our algorithm, updates require O(1) time, and we guarantee  $2^{O(\sqrt{k})}$  time for queries.

### 1 Introduction

The time complexity of the vertex cover problem for planar graphs is known as  $2^{O(\sqrt{k})}n^{O(1)}$  [1]. In our approach, we maintain the number of vertices in the kernel at O(k), which ensures a time complexity of  $2^{O(\sqrt{k})}$ .

We employ a grid wherein each cell's diagonal is of unit length, thereby ensuring that all vertices in a single cell constitute a clique. When analyzing a given cell,  $5 \times 5$  grid centered on that cell will be used. the term "cell around" and "neighborhood" refer to the adjacent  $5 \times 5$  grid of cells surrounding a given cell. Cells are named with distinct names based on  $V_C$ , which is number of vertices in the cell C.

- 1. if  $V_C$  is greater than or equal to k+2, saturated cell
- 2. if  $V_C$  is greater than 2 and less than or equal to k+1, friendly cell
- 3. if  $V_C = 1$ , lonely cell
- 4. if  $V_C = 0$ , empty cell

## 2 Algorithm

In this section, we will explain our data structure and the algorithms for updates and queries.

#### 2.1 Data structure

In order to dynamically maintain the kernel, we will preserve this data.

- 1. for each cell C, all the vertices in this cell and  $V_C$
- 2. Number of saturated cell,  $N_S$
- 3. Number of friendly cell,  $N_f$
- 4. Set of edges between lonely cells,  $E_l$

#### 2.2 Insertion

In this section, we will show how to maintain the kernel during the vertex insertion process.

First,  $V_C$  of the cell which contains the new vertex  $V_{new}$  is increased by 1. Determine cells that have become lonely cells from isolated lonely cells and include them in the kernel. If  $V_C$  is greater than k+2, we do nothing with the data structure. If  $V_C$  is equal to k+2, this means this cell is friendly cell before the insertion, but now it is saturated cell. So decrease  $N_f$  by 1 and increase  $N_s$  by 1. Also, delete this cell from the kernel. If  $V_C$  is greater than 3 and less than k+1, include  $V_{new}$  in the kernel. If  $V_C$  is equal to 2, increase  $N_f$  by 1 and include  $V_{new}$  and one other vertex in the kernel. Also, vertices in lonely cells within the surrounding  $5 \times 5$  grid are also included in the kernel. Next, now this cell is no longer a lonely cell, the edges between lonely cells around this cell are removed from  $E_l$ . If  $V_C$  is equal to 1, check the surrounding  $5 \times 5$  grid and calculating the edge between lonely cells to include these edges in  $E_l$ . Next, if at least one cell is friendly cell, include  $V_{new}$  in the kernel. If all the surrounding cells are lonely cells and lonely cells, determine whether this vertex is isolated. if the vertex is isolated, do nothing. Else if the vertex is not isolated, include  $V_{new}$  in the kernel.

#### 2.3 Deletion

In this section, we will show how to maintain the kernel during the vertex deletion process.

First,  $V_C$  of the cell which contains the deleted vertex  $V_{del}$  is decreased by 1 and delete  $V_{del}$  from the kernel. Determine the lonely cell that has become isolated by deleting the vertex and remove it from the kernel. If  $V_C$  is greater than or equal to k+2, do nothing. If  $V_C$  is equal to k+1, this means this cell is saturated cell before the deletion, but now it is friendly cell. So decrease  $N_s$  by 1 and increase  $N_f$  by 1. And this cell and all lonely cells around are added to the kernel. If  $V_C$  is greater than 1 and less than k+1, do nothing. If  $V_C$  is equal to 1, decrease  $N_f$  by 1. Check the surrounding  $5 \times 5$  grid and calculate the edge between this cell and lonely cells to update  $E_l$ . If at least one cell is friendly cell, the remaining one vertex is still kept in the kernel as before. If all the surrounding cells are lonely cells and empty cells, determine whether this vertex is isolated. If the vertex is isolated, remove one remaining vertex from the kernel. Else if the vertex is not isolated, the vertex is still kept in the kernel as before. If  $V_C$  is equal to 0, determines the isolation of surrounding cells and if isolated, removes them from the kernel.

