

# Assignment 2

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## Question 1

According to the definition of norm, the equation  $\|\mathbf{x} - \mathbf{x}_0\|_2 \leq \|\mathbf{x} - \mathbf{x}_1\|_2$  is the same as:

$$(\mathbf{x} - \mathbf{x}_0)^T(\mathbf{x} - \mathbf{x}_0) \leq (\mathbf{x} - \mathbf{x}_1)^T(\mathbf{x} - \mathbf{x}_1)$$

Which can be further expressed as:

$$\mathbf{x}^T(\mathbf{x}_1 - \mathbf{x}_0) + (\mathbf{x}_1 - \mathbf{x}_0)^T \mathbf{x} \leq \mathbf{x}_1^T \mathbf{x}_1 - \mathbf{x}_0^T \mathbf{x}_0 \quad (1)$$

Since  $\mathbf{x}^T(\mathbf{x}_1 - \mathbf{x}_0) = ((\mathbf{x}_1 - \mathbf{x}_0)^T \mathbf{x})^T$ , which produce a constant, we have:

$$\mathbf{x}^T(\mathbf{x}_1 - \mathbf{x}_0) = (\mathbf{x}_1 - \mathbf{x}_0)^T \mathbf{x} \quad (2)$$

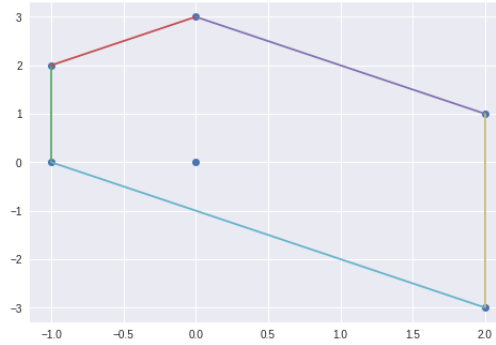
Replace equation 2 to equation 1, there is:

$$2(\mathbf{x}_1 - \mathbf{x}_0)^T \mathbf{x} \leq \mathbf{x}_1^T \mathbf{x}_1 - \mathbf{x}_0^T \mathbf{x}_0$$

Which follow the definition of half-space:  $\lambda^T \mathbf{x} \leq \mathbf{b}$ , where  $\lambda = 2(\mathbf{x}_1 - \mathbf{x}_0)$  and  $\mathbf{b} = \mathbf{x}_1^T \mathbf{x}_1 - \mathbf{x}_0^T \mathbf{x}_0$ .

## Question 2

The polyhedron constructed by the convex hull is the area with the 5 color line as boundary, shown in following figure:



Denote  $\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$  as the point within  $\mathcal{R}^2$ , the hyper-plane defined by the 5 color line shown in above figure are:

$$\begin{bmatrix} -1 & 0 \\ 1 & 1 \\ 1 & 0 \\ 1 & 1 \end{bmatrix} \mathbf{x} = \begin{bmatrix} -1 \\ -1 \\ 2 \\ 3 \end{bmatrix}$$

As a result, the polyhedron constructed by these hyper-plane can be expressed as:

$$\mathcal{A}\mathbf{x} \preceq \mathbf{b}$$

$$\text{Where } \mathcal{A} = \begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 0 \\ 1 & 1 \end{bmatrix} \text{ and } \mathbf{b} = \begin{bmatrix} -1 \\ -1 \\ 2 \\ 3 \end{bmatrix}$$

### Question 3

(a)

Denote set  $\{\mathbf{x} | \alpha \leq \mathbf{a}^T \mathbf{x} \leq \beta\}$  as  $\mathcal{C}$ , then,  $\mathcal{C}$  is a convex set. The prove is as follow:

Assume  $\mathbf{x}_1, \mathbf{x}_2 \in \mathcal{C}$ , their convex combination follow:

$$\mathbf{a}^T(\theta \mathbf{x}_1 + (1 - \theta) \mathbf{x}_2) = \theta \mathbf{a}^T \mathbf{x}_1 + (1 - \theta) \mathbf{a}^T \mathbf{x}_2 \quad (3)$$

Since  $\mathbf{x}_1, \mathbf{x}_2 \in \mathcal{C}$ , there is:

$$\begin{cases} \mathbf{a}^T \mathbf{x}_1 \geq \alpha \\ \mathbf{a}^T \mathbf{x}_2 \geq \alpha \end{cases} \quad (4)$$