## 2.4 Query

For the vertex cover query, algorithm operates as follows.

If  $N_s$  is greater than or equal to 1, k vertex cover is impossible. If  $N_f$  is greater than k, k vertex cover is impossible. if  $|E_l|$  is greater than 20k, k vertex cover is impossible. Else, vertex cover algorithm is performed on the kernel that we maintain.

## 3 Correctness

We need to make sure that the vertex cover of the kernel is same as the vertex cover of the original graph. We also prove the bounds on the number of vertices in the kernel and analyze its time complexity.

### 3.1 Correctness of the algorithm

First, presence of a saturated cell implies we need to select at least k+1 vertices for vertex cover to address a clique consisting of k+2 or more vertices. Therefore, k vertex cover is impossible. Next, if the number of friendly cell is greater than k+1, k vertex cover is impossible because at least one vertex in friendly cell is selected for vertex cover, Last, if  $|E_l|$  is greater than 20k, more than k vertices are needed to cover this all edges because one lonely cells can cover up to  $20 \ lonely \ cells$  around.

Except for the above cases, we have four kinds of edges: edges within the same cell, between friendly cells, between friendly cells and lonely cells, between lonely cells. Because all the vertices in friendly cells are included in the kernel, all edges between vertices in the same cell is covered. Similarly, edges between friendly cells are all included in the kernel. Edges between friendly cells and lonely cells are covered by including lonely cells which have friendly cells as neighborhood in the kernel. Edges between lonely cells are covered because isolated vertex in lonely cells were removed from the kernel and the rest were included in the kernel.

#### 3.2 Number of vertices in kernel

By summing up the number of the vertices in *friendly cells* and *lonely cells*, we can get total number of vertices in the kernel.

For each  $friendly\,cell\,\,C,\,\,V_C-1$  vertices must be included in the vertex cover. For k vertex cover, the size of vertex cover is less than or equal to k. So for all  $friendly\,cells$ ,  $\sum_C V_C - N_f \leq k$ . Using the fact that  $N_f$  is less than k+1, the number of vertices in all  $friendly\,cells$  is less than 2k+1.

Lonely cells can be separated into two types depending on the presence of friendly cells around. The number of friendly cells is less than or equal to k, and each friendly cell can only cover constant number of lonely cells, so the number of lonely cells which have at leat one friendly cell as neighborhood is O(k). Lonely cell that are surrounded by only lonely cells or empty cells has constant number of edge because we remove isolated lonely cell from kernel. In this case, O(k) edges can exist between lonely cell, so the number of vertices in lonely cell is O(k).

Through the above two processes, both of friendly cells and lonely cells in the kernel contain O(k) vertices. Finally, total number of vertices in the kernel is O(k).

## 3.3 Time complexity

In the update process, dealing with  $V_C$ ,  $N_f$  and  $N_S$  takes O(1) time. Determining cell isolation takes O(1) time because we only need to consider constant number of lonely cells around it. Similarly, finding the *friendly cells* and *lonely cells* around the cell also takes constant time. Calculating the edge between *lonely cells* only requires checking constant number of surrounding cells. So each update takes O(1) time.

In 3.2 we show that the total number of vertices in the kernel is O(k). So  $2^{O(\sqrt{k})}$  is guaranteed for each query.

# References

[1] Erik D Demaine, Fedor V Fomin, Mohammadtaghi Hajiaghayi, and Dimitrios M Thilikos. Subexponential parameterized algorithms on bounded-genus graphs and h-minor-free graphs. *Journal of the ACM (JACM)*, 52(6):866–893, 2005.