Combine equation 3 and 4, we have:

$$\begin{aligned} \theta \mathbf{a}^T \mathbf{x}_1 + (1 - \theta) \mathbf{a}^T \mathbf{x}_2 &\geq \theta \alpha + (1 - \theta) \alpha \\ &= \alpha \end{aligned}$$

The equation  $\theta \mathbf{a}^T \mathbf{x}_1 + (1 - \theta) \mathbf{a}^T \mathbf{x}_2 \leq \beta$  can be proved by using the same method. As a result, when  $\mathbf{x}_1, \mathbf{x}_2 \in \mathcal{C}$ ,  $\theta \mathbf{x}_1 + (1 - \theta) \mathbf{x}_2 \in \mathcal{C}$  hold for any  $0 \leq \theta \leq 1$ . Thus,  $\mathcal{C}$  is a convex set.

(b)

The *rectangle* set  $\mathcal{G}$  can be thought as the intersection of different sets that follow:

$$\mathcal{G} = \bigcap_{i=1}^n \mathcal{G}_i$$

Where  $\mathcal{G}_i$  is the set:  $\{\mathbf{x} | \alpha \leq x_i \leq \beta\}$ . It is obvious that  $\mathcal{G}_i$  is the *slab* defined in (a) with

$$\mathbf{a} = \begin{bmatrix} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{bmatrix}$$

In which, the  $i$ th element  $a_i$  that corresponding to  $x_i$  within  $\mathbf{x}$  is set to be 1 and the other elements is 0. Therefore,  $\mathcal{G}_i$  is convex, which means,  $\mathcal{G}$  is the intersection of convex set, which is also convex.

(c)

The set  $\{\mathbf{x} | \mathbf{a}_1^T \mathbf{x} \leq b_1, \mathbf{a}_2^T \mathbf{x} \leq b_2\}$  is the same as:

$$\{\mathbf{x} | \mathbf{a}_1^T \mathbf{x} \leq b_1\} \cap \{\mathbf{x} | \mathbf{a}_2^T \mathbf{x} \leq b_2\}$$

For any  $i \in \{1, 2\}$ , the set  $\{\mathbf{x} | \mathbf{a}_i^T \mathbf{x} \leq b_i\}$  define a half-space, which is a convex set. As a result, the set  $\{\mathbf{x} | \mathbf{a}_1^T \mathbf{x} \leq b_1, \mathbf{a}_2^T \mathbf{x} \leq b_2\}$  is the intersection of two convex set, which is also convex.

(d)

Assume  $\mathcal{S} = \{\mathbf{s}_1, \mathbf{s}_2, \dots, \mathbf{s}_n\}$ . The original set  $\{\mathbf{x} | \|\mathbf{x} - \mathbf{x}_0\|_2 \leq \|\mathbf{x} - \mathbf{s}\|_2 \text{ for any } \mathbf{s} \in \mathcal{S}\}$  can be expressed as:

$$\bigcap_{i=1}^n \{\mathbf{x} | \|\mathbf{x} - \mathbf{x}_0\|_2 \leq \|\mathbf{x} - \mathbf{s}_i\|_2\}$$

The same concept can be expanded to set  $\mathcal{S}$  which has infinite element ( $n \rightarrow \infty$ ). According to Question 1, the single set  $\{\mathbf{x} | \|\mathbf{x} - \mathbf{x}_0\|_2 \leq \|\mathbf{x} - \mathbf{s}_i\|_2\}$  define a half-space and is convex. As a result, the intersection of these convex is also convex, which means,  $\{\mathbf{x} | \|\mathbf{x} - \mathbf{x}_0\|_2 \leq \|\mathbf{x} - \mathbf{s}\|_2 \text{ for any } \mathbf{s} \in \mathcal{S}\}$  is convex.

(e)

We first consider the set:

$$\mathcal{G}_i = \{\mathbf{x} \mid \|\mathbf{x} - \mathbf{s}_i\|_2 \leq \|\mathbf{x} - \mathbf{s}\|_2 \text{ for all } \mathbf{s} \in \mathcal{S}\} \quad (5)$$

Where  $\mathbf{s}_i \in \mathcal{S}$  is a fixed point within  $\mathcal{S}$ . This set is consist of points  $\mathbf{x}$  that have the minimum distance to  $\mathcal{S}$  through  $\mathbf{s}_i$ . It is obvious that

$$\{\mathbf{x} \mid \|\mathbf{x} - \mathbf{s}_i\|_2 \leq \|\mathbf{x} - \mathbf{s}\|_2\} \cap \{\mathbf{x} \mid \|\mathbf{x} - \mathbf{s}_j\|_2 \leq \|\mathbf{x} - \mathbf{s}\|_2\} = \emptyset \quad (6)$$

when  $\mathbf{s}_i, \mathbf{s}_j \in \mathcal{S}$  and  $\mathbf{s}_i \neq \mathbf{s}_j$  as a point  $\mathbf{x}$  can only achieve the minimum distance to  $\mathcal{S}$  by hold  $\|\mathbf{x} - \mathbf{s}_i\| < \|\mathbf{x} - \mathbf{s}_j\|$  or the inverse. Now assume  $\mathcal{S} = \{\mathbf{s}_1, \mathbf{s}_2, \dots, \mathbf{s}_n\}$  and  $\mathcal{T} = \{\mathbf{t}_1, \mathbf{t}_2, \dots, \mathbf{t}_k\}$ . We define the set:

$$\mathcal{Q}_i = \{\mathbf{x} \mid \|\mathbf{x} - \mathbf{s}_i\|_2 \leq \|\mathbf{x} - \mathbf{t}\|_2 \text{ for all } \mathbf{t} \in \mathcal{T}\}$$

Where  $\mathbf{s}_i \in \mathcal{S}$ . This set describe the point  $\mathbf{x}$  that the distance between  $\mathbf{x}$  and a point  $\mathbf{s}_i \in \mathcal{S}$  is less than the distance between  $\mathbf{x}$  and set  $\mathcal{T}$ . As a result, the set  $\{\mathbf{x} \mid \text{dist}(\mathbf{x}, \mathcal{S}) < \text{dist}(\mathbf{x}, \mathcal{T})\}$  can be then expressed as:

$$\bigcup_{i=1}^n (\mathcal{G}_i \cap \mathcal{Q}_i)$$

According to equation 6, for any  $1 \leq i, j \leq n$ ,  $\mathcal{G}_i \cap \mathcal{G}_j = \emptyset$ . Hence,  $(\mathcal{G}_i \cap \mathcal{Q}_i) \cup (\mathcal{G}_j \cap \mathcal{Q}_j) = \emptyset$ , which means, the set  $\{\mathbf{x} \mid \text{dist}(\mathbf{x}, \mathcal{S}) < \text{dist}(\mathbf{x}, \mathcal{T})\}$  is separated and therefore can not be convex.

(f)

Assume  $\mathcal{S}_1 = \{\mathbf{s}_1, \mathbf{s}_2, \dots, \mathbf{s}_n\}$ . Then, the set  $\mathcal{C} = \{\mathbf{x} \mid \mathbf{x} + \mathcal{S}_1 \subset \mathcal{S}_2\}$  can be replaced as the intersection of different set as:

$$\mathcal{C} = \bigcap_{i=1}^n \mathcal{C}_i$$

Where  $\mathcal{C}_i = \{\mathbf{x} \mid \mathbf{x} + \mathbf{s}_i \in \mathcal{S}_2\}$ . It can be proved that  $\mathcal{C}_i$  is convex: Assume  $\mathbf{x}_1, \mathbf{x}_2 \in \mathcal{C}_i$ . The equation  $\theta \mathbf{x}_1 + (1 - \theta) \mathbf{x}_2 + \mathbf{s}_i$  can be expressed as:

$$\theta \mathbf{x}_1 + (1 - \theta) \mathbf{x}_2 + \mathbf{s}_i = \theta(\mathbf{x}_1 + \mathbf{s}_i) + (1 - \theta)(\mathbf{x}_2 + \mathbf{s}_i)$$

Since  $\mathbf{x}_1 + \mathbf{s}_i, \mathbf{x}_2 + \mathbf{s}_i \in \mathcal{S}_2$  and  $\mathcal{S}_2$  is convex, we have  $\theta(\mathbf{x}_1 + \mathbf{s}_i) + (1 - \theta)(\mathbf{x}_2 + \mathbf{s}_i) \in \mathcal{S}_2$ . Hence,  $\mathcal{C}_i$  is convex. As a result,  $\mathcal{C}$  is convex as it is the intersection of convex set.

(g)

The equation  $\|\mathbf{x} - \mathbf{a}\|_2 \leq \theta \|\mathbf{x} - \mathbf{b}\|_2$  is the same as  $\|\mathbf{x} - \mathbf{a}\|_2^2 \leq \theta^2 \|\mathbf{x} - \mathbf{b}\|_2^2$ . Now, let  $\theta^2 = p$ , the equation mentioned before can be expanded as:

$$\mathbf{x}^T \mathbf{x} + \frac{2(p\mathbf{b} - \mathbf{a})^T}{1 - p} \mathbf{x} + \frac{\mathbf{a}^T \mathbf{a} - p\mathbf{b}^T \mathbf{b}}{1 - p} \leq 0 \quad (7)$$

Which has the same form as the equation that describe a ball:

$$\|\mathbf{x} - \mathbf{x}_0\|_2^2 = \mathbf{x}^T \mathbf{x} - 2\mathbf{x}_0^T \mathbf{x} + \mathbf{x}_0^T \mathbf{x}_0 \leq r^2 \quad (8)$$

Compare equation 7 with 8, it is easy to figure out that:

$$\mathbf{x}_0 = \frac{\mathbf{a} - p\mathbf{b}}{1 - p} \text{ and } r^2 = \mathbf{x}_0^T \mathbf{x}_0 - \frac{\mathbf{a}^T \mathbf{a} - p\mathbf{b}^T \mathbf{b}}{1 - p}$$

If  $r^2 \geq 0$  can be verified, then, equation 7 always describe a ball. Indeed,  $r^2$  can be expanded as:

$$r^2 = \frac{(\mathbf{a} - p\mathbf{b})^T (\mathbf{a} - p\mathbf{b})}{(1 - p)^2} - \frac{\mathbf{a}^T \mathbf{a} - p\mathbf{b}^T \mathbf{b}}{1 - p}$$

Which is the same as:

$$r^2 = \frac{p(\mathbf{a}^T \mathbf{a} - 2\mathbf{a}^T \mathbf{b} + \mathbf{b}^T \mathbf{b})}{(1 - p)^2}$$

Since  $\mathbf{a}^T \mathbf{a} - 2\mathbf{a}^T \mathbf{b} + \mathbf{b}^T \mathbf{b} = \|\mathbf{a} - \mathbf{b}\|_2^2 \geq 0$ ,  $r^2$  is also greater or equal to zero. Hence, equation 7 describe a ball, which is a convex set.

## Question 4

In this question, we firstly define the vector:

$$\mathbf{x} = \begin{bmatrix} a_0 \\ a_1 \\ \vdots \\ a_n \end{bmatrix} \quad (9)$$

Which contain all possible value that random variable  $x$  may take. After that, the vector  $\mathbf{p}$  which describe the probability distribution of  $x$ :

$$\mathbf{p} = \begin{bmatrix} p_1 \\ p_2 \\ \vdots \\ p_n \end{bmatrix} \quad (10)$$

Where the element  $p_i$  within  $\mathbf{p}$  corresponding to the probability that  $x = a_i$ . It is obvious that the set  $\mathcal{P} = \{\mathbf{p} | \|\mathbf{p}\| = 1 \text{ and for each } p_i \text{ within } \mathbf{p}, p_i \geq 0\}$  is a convex set.

(a)

Follow the definition used in 9 and 10, we can define vector  $\mathbf{f}$  as:

$$\mathbf{f} = \begin{bmatrix} f(a_1) \\ f(a_2) \\ \vdots \\ f(a_n) \end{bmatrix}$$

The condition  $\alpha \leq \mathcal{E}f(x) \leq \beta$  define a set  $\mathcal{Q}$  which is a intersection of two half-space:

$$\mathcal{Q} = \{\mathbf{p} | -\mathbf{f}^T \mathbf{p} \leq -\alpha\} \cap \{\mathbf{p} | \mathbf{f}^T \mathbf{p} \leq \beta\}$$

As a result, the set of  $\mathbf{p}$  that satisfied the condition  $\alpha \leq \mathcal{E}f(x) \leq \beta$  is the intersection of  $\mathcal{P}$  and  $\mathcal{Q}$ , which produce a convex set.

(b)

We firstly define a indicator vector  $\mathbf{i}$  as:

$$\mathbf{i} = \begin{bmatrix} \mathbb{I}(a_1 > \alpha) \\ \mathbb{I}(a_2 > \alpha) \\ \vdots \\ \mathbb{I}(a_n > \alpha) \end{bmatrix}$$

Where  $\mathbb{I}(s)$  is defined as:

$$\mathbb{I}(s) = \begin{cases} 1 & \text{if } s \text{ is true} \\ 0 & \text{otherwise} \end{cases}$$

Therefore, the constrain can be expressed as:

$$\mathbf{i}^T \mathbf{p} \leq \beta$$

Which obviously, define a half-space. Therefore, the set defined by this half-space:  $\mathcal{Q} = \{\mathbf{p} | \mathbf{i}^T \mathbf{p} \leq \beta\}$  is a convex set. Consequently, the set of  $\mathbf{p}$  that satisfied the constrain can be expressed as  $\mathcal{P} \cap \mathcal{Q}$ , which is convex.

(c)

Let  $f(x)$  in (a) equal to  $x^2$ . Hence, there is:

$$\mathbf{f} = \begin{bmatrix} a_1^2 \\ a_2^2 \\ \vdots \\ a_n^2 \end{bmatrix}$$

The constrain  $\mathcal{E}x^2 \geq \alpha$  can then be expressed as:

$$-\mathbf{f}^T \mathbf{p} \leq -\alpha$$

Which define a half-space. Hence, the set of  $\mathbf{p}$  under this constrain is convex.

(d)

Assume  $\mathbf{x} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ ,  $\mathbf{p}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$  and  $\mathbf{p}_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ . Set  $\alpha = 0.2$ . Therefore, for  $\mathbf{p}_1$ , we have:

$$\text{Var}(\mathbf{x}) = 0 < 0.2$$

For  $\mathbf{p}_2$ , we have:

$$\text{Var}(\mathbf{x}) = 0 < 0.2$$

However, for  $\mathbf{p}_3 = 0.5\mathbf{p}_1 + 0.5\mathbf{p}_2$ , there is:

$$\text{Var}(\mathbf{x}) = 0.25 > 0.2$$

Hence, the set of  $\mathbf{p}$  that satisfied this constrain is not convex.

## Question 5

(a)

As the function  $f(\mathbf{x}, \mathbf{z})$  is convex over  $\mathbf{x}$ , it's Hessian Matrix over  $\mathbf{x}$  is:

$$\mathcal{H}_{\mathbf{x}} = \begin{bmatrix} \frac{\partial^2 f}{\partial x_1^2} & \frac{\partial^2 f}{\partial x_1 \partial x_2} & \cdots & \frac{\partial^2 f}{\partial x_1 \partial x_n} \\ \frac{\partial^2 f}{\partial x_2 \partial x_1} & \frac{\partial^2 f}{\partial x_2^2} & \cdots & \frac{\partial^2 f}{\partial x_2 \partial x_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial^2 f}{\partial x_n \partial x_1} & \frac{\partial^2 f}{\partial x_n \partial x_2} & \cdots & \frac{\partial^2 f}{\partial x_n^2} \end{bmatrix}$$

Which satisfied  $\mathcal{H}_{\mathbf{x}} \succeq 0$ . The Hessian Matrix of  $f$  over  $\mathbf{z}$ :  $\mathcal{H}_{\mathbf{z}}$  has the similar form as  $\mathcal{H}_{\mathbf{x}}$  and satisfied:  $\mathcal{H}_{\mathbf{z}} \preceq 0$ . As a result, the Hessian Matrix over  $\mathbf{x}$  and  $\mathbf{z}$  should be:

$$\nabla^2 f(\mathbf{x}, \mathbf{z}) = \begin{bmatrix} \mathcal{H}_{\mathbf{x}} & \mathcal{H}_{\mathbf{z}} \\ \mathcal{H}_{\mathbf{z}} & \mathcal{H}_{\mathbf{x}} \end{bmatrix}$$

(b)

Firstly, we fix  $\mathbf{x} = \tilde{\mathbf{x}}$ . Since  $f$  is concave over  $\mathbf{z}$  and  $\nabla f(\tilde{\mathbf{x}}, \tilde{\mathbf{z}}) = 0$ , according to the first-order condition of concave function, we have, for any  $\mathbf{z}$ :

$$f(\tilde{\mathbf{x}}, \mathbf{z}) < f(\tilde{\mathbf{x}}, \tilde{\mathbf{z}}) \quad (11)$$

In order to prove  $f(\tilde{\mathbf{x}}, \tilde{\mathbf{z}}) < f(\mathbf{x}, \tilde{\mathbf{z}})$ . We fix  $\mathbf{z} = \tilde{\mathbf{z}}$ . Since  $f$  is convex over  $\mathbf{x}$ , according to the first-order condition of convex function, there is:

$$f(\tilde{\mathbf{x}}, \tilde{\mathbf{z}}) + \nabla f(\tilde{\mathbf{x}}, \tilde{\mathbf{z}})(\mathbf{x} - \tilde{\mathbf{x}}) < f(\mathbf{x}, \tilde{\mathbf{z}})$$

Since  $\nabla f(\tilde{\mathbf{x}}, \tilde{\mathbf{z}}) = 0$ , we can prove that:

$$f(\tilde{\mathbf{x}}, \tilde{\mathbf{z}}) < f(\mathbf{x}, \tilde{\mathbf{z}})$$

In order to prove that  $\sup_{\mathbf{z}} \inf_{\mathbf{x}} f(\mathbf{x}, \mathbf{z}) = f(\tilde{\mathbf{x}}, \tilde{\mathbf{z}})$ . We first prove  $\inf_{\mathbf{x}} f(\mathbf{x}, \mathbf{z}) = f(\tilde{\mathbf{x}}, \mathbf{z})$ : if this equation do not hold, which means, there exist a  $\mathbf{x}^* \neq \tilde{\mathbf{x}}$  that minimize  $f(\mathbf{x}, \mathbf{z})$  over  $\mathbf{z}$ , which means,  $f(\mathbf{x}^*, \tilde{\mathbf{z}}) \leq f(\tilde{\mathbf{x}}, \tilde{\mathbf{z}})$ . However, this conflict with  $f(\tilde{\mathbf{x}}, \tilde{\mathbf{z}}) < f(\mathbf{x}, \tilde{\mathbf{z}})$ . As a result,  $\inf_{\mathbf{x}} f(\mathbf{x}, \mathbf{z}) = f(\tilde{\mathbf{x}}, \mathbf{z})$ . Furthermore, according to equation 11, there is:

$$\sup_{\mathbf{z}} f(\tilde{\mathbf{x}}, \mathbf{z}) = f(\tilde{\mathbf{x}}, \tilde{\mathbf{z}})$$

As a result,  $\sup_{\mathbf{z}} \inf_{\mathbf{x}} f(\mathbf{x}, \mathbf{z}) = f(\tilde{\mathbf{x}}, \tilde{\mathbf{z}})$ . The similar method can be used to prove  $\inf_{\mathbf{x}} \sup_{\mathbf{z}} f(\mathbf{x}, \mathbf{z}) = f(\tilde{\mathbf{x}}, \tilde{\mathbf{z}})$

(c)

We firstly fix  $\mathbf{x} = \tilde{\mathbf{x}}$ . According to  $f(\tilde{\mathbf{x}}, \mathbf{z}) \leq f(\tilde{\mathbf{x}}, \tilde{\mathbf{z}})$ ,  $f(\tilde{\mathbf{x}}, \tilde{\mathbf{z}})$  is the maximum value of function  $f(\tilde{\mathbf{x}}, \mathbf{z})$  over  $\mathbf{z}$ . Hence, there is:

$$\nabla_{\mathbf{z}} f(\tilde{\mathbf{x}}, \tilde{\mathbf{z}}) = 0$$

Furthermore, we can identify that  $f(\tilde{\mathbf{x}}, \tilde{\mathbf{z}})$  is the minimum of  $f(\mathbf{x}, \tilde{\mathbf{z}})$  over  $\mathbf{x}$  when we fix  $\mathbf{z} = \tilde{\mathbf{z}}$ , there is:

$$\nabla_{\mathbf{x}} f(\tilde{\mathbf{x}}, \tilde{\mathbf{z}}) = 0$$

Combine the above two equation, we have:  $\nabla f(\tilde{\mathbf{x}}, \tilde{\mathbf{z}}) = 0$

## Question 6

(a)

This function is convex and quasi-convex. Furthermore, this function is also quasi-concave but not concave.

(b)

This function is neither convex nor concave as it's Hessian Matrix is not semi-definite or negative semi-definite. However, this function is quasi-convex but not quasi-concave.

(c)

This function is convex and quasi-convex as it's Hessian Matrix is semi-definite. This function is neither concave nor quasi-concave.

(d)

This function is neither convex nor concave. However, this function is both quasi-convex and quasi-concave.

(e)

This function is convex and quasi-convex but not concave and quasi-concave.

(f)

This function is concave and quasi-concave but not convex and quasi-convex.